

Enhancing Observability in Power Distribution Grids

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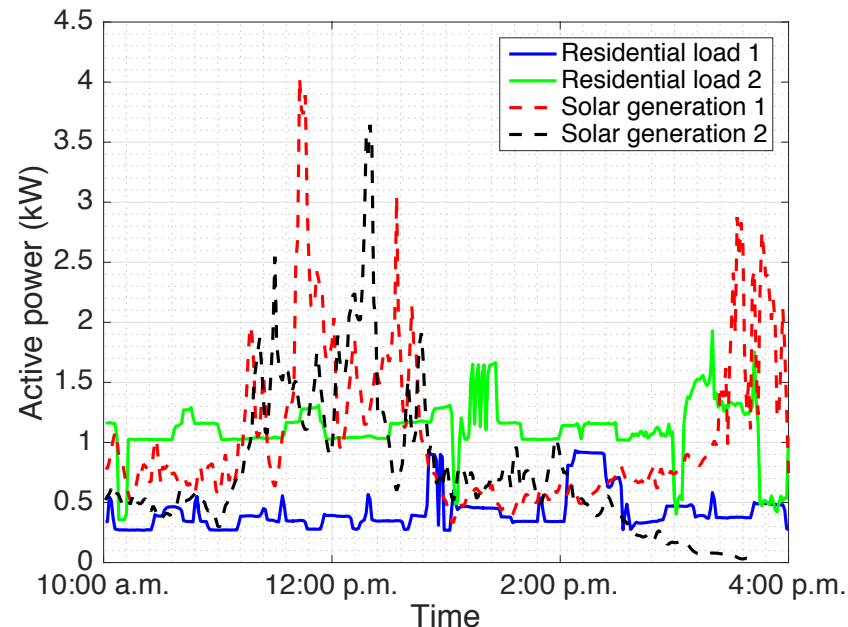
New Orleans, LA
March 8th, 2017

WindLogics

Acknowledgements: Windlogics

Motivation

- Reduced observability due to limited metering infrastructure
- Leverage smart meter data [\[1\]](#)
- Smart PV inverters can be commanded within micro-sec.
- System state needed for grid dispatch tasks



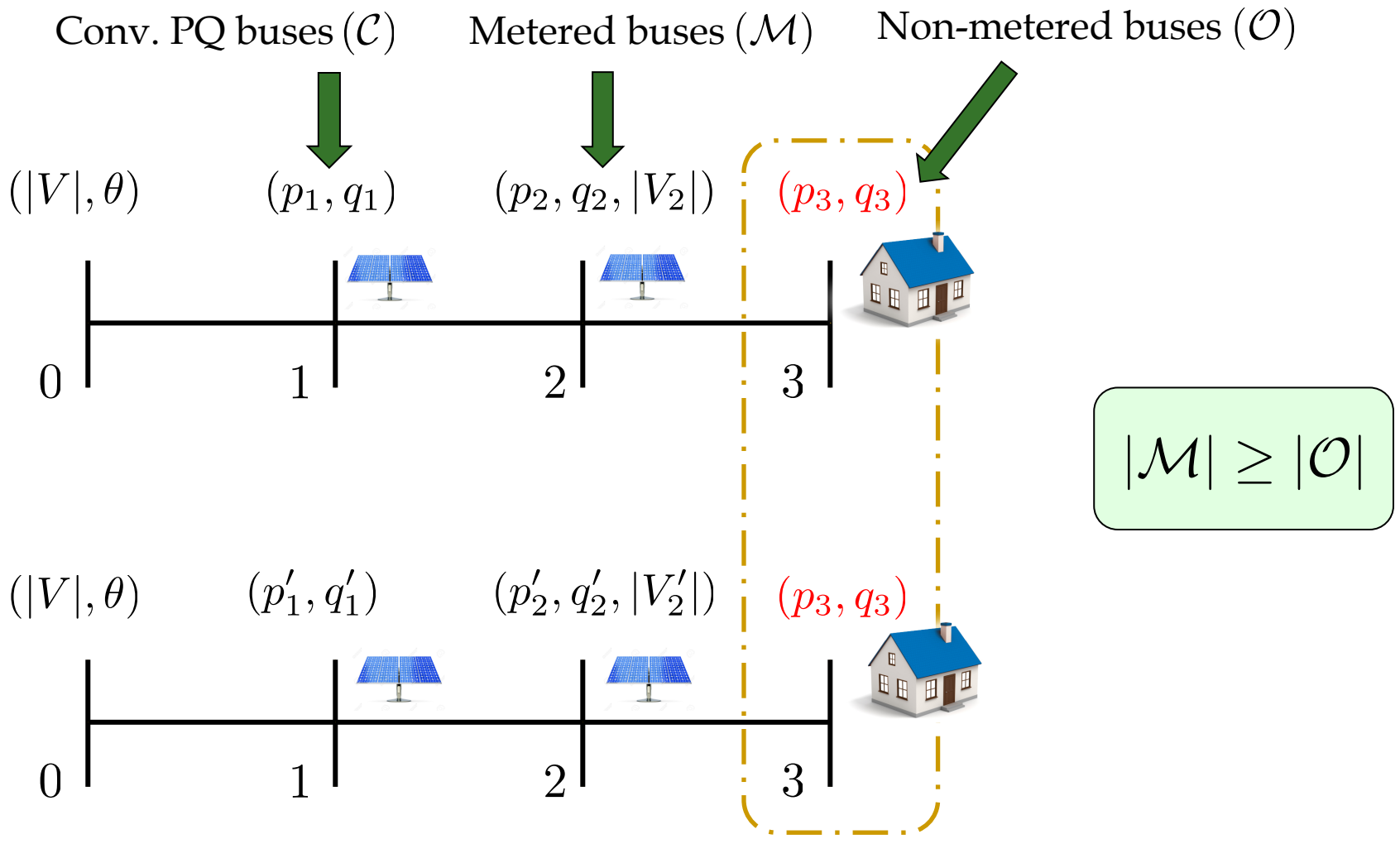
Problem statement

- Define the following set of buses
 - Set \mathcal{M} (metered buses): $(p_n, q_n, |V_n|^2)$ specified
 - Set \mathcal{O} (non-metered buses): no information is available
 - Set \mathcal{C} of conv. PQ buses: (p_n, q_n) specified
 - Substation bus $\mathcal{S} = \{0\}$

$$\mathcal{N} := \{1, \dots, N\} = \mathcal{C} \cup \mathcal{M} \cup \mathcal{O}$$




- Given smart meter data find the system state \mathbf{V} , i.e. the vector of voltages and infer the unobserved loads in \mathcal{O}

Coupled power flow (CPF)



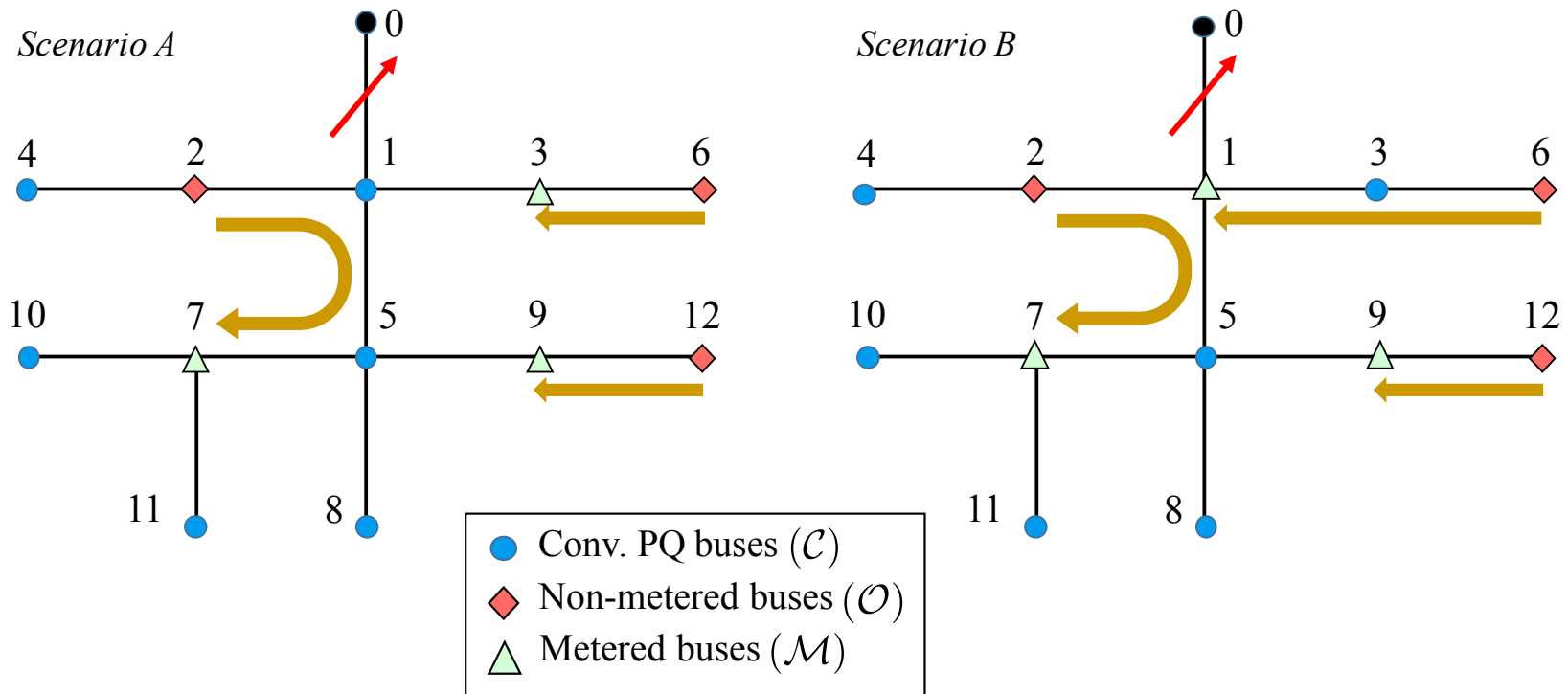
Coupling flows via grid probing

- Grid transitions from state $\mathbf{v} \rightarrow \mathbf{v}'$
- Grid sensing on \mathcal{M} over two consecutive time instances

$v_{i,0}(\mathbf{v})^2 = 0$			Time instance t
$ V_n(\mathbf{v}) ^2 = \hat{V}_n ^2$	$\forall n \in \mathcal{S} \cup \mathcal{M}$		
$q_n(\mathbf{v}) = \hat{q}_n$	$\forall n \in \mathcal{C} \cup \mathcal{M}$		
$p_n(\mathbf{v}) = \hat{p}_n$	$\forall n \in \mathcal{C} \cup \mathcal{M}$		
$p_n(\mathbf{v}) = p_n(\mathbf{v}')$	$\forall n \in \mathcal{O}$		Coupling
$q_n(\mathbf{v}) = q_n(\mathbf{v}')$	$\forall n \in \mathcal{O}$		
$v_{i,0}(\mathbf{v}')^2 = 0$			Time instance t'
$ V_n(\mathbf{v}') ^2 = \hat{V}'_n ^2$	$\forall n \in \mathcal{S} \cup \mathcal{M}$		
$q_n(\mathbf{v}') = \hat{q}'_n$	$\forall n \in \mathcal{C} \cup \mathcal{M}$		
$p_n(\mathbf{v}') = \hat{p}'_n$	$\forall n \in \mathcal{C} \cup \mathcal{M}$		

Criterion for solvability

If there exists a set of vertex-disjoint paths from $\mathcal{O} \rightarrow \mathcal{M}$ in $\mathcal{T} = (\mathcal{N}, \mathcal{L})$ then the CPF equations are locally invertible in general.



Solving PF as an SDP

- PF as a feasibility problem

$$\begin{aligned} \text{find} \quad & \mathbf{v} \in \mathbb{C}^n \\ \text{s.t.} \quad & \mathbf{v}^H \mathbf{M}_k \mathbf{v} = \hat{s}_k, \quad k = 1, \dots, m \end{aligned}$$

- PF in standard form [2]

$$\begin{aligned} \min_{\mathbf{V}} \quad & \text{tr}(\mathbf{M}\mathbf{V}) \\ \text{s.t.} \quad & \text{tr}(\mathbf{M}_k \mathbf{V}) = \hat{s}_k \quad k = 1, \dots, m \\ & \mathbf{V} \succeq 0 \\ & \text{rank}(\mathbf{V}) = 1 \end{aligned}$$

$\mathbf{V} = \mathbf{v}\mathbf{v}^H$

Coupled PSSE

- Measurements are corrupted with noise and/or unknown loads may change over time.

$$\hat{s}_k = s(\mathbf{v}) + \epsilon_k$$

- Rather than solving exactly the CPF equations, minimize a least-squares cost

$$\underbrace{\sum_k (\hat{s}_k - \mathbf{v}^H \mathbf{M}_k \mathbf{v})^2}_{\text{Time instance } t} + \underbrace{\sum_k (\hat{s}_k - \mathbf{v}'^H \mathbf{M}_k \mathbf{v}')^2}_{\text{Time instance } t'} + \underbrace{\sum_k (\mathbf{v}^H \mathbf{M}_k \mathbf{v} - \mathbf{v}'^H \mathbf{M}_k \mathbf{v}')^2}_{\text{Coupling}}$$

SDP-based PSSE

$$\begin{aligned}
 & \min_{\mathbf{V}, \mathbf{V}', \boldsymbol{\epsilon}} \sum_{\ell=1}^{2L+2O} f_{\ell}(\epsilon_{\ell}) + \alpha [\text{tr}(\mathbf{M}\mathbf{V}) + \text{tr}(\mathbf{M}\mathbf{V}')] \\
 & \text{s.t. } \text{tr}(\mathbf{M}_{\ell}\mathbf{V}) + \epsilon_{\ell} = \hat{s}_{\ell}, \quad \ell = 1, \dots, L \\
 & \quad \text{tr}(\mathbf{M}_{\ell}\mathbf{V}') + \epsilon_{\ell} = \hat{s}'_{\ell}, \quad \ell = L+1, \dots, 2L \\
 & \quad \text{tr}(\mathbf{M}_{\ell}(\mathbf{V}' - \mathbf{V})) = \epsilon_{\ell}, \quad \ell = 2L+1, \dots, 2L+2O \\
 & \quad \mathbf{V} \succeq \mathbf{0}, \mathbf{V}' \succeq \mathbf{0}.
 \end{aligned}$$

- **Least-Squares (LS) [3],[4],[5],[6]**

$$f(\boldsymbol{\epsilon}) = \sum_{\ell=1}^{2L+2O} \epsilon_{\ell}^2$$

- **Least-Absolute Value (LAV)**

$$f(\boldsymbol{\epsilon}) = \sum_{\ell=1}^{2L+2O} |\epsilon_{\ell}|$$

- **Strengthen SDP relaxation**

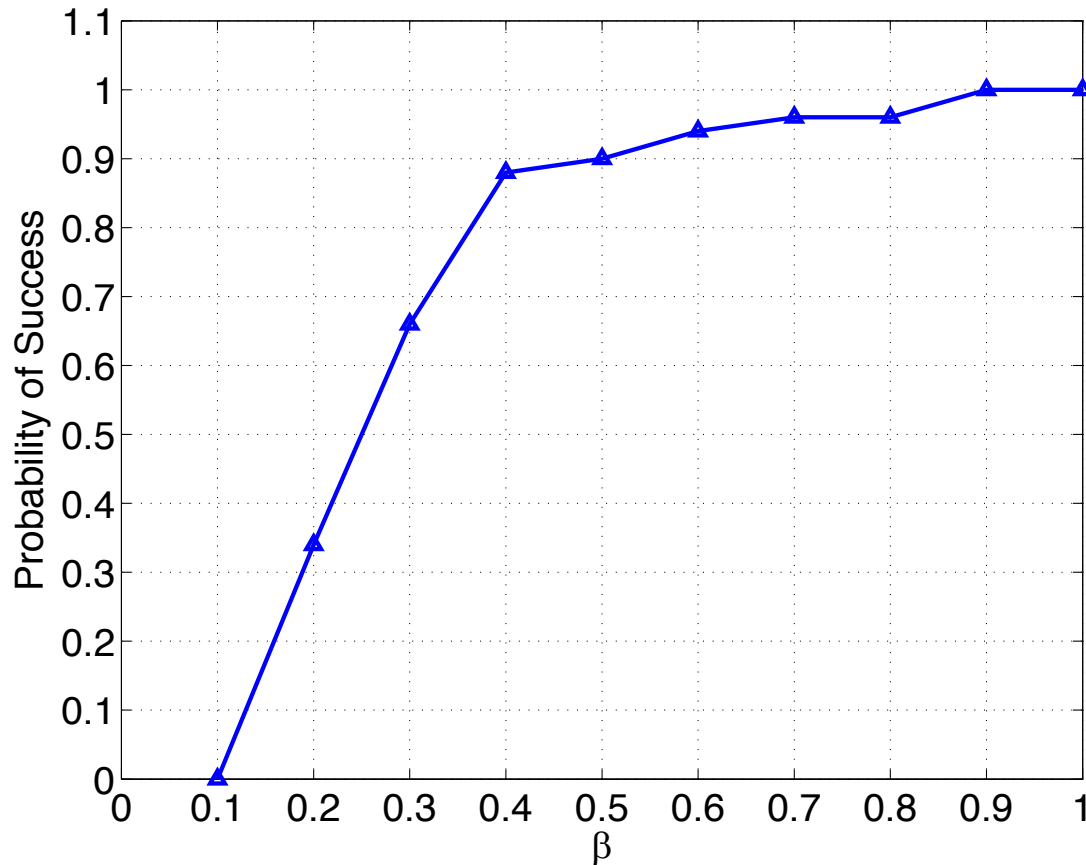
$$\text{tr}(\mathbf{M}_{pn}\mathbf{V}) < 0$$

$$\forall n \in \mathcal{O}$$

$$\text{tr}(\mathbf{M}_{pn}\mathbf{V}') < 0$$

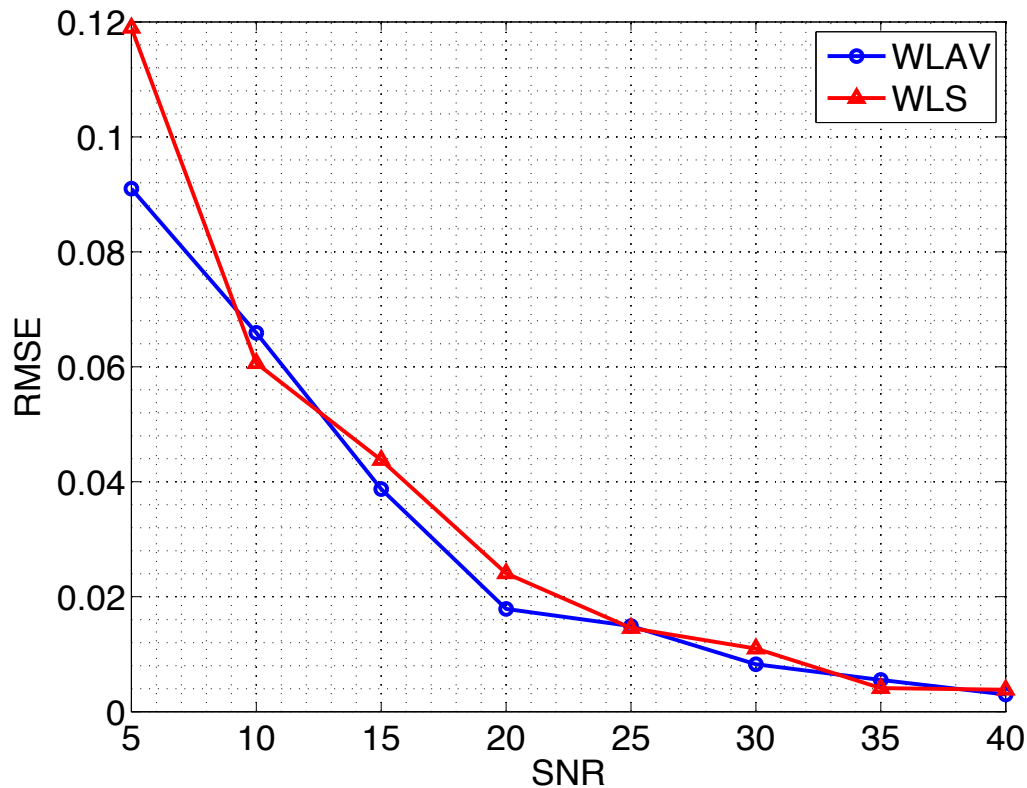
$$\forall n \in \mathcal{O}$$

Probability of success



- β captures the ℓ_2 -norm between the two states $(\mathbf{v}, \mathbf{v}')$ [6]
- As $\|\mathbf{v} - \mathbf{v}'\|_2$ increases, grid probing changes system state

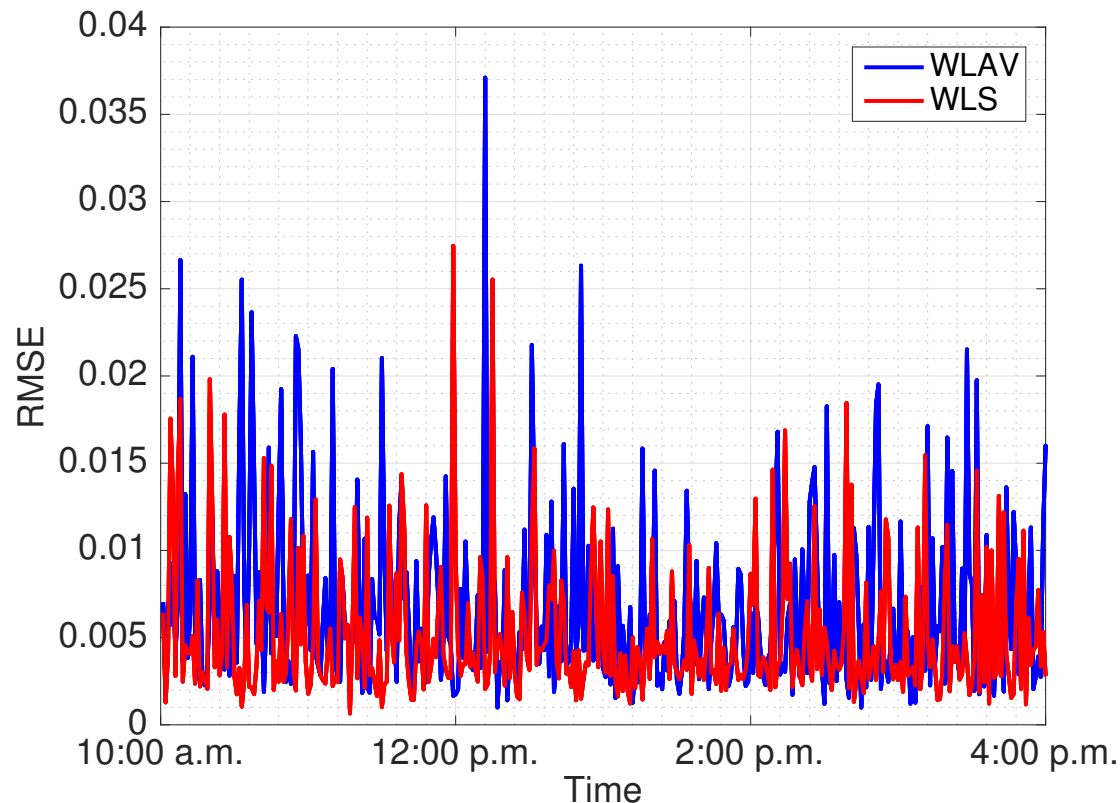
Estimation error



- Averaged over **20** simulations for each step [6]

- RMSE:
$$\sqrt{\sum_{t=1}^N \frac{(\hat{v}_t - v_{t,true})^2 + (\hat{v}'_t - v'_{t,true})^2}{2N}}$$

Numerical tests with real data



- Simulation over one day with **real data** [1],[6]
- Grid probing to change system state
- RMSE is very low

Conclusions

- Used smart inverters for grid probing
- Novel technique using time coupling
- Fewer measurements needed to estimate the system state
- Characterized local invertibility via an intuitive **criterion**
- Developed an SDP-based solver for coupled power flow (CPF) and coupled power system state estimation (CPSSE).

References

- [1] Pecan street Inc. Dataport 2013. Available: <https://dataport.pecanstreet.org/>
- [2] R. Madani, J. Lavaei, and R. Baldick, "Convexification of power flow problem over arbitrary networks," in Proc. IEEE Conf. on Decision and Control, Osaka, Japan, Dec. 2015.
- [3] H. Zhu and G. B. Giannakis, "Power System Nonlinear State Estimation Using Distributed Semidefinite Programming," *IEEE Journal of Selected Topics in Signal Processing*, vol. 8, no. 6, pp. 1039-1050, Dec. 2014.
- [4] C. Klauber and H. Zhu, "Distribution system state estimation using semidefinite programming," in Proc. North American Power Symposium, Charlotte, NC, Oct. 2015.
- [5] R. Madani, A. Ashraphijuo, J. Lavaei, and R. Baldick, "Power system state estimation with a limited number of measurements," in Proc. IEEE Conf. on Decision and Control, Las Vegas, NV, Dec. 2016.
- [6] S. Bhela, V. Kekatos, and S. Veeramachaneni, "Enhancing Observability in Distribution Grids using Smart Meter Data," *IEEE Trans. on Smart Grid*, Feb. 2016 (accepted).