

# COMPARISON OF OBJECTIVE FUNCTIONS IN CNN-BASED PROSTATE MAGNETIC RESONANCE IMAGE SEGMENTATION

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## Introduction

- In CNNs training, the impacts of objective functions on the performance of deep-learning-based algorithms is as enormous as the network architecture
- 3D MR image has severe inter-intra variations that hinder the network from learning dataset
- 3D Fully convolutional network architecture which adapts the feature forwarding method is reliably trained with various objective functions
- Cosine similarity function is the best for training the 3D MR prostate image while various objective functions achieve remarkable performance

## Related Work

### 1) 3D MR Prostate Image Segmentation

- Malmberg et al. propagate initial user annotations from seed voxels to others [1]
- Tian et al. over-segment each image slice into super-pixels, and then dichotomize the super-pixels in to either prostate or non-prostate class based on the graph-cut optimization [2]
- Vincent et al. construct a generative prostate model using appearance, position, and texture features [3]

### 2) Deep Convolutional Neural Network

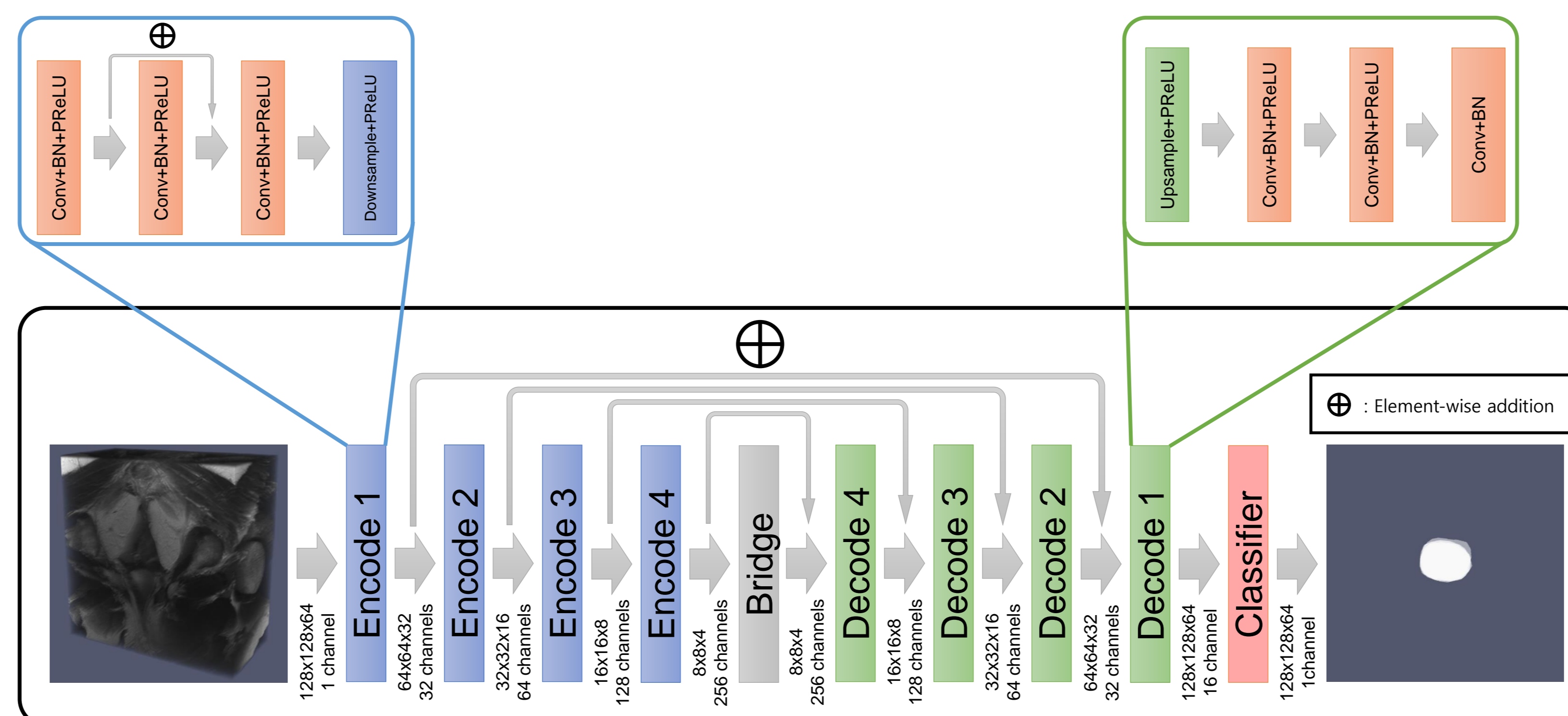
- Dai et al. proposed the fully convolutional network (FCN) for the image segmentation algorithms [4]
- He. Et al. provided the reliable training method that forwards the intermediate features [5]
- Ronneberger et al. adapted the encode-decode architecture and improved the performance with feature forwarding method [6]

### 3) CNN-based Image Segmentation

- Milletari et al. ameliorated the Ronneberger's algorithm with 3D convolutional layers and objective function which optimizes dice similarity [7]
- Yu et al. adopted the residual feature forwarding and perform the sliding window sampling to obtain segments statistically [8]

## Proposed Algorithm

### Base Network and objective functions



The architecture of the proposed BCNN, which uses the encoding, bridge, decoding, and classification modules.

- We construct the baseline convolutional neural network (BCNN) with encode-decode architecture including feature forwarding technique
- The network consists of 3D convolutional, pooling, and deconvolutional layers that process the 3D input data at once
- BCNN learns the given dataset with various objective functions as follow

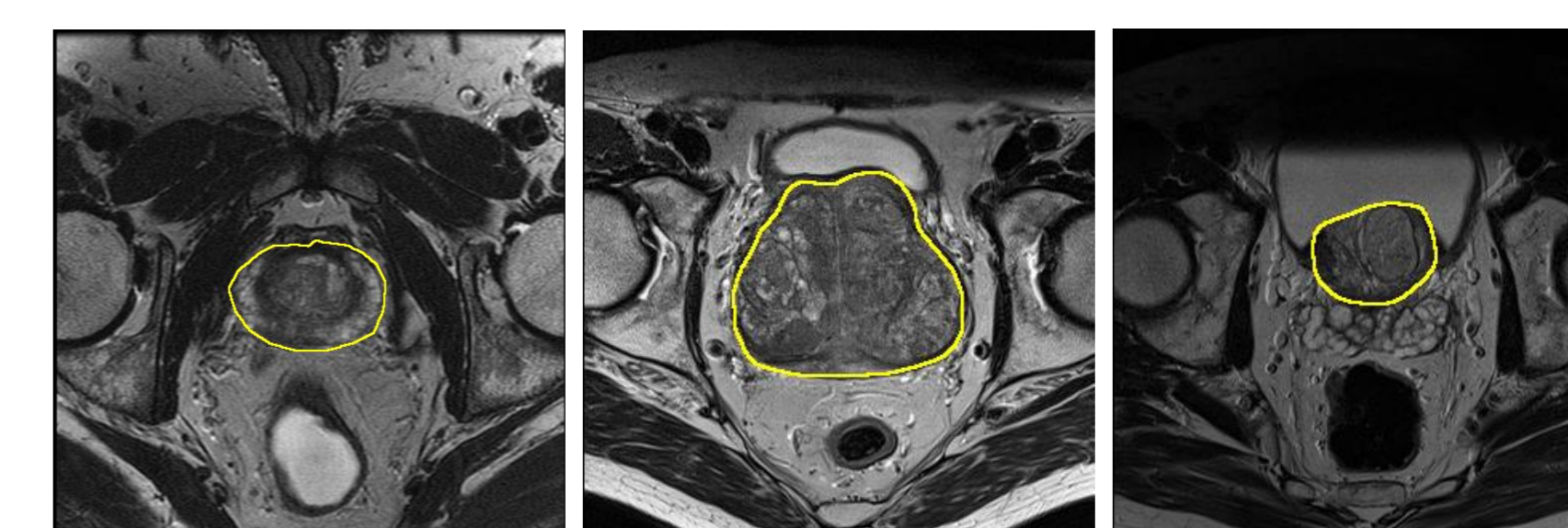
Table 1. Objective functions used in training:

$p_i, q_i$  are estimated results and ground-truth respectively

Objective function	OTUs	Definition	Gradients
Hamming Distance	$b + c$	$\sum_{i=1}^N (p_i^2 + q_i^2 - 2p_i q_i)$	$2(p_j - q_j)$
Euclidean Distance	$\sqrt{b + c}$	$\sqrt{\sum_{i=1}^N (p_i^2 + q_i^2 - 2p_i q_i)}$	$\frac{p_j - q_j}{\sqrt{\sum_{i=1}^N (p_i^2 + q_i^2 - 2p_i q_i)}}$
Jaccard Index	$\frac{a}{a + b + c}$	$\frac{\sum_{i=1}^N p_i q_i}{\sum_{i=1}^N (p_i^2 + q_i^2 - p_i q_i)}$	$\frac{q_j \sum_{i=1}^N (p_i^2 + q_i^2 - p_i q_i) - (2p_j - q_j) \sum_{i=1}^N p_i q_i}{(\sum_{i=1}^N (p_i^2 + q_i^2 - p_i q_i))^2}$
Dice Coefficient	$\frac{2a}{2a + b + c}$	$\frac{2 \sum_{i=1}^N p_i q_i}{\sum_{i=1}^N (p_i^2 + q_i^2)}$	$\frac{2q_j \sum_{i=1}^N (p_i^2 + q_i^2) - 4p_j \sum_{i=1}^N p_i q_i}{(\sum_{i=1}^N (p_i^2 + q_i^2))^2}$
Cosine similarity	$\frac{a}{\sqrt{(a + b)(a + c)}}$	$\frac{\sum_{i=1}^N p_i q_i}{\sqrt{\sum_{i=1}^N p_i^2 \sum_{i=1}^N q_i^2}}$	$\frac{q_j \sum_{i=1}^N p_i^2 \sum_{i=1}^N q_i^2 - p_j \sum_{i=1}^N p_i q_i \sum_{i=1}^N q_i^2}{(\sum_{i=1}^N p_i^2 \sum_{i=1}^N q_i^2)^{3/2}}$

## Experimental Results

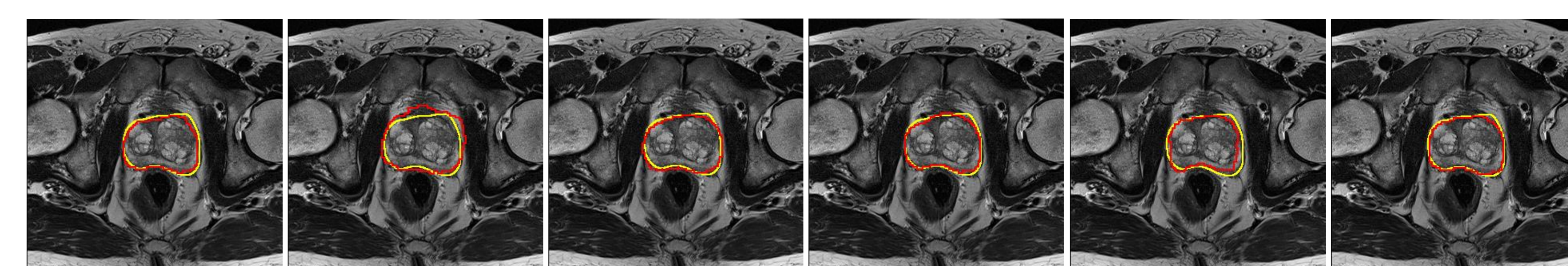
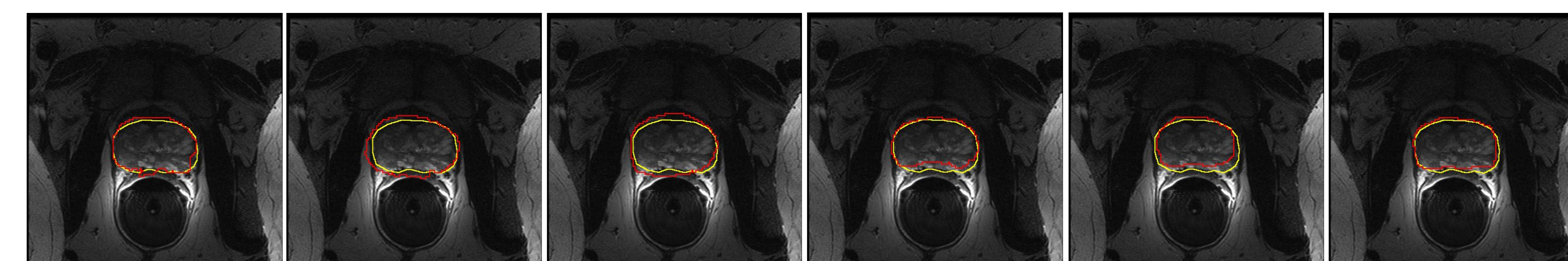
### 3D MR Prostate Image Dataset



#### PROMISE12

- Total 50 MR prostate images are given with GT
- The outlines of the prostate are depicted in yellow
- We evaluate algorithms with 10-fold cross validation
- Available: <https://promise12.grand-challenge.org>

### Qualitative and Quantitative Results



Qualitative comparison of the six objective functions for training the proposed BCNN.

The yellow and red boundaries outline the ground-truth and predicted prostate segments, respectively

Table 2. Quantitative results:

The score is Dice coefficient between results and ground-truth

Algorithm	Objective function	Score
BCNN	Hamming distance	0.8366
	Euclidean distance	0.8467
	Jaccard similarity	0.8291
	Dice coefficient	<u>0.8507</u>
	Cosine similarity	<b>0.8537</b>
	Cross entropy	0.8275
[8]	Cross entropy	0.8693

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 [2] Z. Tian, L. Liu, Z. Zhang, and B. Fei, "Superpixel-based segmentation for 3D prostate MR images," IEEE Trans. Medical Imaging, vol. 35, no. 3, 2016.  
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 [6] O. Ronneberger, P. Fischer, and T. Brox, "U-Net: Convolutional networks for biomedical image segmentation," in International Conference on Medical Image Computing and Computer-Assisted Intervention, Springer, 2015.  
 [7] F. Milletari, N. Navab, and S.-A. Ahmadi, "V-Net: Fully convolutional neural networks for volumetric medical image segmentation," in Proc. IEEE International Conference on Medical Image Computing and Computer-Assisted Intervention, 2016.  
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