# **Exemplar-Embed Complex Matrix Factorization for Facial Expression Recognition**

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## 1. Major Contribution

- ✓ This paper presents an image representation approach, which is called exemplar-embed complex matrix factorization (EE-CMF) and is based on matrix factorization in the complex domain.
- ✓ The proposed EE-CMF approach effectively improve the performance of facial expression recognition.
- Wirtinger's calculus was employed to determine derivatives and the gradient descent method was utilized to solve the complex optimization problems

## 2. Existing Representation Methods

- Principal component analysis (PCA) based method
- Linear discriminant analysis (LDA)
- Nonnegative matrix factorization (NMF)
- Semi-NMF, Convex-NMF, Cluster NMF

### **Nonnegative Matrix Factorization**

Given an  $N \times M$  input data matrix  $\mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_M)$ 

M is the number of facial images and each column  $\mathbf{x}_m$  corresponds to an image with size  $N = a \times b$ .

The NMF problem is to find W and V that can minimize the follow objective function:

$$\min_{\mathbf{W} \geq 0, \mathbf{V} \geq 0} \mathcal{O}_{NMF}(\mathbf{W}, \mathbf{V}) = \frac{1}{2} \|\mathbf{X} - \mathbf{W} \mathbf{V}\|_{F}^{2}$$

To relax the constraint of nonnegative data, EE-NMF imposes a constraint that the column vectors of **W** must lie within the column space of **X**, i.e. **W** = **XA** 

$$\min_{\mathbf{N} \in \mathcal{N}} O_{conNMF}(\mathbf{A}, \mathbf{V}) = \frac{1}{2} \|\mathbf{X} - \mathbf{X}\mathbf{A}\mathbf{V}\|_{F}^{2}$$

The factors V and A are updated as follows:

$$\begin{split} \mathbf{A} \leftarrow \mathbf{A} \sqrt{\frac{(\mathbf{X}^T\mathbf{X})^+\mathbf{V}^T + (\mathbf{X}^T\mathbf{X})^-\mathbf{A}\mathbf{V}\mathbf{V}^T}{(\mathbf{X}^T\mathbf{X})^-\mathbf{V}^T + (\mathbf{X}^T\mathbf{X})^+\mathbf{A}\mathbf{V}\mathbf{V}^T}} \\ \mathbf{V} \leftarrow \mathbf{V} \sqrt{\frac{\mathbf{A}^T(\mathbf{X}^T\mathbf{X})^+ + \mathbf{A}^T(\mathbf{X}^T\mathbf{X})^-\mathbf{A}\mathbf{V}}{\mathbf{A}^T(\mathbf{X}^T\mathbf{X})^- + \mathbf{A}^T(\mathbf{X}^T\mathbf{X})^+\mathbf{A}\mathbf{V}}} \end{split}$$

where  $\mathbf{X}^T \mathbf{X} = (\mathbf{X}^T \mathbf{X})^+ - (\mathbf{X}^T \mathbf{X})^-$ 

## 3. Wirtinger's Calculus and Complex Optimization

 $\checkmark$  If  $g(z, z^*) = f(x, y)$  where z = x + jy

$$\frac{\partial g}{\partial z} = \frac{1}{2} \left( \frac{\partial f}{\partial x} - i \frac{\partial f}{\partial y} \right) \qquad \frac{\partial g}{\partial z^*} = \frac{1}{2} \left( \frac{\partial f}{\partial x} + i \frac{\partial f}{\partial y} \right)$$

$$\nabla f(\mathbf{Z}) = 2 \frac{df(\mathbf{Z})}{d\mathbf{Z}^*} = \frac{\partial f(\mathbf{Z})}{\partial \operatorname{Re} \mathbf{Z}} + i \frac{\partial f(\mathbf{Z})}{\partial \operatorname{Im} \mathbf{Z}}$$

For the real-valued function  $f(\mathbf{Z}, \mathbf{Z}^*)$ , we have

$$\Delta f(\mathbf{Z}, \mathbf{Z}^*) \approx \langle \nabla_{\mathbf{z}} f, \Delta \mathbf{Z}^* \rangle + \langle \nabla_{\mathbf{z}^*} f, \Delta \mathbf{Z} \rangle$$

$$\Delta f(\mathbf{Z}, \mathbf{Z}^*) \approx \langle \nabla_{\mathbf{z}^*} f, \Delta \mathbf{Z}^* \rangle + \langle \nabla_{\mathbf{z}^*} f, \Delta \mathbf{Z} \rangle = 2 \operatorname{Re} \{ \langle \nabla_{\mathbf{z}^*} f, \Delta \mathbf{Z} \rangle \}$$

## 4. Proposed Method

mapping  $f: \mathbb{R}^N \to \mathbb{C}^N$ 

$$f(\mathbf{x}_{t}) = \mathbf{z}_{t} = \frac{1}{\sqrt{2}} e^{i\alpha n \mathbf{x}_{t}} = \frac{1}{\sqrt{2}} \begin{vmatrix} e^{i\alpha n \mathbf{x}_{t}(1)} \\ \vdots \\ e^{i\alpha n \mathbf{x}_{t}(N)} \end{vmatrix}$$

EE-CMF aims at factorizing  $\mathbf{Z}$  into two matrices,  $\mathbf{W} \in \mathbb{C}^{^{M \times K}}$  and  $\mathbf{V} \in \mathbb{C}^{^{K \times M}}$  to satisfy the follow objective function:

$$\min_{\mathbf{w},\mathbf{v}} O_{conCMF}(\mathbf{W},\mathbf{V}) = \min_{\mathbf{w},\mathbf{v}} \frac{1}{2} \|\mathbf{Z} - \mathbf{ZWV}\|_{F}^{2}$$

where 
$$\|\mathbf{Z} - \mathbf{ZWV}\|_F^2 = Trace(\mathbf{Z} - \mathbf{ZWV})^H(\mathbf{Z} - \mathbf{ZWV})$$

$$= Trace(\mathbf{Z}^{H}\mathbf{Z} - \mathbf{V}^{H}\mathbf{W}^{H}\mathbf{Z}^{H}\mathbf{Z} - \mathbf{Z}^{H}\mathbf{Z}\mathbf{W}\mathbf{V} + \mathbf{V}^{H}\mathbf{W}^{H}\mathbf{Z}^{H}\mathbf{Z}\mathbf{V})$$

Optimal Solution: Wirtinger's calculus

First, fix W and solve V by

$$\min_{\mathbf{V}} f(\mathbf{V}) \text{ where } f(\mathbf{V}) = \frac{1}{2} \|\mathbf{Z} - \mathbf{ZWV}\|_F^2$$

where V be can solved iteratively

$$\mathbf{V}_{t+1} = \mathbf{V}_{t} - \boldsymbol{\beta}_{t} \nabla_{\mathbf{V}_{t}^{*}} f(\mathbf{V}_{t})$$

$$\nabla_{\mathbf{V}^{*}} f(\mathbf{V}) = 2 \frac{\partial f(\mathbf{V})}{\partial \mathbf{V}^{*}} = \frac{\partial f(\mathbf{V})}{\partial (\operatorname{Re} \mathbf{V})} + i \frac{\partial f(\mathbf{V})}{\partial (\operatorname{Im} \mathbf{V})}$$

$$\nabla_{\mathbf{v}^*} f(\mathbf{V}) = -\mathbf{W}^H \mathbf{Z}^H \mathbf{Z} + \mathbf{W}^H \mathbf{Z}^H \mathbf{Z} \mathbf{W} \mathbf{V}$$

Then, W is updated based on the Moore–Penrose pseudoinverse,  $\dagger$ , and  $\mathbf{W} = \mathbf{Z}(\mathbf{V}\mathbf{Z})^{\dagger}$  with fixed V

#### 5. Simulation Results

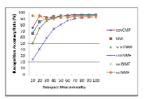
Cohn–Kanade (CK) database



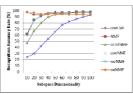
JFFA database



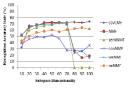
CK database training: set = 1:4



CK database training: set = 2:3



JFFA database training: set = 1:4



JFFA database training: set = 2:3

