

Fast Camera Fingerprint Matching In Very Large Databases

Samet Taspinar, Taha Sencar, Sevinc Bayram, Nasir Memon



### **MOTIVATION AND OBJECTIVE**

• PRNU based source camera attribution is a technique to determine the origin of images. However, querying a camera fingerprint is a computationally expensive task when the database is very large (i.e. millions of cameras). Efficient algorithms are required to make this task feasible







Motivation: Who captured the image?

Objective: How to determine origin camera efficiently?

# **APPROACH: PRNU BASED METHOD**

Every camera has a unique PRNU (Photo Response Non Uniformity) noise that can act as fingerprint.



**OUR SOLUTION** 

### **Approach 1**



Finding exact PRNU difficult. Fingerprint can be found from a set from estimated PRNU of a set of video frames.



### **IDENTIFICATION CHALLANGES**



- Search: Linear search takes 1000+ seconds when 16K fingerprint exist.
- Storage: Each fingerprint is 4 MB for 1 MP image.
- Due to random nature of fingerprint, it cannot be compressed.

- 2-level hybrid tree
- Root is a composite fingerprint
- Leaves are fingerprint digest

#### Approach 2



Root node (composite) is also a fingerprint digest

# **EXPERIMENTS**

- 176K images, 11 trees of 16K
- 3 known cameras, 18 random cameras
- $H_0, H_1^1, H_1^5$ Composite Size: 64, 128, 256, 512, 1024, 2048, 4096 Composite Digest Length: 16K, 20K, 36K, 64K Fingerprint Digest Length: 14K pixels

### **PREVIOUS WORK**

Linear Search Over Fingerprint Digests



Composite Based Search



- Subset of pixels Faster pairwise correlation
- Fewer number of correlations

# RESULTS

#### Querying single camera fingerprint in 16K noise set

- Linear Search : 1163 sec
- Fingerprint Digest : 22.1 sec
- Composite Search : 18.8 46.9 sec
- Approach 1 : 11.2 16.3 sec
- Approach 2 : 3.5 – 10.6 sec
- Approach 2 achieves around 3-7 times speed up compared to previous work