CentraleSupélec

Introduction and Motivations

In signal processing applications:

• complex multinormality is a poor approximation of the underlying physics • non Gaussian data, missing data, outliers \implies robust estimators

A r. vect. **z** has a complex elliptically symmetric distribution $\mathbf{z} \sim \mathbb{C}ES_m(\boldsymbol{\mu}, \mathbf{M}, g_{\mathbf{z}})$, if its probability density function (PDF) can be written as

$$h_{\mathbf{z}}(\mathbf{z}) = |\mathbf{M}|^{-1} g_{\mathbf{z}} ((\mathbf{z} - \boldsymbol{\mu})^{H} \mathbf{M}^{-1})$$

where $h_{\mathbf{z}}: [0, \infty) \to [0, \infty)$ is any function such that (1) defines a PDF, $\boldsymbol{\mu}$ is the statistical mean and \mathbf{M} is a scatter matrix (equal to the covariance matrix - \mathbf{CM} - up to a scale factor). • e.g., $g_{\mathbf{x}}(x) \propto e^{-x/2} \implies$ Gaussian distribution $\mathbf{x} \sim \mathbb{C}N_m(\boldsymbol{\mu}, \mathbf{M})$ Let us consider an N-sample $(\mathbf{z}_1,...,\mathbf{z}_N)$ of i.i.d. vectors $\mathbf{z}_k \sim \mathbb{C}ES_m(\mathbf{0},\mathbf{M},g_{\mathbf{z}}), k = 1,...,N$ with $\mathbf{z}_k = \sqrt{\tau_k} \mathbf{x}_k / \|\mathbf{x}_k\|$, where $\mathbf{x}_k \sim \mathbb{C} N_m(\mathbf{0}, \mathbf{M})$ and τ_k is an independent random variable. Let us consider the sample covariance matrix (SCM) $\widehat{\mathbf{M}}_{SCM}$ built with $(\mathbf{x}_1,...,\mathbf{x}_N)$

$$\widehat{\mathbf{M}}_{SCM} = \frac{1}{N} \sum_{k=1}^{N} \mathbf{x}_k \mathbf{x}_k^H$$

and the Tyler (TyE) estimator (also called fixed-point (FP) estimator) \mathbf{M}_{FP} built with $(\mathbf{z}_1,...,\mathbf{z}_N)$

$$\widehat{\mathbf{M}}_{FP} = \frac{m}{N} \sum_{k=1}^{N} \frac{\mathbf{z}_k \mathbf{z}_k^H}{\mathbf{z}_k^H \widehat{\mathbf{M}}_{FP}^{-1}}$$

Detection/estimation problem

For the detection/estimation problem, we focus on the Adaptive Normalized Matched Filter (ANMF):

$$I(\widehat{\mathbf{M}}) = \frac{|\mathbf{p}^H \widehat{\mathbf{M}}^{-1} \mathbf{y}|^2}{|\mathbf{p}^H \widehat{\mathbf{M}}^{-1} \mathbf{p}| |\mathbf{y}^H \widehat{\mathbf{M}}^{-1}}$$

where \mathbf{p} is the steering vector, \mathbf{y} is the observation under test and \mathbf{M} is the CM estimator. The asymptotic distribution of (4) is given by

$$\sqrt{N}(H(\widehat{\mathbf{M}}) - H(\mathbf{M}))_{\mathbf{z}} \stackrel{d}{\to} N$$

where Σ_H is defined by

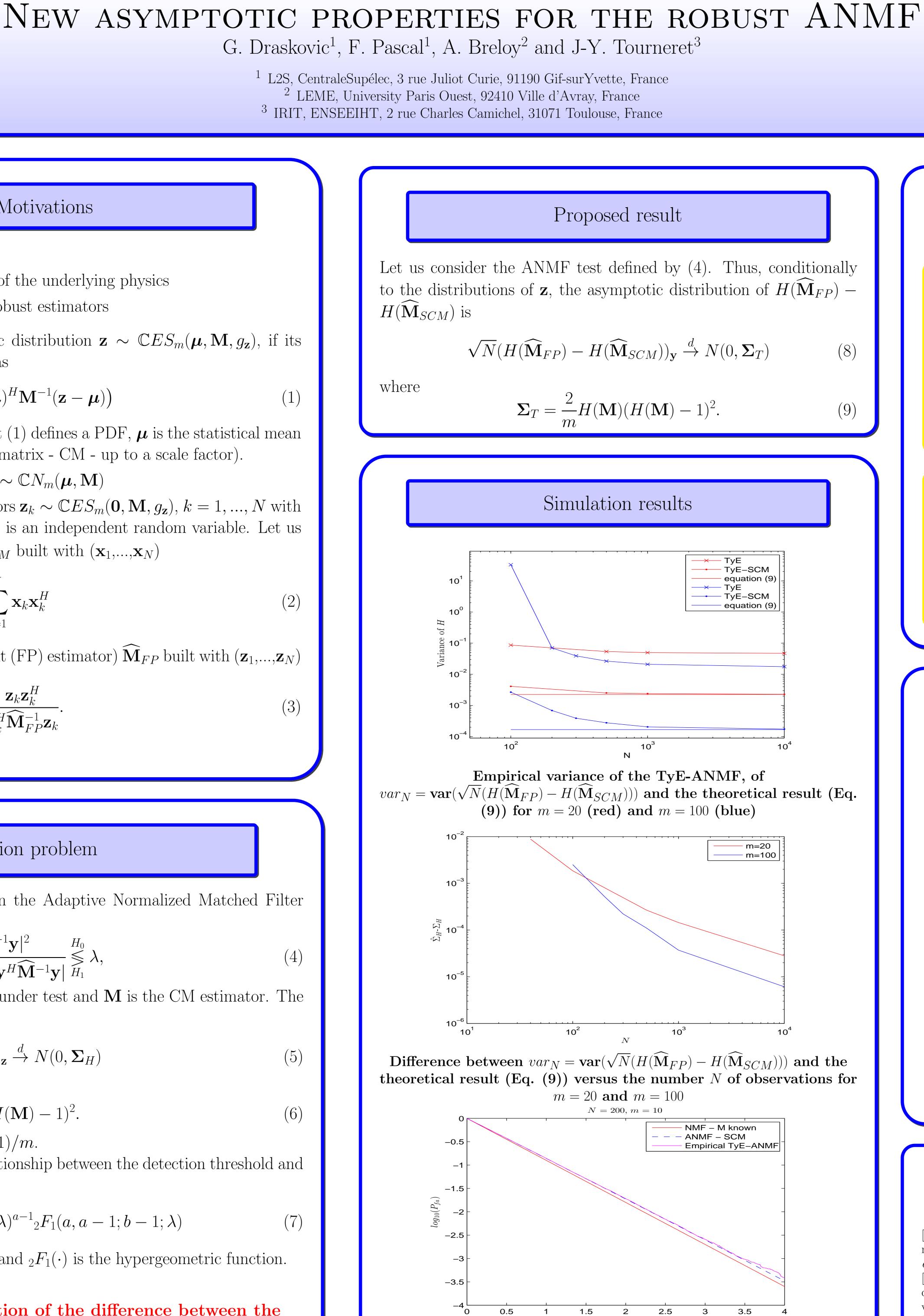
 $\Sigma_H = 2\nu_1 H(\mathbf{M})(H(\mathbf{M}) - 1)^2.$

where for the SCM $\nu_1 = 1$ and for TyE $\nu_1 = (m+1)/m$. Assuming that the SCM is used, the theoretical relationship between the detection threshold and the Probability of False Alarm (PFA) is defined as

$$P_{fa} = P(H(\widehat{\mathbf{M}}) > \lambda | H_0) = (1 - \lambda)^{a - 1} {}_2 H_0$$

where $K = \frac{(a-1)(m-1)}{N+1}$, a = N - m + 2, b = N + 2 and ${}_2F_1(\cdot)$ is the hypergeometric function.

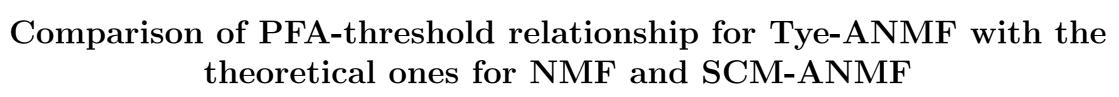
GOAL: Derive the asymptotic distribution of the difference between the ANMF built with TyE and the one based on the SCM



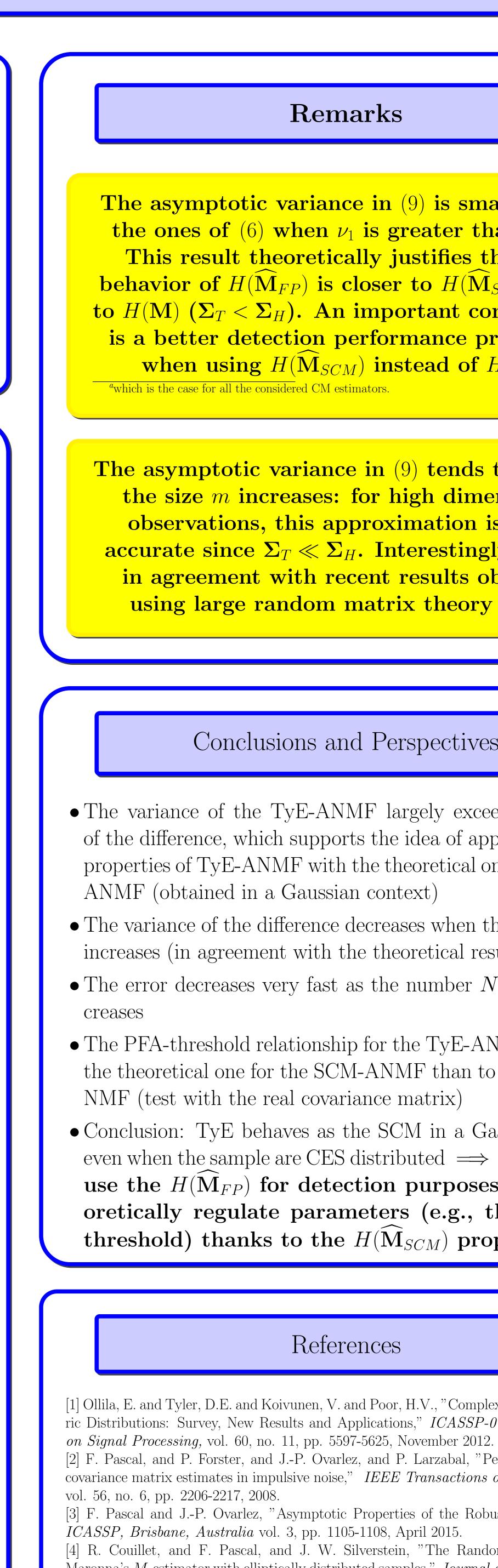
0.5

$$-H(\widehat{\mathbf{M}}_{SCM}))_{\mathbf{y}} \xrightarrow{d} N(0, \mathbf{\Sigma}_T)$$
 (

$$\frac{2}{n}H(\mathbf{M})(H(\mathbf{M})-1)^2.$$



 $-m \log_{10}(1-\lambda)$



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Remarks

The asymptotic variance in (9) is smaller than the ones of (6) when ν_1 is greater than one^{*a*}. This result theoretically justifies that the behavior of $H(\mathbf{M}_{FP})$ is closer to $H(\mathbf{M}_{SCM})$ than to $H(\mathbf{M})$ ($\Sigma_T < \Sigma_H$). An important consequence is a better detection performance prediction when using $H(\mathbf{M}_{SCM})$ instead of $H(\mathbf{M})$.

The asymptotic variance in (9) tends to 0 when the size *m* increases: for high dimensional observations, this approximation is more accurate since $\Sigma_T \ll \Sigma_H$. Interestingly, this is in agreement with recent results obtained using large random matrix theory in [4].

Conclusions and Perspectives

• The variance of the TyE-ANMF largely exceed the variance of the difference, which supports the idea of approximating the properties of TyE-ANMF with the theoretical ones of the SCM-

• The variance of the difference decreases when the dimension mincreases (in agreement with the theoretical result)

• The error decreases very fast as the number N of samples in-

• The PFA-threshold relationship for the TyE-ANMF is closer to the theoretical one for the SCM-ANMF than to the one for the

• Conclusion: TyE behaves as the SCM in a Gaussian context, even when the sample are CES distributed \implies it allows one to use the $H(\mathbf{M}_{FP})$ for detection purposes and to theoretically regulate parameters (e.g., the detection threshold) thanks to the $H(\mathbf{M}_{SCM})$ properties

References

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