LOW-FREQUENCY IMAGE NOISE REMOVAL **USING WHITE NOISE FILTER**

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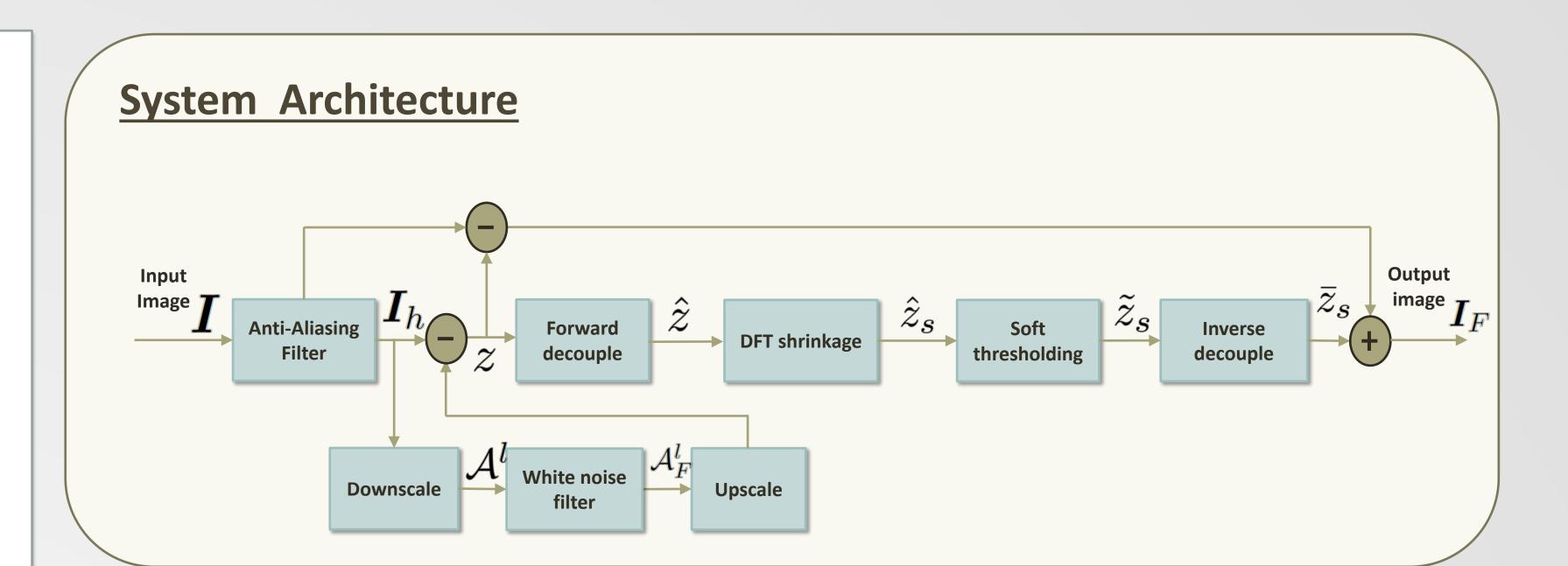
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Introduction

Problems:

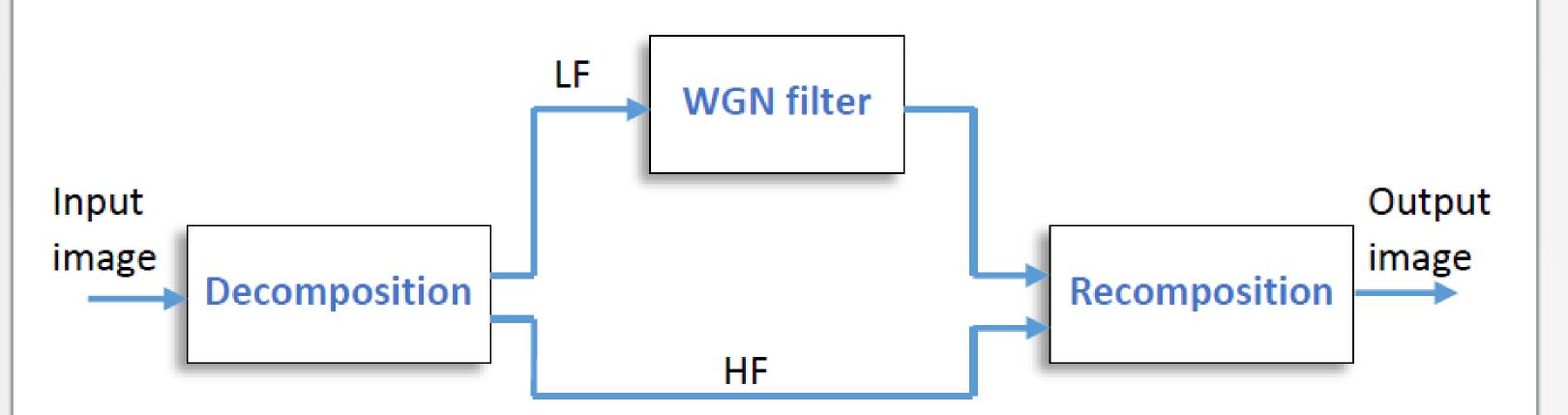
- Real-world image/video capturing introduces low-frequency or grainy noise.
- > High-frequency details of the image cannot be seen on a small display.
- > Conventional noise reduction methods are designed to remove white or all-frequency noise.



Solution:

 \geq We propose an approach for a coarse-grain removal using existing white noise filters.

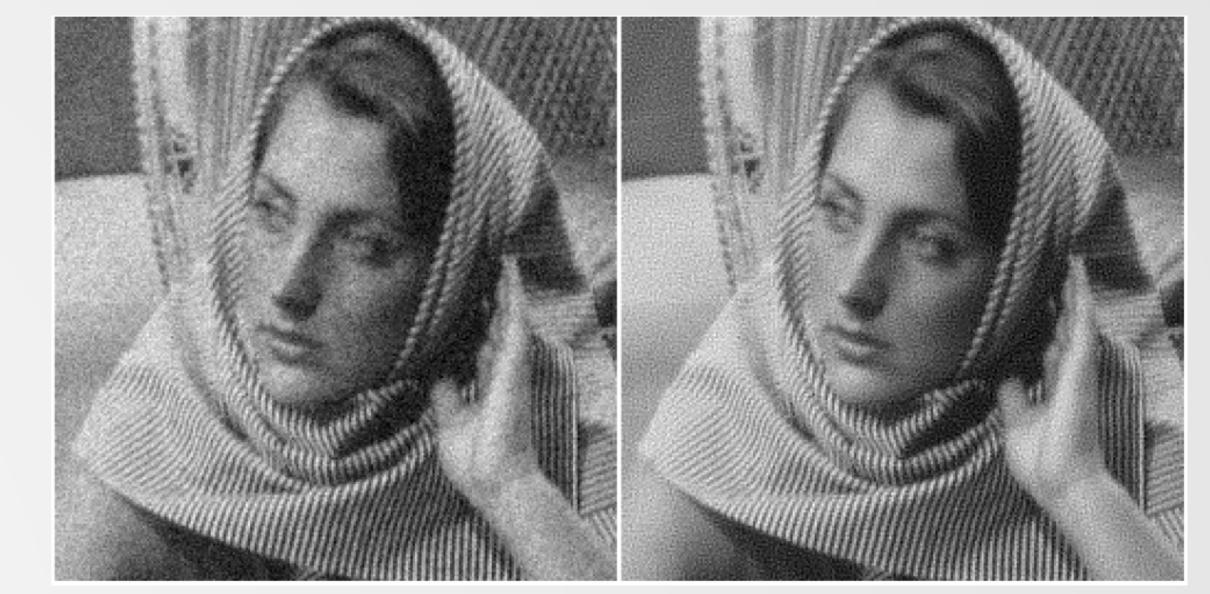
Conventional Removal of Low Frequency Noise



Problem:

 \rightarrow HF contains noise \rightarrow output is still noisy

LF noise has a more impact on visual quality



White noise Same PSNR

HF noise

Experimental results

Synthetic noise

 $I_n = I + n^*h$

n Gaussian noise with $\sigma_o = 15$

Our Algorithm:

 $I_h = I * h_a$ 1: Anti-aliasing (Low-pass) filter:

- $\mathcal{A}^l = \mathbf{I}_h(0:2^l:\mathbf{c},\ 0:2^l:\mathbf{r})$ **2:** Downscale and filter image using a white noise filter $\mathcal{A}_{F}^{l} = \mathbf{WGF}(\mathcal{A}^{l}, \sigma_{w})$
- **3- Upscale filtered image and compute the residual image**

 $z = I_h - \mathbf{U}_l(\mathcal{A}_F^l)$

4- Filter the decoupled residual image using DCT shrinkage

 $\hat{z} = \mathbf{FDC}(\mathbf{I}_h) \qquad \qquad \tilde{z}_s = \hat{z}_s \left[1 - \exp(-p)\right], p = \max\left(\frac{|\hat{z}_s|}{c_t \sigma_w} - 1, 0\right)$

5- inverse decouple

 $I_F = I - z + \bar{z}_s$, $\bar{z}_s = IDC(\tilde{z}_s)$

Decoupling makes the low-frequency noise less spatially correlated

h Gaussian filter with $\sigma_{corr} = 0.6$

PSNR averaged over the TID2013 dataset degraded with LF noise, comparing proposed and related decomposition methods

WGN filter	Wavelet Harr	Wavelet D4	Gaussian pyramid bilinear	Gaussian pyramid bicubic	Gaussian pyramid Lanczos	Proposed
BM3D	31.94	32.02	31.41	31.87	32.02	32.97
PID	31.73	31.90	31.35	31.83	32.00	32.96

Real filtered and compressed noise



BM3D

BM3D in the proposed framework

Synthetic low-frequency noise



Original

Decoupled **Decoupling of neighbor pixels**

Decoupled of decoupled



BM3D

BM3D in the proposed framework