ProSparse Denoise: Prony's based Sparse Pattern Recovery in the Presence of Noise

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- Sparse Representation in Pairs of Bases
- **ProSparse**: A new polynomial time algorithm for sparse signal representation
 - Determinist Bounds
 - Average case performance
 - ProSparse Denoise: signal recovery in the presence of noise

Sparse Representation in Fourier and Canonical Bases



Goal:

Given y, finds its *sparse* representation in Fourier and canonical bases

Applications

- Source separation: decompose signals into a smooth part and local innovations
- Prototype for the following problem:

Given two bases (or frames) $m{D}=[m{\Psi}, m{\Phi}]$. Represent an observed signal as a superposition of a few atoms from $m{\Psi}$ and a few atoms from $m{\Phi}$.

Example: (Curvelets + DCT)



images from [Elad, Starck, Querre, Donoho, 2005]

Problem formulation:

Assume that

$$y = [F, I] = Dx$$

 \boldsymbol{x} : a (K_p, K_q) -sparse signal. Given \boldsymbol{y} , find its sparse representation \boldsymbol{x} .

Ideally, solve $(P_0): \arg \min_{\widetilde{x}} \|\widetilde{x}\|_0 \quad \text{s.t.} \quad y = D\widetilde{x}$ Convex relaxation: $(P_1): \arg \min_{\widetilde{x}} \|\widetilde{x}\|_1 \quad \text{s.t.} \quad y = D\widetilde{x}$

[Donoho & Huo, '01]:

- (P_0) has a unique solution when $K = K_p + K_q < \sqrt{N}$
- (P_0) and (P_1) are equivalent when $K < 0.5\sqrt{N}$

[Elad & Bruckstein, 2002]:

Given an arbitrary pair of orthogonal bases Ψ and Φ . Define the mutual coherence

$$\mu(D) = \max_{1 \le k, j \le M, k \ne j} \frac{|d_k^* d_j|}{\|d_k\|_2 \|d_j\|_2}$$

- (P_0) is unique when $K < 1/\mu(oldsymbol{D})$
- (P_0) and (P_1) are equivalent when

 $2\mu(D)^2 K_p K_q + \mu(D) \max\{K_p, K_q\} - 1 < 0$ (Tight Bound)

• Alternatively, (P_0) and (P_1) are equivalent when

 $K < \sqrt{2} - 0.5/\mu(D) \sim 0.9/\mu(D)$ (Weaker Bound)

Note: when $\Psi = F$ and $\Phi = I$, then $\mu(D) = 1/\sqrt{N}$

Sparsity Bounds

Fourier and canonical bases: N = 144



Fourier and canonical bases: N = 144



ProSparse: Prony's based sparse signal recovery

Consider the case when the signal $m{y} = m{F}_N m{c}$, for some K-sparse vector $m{c} \in \mathbb{R}^N$

The sparse vector $m{c}$ can be reconstructed from *any* 2K *consecutive* entries of $m{y}$

• The *n*th entry of *y*:

Prony's Method



 $y_n = \frac{1}{\sqrt{N}} \sum_{k=0}^{K-1} c_{m_k} e^{j2\pi m_k n/N} = \sum_{k=0}^{K-1} \alpha_k u_k^n$

where $\alpha_k \stackrel{\text{def}}{=} c_{m_k} / \sqrt{N}$ and $u_k \stackrel{\text{def}}{=} e^{j2\pi m_k/N}$

G. C. F. M. R. de Prony

• Sparse recovery \rightarrow harmonic retrieval

Applications: harmonic retrieval, ECC, finite rate of innovation sampling, ...

ProSparse: Basic Ideas

Given $\boldsymbol{y} = [\boldsymbol{F}, \boldsymbol{I}] = \boldsymbol{D}\boldsymbol{x}$, where \boldsymbol{x} is (K_p, K_q) -sparse



- K_p Fourier atoms —> need a "clean" interval of length $2K_p$
- For sufficiently sparse signals, such intervals always exist
- Sequential search and test: polynomial complexity

Theorem [Dragotti & Lu, 2014]: Let D = [F, I] and $y \in \mathbb{C}^N$ an arbitrary signal. There exists an algorithm, with a worst-case complexity of $O(N^3)$, that finds *all* (K_p, K_q) -sparse signal x such that

y = Dx and $K_p K_q < N/2$.



Works for $m{D} = [m{\Psi}, m{\Phi}]$ if the columns of $m{F} m{\Psi}^* m{\Phi}$ have *localized supports*

More generally:

$$y = x + s$$

- *s* : noise with local "footprints"
- x : a "*locally reconstructable*" signal

Examples:

- Sparse in Fourier, DCT, random bases or frames ...
- Continuous sparse sinusoids: $x_n = \sum_{k} c_k e^{j\omega_k n}$
- Low-dimensional subspace

Average-Case Analysis



 $K_q = \alpha N$ for $0 < \alpha < 1$

Bound: $K_p < 1/(2\alpha)$

In practice: $K_p < \tau(\alpha) \log N$

${\cal N}\,$ consecutive integers

Randomly select K integers (sampling w/o replacement)



Joint distribution of the interval lengths:

$$\mathbb{P}(d_0, d_1, \dots, d_K) = \frac{1}{\binom{N}{K}} \mathbb{1}(\sum_k d_k = N - K) \quad \text{for } d_k = 0, 1, 2, \dots$$

Related to **Bose-Einstein distribution** in statistical physics

Phase Transitions

Proposition [Oñativia, Dragotti & Lu, 2015]:

Let $K = \lfloor \alpha N \rfloor$ for some $0 < \alpha < 1$

$$\lim_{N \to \infty} \frac{\max_k d_k}{\log N} = \frac{-1}{\log(1-\alpha)} \stackrel{\text{def}}{=} \tau^*(\alpha) \text{ in prob.}$$



Corollary: Let $y \in \mathbb{C}^N$ be a linear combination of $K_p = \tau \log N$ Fourier atoms and $K_q = \lfloor \alpha N \rfloor$ spikes. If the locations of the spikes are sampled uniformly at random, then

$$\lim_{N \to \infty} \mathbb{P}(\text{ProSparse succeeds}) = \begin{cases} 1, & \text{if } \tau < \tau^*(\alpha) \\ 0, & \text{if } \tau > \tau^*(\alpha) \end{cases}$$

Comparing with BP (Average-Performance)

BP: $K_p + K_q \doteq cN/\sqrt{\log N}$ [Candes & Romberg, 2006]

ProSparse: $K_p = \tau(\alpha) \log N, K_q = \alpha N$

But:

- ProSparse only depends on the distribution of spike locations;
- Fourier frames
- Arbitrary coefficient distributions



- Setting: $\mathbf{y} = [\mathbf{F}, \mathbf{I}][\mathbf{x}_p^T, \mathbf{x}_q^T] + \epsilon$ where the noise is i.i.d. Gaussian
- Key Ingredients of ProSparse Denoise:
 - Replace Prony's with a noise resilient version: Cadzow algorithm
 - Treat Spikes as noise
- Algorithm:
 - 1. Estimate the K_p Fourier atoms using Cadzow
 - 2. Remove this contribution from *y*, estimate the largest spike from the residual and remove it from *y*
 - 3. Repeat steps 1 and 2, K_q times.
 - 4. Estimate the spikes using duality



(a) SNR = 10 dB, bias = 50%.



(c) SNR = 10 dB, bias = 25%.

Simulation Results (cont'd)



(b) SNR = 5 dB, bias = 50%.



(d) SNR = 5 dB, bias = 25%.

Summary

- **ProSparse**: a polynomial time algorithm that decomposes a signal into a sum of a sparse signals and a locally-reconstructable signal
- ProSparse is based on mapping sparse representation problem with Structured Least Squares Methods
- For Fourier + Identity, deterministic bound is better than BP and unicity bounds
- Tight Bound on Average case performance
- Promising denoising results
- How far can the basic ideas behind ProSparse be extended?

Thank you for your attention!



Deterministic results:

P. L. Dragotti and Y. M. Lu, "On Sparse Representation in Fourier and Local Bases," IEEE Transactions on Information Theory, vol. 60, no. 12, pp. 7888-7899, 2014.

Average-case performance:

Paper with full proofs will be posted on arXiv soon.

ProSparse Denoise: J. Onativia, Y.M. Lu and P.L. Dragotti, ICASSP 2016