Introduction

- Dictionary learning methods have been successfully applied to single subject fMRI data analysis.
- Dictionary learning methods do not naturally extend to multiple subjects.
- We propose CSMSDL to learn shared temporal dynamics from spatially concatenated fMRI datasets.
- Method is based on a modified Power Method.

Background

Given a set of signals $\mathbf{Y} = [\mathbf{y}_1, \mathbf{y}_2, ..., \mathbf{y}_N]$, our objective is to find a linear representation for the set of signals \mathbf{Y} .

$$\{\mathbf{D}, \mathbf{X}\} = \arg\min_{\mathbf{D}, \mathbf{X}} \| \mathbf{Y} - \mathbf{D}\mathbf{X} \|_{F}^{2}$$

This problem is ill-posed, extra constraints are imposed on both \mathbf{D} and \mathbf{X} , which are

- Columns of $\mathbf{X} \in \mathbb{R}^{K \times N}$ should be sparse.
- Columns of $\mathbf{D} \in \mathbb{R}^{n \times K}$ should have unit ℓ_2 norm.

The problem is solved by alternating two steps, i.e.

$$\hat{\mathbf{x}}_i = \arg\min_{x_i} \| \mathbf{y}_i - \mathbf{D}\mathbf{x}_i \|^2; \qquad (1)$$

subject to
$$\| \mathbf{x}_i \|_0 \leq s \quad i = 1, ..., N.$$

and

$$\mathbf{D} = \arg\min_{D} \| \mathbf{Y} - \mathbf{D}\mathbf{X} \|_{F}^{2}$$
(2)

In [1] (2) is solved sequentially by alternating

$$\mathbf{d}_{k} = \frac{\mathbf{E}_{k} \mathbf{x}_{k}^{row^{\top}}}{||\mathbf{E}_{k} \mathbf{x}_{k}^{row^{\top}}||_{2}}.$$
(3)

$$\mathbf{x}_{k}^{row} = \operatorname{sgn}(\mathbf{d}_{k}^{\top}\mathbf{E}_{k}) \circ \left(|\mathbf{d}_{k}^{\top}\mathbf{E}_{k}| - \frac{\alpha}{2}\mathbf{1}_{(N)}^{\top}\right)_{+}$$
(4)

Here $\mathbf{E}_k = \sum_{i=1, i \neq k}^{K} \mathbf{d}_i \mathbf{x}_i^{row}$.

CSMSDL: A Common Sequential Dictionary Learning Algorithm for Multi-Subject fMRI Data Sets Analysis

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CSMSDL

Starting with $\mathbf{Y} = [\mathbf{Y}_1, \mathbf{Y}_2, ..., \mathbf{Y}_p]$ of size $n \times pN$, the proposed model is $[\mathbf{Y}_1, \mathbf{Y}_2, ..., \mathbf{Y}_p] \simeq \mathbf{D}[\mathbf{X}_1, \mathbf{X}_2, ..., \mathbf{X}_p]$ (5) The sparse codes are found by solving (1) followed by dictionary update stage which is obtained from $\{\mathbf{d}_k, \mathbf{x}_k^{row}\} = \arg\min_{\mathbf{d}_k, \mathbf{x}_k^{row}} \|\mathbf{E}_k - \mathbf{d}_k \mathbf{x}_k^{row}\|_F^2 + \alpha \|\mathbf{x}_k^{row}\|_1$ where $\mathbf{E}_k = [\mathbf{E}_{k_1}\mathbf{E}_{k_2}...\mathbf{E}_{k_p}]$ with $\mathbf{E}_{k_j} = \mathbf{Y}_j$ – $\sum_{i=1,i\neq k}^{K} \mathbf{d}_i \mathbf{x}_{i_i}^{row}$. The full solution is shown below:

Algorithm Overview

Given: $\mathbf{Y}_1, \mathbf{Y}_2, ..., \text{ and } \mathbf{Y}_p, \mathbf{D}_{ini}, \mathbf{s}, \alpha, iter \text{ and } J.$ Set $\mathbf{D} = \mathbf{D}_{ini}$ For i=1 to J 1: Sparse Coding Stage: Find sparse coefficients X, by approximately solving $\hat{\mathbf{x}}_i = \arg\min_{x_i} \| \mathbf{y}_i - \mathbf{D}\mathbf{x}_i \|^2;$ subject to $\| \mathbf{x}_i \|_0 \leq s$ i = 1, ..., pN2: Dictionary Update Stage: For each column k = 1, 2, ..., K in **D**, 2.a: Compute the error matrices using $\mathbf{E}_{k_j} = \mathbf{Y}_j - \sum_{i=1, i \neq k}^{K} \mathbf{d}_i \mathbf{x}_{i_j}^{row}, \ j = 1, ..., p$ 2.b: Construct the error matrix \mathbf{E}_k as $\mathbf{E}_k = \begin{bmatrix} \mathbf{E}_{k_1} \mathbf{E}_{k_2} ... \mathbf{E}_{k_p} \end{bmatrix}$ While $\|\mathbf{d}_{k}^{iter} - \mathbf{d}_{k}^{iter+1}\|_{2}^{2} \geq \varepsilon$ iterate 2.c: Update the p block rows $\mathbf{x}_{k_i}^{row}$'s and its sparsity $\mathbf{x}_{k_j}^{row} = \operatorname{sgn}(\mathbf{d}_k^{\top} \mathbf{E}_{k_j}) \cdot \left(|\mathbf{d}_k^{\top} \mathbf{E}_{k_j}| - \frac{\alpha}{2} \mathbf{1}_{(N)}^{\top} \right)_{\perp}$ 2.d: Update the dictionary atom \mathbf{d}_k using $\mathbf{d}_{k}^{iter} = \frac{\sum_{j=1}^{p} \mathbf{E}_{k_{j}} \mathbf{x}_{k_{j}}^{row^{\top}}}{||\sum_{j=1}^{p} \mathbf{E}_{k_{j}} \mathbf{x}_{k_{j}}^{row^{\top}}||_{2}}$ iter = iter + 1end. Output: D,X





Figure 3: Most correlated dictionary atom w.r.t. MHR.



Figure 4: Average F-statistics activation maps (5 contiguous slices) for right finger tapping task stimulus random field correction p < 0.0001.



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Simulation Results

R dB		Sub_1	Sub_2	Sub_3
)	T_3	0.996	0.996	0.996
	С	0.978	0.995	0.996
5	T_3	0.963	0.963	0.963
	С	0.971	0.984	0.985
10	T_3	0.741	0.741	0.741
	С	0.866	0.869	0.872

References

[1] A. K. Seghouane and M. Hanif. A sequential dictionary learning algorithm with enforced sparsity. IEEE International Conference on Acoustic Speech and signal Processing, ICASSP, pages 3876-3880, 2015.