ESTIMATION OF SCATTER MATRIX WITH CONVEX STRUCTURE UNDER T-**DISTRIBUTION** Bruno Mériaux¹, Chengfang Ren¹, Mohammed Nabil El Korso², Arnaud Breloy² and Philippe Forster³ 6 S O N R A

Objectives

Covariance Matrix (CM):

- plays a central role in adaptive signal processing \Rightarrow CM estimation
- generally exhibits a specific structure (e.g. Toeplitz for ULA)

Structured CM estimation:

- Gaussian context: COvariance Matching Estimation Technique [1]
- *t*-distribution framework: used as heavy-tailed model
- normalizing the data: RCOMET [2], COCA [3], Constrained Tyler [4] • taking into account the texture \rightarrow still an open problem

The purposes of this work consist in:

- proposing a new estimation procedure, for t-distributed data with a convexly structured CM matrix.
- studying the asymptotic performance: consistency, normality and efficiency.

Problem setup

N i.i.d. t-distributed data, $\mathbf{y}_n \sim \mathbb{C}t_{m,d}(\mathbf{0}, \mathbf{R}), n = 1, \dots, N$ [5]:

- $\mathbf{y}_n \in \mathbb{C}^m$ with N > m
- *d* degrees of freedom assumed known

Scatter matrix \mathbf{R}

- belongs to \mathcal{S} , a convex subset of Hermitian positive-definite matrices
- there exists a one-to-one differentiable mapping $\mu \mapsto \mathbf{R}(\mu)$ from \mathbb{R}^P to \mathcal{S}

Unknown interest parameter: $\boldsymbol{\mu} \in \mathbb{R}^p$, with exact value $\boldsymbol{\mu}_e$ Maximum Likelihood Estimator (MLE) of μ

$$\hat{\boldsymbol{\mu}}_{\mathrm{ML}} = \arg \max_{\boldsymbol{\mu}} - (d+m) \sum_{n=1}^{N} \log \left(1 + \frac{\mathbf{y}_{n}^{H} \mathbf{R}(\boldsymbol{\mu})^{-1} \mathbf{y}_{n}}{d} \right) - \mathbf{h}$$

Fisher information matrix

Let be $\mathbf{y} \sim \mathbb{C}t_{m,d}(\mathbf{0}, \mathbf{R}(\boldsymbol{\mu}_e))$, with $\boldsymbol{\mu}_e \in \mathbb{R}^P$. The FIM is expressed by [6]

$$\mathbf{F}(\boldsymbol{\mu}_{\mathrm{e}}) = \frac{\partial \mathbf{r}(\boldsymbol{\mu})}{\partial \boldsymbol{\mu}} \Big|_{\boldsymbol{\mu}_{\mathrm{e}}}^{H} \mathbf{Y}_{\mathrm{e}} \frac{\partial \mathbf{r}(\boldsymbol{\mu})}{\partial \boldsymbol{\mu}} \Big|_{\boldsymbol{\mu}_{\mathrm{e}}}$$

where $\frac{\partial \mathbf{r}(\boldsymbol{\mu})}{\partial \boldsymbol{\mu}}$ refers to the Jacobian matrix of $\mathbf{r}(\boldsymbol{\mu}) = \operatorname{vec}(\mathbf{R}(\boldsymbol{\mu}))$, $\mathbf{W}_{\mathrm{e}} = \mathbf{R}_{\mathrm{e}}^{T} \otimes \mathbf{R}_{\mathrm{e}} \text{ and } \mathbf{Y}_{\mathrm{e}} = \frac{(d+m)\mathbf{W}_{\mathrm{e}}^{-1} - \operatorname{vec}(\mathbf{R}_{\mathrm{e}}^{-1})\operatorname{vec}(\mathbf{R}_{\mathrm{e}}^{-1})^{H}}{d+m+1}$.

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Main results

Proposed algorithm

• Step 1: unstructured MLE of **R**

The unstructured MLE, $\widehat{\mathbf{R}}$, is the solution of the fixed point equation:

$$\widehat{\mathbf{R}} = \frac{d+m}{N} \sum_{n=1}^{N} \frac{\mathbf{y}_n \mathbf{y}_n^{n}}{d + \mathbf{v}_n^H \widehat{\mathbf{R}}^{-1} \mathbf{v}_n} \triangleq \mathcal{H}_N(\widehat{\mathbf{R}})$$
(2)

Existence and uniqueness of this solution, convergence of the iterative algorithm $\mathbf{R}_{k+1} = \mathcal{H}_N(\mathbf{R}_k)$ to $\widehat{\mathbf{R}}$ for any initialization and consistency of \mathbf{R} are ensured [5].

• Step 2: Estimation of μ

The minimization of the following criterion w. $\widehat{\boldsymbol{\mu}} = \arg\min_{\boldsymbol{\mu}} (\widehat{\mathbf{r}} - \mathbf{r}(\boldsymbol{\mu}))^H \widehat{\mathbf{Y}}$

with $\widehat{\mathbf{Y}} = (d+m)\widehat{\mathbf{W}}^{-1} - \operatorname{vec}\left(\widehat{\mathbf{R}}^{-1}\right)\operatorname{vec}\left(\widehat{\mathbf{R}}^{-1}\right)$ yields a unique solution $\hat{\mu}$ for μ .

Asymptotic analysis

 $\hat{\mu}$, obtained by (3), is consistent, asymptotically Gaussian and efficient: $\sqrt{N} \left(\hat{\boldsymbol{\mu}} - \boldsymbol{\mu}_{\mathrm{e}} \right) \stackrel{\mathcal{L}}{\rightarrow} \mathcal{N} \left(\boldsymbol{0}, \mathbf{F}(\boldsymbol{\mu}_{\mathrm{e}})^{-1} \right)$

Numerical results

Simulation settings:

- the real and imaginary parts of the first row of \mathbf{R}_{e} .
- m = 4, d = 5, 5000 sets of N i.i.d. $\mathbf{y}_n \sim \mathbb{C}t_{m,d}(\mathbf{0}, \mathbf{R}_e), n = 1, \dots, N.$ • $\mathbf{R}_{e} \triangleq \mathbf{R}(\boldsymbol{\mu}_{e})$ is Hermitian Toeplitz, $\boldsymbol{\mu}_{e}$ is a real-valued vector containing

Comparison of the performance with the state of the art:

- Proposed algorithm with unstructured ML, $\widehat{\mathbf{R}}$ as step 1 • Proposed algorithm with joint estimation of d and \mathbf{R} [7] as step 1 \Rightarrow to deal with the possibility of unknown parameter d
- RCOMET [2] and COCA [3] based on $\mathbf{z}_n = \mathbf{y}_n / \|\mathbf{y}_n\|$
- Projection onto the Toeplitz set by averaging the diagonals of **R**

Conclusion

In this paper, we addressed structured covariance estimation for convex structures. A consistent, asymptotically unbiased and efficient estimator is proposed for t-distribution. A generalization for any Complex Elliptically Symmetric distributions is studied in [8]. Numerical simulations confirm the theoretical analysis and the practical interest of this approach.

 $N \log |\mathbf{R}(\boldsymbol{\mu})|$

(1)

i.r.t
$$\boldsymbol{\mu}$$

 $(\widehat{\mathbf{r}} - \mathbf{r}(\boldsymbol{\mu}))$ (3)
 $(\widehat{\mathbf{R}}^{-1})^{H}$ and $\widehat{\mathbf{W}} = \widehat{\mathbf{R}}^{T} \otimes \widehat{\mathbf{R}}$



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