Sparse Eigenvectors of Graphs

Oguzhan Teke P. P. Vaidyanathan

Department of Electrical Engineering California Institute of Technology

42nd International Conference on Acoustics, Speech and Signal Processing

Caltech

1 Graph Signal Processing

2 Motivation

3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs

Generalizations

4 Real-World Examples

Graph Signal Processing

2 Motivation

3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs

Generalizations

4 Real-World Examples

Graph Signal Processing

2 Motivation

3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs
 Generalizations

4 Real-World Examples

- 1 Graph Signal Processing
- 2 Motivation
- Sparse Eigenvectors of Graphs
 Disconnected Graphs
 - Connected GraphsGeneralizations
- 4 Real-World Examples

- 1 Graph Signal Processing
- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs
 Generalizations
- 4 Real-World Examples

- 1 Graph Signal Processing
- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 - Disconnected Graphs
 - Connected Graphs
 - Generalizations
- 4 Real-World Examples

- 1 Graph Signal Processing
- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 - Disconnected Graphs
 - Connected Graphs
 - Generalizations
- 4 Real-World Examples
- 5 Conclusions

- 1 Graph Signal Processing
- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 - Disconnected Graphs
 - Connected Graphs
 - Generalizations
- 4 Real-World Examples

1 Graph Signal Processing

- 2 Motivation
- 3 Sparse Eigenvectors of GraphsDisconnected Graphs
 - Connected Graphs
 - Generalizations
- 4 Real-World Examples





 \boldsymbol{S} is the graph operator



S is the graph operator Adjacency matrix¹ : AGraph Laplacians² : L, or \mathcal{L} Other selections³

Sandryhaila & Moura, "Discrete Signal Processing on Graphs," IEEE Trans. S. P. vol. 61, no. 7, 2013

² Shuman et al, "The emerging field of signal processing on graphs: ...," IEEE S. P. Magazine, vol. 30, no. 3 2013

³ Gavili & Zhang, "On the shift operator and optimal filtering in graph signal processing," arXiv:1511.03512v3, 2016

Teke & Vaidyanathan



S is the graph operator A djacency matrix¹ : A Graph Laplacians² : L, or \mathcal{L} Other selections³

 $L = V \Lambda V^{-1}$

Sandryhaila & Moura, "Discrete Signal Processing on Graphs," IEEE Trans. S. P. vol. 61, no. 7, 2013

² Shuman et al, "The emerging field of signal processing on graphs: ...," IEEE S. P. Magazine, vol. 30, no. 3 2013

³ Gavili & Zhang, "On the shift operator and optimal filtering in graph signal processing," arXiv:1511.03512v3, 2016



¹ Sandryhaila & Moura, "Discrete Signal Processing on Graphs," IEEE Trans. S. P. vol. 61, no. 7, 2013

² Shuman et al, "The emerging field of signal processing on graphs: ...," IEEE S. P. Magazine, vol. 30, no. 3 2013

³ Gavili & Zhang, "On the shift operator and optimal filtering in graph signal processing," arXiv:1511.03512v3, 2016



2 Motivation

3 Sparse Eigenvectors of GraphsDisconnected Graphs

- Connected Graphs
- Generalizations

4 Real-World Examples

Sparse (localized/concentrated) eigenvectors exist!

Sparse (localized/concentrated) eigenvectors exist!

They are *observed*^{4,5}, but no general theory!

⁴ P. N. McGraw, M. Menzinger, "Laplacian spectra as a diagnostic tool for network structure and dynamics," *Phys. Rev. E*, (2008)
 ⁵ Perraudin et al., "Global and Local Uncertainty Principles for Signals on Graphs," *arXiv:1603.03030*

Teke & Vaidyanathan

Sparse (localized/concentrated) eigenvectors exist!

They are *observed*^{4,5}, but no general theory!

$$s_0(x) = \frac{\|x\|_0 + \|Fx\|_0}{2}$$

⁴ P. N. McGraw, M. Menzinger, "Laplacian spectra as a diagnostic tool for network structure and dynamics," *Phys. Rev. E*, (2008)
 ⁵ Perraudin et al., "Global and Local Uncertainty Principles for Signals on Graphs," *arXiv:1603.03030*

⁶ Teke & Vaidyanathan, "Uncertainty Principles and Sparse Eigenvectors of Graphs," *IEEE Trans. S. P., under review.*

Teke & Vaidyanathan

[6]

Sparse (localized/concentrated) eigenvectors exist!

They are *observed*^{4,5}, but no general theory!

$$s_0(\boldsymbol{x}) = \frac{\|\boldsymbol{x}\|_0 + \|\boldsymbol{F}\boldsymbol{x}\|_0}{2}$$
 $s_0^{\star} = \min_{\boldsymbol{x}\neq \boldsymbol{0}} s_0(\boldsymbol{x})$ [6]

⁴ P. N. McGraw, M. Menzinger, "Laplacian spectra as a diagnostic tool for network structure and dynamics," *Phys. Rev. E*, (2008)
 ⁵ Perraudin et al., "Global and Local Uncertainty Principles for Signals on Graphs," *arXiv:1603.03030*

⁶ Teke & Vaidyanathan, "Uncertainty Principles and Sparse Eigenvectors of Graphs," *IEEE Trans. S. P., under review.*

Teke & Vaidyanathan

Sparse (localized/concentrated) eigenvectors exist!

They are *observed*^{4,5}, but no general theory!

$$s_{0}(\boldsymbol{x}) = \frac{\|\boldsymbol{x}\|_{0} + \|\boldsymbol{F}\boldsymbol{x}\|_{0}}{2} \qquad s_{0}^{\star} = \min_{\boldsymbol{x}\neq\boldsymbol{0}} s_{0}(\boldsymbol{x}) \quad [6]$$
$$\boldsymbol{F}^{-1} = \boldsymbol{V} = [\boldsymbol{v}_{1} \ \boldsymbol{v}_{2} \ \cdots \ \boldsymbol{v}_{N}] \qquad s_{0}(\boldsymbol{v}_{i}) = \frac{\|\boldsymbol{v}_{i}\|_{0} + 1}{2}$$

⁴ P. N. McGraw, M. Menzinger, "Laplacian spectra as a diagnostic tool for network structure and dynamics," *Phys. Rev. E*, (2008)
 ⁵ Perraudin et al., "Global and Local Uncertainty Principles for Signals on Graphs," *arXiv:1603.03030*

⁶ Teke & Vaidyanathan, "Uncertainty Principles and Sparse Eigenvectors of Graphs," *IEEE Trans. S. P., under review.*

Teke & Vaidyanathan



2 Motivation

Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs

Generalizations

4 Real-World Examples

Disconnected Graphs

The graph of size N has D disconnected components

The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$

The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$



The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$

$$oldsymbol{A} = egin{bmatrix} oldsymbol{A}_1 & & \ & \ & & \ &$$

There is an eigenvector with at most N_i non-zero elements.

The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$

$$oldsymbol{A} = egin{bmatrix} oldsymbol{A}_1 & & \ & \ & & \$$

There is an eigenvector with at most N_i non-zero elements.

Small component —> Sparse eigenvectors exist *trivially*!

The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$

$$oldsymbol{A} = egin{bmatrix} oldsymbol{A}_1 & & \ & \ & & \$$

There is an eigenvector with at most N_i non-zero elements.

Small component —> Sparse eigenvectors exist *trivially!*

The graph of size N has D disconnected components

Each component has size N_i with $\sum_i N_i = N$

$$oldsymbol{A} = egin{bmatrix} oldsymbol{A}_1 & & \ & \ & & \$$

There is an eigenvector with at most N_i non-zero elements.

Small component —> Sparse eigenvectors exist *trivially*!

Sparse eigenvectors in *connected* graphs.

Connected Graphs

1-sparse Case

When does a graph have a 1-sparse eigenvector?

When does a graph have a 1-sparse eigenvector?

Theorem (1-sparse eigenvectors)

When does a graph have a 1-sparse eigenvector?

Theorem (1-sparse eigenvectors)

Assume the graph is weighted and undirected.

When does a graph have a 1-sparse eigenvector?

Theorem (1-sparse eigenvectors)

Assume the graph is weighted and undirected. Then, for the graph Laplacian, *L*,

$$\left\{ \exists v \text{ s.t. } \frac{Lv = \lambda v}{\|v\|_0 = 1} \right\} \Longleftrightarrow$$
When does a graph have a 1-sparse eigenvector?

Theorem (1-sparse eigenvectors)

Assume the graph is weighted and undirected. Then, for the graph Laplacian, *L*,

$$\left\{ \exists v \text{ s.t. } \frac{Lv = \lambda v}{\|v\|_0 = 1} \right\} \Longleftrightarrow \left\{ \exists \text{ an isolated node} \right\}$$

When does a graph have a 1-sparse eigenvector?

Theorem (1-sparse eigenvectors)

Assume the graph is weighted and undirected. Then, for the graph Laplacian, *L*,

$$\left\{ \exists v \text{ s.t. } \frac{Lv = \lambda v}{\|v\|_0 = 1} \right\} \Longleftrightarrow \left\{ \exists \text{ an isolated node} \right\}$$

Connected graph \implies No 1-sparse eigenvector!

Connected Graphs

2-sparse Case

Theorem (2-sparse eigenvectors)

Theorem (2-sparse eigenvectors)

Assume the graph is weighted, undirected and connected.

Theorem (2-sparse eigenvectors)

$$\begin{cases} \boldsymbol{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \boldsymbol{v} \text{ s.t. } \lambda \neq 0 \\ \|\boldsymbol{v}\|_0 = 2 \end{cases} \Leftarrow$$

Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \boldsymbol{v} \text{ s.t. } \lambda \neq 0 \\ \|\boldsymbol{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} \quad \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$

Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} \quad \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$
$$\iff \{ \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \} \text{(unweighted)} \end{cases}$$

Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} & \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases} \\ \iff \begin{cases} \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \end{cases} (unweighted) \end{cases}$$



Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} \quad \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$
$$\iff \{ \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \} \text{(unweighted)} \end{cases}$$



Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} \quad \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$
$$\iff \{ \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \} \text{(unweighted)} \end{cases}$$



Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L}\mathbf{v} = \lambda\mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} & \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases} \\ \iff \begin{cases} \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \end{cases} (unweighted) \end{cases}$$



Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} & \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$
$$\iff \{ \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \} \text{(unweighted)} \end{cases}$$



Theorem (2-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 2 \end{cases} \iff \begin{cases} \exists i, j \text{ s.t. } a_{i,k} = a_{j,k} & \forall k \in \{1, \cdots, N\} \setminus \{i, j\} \end{cases}$$
$$\iff \{ \exists i, j \text{ s.t. } \mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\} \} \text{(unweighted)} \end{cases}$$



Connected Graphs

3-sparse Case

Theorem (3-sparse eigenvectors)

Theorem (3-sparse eigenvectors)

Assume the graph is unweighted, undirected and connected.

Theorem (3-sparse eigenvectors)

$$\begin{cases} \boldsymbol{L}\boldsymbol{v} = \lambda\boldsymbol{v} \\ \exists \boldsymbol{v} \text{ s.t. } \lambda \neq 0 \\ \|\boldsymbol{v}\|_0 = 3 \end{cases} \iff$$

Theorem (3-sparse eigenvectors)

$$\begin{cases} \boldsymbol{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \boldsymbol{v} \text{ s.t. } \lambda \neq 0 \\ \|\boldsymbol{v}\|_{0} = 3 \end{cases} \iff \begin{cases} \exists i, j, k \text{ s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$

Theorem (3-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 3 \end{cases} \iff \begin{cases} \exists i, j, k \text{ s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Theorem (3-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \mathbf{v} = \lambda \mathbf{v} \\ \exists \mathbf{v} \text{ s.t. } \lambda \neq 0 \\ \|\mathbf{v}\|_{0} = 3 \end{cases} \iff \begin{cases} \exists i, j, k \text{ s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Theorem (3-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \ \boldsymbol{v} \ \text{s.t.} \quad \lambda \neq 0 \\ \| \boldsymbol{v} \|_{0} = 3 \end{cases} \iff \begin{cases} \exists \ i, j, k \ \text{s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Theorem (3-sparse eigenvectors)

$$\begin{cases} \boldsymbol{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \boldsymbol{v} \text{ s.t. } \lambda \neq 0 \\ \|\boldsymbol{v}\|_{0} = 3 \end{cases} \iff \begin{cases} \exists i, j, k \text{ s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Theorem (3-sparse eigenvectors)

$$\begin{cases} \mathbf{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \ \boldsymbol{v} \ \text{s.t.} \quad \lambda \neq 0 \\ \| \boldsymbol{v} \|_0 = 3 \end{cases} \iff \begin{cases} \exists \ i, j, k \ \text{s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Theorem (3-sparse eigenvectors)

Assume the graph is unweighted, undirected and connected. Then, for the graph Laplacian, *L*,

$$\begin{cases} \mathbf{L} \boldsymbol{v} = \lambda \boldsymbol{v} \\ \exists \ \boldsymbol{v} \ \text{s.t.} \quad \lambda \neq 0 \\ \| \boldsymbol{v} \|_0 = 3 \end{cases} \iff \begin{cases} \exists \ i, j, k \ \text{s.t.} \\ \mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(k) \setminus \{i, j\} \end{cases}$$



Teke & Vaidyanathan

Can we generalize to arbitrary K?

Can we generalize to arbitrary K?

1-sparse eigenvector $\iff \mathcal{N}(i) = \{\}$

Can we generalize to arbitrary K?

1-sparse eigenvector \iff $\mathcal{N}(i) = \{\}$ 2-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$

Can we generalize to arbitrary K?

1-sparse eigenvector \iff $\mathcal{N}(i) = \{\}$ 2-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$ 3-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j, k\} = \mathcal{N}(j) \setminus \{i, k\} = \mathcal{N}(j) \setminus \{i, k\}$

Can we generalize to arbitrary K?

1-sparse eigenvector \iff $\mathcal{N}(i) = \{\}$ 2-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$ 3-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j,k\} = \mathcal{N}(j) \setminus \{i,k\} = \mathcal{N}(j) \setminus \{i,k\}$

K-nodes such that neighbors (except from each other) are the same. \downarrow

Can we generalize to arbitrary K?

1-sparse eigenvector \iff $\mathcal{N}(i) = \{\}$ 2-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$ 3-sparse eigenvector \iff $\mathcal{N}(i) \setminus \{j,k\} = \mathcal{N}(j) \setminus \{i,k\} = \mathcal{N}(j) \setminus \{i,k\}$

K-nodes such that neighbors (except from each other) are the same. \downarrow There is a *K*-sparse eigenvector.

Can we generalize to arbitrary K?

- 1-sparse eigenvector \longleftrightarrow $\mathcal{N}(i) = \{\}$ 2-sparse eigenvector \longleftrightarrow $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$
- $3\text{-sparse eigenvector} \quad \Longleftrightarrow \quad \mathcal{N}(i) \backslash \{j,k\} = \mathcal{N}(j) \backslash \{i,k\} = \mathcal{N}(j) \backslash \{i,k\}$

K-nodes such that neighbors (except from each other) are the same.

There is a K-sparse eigenvector.

This is only sufficient, but not necessary.

(Counter-examples to follow)

Outline

- 1 Graph Signal Processing
- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs
 - Generalizations

4 Real-World Examples

5 Conclusions

Minnesota Road Graph



Minnesota Road Graph

2-Sparse Case: $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$



Minnesota Road Graph

2-Sparse Case: $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$








2-Sparse Case: $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$





Pairs 1 - 4 have $\lambda = 1$



2-Sparse Case: $\mathcal{N}(i) \setminus \{j\} = \mathcal{N}(j) \setminus \{i\}$



Pairs 1 - 4 have $\lambda = 1$ Pairs 5 - 6 have $\lambda = 2$





- Pairs 1 4 have $\lambda = 1$ Pairs 5 - 6 have $\lambda = 2$
- 4, 6, 8-sparse exist as well!







- Pairs 1 4 have $\lambda = 1$ Pairs 5 - 6 have $\lambda = 2$
- 4, 6, 8-sparse exist as well! 3-sparse does *not* exist!

Teke & Vaidyanathan



Nodes = Characters (77) Connectivity = Co-Appearance⁷ (weighted)

7 M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/



⁷ M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/



⁷ M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/



⁷ M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/



7 M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/



7 M. E. J. Newman," (2013) Network data. [Online]." Available: http://www-personal.umich.edu/~mejn/netdata/

• An unweighted graph has a sparse eigenvector iff its complement has.

- An unweighted graph has a sparse eigenvector iff its complement has.
- Sparsity of graph is irrelevant to the existence of sparse eigenvectors.

- An unweighted graph has a sparse eigenvector iff its complement has.
- Sparsity of graph is irrelevant to the existence of sparse eigenvectors.



- An unweighted graph has a sparse eigenvector iff its complement has.
- Sparsity of graph is irrelevant to the existence of sparse eigenvectors.
- $2 \mbox{ and } 3\mbox{-sparse eigenvectors are necessarily localized.} \end{tabula}$
- A K-sparse eigenvector may not be localized.



- An unweighted graph has a sparse eigenvector iff its complement has.
- Sparsity of graph is irrelevant to the existence of sparse eigenvectors.
- $2 \mbox{ and } 3\mbox{-sparse eigenvectors are necessarily localized.} \end{tabula}$
- A *K*-sparse eigenvector may not be localized.

-93.42 -93.41 -93.4 -93.39 -93.38

44.81 44.8

44.78

44.77

• Sparse eigenvectors \implies Large coherence of graph Fourier basis ⁶.

⁶ Teke & Vaidyanathan, "Uncertainty Principles and Sparse Eigenvectors of Graphs," IEEE Trans. S. P., under review.

- An unweighted graph has a sparse eigenvector iff its complement has.
- Sparsity of graph is irrelevant to the existence of sparse eigenvectors.
- $2 \mbox{ and } 3\mbox{-sparse eigenvectors are necessarily localized.} \ensuremath{^{\mbox{\tiny 44.79}}}$
- A *K*-sparse eigenvector may not be localized.



44 81

• Sparse eigenvectors \implies Large coherence of graph Fourier basis ⁶.

Theorem

Assume the graph is simple and connected. 3-sparse eigenvector $\implies 2$ -sparse eigenvector.

⁶ Teke & Vaidyanathan, "Uncertainty Principles and Sparse Eigenvectors of Graphs," IEEE Trans. S. P., under review.

Outline



- 2 Motivation
- 3 Sparse Eigenvectors of Graphs
 Disconnected Graphs
 Connected Graphs
 - Generalizations

4 Real-World Examples

5 Conclusions

- Conclusions
 - 1 Graphs *do* have sparse eigenvectors.
 - 2 Disconnected graphs trivially have sparse eigenvectors.
 - 3 Necessary&Sufficient conditions for 1, 2 and 3-sparse eigenvectors
 - 4 Classical and real-world examples of graphs

- Conclusions
 - 1 Graphs *do* have sparse eigenvectors.
 - 2 Disconnected graphs trivially have sparse eigenvectors.
 - 3 Necessary&Sufficient conditions for 1, 2 and 3-sparse eigenvectors
 - 4 Classical and real-world examples of graphs

Questions

Necessary condition for an arbitrary *K*-spare eigenvector

- Conclusions
 - 1 Graphs *do* have sparse eigenvectors.
 - 2 Disconnected graphs trivially have sparse eigenvectors.
 - 3 Necessary&Sufficient conditions for 1, 2 and 3-sparse eigenvectors
 - 4 Classical and real-world examples of graphs

Questions

- 1 Necessary condition for an arbitrary K-spare eigenvector
- 2 Extension to directed graphs

- Conclusions
 - **1** Graphs *do* have sparse eigenvectors.
 - Disconnected graphs trivially have sparse eigenvectors.
 - 3 Necessary&Sufficient conditions for 1, 2 and 3-sparse eigenvectors
 - 4 Classical and real-world examples of graphs

Questions

- Necessary condition for an arbitrary K-spare eigenvector
- 2 Extension to directed graphs
- 3 Interplay between *sparsity*, *localization* and *concentration*

- Conclusions
 - 1 Graphs *do* have sparse eigenvectors.
 - Disconnected graphs trivially have sparse eigenvectors.
 - 3 Necessary&Sufficient conditions for 1, 2 and 3-sparse eigenvectors
 - 4 Classical and real-world examples of graphs

Questions

- Necessary condition for an arbitrary K-spare eigenvector
- 2 Extension to directed graphs
- 3 Interplay between *sparsity*, *localization* and *concentration*

Thank you!