

HIGH-ORDER LOCAL NORMAL DERIVATIVE PATTERN (LNDP) FOR 3D FACE RECOGNITION



Sima Soltanpour*, Q.M. Jonathan Wu, CVSS lab, Department of Electrical & Computer Engineering
University of Windsor, Windsor, Canada
*soltanps@uwindsor.ca



METHODS CATEGORIZATION

Face recognition: global and local feature-based Methods

Local descriptors: prominent points, patches or regions of the face to handle facial expression, occlusion, and missing data

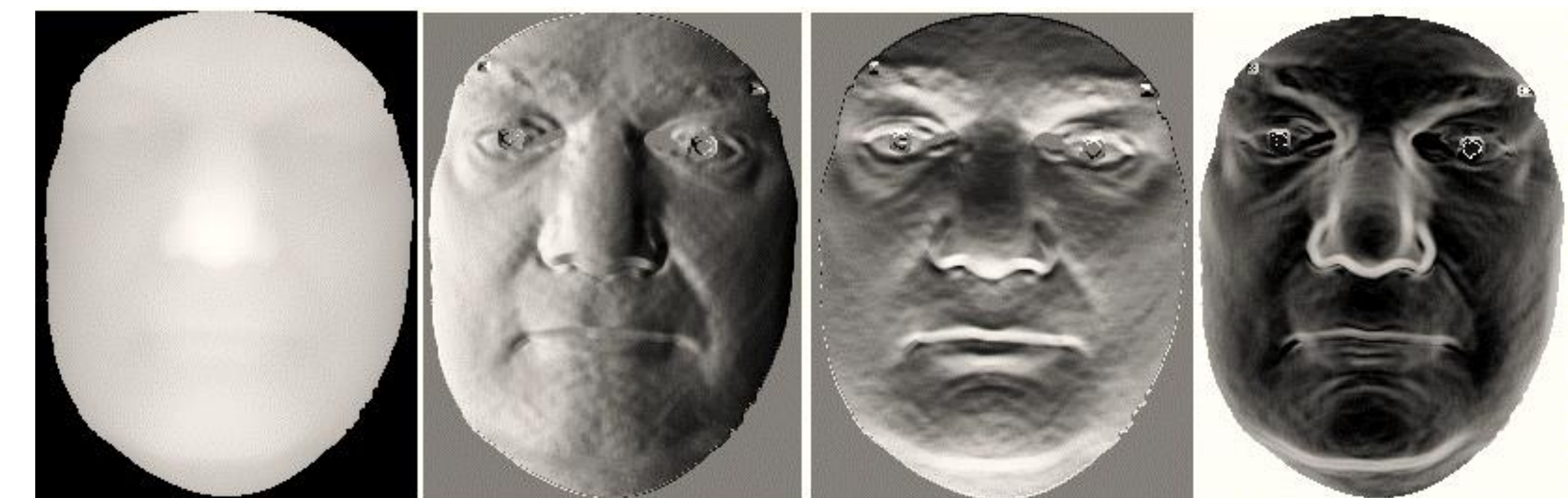
PRE-PROCESSING

- Remove spike and noises using median filter
- Hole filling by fitting square surface
- Nose detection by curvature-based method, and region of interest (ROI) cropping
- Pose correction (the iterative closest point (ICP))

SURFACE NORMAL

$$P = [p_1, p_2, \dots, p_n]^T, p_i \in R^3 \quad p_i = [p_{ix}, p_{iy}, p_{iz}]^T$$

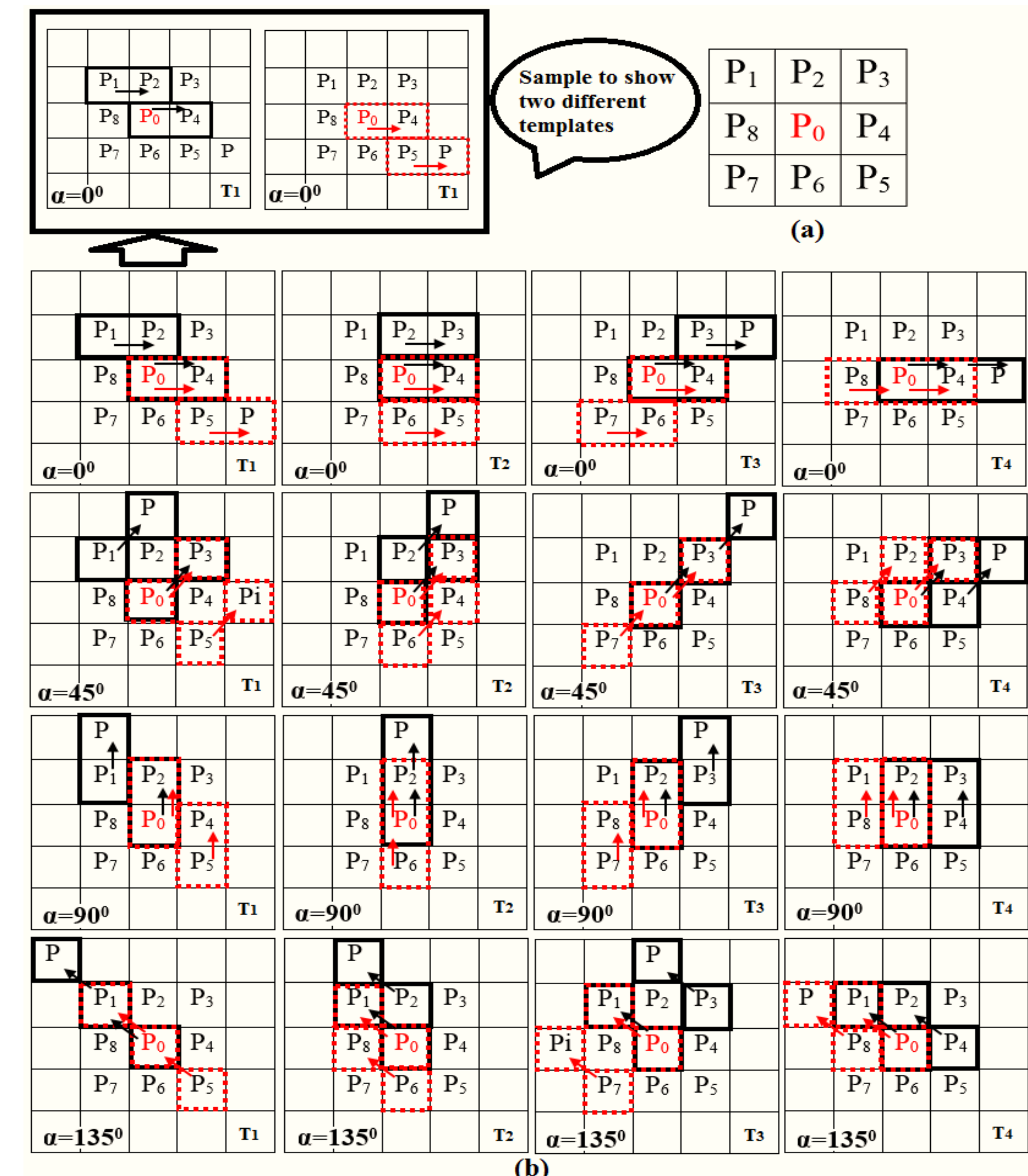
$$n_i = [n_{ix}, n_{iy}, n_{iz}]^T \quad Q_i = [q_{i1}, q_{i2}, \dots, q_{il}]^T \quad \min A(p_i, Q_i, n_i)$$



Range image, normal component x, normal component y, and normal component z

LOCAL DERIVATIVE PATTERN

LDP: encoding directional pattern features



(a) 8-neighborhood around P0

(b) 32 templates for $\alpha = 0, 45, 90, 135$

The black and dashed red lines represent two different templates: T1(i = 1, 5), T2(i = 2, 6), T3(i = 3, 7), and T4(i = 4, 8)

References

- [1] D. Huang, M. Ardabilian, Y. Wang, and L. Chen, "3-D face recognition using eLBP-based facial description and local feature hybrid matching," IEEE Transactions on Information Forensics and Security, vol. 7, no. 5, pp. 1551–1565, 2012.
- [2] H. Tang, B. Yin, Y. Sun, and Y. Hu, "3D face recognition using local binary patterns," Signal Processing, vol. 93, no. 8, pp. 2190–2198, 2013.
- [3] H. Li, D. Huang, J.-M. Morvan, L. Chen, and Y. Wang, "Expression-robust 3D face recognition via weighted sparse representation of multi-scale and multi-component local normal patterns," Neurocomputing, vol. 133, pp. 179–193, 2014.
- [4] A. Aissaoui, J. Martinet, and C. Djeraba, "DLBP: A novel descriptor for depth image based face recognition," in IEEE International Conference on Image Processing (ICIP), 2014, pp. 298–302.
- [5] S. Lv, F. Da, and X. Deng, "A 3D face recognition method using region-based extended local binary pattern," in IEEE International Conference on Image Processing (ICIP), 2015, pp. 3635–3639.

PROPOSED LNDP

Algorithm 1 n^{th} -order LNDP

Input: 3D face data P

- 1: for each point in P do
- 2: Calculate normal components (N_x, N_y , and N_z)
- 3: end for
- 4: for each N do
- 5: Divide into 10×8 patches
- 6: end for
- 7: for $\alpha = 0^\circ, 45^\circ, 90^\circ, 135^\circ$ do
- 8: for each patch do
- 9: for each pixel in patch of N do
- 10: Apply Equation (★)
- 11: end for
- 12: Encode LNDP using Equation (★★)
- 13: Histogram construction
- 14: end for
- 15: Concatenate the histogram for different patches
- 16: end for
- 17: Concatenate the histogram for different α
- 18: return $HLNDP_x^n, HLNDP_y^n, HLNDP_z^n$

The decimal value of the descriptor:

$$LNDP_\alpha^n(P_0) = \sum_{l=1}^L LNDP_\alpha^n(P_0) \times 2^{l-1} \quad \star\star$$

Similarity:

$$S(H_G, H_Q) = \sum_{i=1}^C \min(H_G(i), H_Q(i))$$

For a normal component the first-order derivatives:

$$N'_{0^\circ}(P_0) = N(P_0) - N(P_4) \quad N'_{90^\circ}(P_0) = N(P_0) - N(P_2)$$

$$N'_{45^\circ}(P_0) = N(P_0) - N(P_3) \quad N'_{135^\circ}(P_0) = N(P_0) - N(P_1)$$

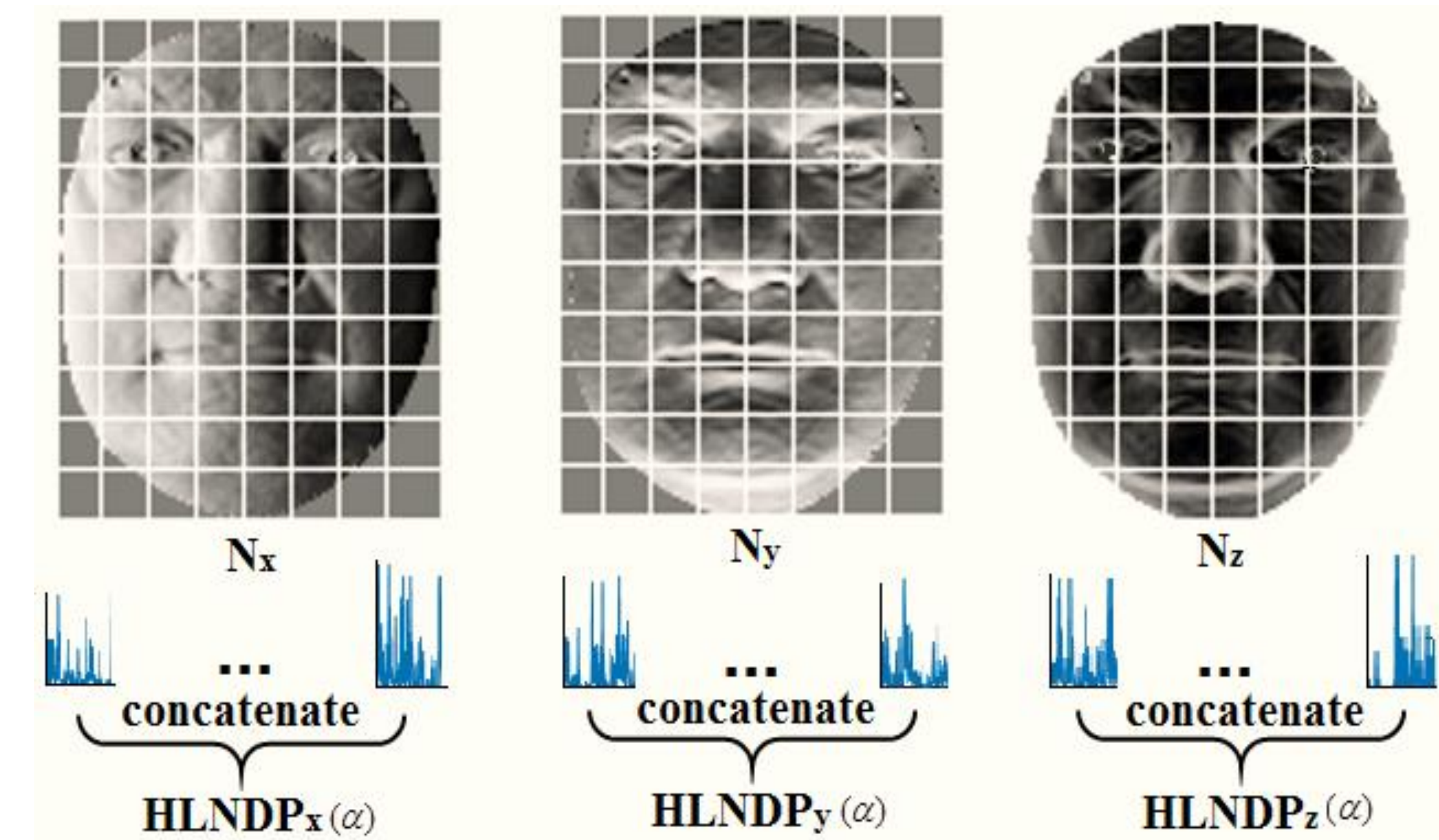
The second-order normal local derivative pattern:

$$LNDP_\alpha^2(P_0) = (f(N'_\alpha(P_0), N'_\alpha(P_1)), f(N'_\alpha(P_0), N'_\alpha(P_2)), \dots, f(N'_\alpha(P_0), N'_\alpha(P_8)))$$

Binary coding function is equal to 0 if $f(N'_\alpha(P_0), N'_\alpha(P_i)) > 0$ and equal to 1 if $f(N'_\alpha(P_0), N'_\alpha(P_i)) \leq 0$.

n^{th} - order of LNDP:

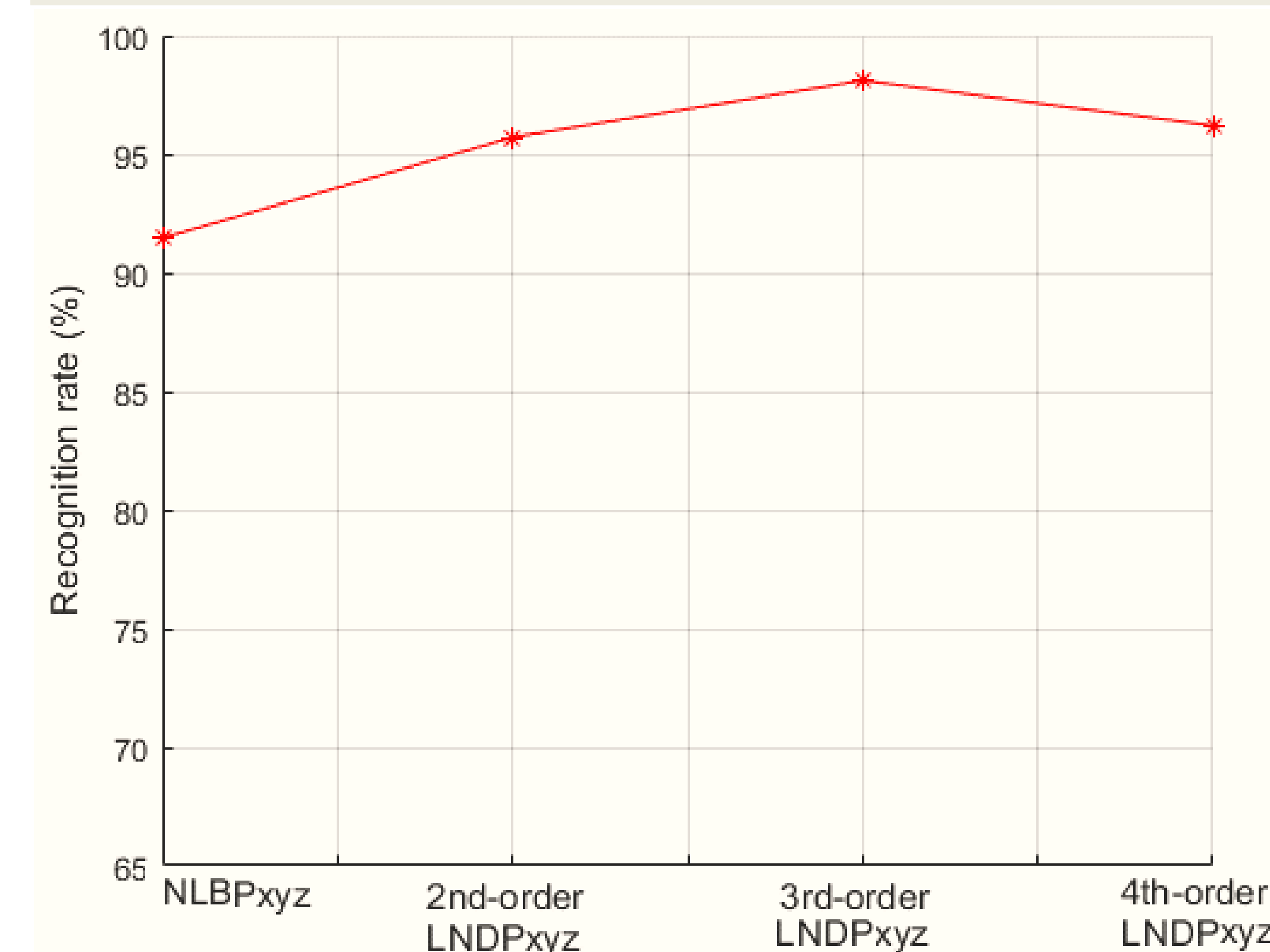
$$LNDP_\alpha^n(P_0) = (f(N_\alpha^{n-1}(P_0), N_\alpha^{n-1}(P_1)), f(N_\alpha^{n-1}(P_0), N_\alpha^{n-1}(P_2)), \dots, f(N_\alpha^{n-1}(P_0), N_\alpha^{n-1}(P_8)))$$



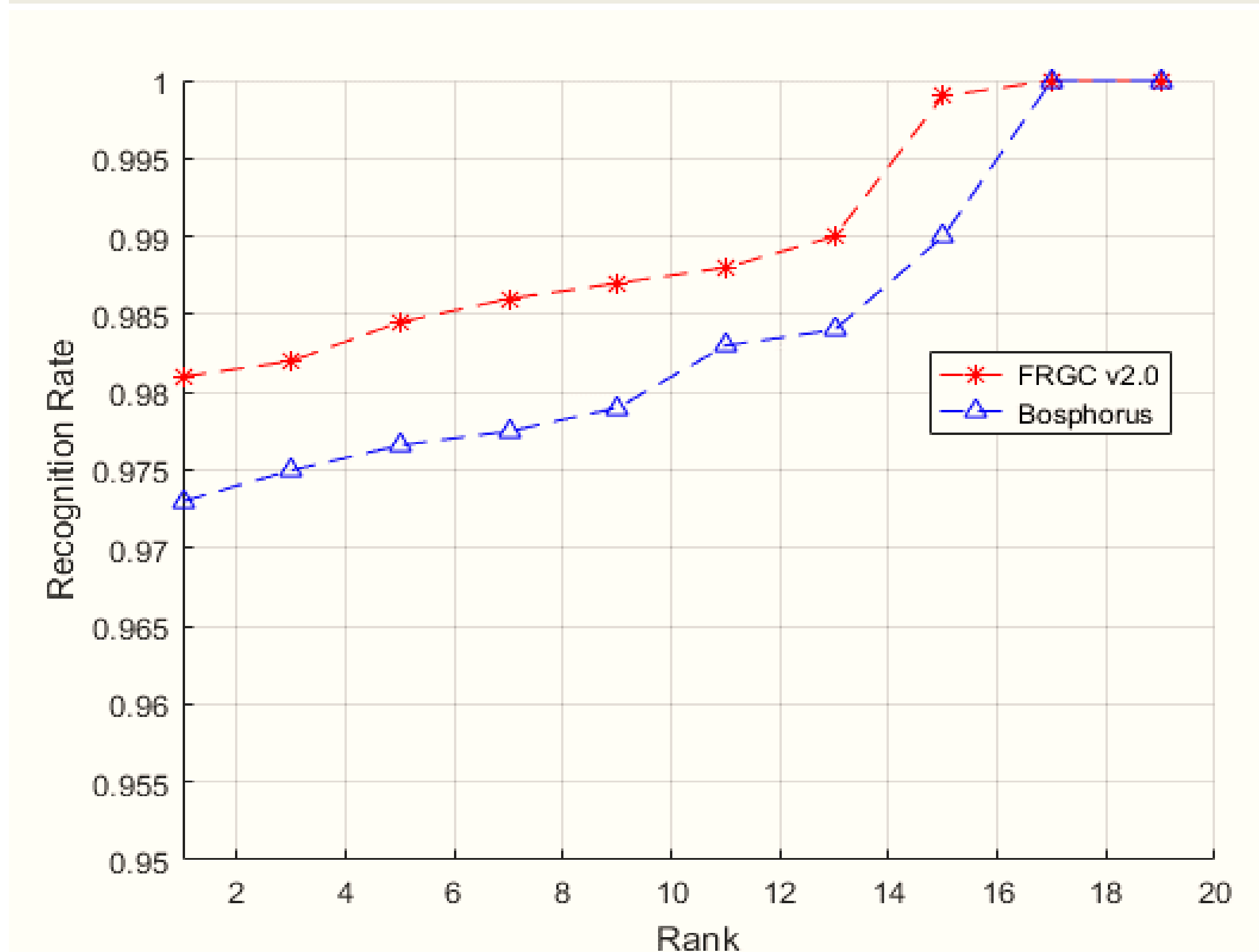
HLNDP for x, y, and z facial normal components

EXPERIMENTAL RESULTS

Different orders on FRGC v2.0 DB



CMC (score-level fusion third-order LNDP)



Comparison of LBP, LDP, and LNDP

Descriptor	RR1 (FRGC v2.0)
DepthLBP	86.2%
DLDP ³	89.08%
LNDP _x ³	92.53%
LNDP _y ³	91.18%
LNDP _z ³	96.04%
LNDP _{xyz} ³	98.1%

Comparison of LBP-based methods

Methods	RR1 (FRGC v2.0)	RR1 (Bosphorus)
MS-eLBPDPs [1]	97.6%	97%
V-LBP [2]	94.89% (900/150)	-
MSMC-LNP [3]	96.3%	95.4% (2797/105)
DLBP [4]	90%	90%
Region-based-eLBP [5]	97.8%	-
LNDP _{xyz} ³	98.1%	97.3%

Conclusion

- High-order LNDP (more detailed distinct information from the 3D facial image) is proposed.
- The score-level fusion (LNDP_x, LNDP_y, and LNDP_z) is applied.
- The algorithm is training free and computationally efficient.
- The proposed descriptor can be used in 3D object recognition as well.