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Label Propagation on Facial Images Using Similarity and Dissimilarity Labelling Constraints

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- Tagging facial regions with person ID in images and videos is useful for archival/search but time consuming when done manually.
- One approach that can be used is label propagation:
 - Manual labeling of faces with person ID in specific video frames or images
 - ► Spreading the labels from the (small) labeled facial image dataset to the unlabeled images.
 - Semi-supervised classification approach

Label Propagation Example

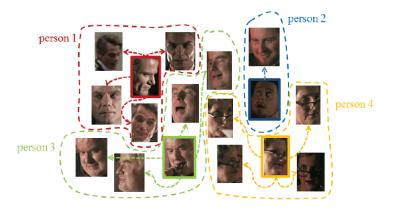


Figure: Propagate the labels from the manually labelled images (in rectangles) to the remaining ones.

Overview



Goal:

Enhance classification performance (labeling accuracy) of the Multiple-graph Locality Preserving Projections – Cluster based Label Propagation (MLPP-CLP) technique (Zoidi et al ¹), when applied on facial images derived from stereo videos,

► How:

Incorporate pairwise facial image similarity and dissimilarity constraints into the objective function of MLPP-CLP.

¹O Zoidi, A Tefas, N Nikolaidis, and I Pitas, "Person identity label propagation in stereo videos," IEEE Transactions on Multimedia, vol.16, no. issue 5, pp. 1358–1368, 2014.

- Facial images are extracted by applying face detection and tracking in the left/ right view of a stereo video.
- Facial image trajectories are derived: sequences of facial images representing a tracked face over time.



 Each such facial trajectory is represented by one image (short trajectories) or more images (longer trajectories).

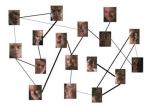
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Inputs:

- Set of labeled facial images: $X_L = {\mathbf{x}_i}_{i=1}^{m_l}$
- Set of persons names (labels): $L = \{I_j\}_{j=1}^Q$
- Set of unlabeled data: $X_U = {\{\mathbf{x}_i\}_{i=1}^{m_u}}$
- ► Set of labeled and unlabeled facial images: $X = {\mathbf{x}_1, ..., \mathbf{x}_{m_l}, \mathbf{x}_{m_l+1}, ..., \mathbf{x}_M}, M = m_l + m_u$

Objective: spread the labels in *L* from the set of labeled data X_L to the set of unlabeled data X_U .

- MLPP-CLP: Extension of the Zhou et al² approach to data with multiple representations
- ► Facial images in stereoscopic video: *K*=2 data representations, left/right channel
- ► Build facial images similarity matrix W using heat kernel
- ► $W_{ij} = e^{-\frac{\left\|\mathbf{x}_i \mathbf{x}_j\right\|^2}{\sigma}}, i \neq j, \mathbf{x}_i, \mathbf{x}_j \text{ are k-NN}$
- ► W represents the corresponding similarity graph (nodes=images)



²D. Zhou, O. Bousquet, T.N. Lal, J. Weston, and B. Scholkopf, "Learning with local and global consistency," NIPS 2004.

► Build matrix Y containing information regarding the labels in labeled data set X_L :

$$Y_{ij} = \begin{cases} 1, & \text{if image } i \text{ is labeled as } y_i = j \\ 0, & \text{otherwise.} \end{cases}$$

Label Inference: Assign a score for every label to each facial image through matrix F:

$$\boldsymbol{\mathsf{F}} = [\boldsymbol{\mathsf{f}}_1^{\mathsf{T}},...,\boldsymbol{\mathsf{f}}_M^{\mathsf{T}}]^{\mathsf{T}} \in \boldsymbol{\mathsf{R}}^{M \times Q}$$

- *F_{ij}*: score for *j*-th label in *i*-th image
- Q: number of labels, M: number of images



$$\mathbf{F} = (1-a)(\mathbf{I} - a\mathbf{S})^{-1}\mathbf{Y},$$

- ▶ $S = D^{-1/2}WD^{-1/2}$
- $D_{ii} = \sum_{i} W_{ij}$ degree matrix
- ► Label y_i for *i*-th image: $y_i = \underset{j \in 1,...,Q}{\operatorname{arg max}} [f_{i1}, \ldots, f_{ij}, \ldots, f_{iQ}]$
 - Image is assigned the label with the highest score

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- MLPP-CLP extends this approach to data with multiple representations,
- ► A separate graph is constructed for each of the *K* facial image representations
 - ► K = 2 for stereoscopic images: left / right view.
- ► Each graph is represented by the corresponding similarity matrix W_k, k = 1, ..., K
- The regularization framework takes the form:

$$Q(\mathbf{F},\tau) = \frac{1}{2} \sum_{k=1}^{K} \tau_k tr(\mathbf{F}^T \mathbf{L}_k \mathbf{F}) + \mu tr((\mathbf{F} - \mathbf{Y})^T (\mathbf{F} - \mathbf{Y})),$$

- ► $L_k = D_k W_k$: graph Laplacian for the *k*-th data representation.
- ▶ τ_k , k = 1,...,K: weight for the *k*-th data representation



- ► This leads to the following solution for F:
 - $\mathbf{F} = (1 a) (\mathbf{I} a \sum_{k} \tau_k \mathbf{S}_k)^{-1} \mathbf{Y}$

$$\bullet \ \mathbf{S}_k = \mathbf{D}^{-1/2} \mathbf{W}_k \mathbf{D}^{-1/2}$$

- MLPP also performs dimensionality reduction by extending Locality Preserving Projections (LPP) method³ to a multiple-graph framework
- A single projection matrix A is constructed for all data representations, while preserving locality information and similarity/dissimilarity constraints.

³X. He, P. Niyogi, "Locality Preserving Projections", NIPS 2003

- Proposed Constrained MLPP-CLP (CMLPP-CLP) approach incorporates pairwise image similarity and dissimilarity constraints in the MLPP-CLP objective function.
 - Similar images shall be assigned the same label:
 - S: set of similar facial image pairs:

 $S = \{(i, j) | \mathbf{x}_i, \mathbf{x}_j \text{ must have the same label} \}$

► *S* contains facial images belonging to the same facial image trajectory

They depict the same actor

Dissimilar images shall be assigned different labels:

► *D*: set of dissimilar pairs:

 $D = \{(i, j) | \mathbf{x}_i, \mathbf{x}_j \text{ must have different labels} \}$

► *D* includes facial image pairs that appear on the same frame

They belong to different actors.

► Two weight matrices **W**_s, **W**_d are constructed:

$$W_{s,ij} = \begin{cases} 1, & \text{if } (i,j) \in S \\ 0, & \text{otherwise,} \end{cases}$$

$$W_{d,ij} = \begin{cases} 1, & \text{if } (i,j) \in D \\ 0, & \text{otherwise.} \end{cases}$$

 Similarity and dissimilarity information is propagated to neighboring nodes according to an iterative procedure that converges to the steady state solution:

$$\mathbf{F}_s = (1 - \alpha)(\mathbf{I} - \alpha \mathbf{P})^{-1} \mathbf{W}_s$$
$$\mathbf{F}_d = (1 - \alpha)(\mathbf{I} - \alpha \mathbf{P})^{-1} \mathbf{W}_d.$$

▶ $\mathbf{P} \in \Re^{M \times M}$: sparse neighborhood probability matrix:

$$P_{ij} = \left\{ egin{array}{cc} rac{1}{|N_i|} & ext{if } j \in N_i \ 0, & ext{otherwise}. \end{array}
ight.$$

N_i: neighborhood of node i

- Then dimensionality reduction is performed through MLPP.
- Label propagation is conducted on the data projections, by incorporating the pairwise similarity and dissimilarity constraints to the label propagation objective function:

$$Q(\mathbf{F}) = \frac{1}{2} tr(\mathbf{F}^T \left(\sum_{k=1}^{K} \tau_k \mathbf{L}_k + \beta \mathbf{L}_s - \gamma \mathbf{L}_d \right) \mathbf{F}) + \mu tr((\mathbf{F} - \mathbf{Y})^T (\mathbf{F} - \mathbf{Y}))$$

► L_s = D_s - F_s, L_d = D_d - F_d: graph Laplacians of the similarity and dissimilarity constrains.

▶ Minimization of *Q*(**F**) leads to the following solution for **F**:

$$\mathbf{F} = \mu \left(\mathbf{a} \mathbf{I} + \sum_{k=1}^{K} \tau_k \mathbf{L}_k + \beta \mathbf{L}_s - \gamma \mathbf{L}_d \right)^{-1} \mathbf{Y}.$$

Experimental evaluation



Dataset:

- 3 stereo movies
- Duration: 2 hours each
- ► Facial images per movie: 5300, 3500, 5000 (after retaining one/more image(s) per facial trajectory)
- Actors (classes) per movie: 26, 44, 58.
- ▶ 5% of the facial images were manually labeled.
- Dimensionality reduction down to 75 dimensions



	MLPP-CLP	CMLPP-CLP
Movie 1	0.7859	0.801223
Movie 2	0.6395	0.672213
Movie 3	0.62	0.710133

Classification accuracy obtained using MLPP-CLP and Constrained MLPP-CLP (CMLPP-CLP).

- Incorporation of pairwise constraints into the objective function of label propagation increases the classification accuracy by 4.6% on average.
- Recent experiments showed that CMLPP-CLP outperforms both older and recent approaches
 - OMNI-Prop, Yamaguchi et al., AAAI 2015
 - CAMLP, Yamaguchi et al., SIAM Int. Conf. on Data Mining, 2016
 - MLAN, Nie et al, AAAI 2017



- A human annotator can perform two different actions towards reaching a desired classification accuracy:
 - Manually label additional unlabeled images or
 - Place additional pairwise facial image similarity or dissimilarity constraints
- Experiments were conducted in order to answer the following questions:
 - ► What is the effect of inserting one or more constraints or labeling one or more images?
 - Which of the two actions is more beneficial?



► *N_{RL}*: current number of manually labeled images

• N_{TL} : number of manually labeled images required in order to reach the desired classification accuracy P (without using pairwise constraints)

• N_c : number of pairwise similarity constraints needed (in addition to the N_{RL} labeled images) in order to reach P

► Ratio *r* of additional labeled images over additional constraints for achieving desired classification accuracy:

$$r = (N_{TL} - N_{RL})/N_c$$

► Small *r* (below 1): more constraints than labels are needed in order to reach the desired accuracy *P*

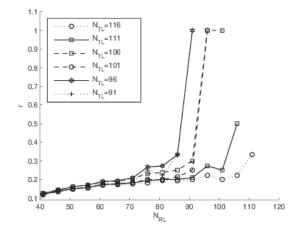


Figure: *r* versus N_{RL} for various values of N_{TL} (desired accuracy *P*).



- r is in most cases significantly below 1:
 - ► Less labeled images than labeling constraints are neededto reach the desired accuracy
 - ► Labeled images carry more information than constraints.
- However, the effort of labeling an image is larger than that of assigning a pairwise labeling constraint.

Conclusions



- A novel method (CMLPP-CLP) for propagating person identity labels on facial images extracted from stereo videos was introduced.
- It incorporates similarity and dissimilarity labelling constraints in order to increase the classification accuracy
- ► The proposed method outperforms current methods.
- It can be used to perform label propagation in other types of images or data in general.
- It can be easily adapted to work with images taken from monocular cameras.
- An investigation of labels vs constraints strategy that should be followed in order to reach a desired accuracy was also conducted.





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Thank you for your attention!