

## Problem Essence

Probabilistic Modeling: use a probabilistic model Q to estimate an unknown distribution P. This can be quantified by a distance measure  $\mathcal{D}$ , such that:

 $\mathcal{D}(P, Q) \to 0, Q \to P$ 

#### Motivations

Cases where KL (Kullback-Leibler) or JS (Jensen-Shannon) divergence may be problematic:

- No explicit density function of probability model
- Support mismatch
- In high-dimensional space, KL and JS are sensitive to perturbations.

#### What else?

Benefit of employing OT distance:

- Applicable to both implicit and explicit models
- Regardless of match or mismatch of supports
- Bound up for distribution perturbation

Advantages of entropy regulation:

- Smoothed solution
- Avoid Lipschitz constraint to enforce (Kantorovich-Rubinstein duality solution, e.g. WGAN).

#### Preliminary

- •Work space,  $(\mathcal{X}, \|\cdot\|_2), \mathcal{X} \subset \mathbb{R}^d$
- Distribution P with finite support  $\mathcal{X}_1 \subset \mathcal{X}$
- Distribution Q with finite support  $\mathcal{X}_2 \subset \mathcal{X}$

### Modeling

$$\underset{g: \mathcal{Z} \to \mathcal{X}}{\operatorname{argmin}} W(P, Q) = \underset{\theta}{\operatorname{argmin}} W(P, Q)$$

with

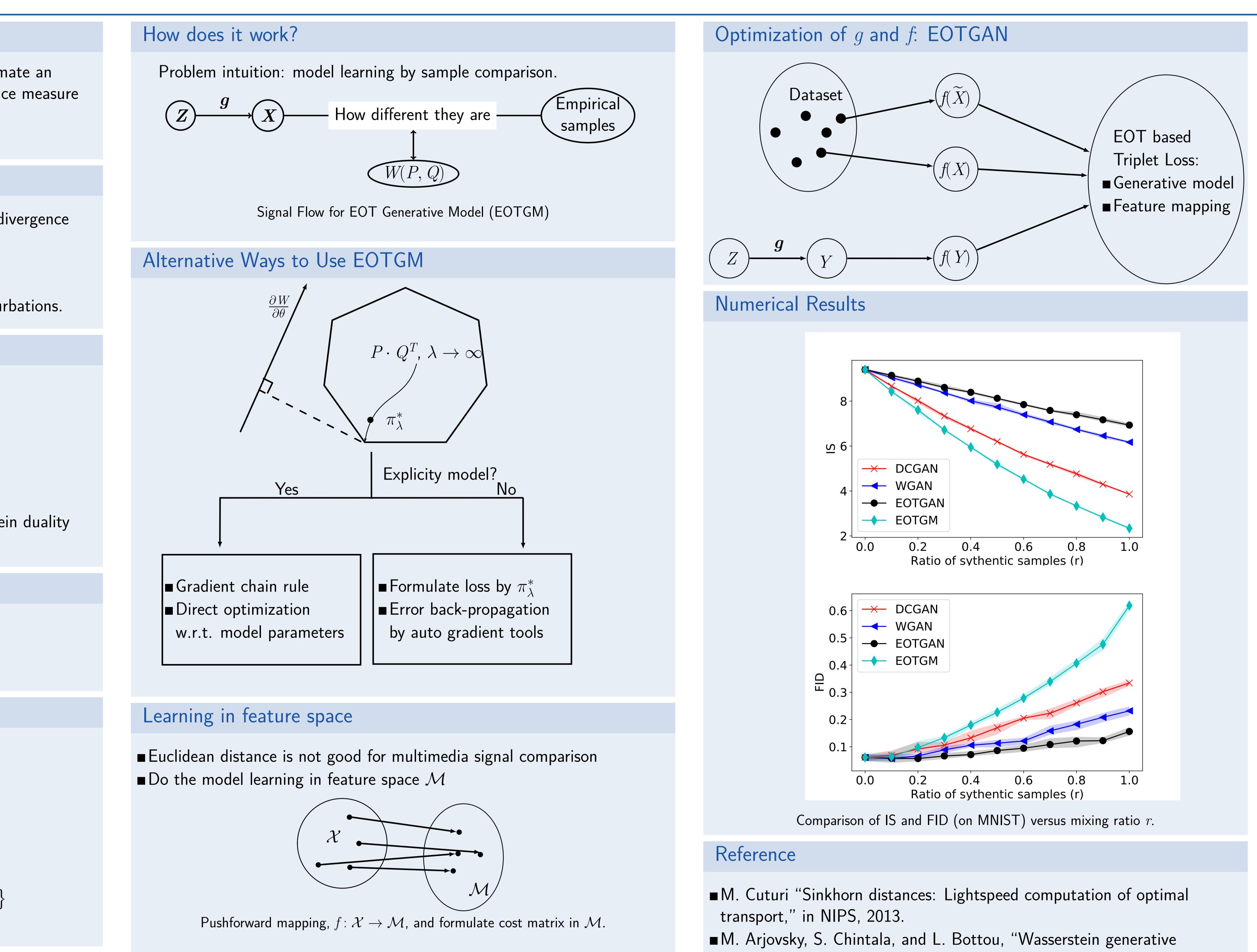
$$W(P, Q) = \min_{\pi \in \Pi(P, Q)} \langle \pi, M \rangle - \lambda H(\pi),$$

- Cost matrix  $[M]_{i,j} = d(x^{(i)}, y^{(j)}) = ||x^{(i)} y^{(j)}||_2^2$  Optimization domain  $\Pi(P, Q) = \{\pi : \pi \mathbb{1} = P, \pi^T \mathbb{1} = Q\}$  $\bullet H(\pi) = \sum_{i,j} -\pi_{i,j} \log(\pi_{i,j})$

# ntropy-Regularized Optimal Transport Generative Models

ong Liu, Minh Thành Vu, Saikat Chatterjee, and Lars K. Rasmussen

ivision of Information Science and Engineering TH Royal Institute of Technology, Stockholm, SE-100 44, Sweden. -mail: {doli, mtvu, sach, Ikra}@kth.se



adversarial networks," in ICML, 2017.