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Conclusion and Future Work Unsupervised Keyword Spotting using Bounded Generalized Gaussian Mixture Model with ICA

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Unsupervised Keyword Spotting

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• Automatic Speech Recognition (ASR)

- Problems associated with ASR
- Unsupervised Methods for ASR
- Keyword Spotting and ASR
- Dynamic Time Warping and Mixture Model



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Development in Mixture Models

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• Problems in Mixture Models: Senitivity to the outliers in GMM

- Development in Mixture model: SMM, GGMM
 - SMM: Improved robustness of algorithm and more flexible approach

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 GGMM: Extensible to fit different shapes using shape parameters, i.e. can generalized into GMM and LMM

Bounded Support Mixture Models: BGMM, BGGMM



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- Data comes from a mixture model and it can be categorized into mutually exclusive classes
 - Each class of data is modeled as ICA
 - Computation of Data log-likelihood
 - Computation of Posterior
 - Adaptation of Parameters using standard ICA Model
- Applications: Blind source separation, classification, image Segmentation and speech and image processing etc.

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Multivariate Bounded Generalized Gaussian Mixture Model

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Conclusion and Future Work • The data $\mathcal{X} = (\vec{X}_1, ..., \vec{X}_N)$, with a mixture of *K* distributions can be modeled as :

$$p(\mathcal{X}|\Theta) = \prod_{i=1}^{N} \sum_{j=1}^{K} p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) p_j$$
(1)

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Where Θ represents the parameters of mixture model having *K* classes as $\Theta = (\xi_1, \xi_2, \xi_3, \xi_4)$, with $\xi_1 = (\vec{\mu}_1, ..., \vec{\mu}_K), \xi_2 = (\vec{\sigma}_1, ..., \vec{\sigma}_K), \xi_3 = (\vec{\lambda}_1, ..., \vec{\lambda}_K)$ and $\xi_4 = (p_1, ..., p_K)$.

• The term $p(\vec{X}|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)$ represents the bounded generalized Gaussian distribution (BGGD).

$$p(\vec{X}|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) = \frac{f(\vec{X}|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) \mathbf{H}(\vec{X}|\Omega_j)}{\int_{\partial_{\Omega_i}} f(\mathbf{X}|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) d\mathbf{X}}$$



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(2)

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Multivariate Bounded Generalized Gaussian Mixture Model

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Experiment an Results

Conclusion and Future Work Where $H(\vec{X}|\Omega_j) = \begin{cases} 1 & \text{if } \vec{X} \in \partial_{\Omega_j} \\ 0 & \text{otherwise} \end{cases}$

and
$$f(\vec{X}|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) = \prod_{d=1}^{D} B(\lambda_{jd}) \exp\left(-A(\lambda_{jd}) \left|\frac{X_d - \mu_{jd}}{\sigma_{jd}}\right|^{\lambda_{jd}}\right)$$
 (4)

with

$$B(\lambda_{jd}) = \frac{\lambda_{jd}\sqrt{\Gamma(3/\lambda_{jd})}}{2\sigma_{jd}\Gamma(1/\lambda_{jd})\sqrt{\Gamma(1/\lambda_{jd})}} \text{ and } A(\lambda_{jd}) = \left[\frac{\Gamma(3/\lambda_{jd})}{\Gamma(1/\lambda_{jd})}\right]^{\lambda_{jd}/2}$$
(5)

where $\Gamma(.)$ is the gamma function and $\vec{\mu} = (\mu_1, ..., \mu_D)$, $\vec{\sigma} = (\sigma_1, ..., \sigma_D)$, and $\vec{\lambda} = (\lambda_1, ..., \lambda_D)$ are the mean, standard deviation and shape parameters respectively.

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(3)



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$$\vec{X}_i = A_j \vec{s}_{j,i} + \vec{b}_j \tag{6}$$

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where A_j is $L \times D$ basis matrix, $\vec{s}_{j,i}$ is *D*-dimensional source vector and \vec{b}_j is an *L*-dimensional bias vector for a particular mixture *j*. For the simplicity, number of linear combinations (*L*) is considered to be equal to the number of sources (*D*) for each observation of the dataset.



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$$p(\mathcal{X}, Z|\Theta) = \prod_{i=1}^{N} \sum_{j=1}^{K} \left(p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) p_j \right)^{Z_{ij}}$$
(7)

• The log-likelihood function is given below.

$$L(\mathcal{X}, Z|\Theta) = \sum_{i=1}^{N} \sum_{j=1}^{K} Z_{ij} \log \left(p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) p_j \right)$$
(8)

where Z_{ij} is the posterior probability and can be written as:

$$Z_{ij} = p(j|\vec{X}_i) = \frac{p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)p_j}{\sum_{j=1}^{K} p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)p_j}$$
(9)

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and $Z = \{\vec{Z}_1, ..., \vec{Z}_N\}$



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$$p(\mathcal{X}, Z|\Theta) = \prod_{i=1}^{N} \sum_{j=1}^{K} \left(p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) p_j \right)^{Z_{ij}}$$
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• The log-likelihood function is given below.

$$L(\mathcal{X}, Z|\Theta) = \sum_{i=1}^{N} \sum_{j=1}^{K} Z_{ij} \log \left(p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) p_j \right) \quad (8)$$

where Z_{ij} is the posterior probability and can be written as:

$$Z_{ij} = p(j|\vec{X}_i) = \frac{p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)p_j}{\sum_{j=1}^{K} p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)p_j}$$
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Parameter Estimation

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• Maximization of the log-likelihood Mean, standard deviation and prior probability

• Standard ICA Model Basis function, bias vector and shape parameter



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Parameter Estimation: Maximization of the log-likelihood

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• Prior Probability

$$\hat{p}_j = \frac{1}{N} \sum_{i=1}^{N} p(j | \vec{X}_i)$$
(10)

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• Mean

$$\hat{\mu}_{jd} = \frac{\sum_{i=1}^{N} p(j | \vec{X}_i) (|X_{id} - \mu_{jd}|^{\lambda_{jd} - 2} X_{id} + T_{jd})}{\sum_{i=1}^{N} p(j | \vec{X}_i) |X_{id} - \mu_{jd}|^{\lambda_{jd} - 2}}$$
(11)

where

$$T_{jd} = \frac{\sum_{m=1}^{M} \operatorname{sign}(\mu_{jd} - s_{j_{md}}) |\mu_{jd} - s_{j_{md}}|^{\lambda_{jd}-1} \operatorname{H}(s_{j_{md}} |\Omega_j)}{\sum_{m=1}^{M} \operatorname{H}(s_{j_{md}} |\Omega_j)}$$
(12)

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Parameter Estimation: Maximization of the log-likelihood

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(12)



Parameter Estimation: Maximization of the log-likelihood

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• Standard Deviation

$$\hat{\sigma}_{jd} = \left(\frac{\lambda_{jd} A(\lambda_{jd}) \sum_{i=1}^{N} p(j | \vec{X}_i) |X_{id} - \mu_{jd}|^{\lambda_{jd}}}{\sum_{i=1}^{N} p(j | \vec{X}_i) (1 + Q_{jd})}\right)^{1/\lambda_{jd}}$$
(13)

where

$$Q_{jd} = \frac{\sum_{m=1}^{M} (-1 + \lambda_{jd} A(\lambda_{jd}) |s_{mjd} - \mu_{jd}|^{\lambda_{jd}} (\sigma_{jd})^{-\lambda_{jd}}) \mathbf{H}(s_{mjd} |\Omega_j)}{\sum_{m=1}^{M} \mathbf{H}(s_{mjd} |\Omega_j)}$$
(14)

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with
$$i = 1, ..., N, j = 1, ..., K, d = 1, ..., D$$
 and $m = 1, ..., M$.



Parameter Estimation: Standard ICA Model

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Conclusion and Future Work • The gradient of log-likelihood for the parameters of each class is given below.

$$\nabla_{\theta_j} L(\mathcal{X}, Z | \Theta) = \sum_{i=1}^N Z_{ij} \left(\nabla_{\theta_j} \log p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) + \nabla_{\theta_j} \log p_j \right)$$
(15)

The ∇_{θ_j} represent gradient with respect to basis function, bias vector and shape parameter.

• The standard ICA model is used for the log-likelihood as follows:

$$\log p(\vec{X}_i | \vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) = \log \frac{p(\vec{s}_{j,i})}{|\det A_j|}$$
(16)

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Parameter Estimation: Standard ICA Model

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Conclusion and Future Work • The gradient ascent is used to estimate the shape parameter by maximizing the log-likelihood and represented as:

$$\nabla_{\vec{\lambda}_j} \log[p(\mathcal{X}|\Theta)] = \sum_{i=1}^N p(j|\vec{X}_i) \nabla_{\vec{\lambda}_j} \log p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) \quad (17)$$

• The gradient ascent is used for the adaptation, with the gradient of the component density with respect to shape parameter vector $\vec{\lambda}_j$ for each component of the mixture model.

$$\Delta \vec{\lambda}_j \propto p(j|\vec{X}_i) \frac{\partial}{\partial \vec{\lambda}_j} \log p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)$$
(18)

 $\frac{\partial}{\partial \vec{\lambda}_{j}} \log p(\vec{X}_{i} | \vec{\mu}_{j}, \vec{\sigma}_{j}, \vec{\lambda}_{j}) = \vec{\lambda}_{j} [I - 2 \tanh(\vec{s}_{j,i}) \vec{s}_{j,i}^{T}]$ (19)

• By combining Eqs. (18) and (19), we get:

$$\Delta \vec{\lambda}_j \propto p(j|\vec{X}_i) \vec{\lambda}_j [I - 2 \tanh(\vec{s}_{j,i}) \vec{s}_{j,i}^T]$$
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$$\hat{\lambda}_j = \vec{\lambda}_j + \alpha (p(j|\vec{X}_i)\vec{\lambda}_j[I - 2\tanh(\vec{s}_{j,i})\vec{s}_{j,i}^T])$$
(21)

where the source is represented as: $\vec{s}_{j,i} = A_j^{-1}(\vec{X}_i - \vec{b}_j)$.

• The adaptation of basis functions for each class is performed by maximizing the log-likelihood with respect to basis functions *A_j* for each component of mixture model.

$$\nabla_{A_j} \log[p(\mathcal{X}|\Theta)] = \sum_{i=1}^{N} p(j|\vec{X}_i) \nabla_{A_j} \log p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j) \quad (22)$$

• The adaptation performed by the gradient ascent with respect to the basis functions is given as:

$$\Delta A_j \propto p(j|\vec{X}_i) \frac{\partial}{\partial A_j} \log p(\vec{X}_i|\vec{\mu}_j, \vec{\sigma}_j, \vec{\lambda}_j)$$
(23)

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Bounded Generalized Gaussian Mixture Model with ICA

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Conclusion and Future Work • By using the standard ICA model for log-likelihood, we get: $\Delta A_i \propto p(j|\vec{X}_i)A_j[I-2\tanh(\vec{s}_{j,i})\vec{s}_{i,j}^T] \qquad (24)$

• The bias vector \vec{b}_j is estimated using an approximate method as below:

$$\vec{b}_{j} = \frac{\sum_{i=1}^{N} \vec{X}_{i} p(j | \vec{X}_{i})}{\sum_{i=1}^{N} p(j | \vec{X}_{i})}$$
(25)

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• In the adaptation of the shape parameter, basis functions and bias vector, the gradient of the component of the mixture model is weighted by $p(j|\vec{X}_i)$.



Bounded Generalized Gaussian Mixture Model with ICA

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Model Learning with BGGMM using ICA

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```
1: Input:Dataset \mathcal{X} = \{\vec{X}_1, \dots, \vec{X}_N\}, t_{min}.
2: Output: \xi_1, \xi_2, \xi_3, and \xi_4.
3:
     {Initialization}: K-Means Algorithm. Set \xi_3 = 2.
4:
     while relative change in log-likelihood > t_{min} do
5:
        {[E Step]}:
6:
          for all 1 \le j \le K do
7:
             Compute p(\vec{X}_i | \vec{\mu}_i, \vec{\sigma}_i, \vec{\lambda}_i) for i = 1, \dots, N.
8:
             Compute p(i|\vec{X}_i) for i = 1, \dots, N.
9:
          end for
10:
          {[M step]}:
11:
             for all 1 \le i \le K do
12:
                start ICA Algorithm
13:
                   Update the basis functions A_i.
14:
                   Update the bias vector \vec{b}_i.
15:
                   Update shape parameter \vec{\lambda}_i.
16:
17:
                end ICA
                Update the mixing parameter p_i.
18:
                Update the mean \vec{\mu}_i.
19:
                Update standard deviation \vec{\sigma}_i.
20:
             end for
21: end while
```

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• Feature Extraction: MFCC

- Training ICA Mixture Model
- Gaussian Posteriorgrams for keyword example and test data
- Segmental Dynamic Time Warping
- Keyword detection: Score Fusion



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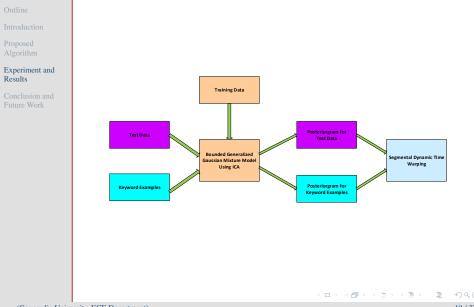


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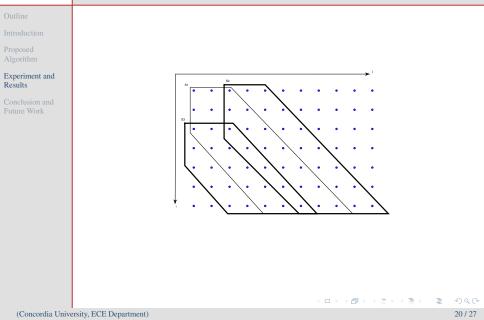
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Segmental Dynamic Time Warping





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• TIMIT Speech Corpus, 6300 speech utterances (Training:4620, Test:1680)

- Same Parameters for keyword spotting from the literature
- Evaluation Matrices, average precision (P@10 and P@N), Equal Error Rate (EER) and the ranking of several keywords based on EER
- Comparison of detection results: ICA mixture model with GMM



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• TIMIT 10 Keyword List

• Evaluation matrix using ICA Mixture Model

• Evaluation matrix using Gaussian Mixture Model

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• TIMIT 10 Keyword List

age(3:10) artists(7:7) surface(3:7)	warm(10:8) problem(22:9) development(9:8)	year(11:177) children(18:15) organizations(7:7)	money(19:17)
surface(3:7)	development(9:8)	organizations(7:7)	

• Evaluation matrix using ICA Mixture Model

P@10	P@N	EER
28.37%	26.43%	29.20%
57.75%	51.39%	13.79%
64.87%	58.27%	12.35%
	28.37% 57.75%	28.37% 26.43% 57.75% 51.39%

• Evaluation matrix using Gaussian Mixture Model

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surface(3:7)	development(9:8)	organizations(7:7)	

• Evaluation matrix using ICA Mixture Model

# of Examples	P@10	P@N	EER
1	28.37%	26.43%	29.20%
5	57.75%	51.39%	13.79%
10	64.87%	58.27%	12.35%

• Evaluation matrix using Gaussian Mixture Model

P@10	P@N	EER
27.0%	17.3%	27.0%
61.3%	33.0%	16.8%
68.3%	39.3%	15.8%
	27.0% 61.3%	27.0% 17.3% 61.3% 33.0%

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• Ranking of Keywords by EER

• 5 examples of each keyword

• The words with more syllables have better performance

organizations(6.1%) problem(12.6%) warm(21.4%) development(6.7% artists(13.5%) year(22.9%) childern(11.3%) money(15.8%)



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- TIMIT Speech Corpus for evaluation of keyword spotting framework
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• More simulations with large vocabulary database

• Use of ICA Mixture Model in different applications to validate the algorithm

• Variational Bayesian learning or minimum description length to automatically optimize the parameters



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