

# ICIP 2017

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 POLITECNICO DI MILANO



## Inpainting-based Camera Anonymization

S. Mandelli, L. Bondi, S. Lameri, V. Lipari, P. Bestagini, S. Tubaro

- When **privacy** related to digital images ownerships is a concern
  - Censorship
  - Photo-reporters protection in hot zones



- When **privacy** related to digital images ownerships is a concern
  - Censorship
  - Photo-reporters protection in hot zones
- **Remove** every way to back-track to the original photographer
  - Metadata manipulation
  - Sensor fingerprint removal or obfuscation

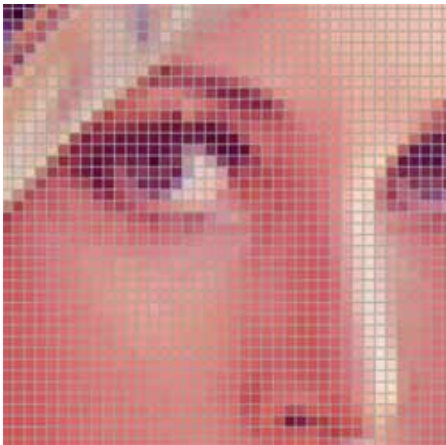


- Camera characterized by a certain **Photo-Response-Non-Uniformity** signal



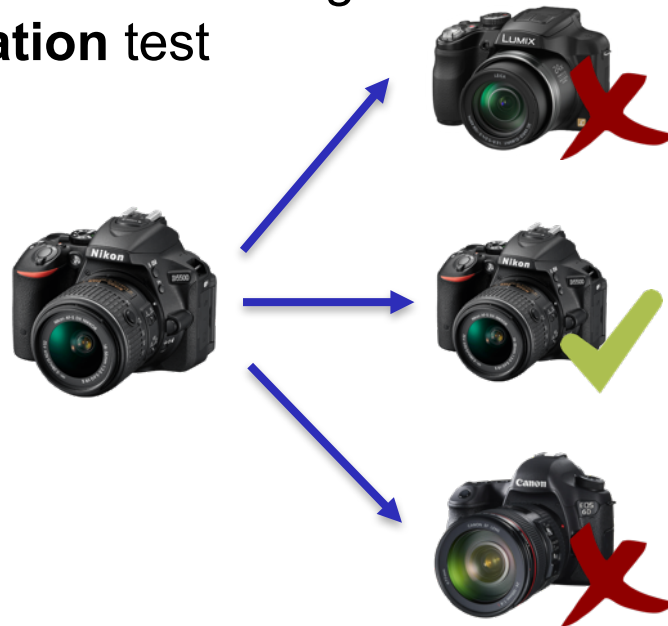
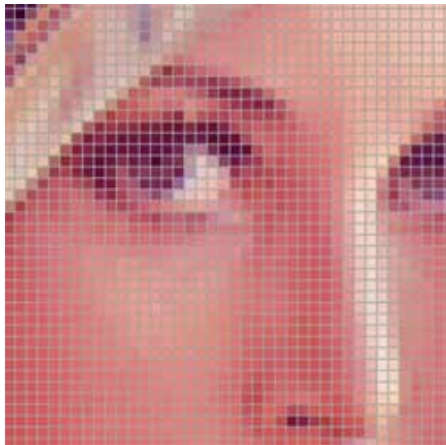
# Problem Formulation

- Camera characterized by a certain **Photo-Response-Non-Uniformity** signal
- Image shot with the same camera

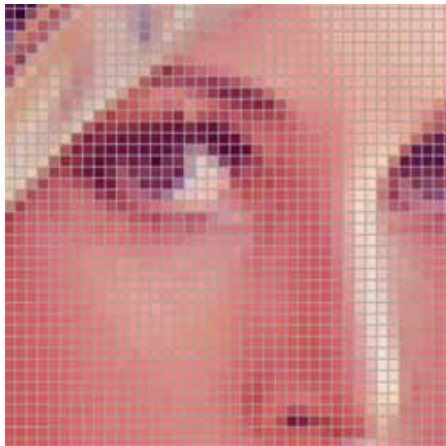




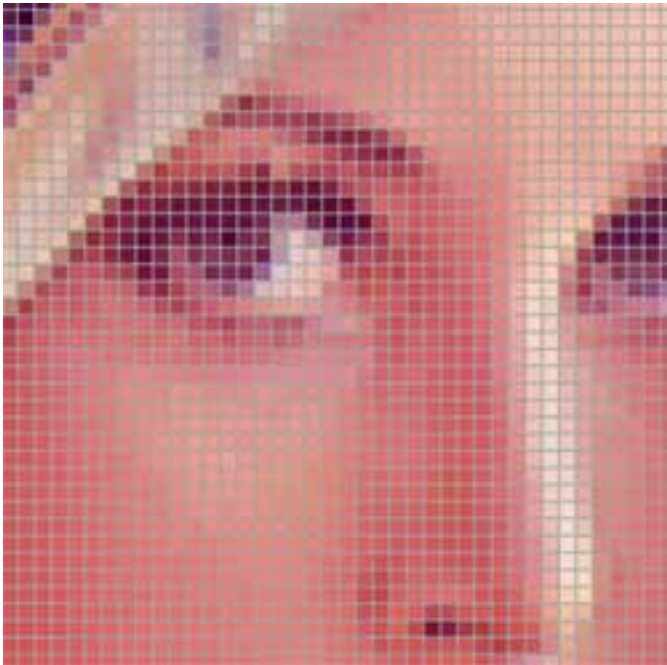
- Camera characterized by a certain **Photo-Response-Non-Uniformity** signal
- Image shot with the same camera
- **Noise residual** extracted from the image to perform **cross-correlation** test



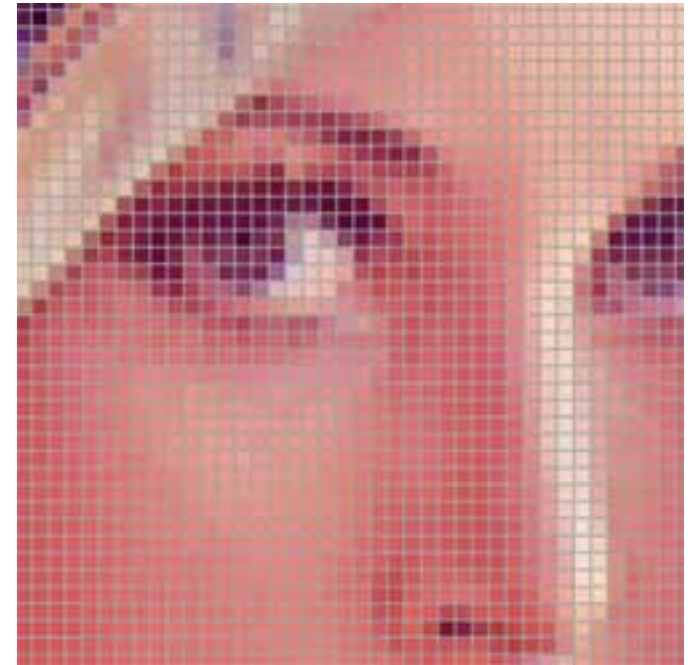
- **Anonymize** the image
- Preserving perceived image quality
- **Reducing cross-correlation** so that image source attribution becomes impossible



- **Substitute** each **pixel** of the image with an **inpainted** version based on its **neighbors**, so to corrupt PRNU traces embedded into it



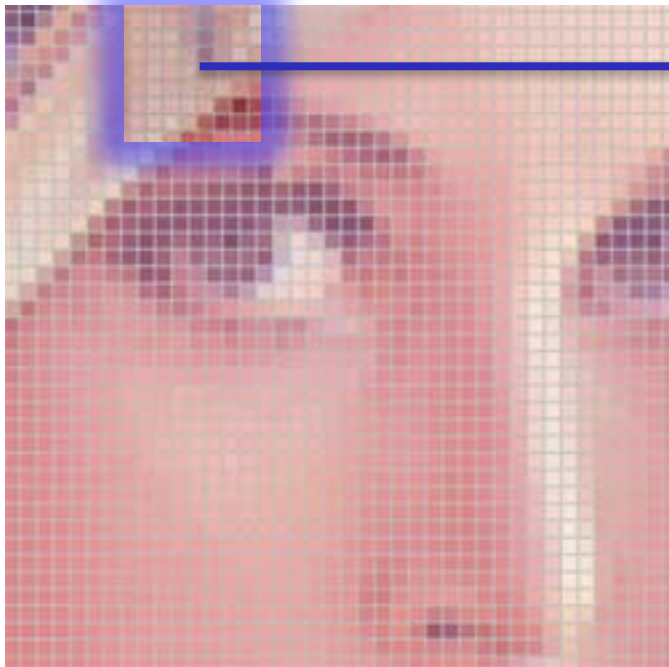
Original image



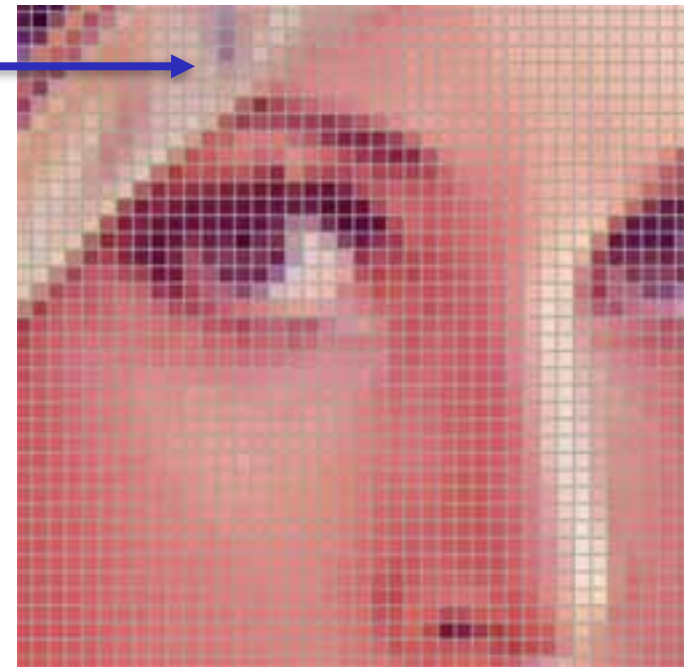
Anonymized image



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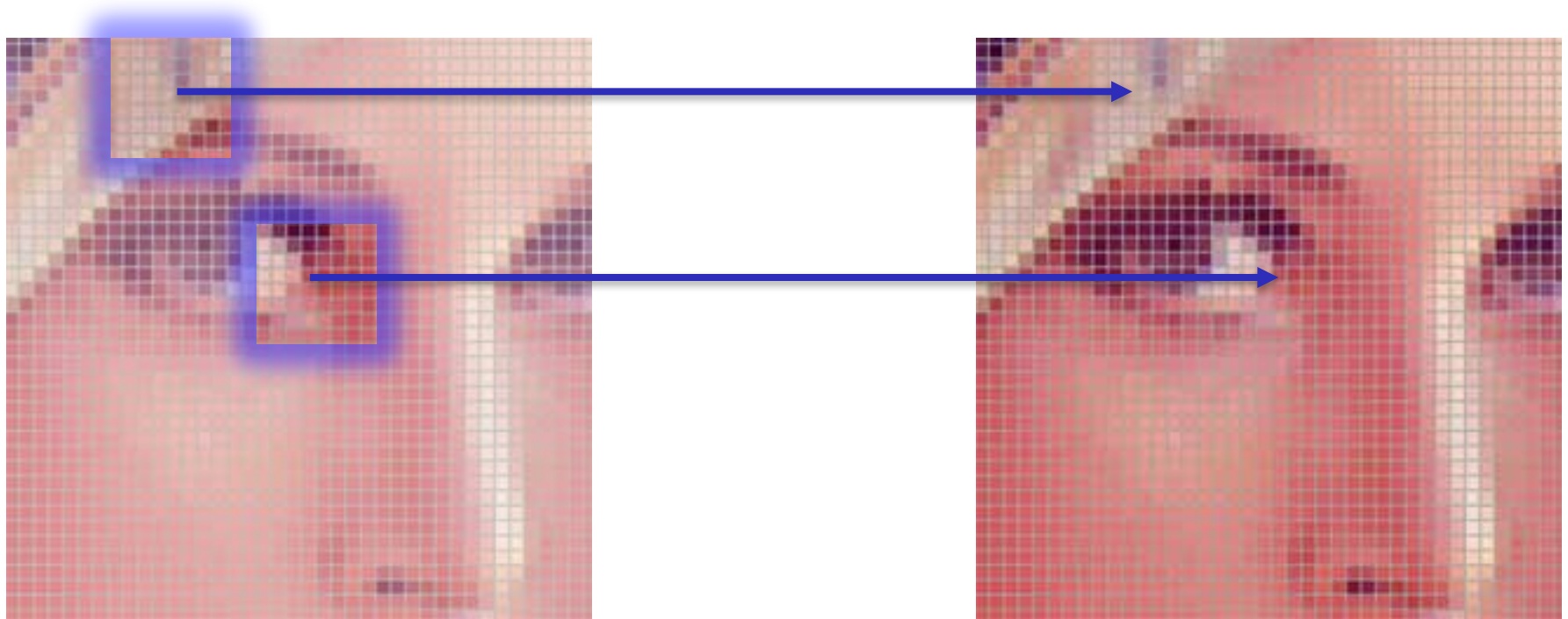


Original image



Anonymized image

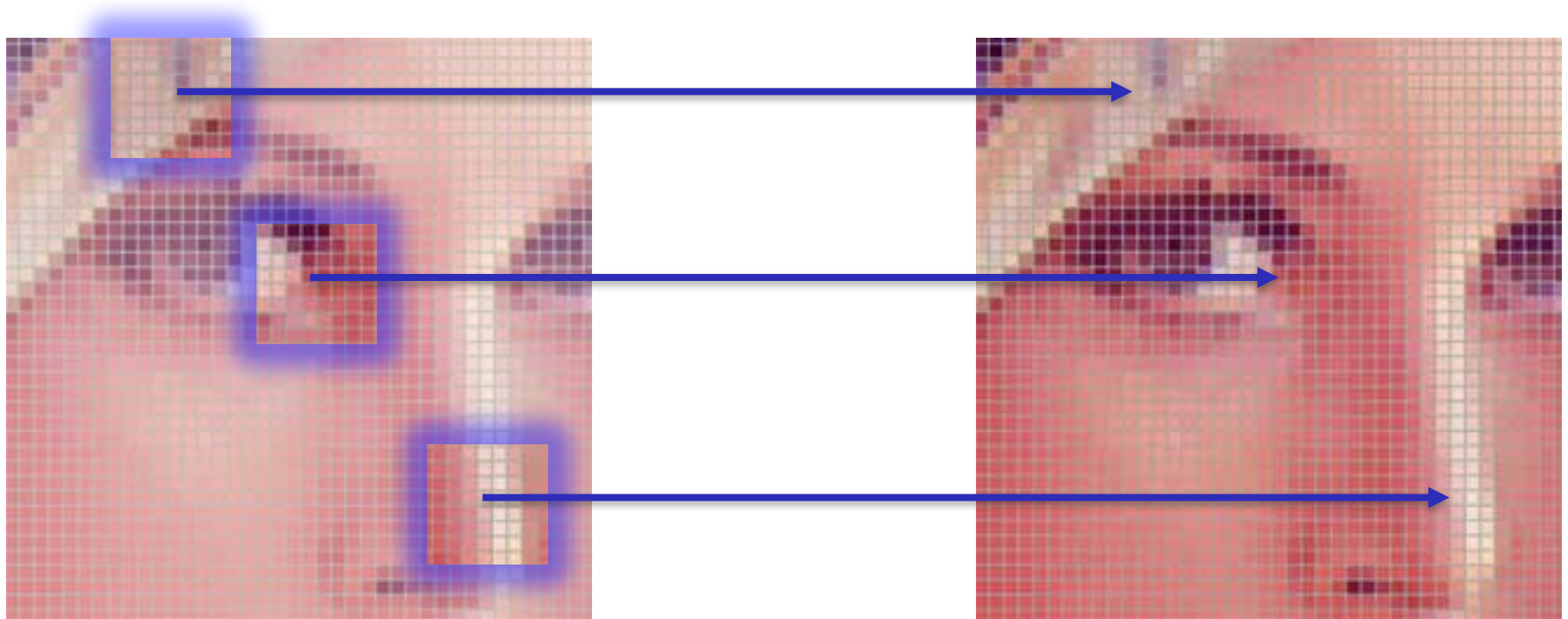
- **Substitute** each **pixel** of the image with an **inpainted** version based on its **neighbors**, so to corrupt PRNU traces embedded into it



Original image

Anonymized image

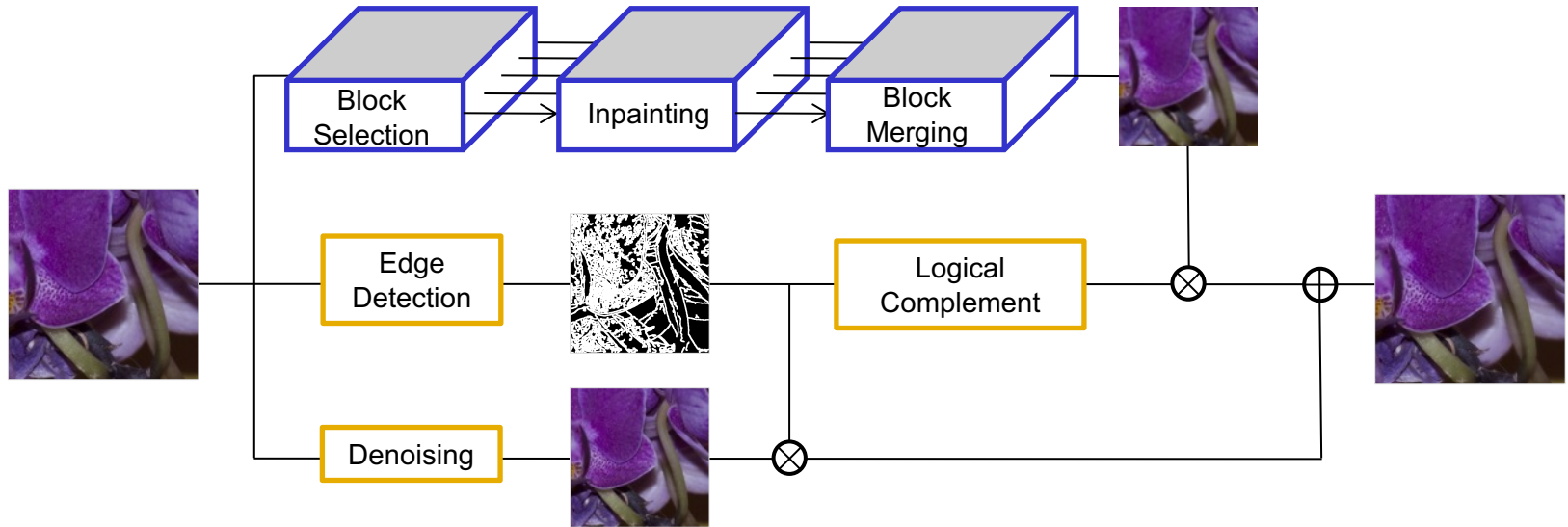
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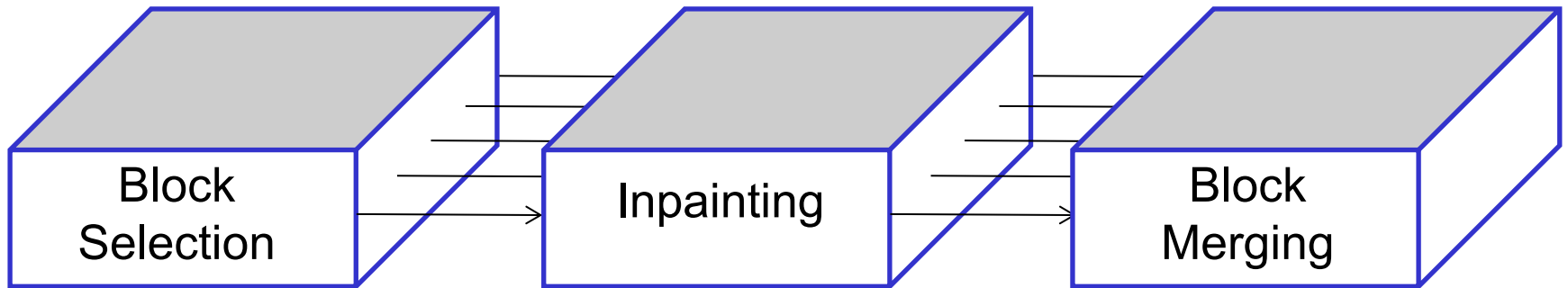
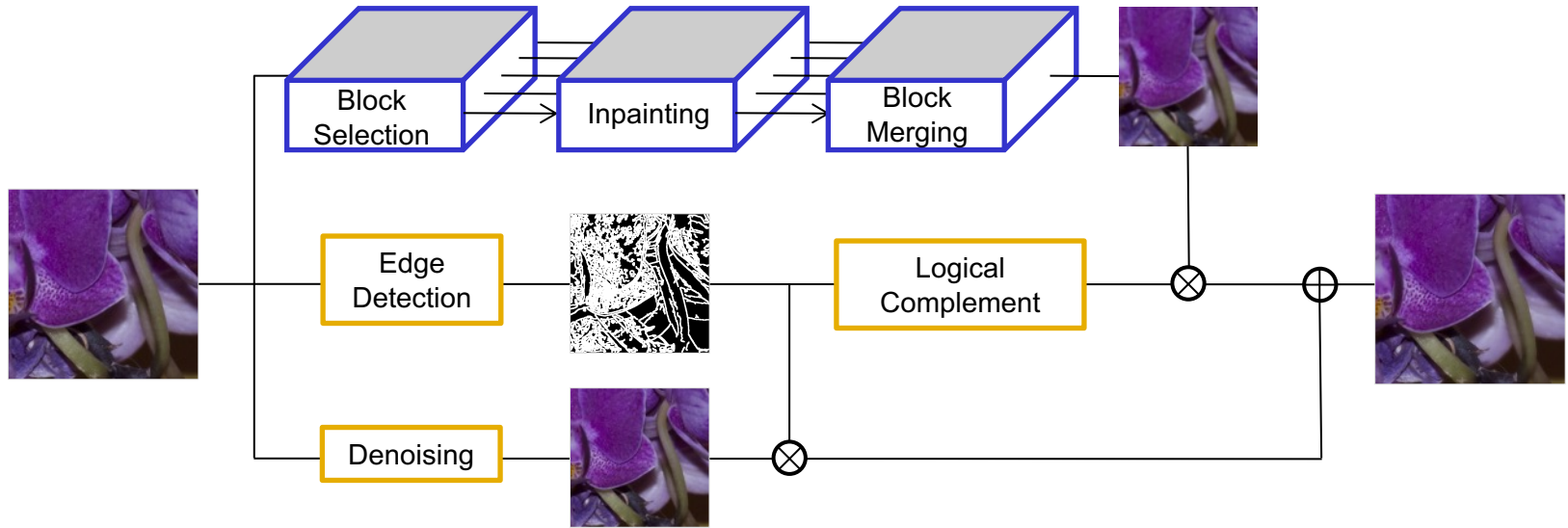
Original image

Anonymized image

## Overview

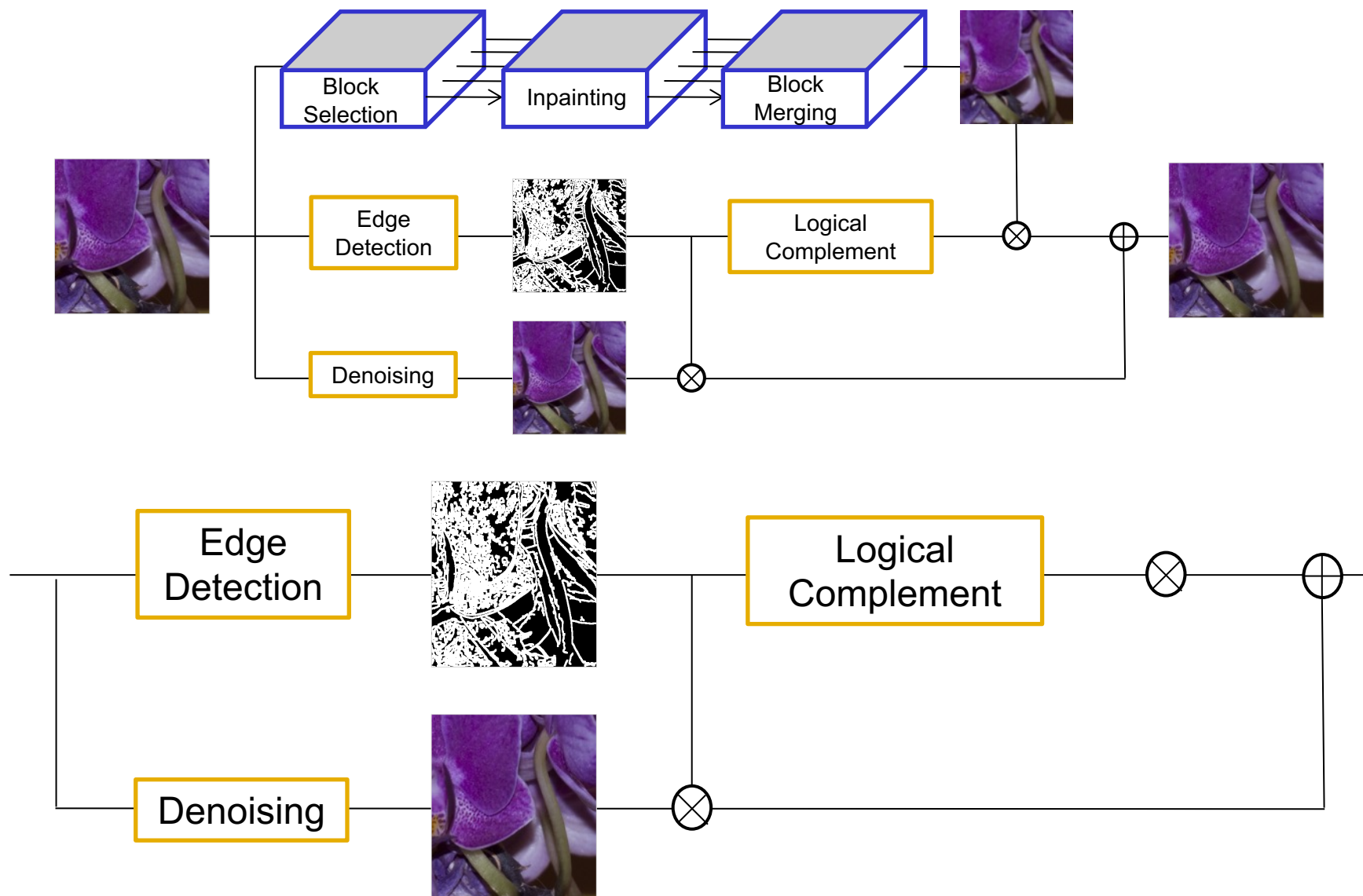


## Overview



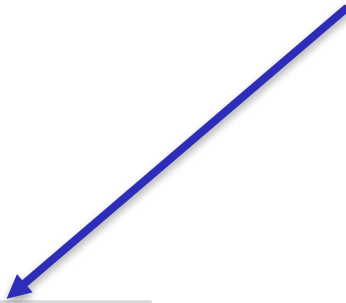
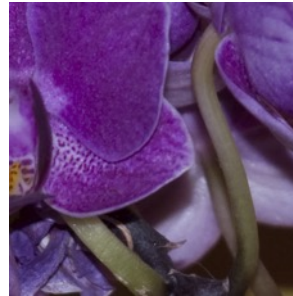


## Overview



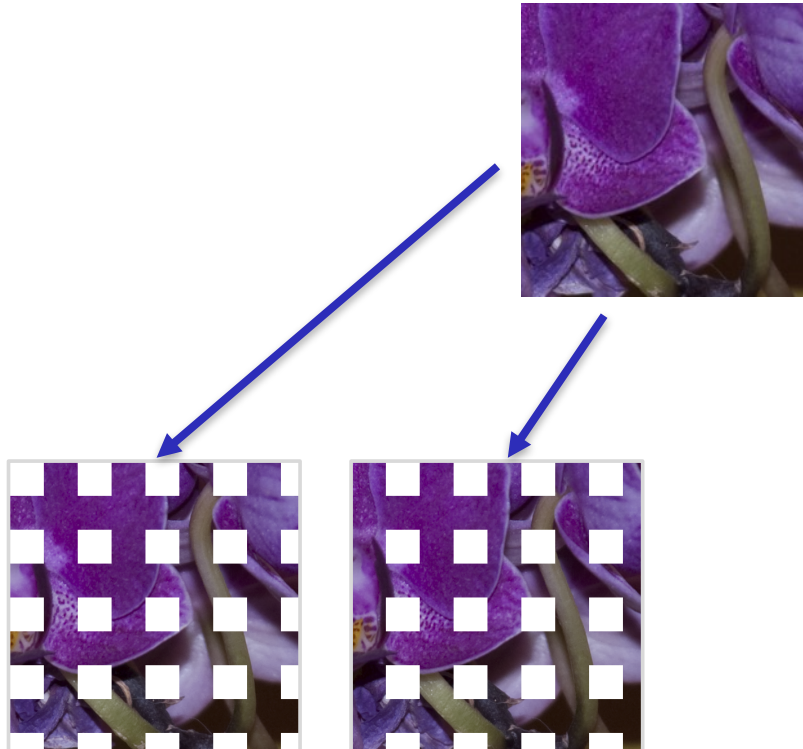
## Block selection

- Create **several versions** of the image with **missing** pixels
- Holes based on a regular grid



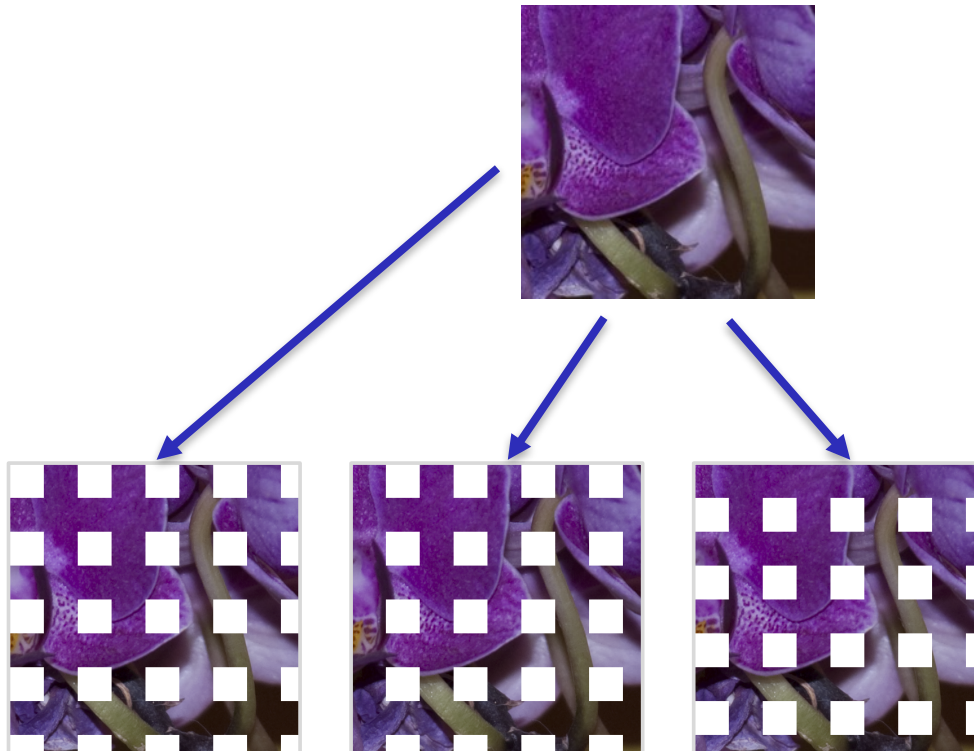
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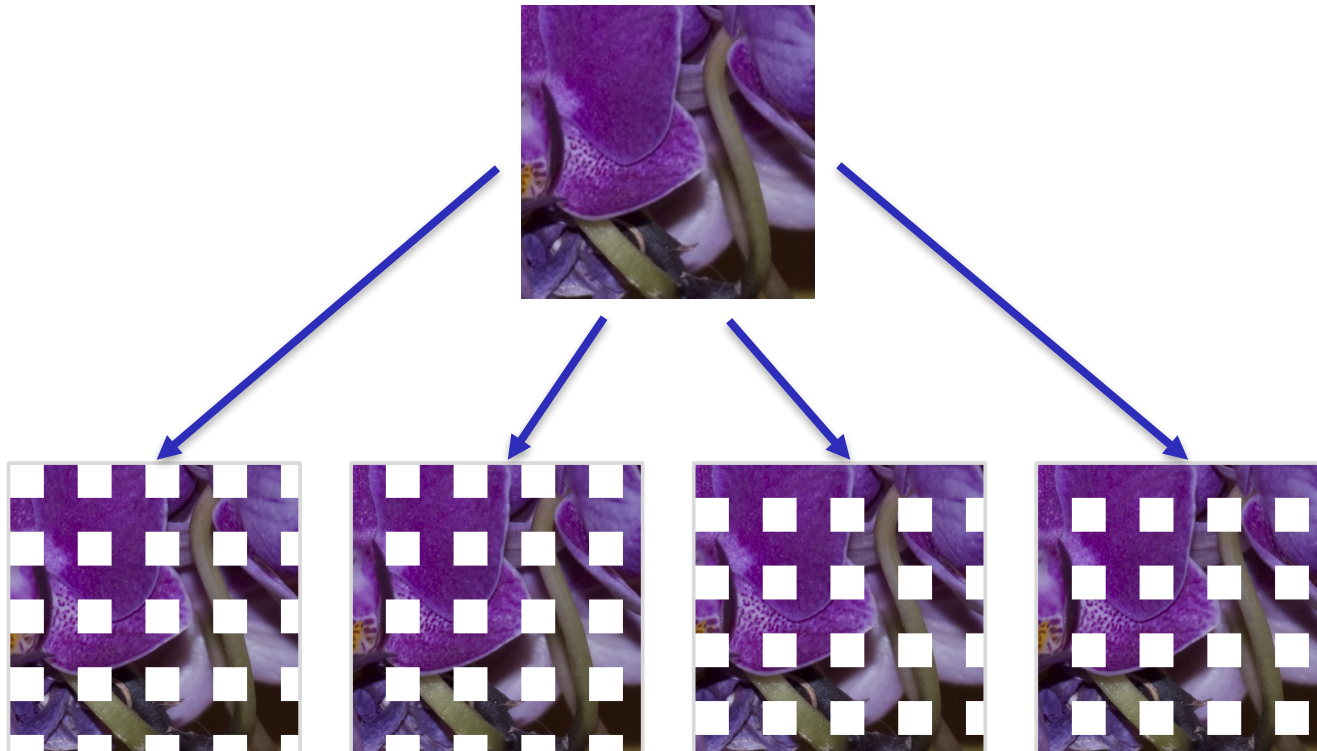
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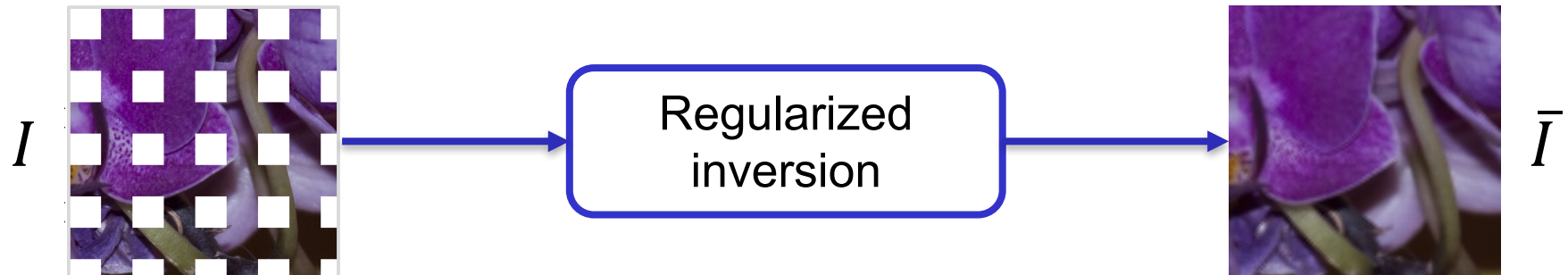


# Proposed Algorithm

## Holed images inpainting

- **Inpainting** through **regularized inversion**

$$\arg_{\bar{I}} \min \|S\bar{I} - I\|_F^2 + \mu \|R(\bar{I})\|_p^p$$



# Proposed Algorithm

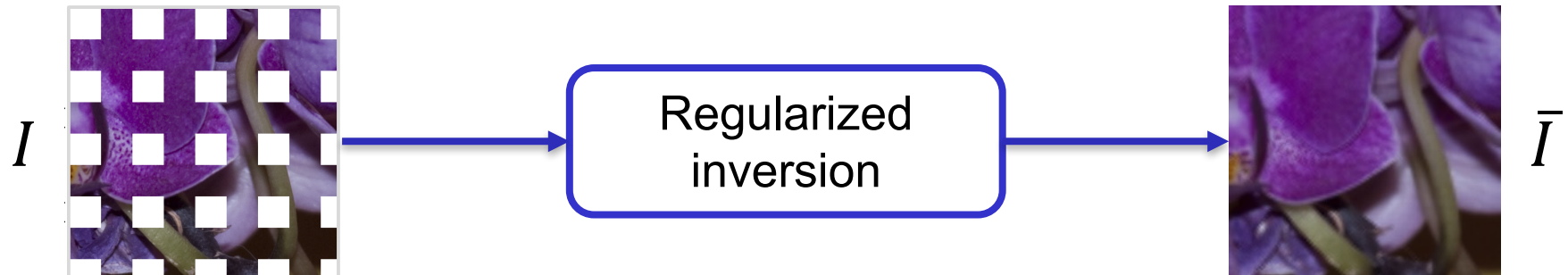
## Holed images inpainting

- **Inpainting** through **regularized inversion**

$$\arg_{\bar{I}} \min \left\| S\bar{I} - I \right\|_F^2 + \mu \|R(\bar{I})\|_p^p$$

- Fitting condition on original pixels

$$\|S\bar{I} - I\|_F^2$$



# Proposed Algorithm

## Holed images inpainting

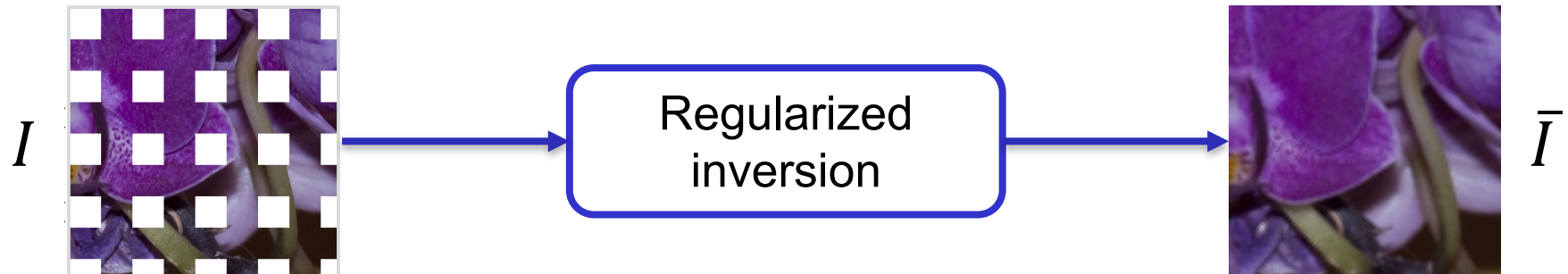
- **Inpainting** through **regularized inversion**

$$\arg_{\bar{I}} \min \|S\bar{I} - I\|_F^2 + \mu \|R(\bar{I})\|_p^p$$

- Fitting condition on original pixels
- Regularization term to impose smoothness
  - First derivative operator
  - L1 (Total Variation) and L2 norm (Tikhonov)

$$\|S\bar{I} - I\|_F^2$$

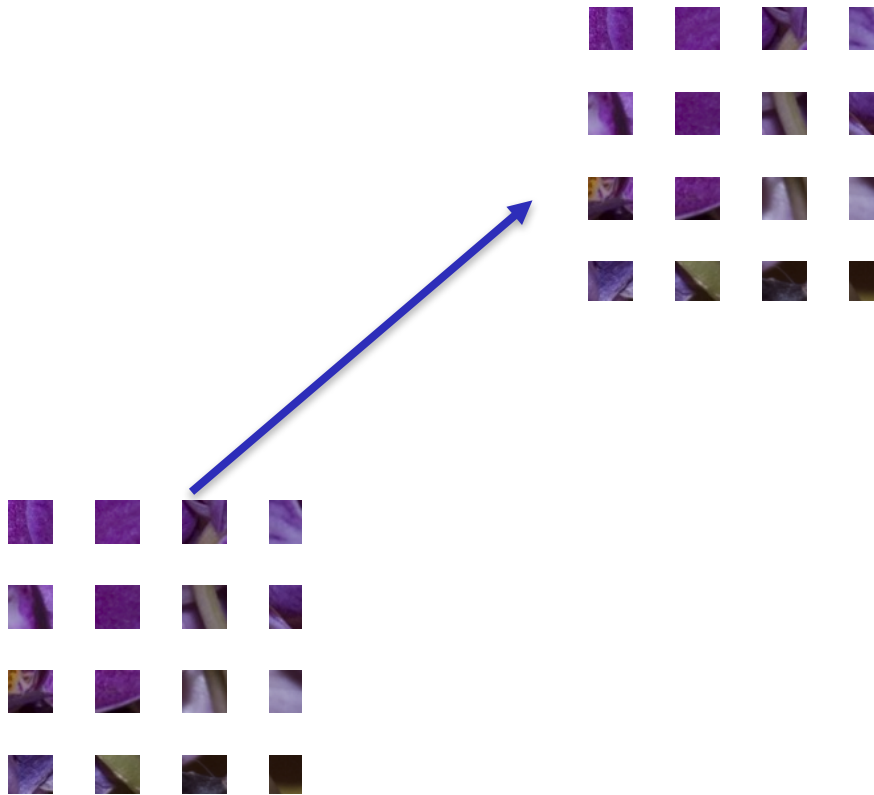
$$\|R(\bar{I})\|_p^p$$



# Proposed Algorithm

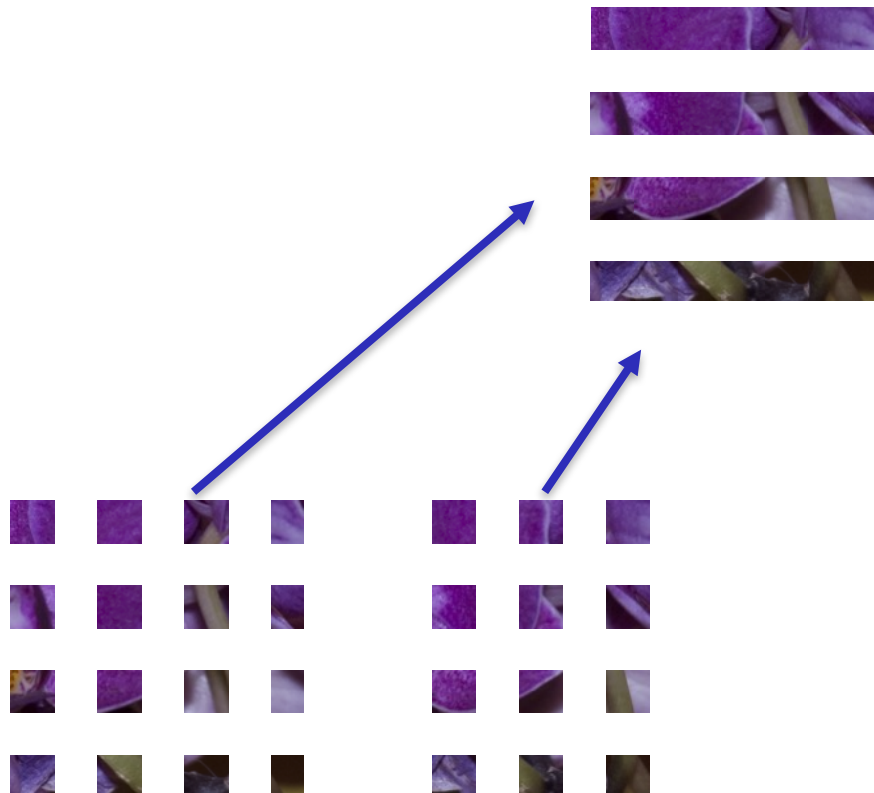
## Block merging

- Merge selecting **only reconstructed pixels**



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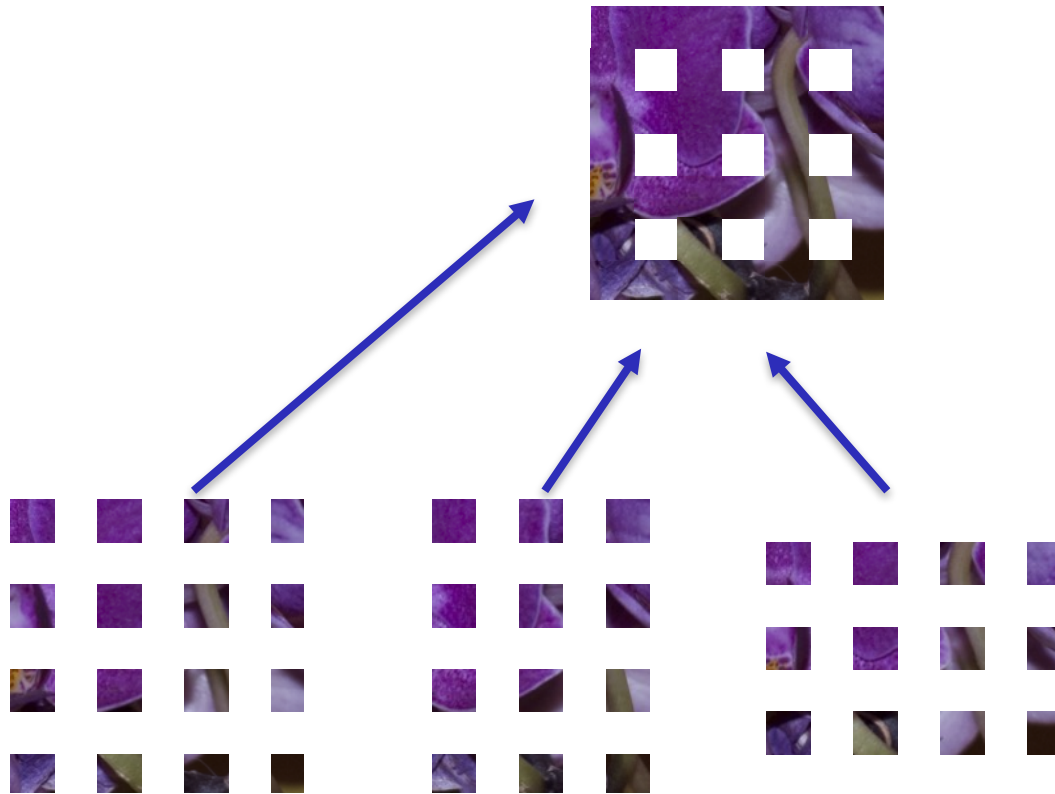




# Proposed Algorithm

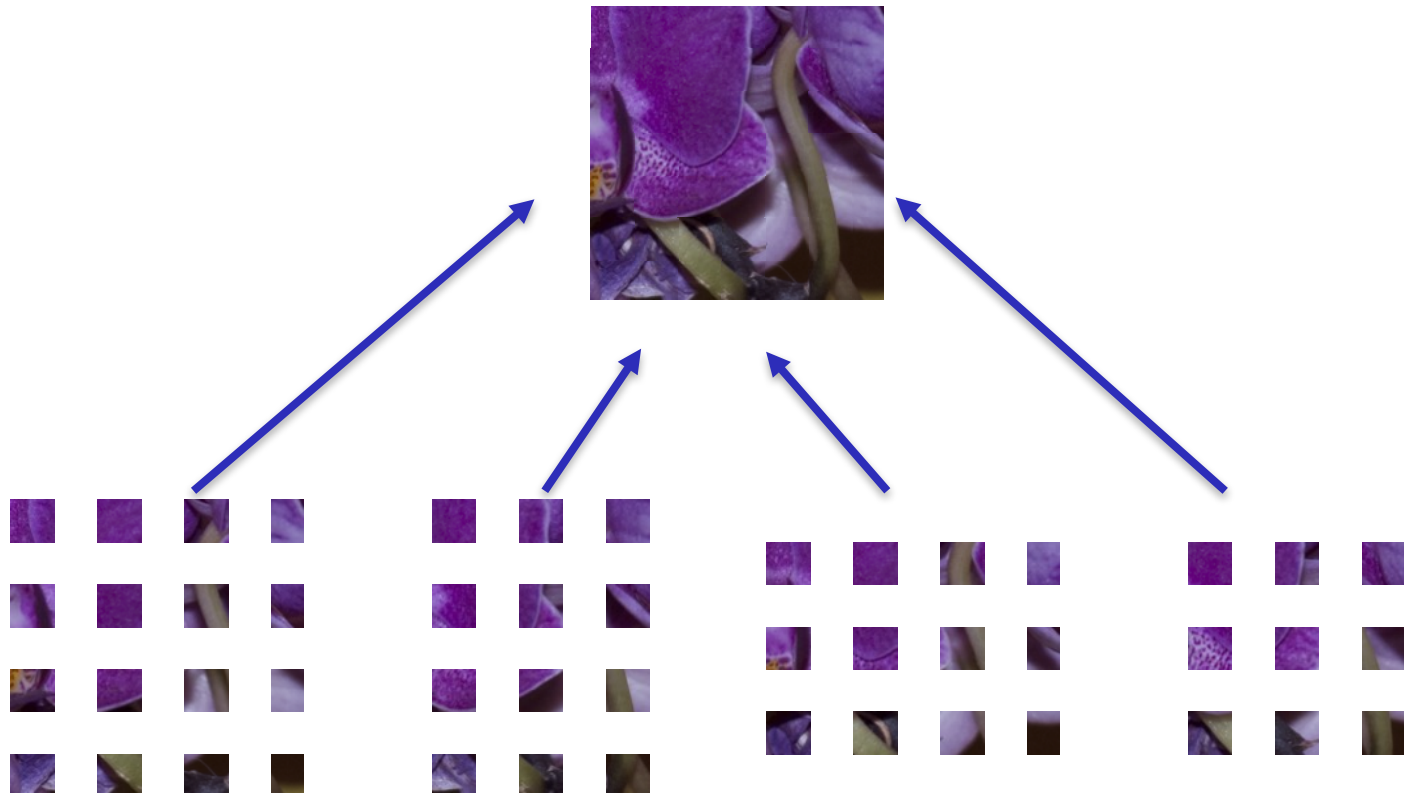
## Block merging

- Merge selecting **only reconstructed pixels**



## Block merging

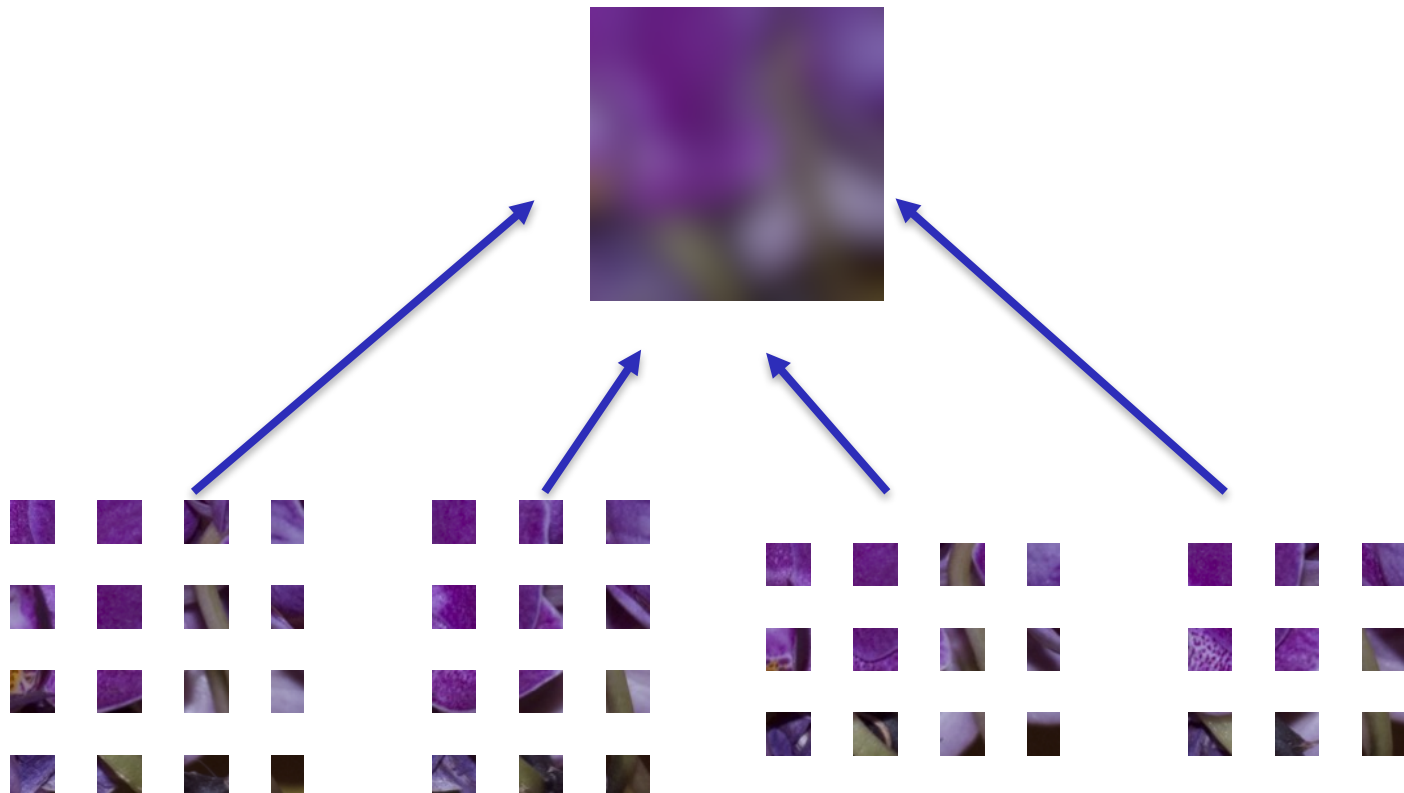
- Merge selecting **only reconstructed pixels**



# Proposed Algorithm

## Block merging

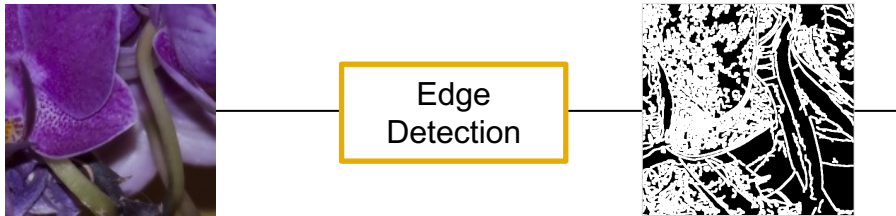
- Merge selecting **only reconstructed pixels**
- Drawback: **quality loss**



# Proposed Algorithm

## Edge Reconstruction

- Canny **edge detector** on original image
- Edge **dilation**

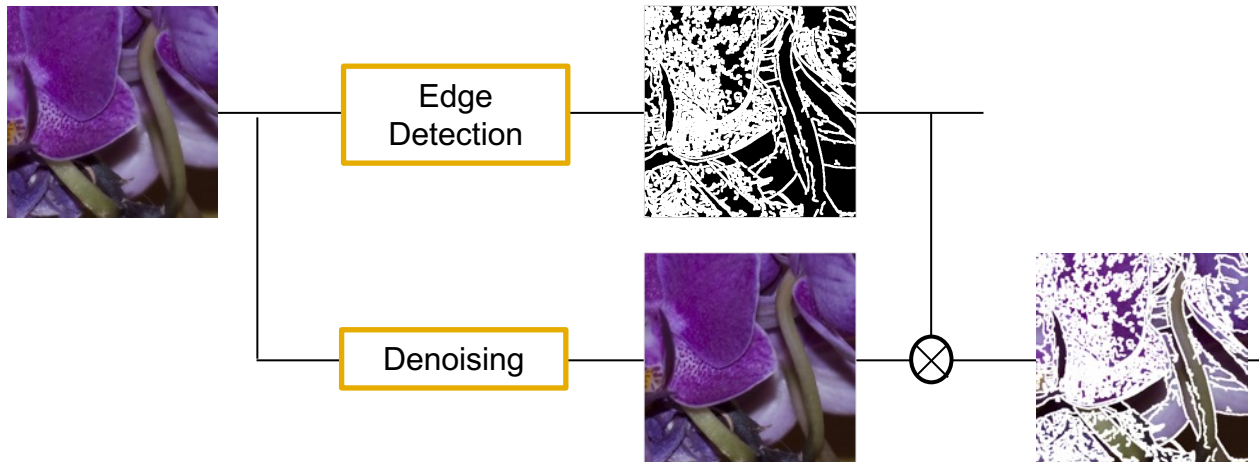


# Proposed Algorithm

## Edge Reconstruction

- Canny **edge detector** on original image
- Edge **dilation**

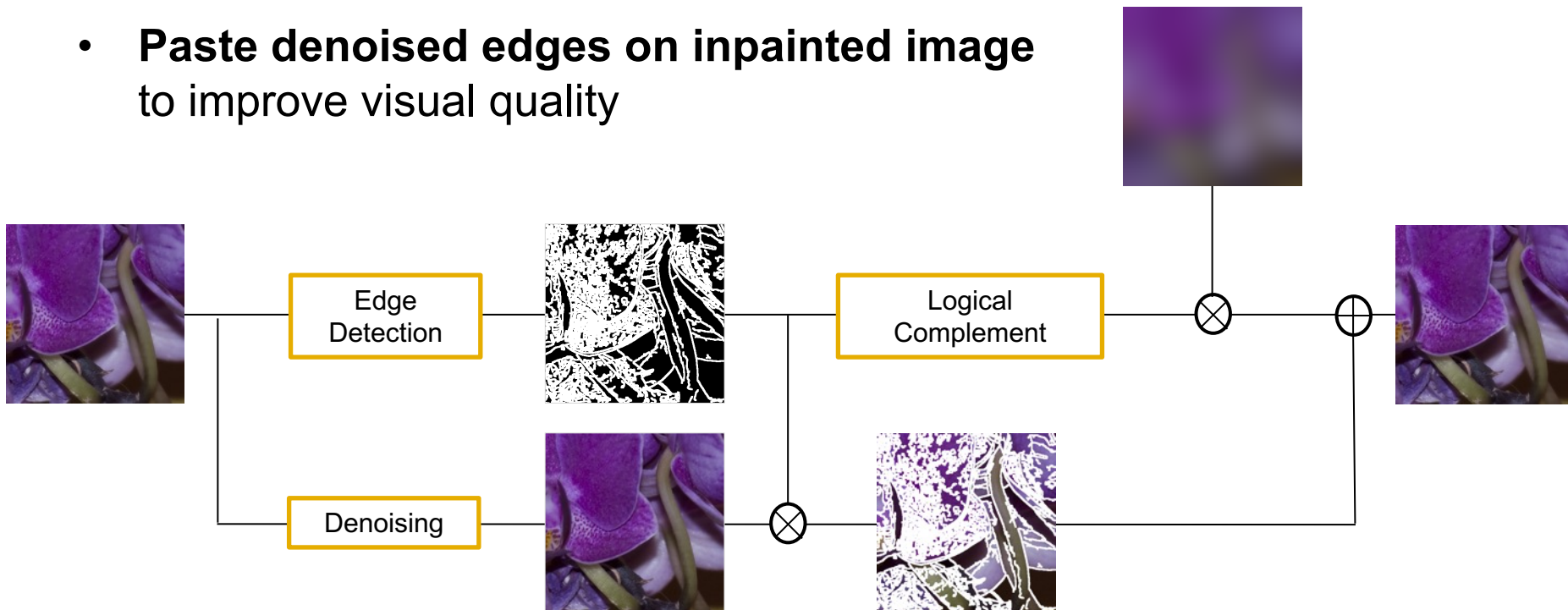
**denoised edges**



# Proposed Algorithm

## Edge Reconstruction

- Canny **edge detector** on original image
- Edge **dilation**
- **Paste denoised edges on inpainted image** to improve visual quality



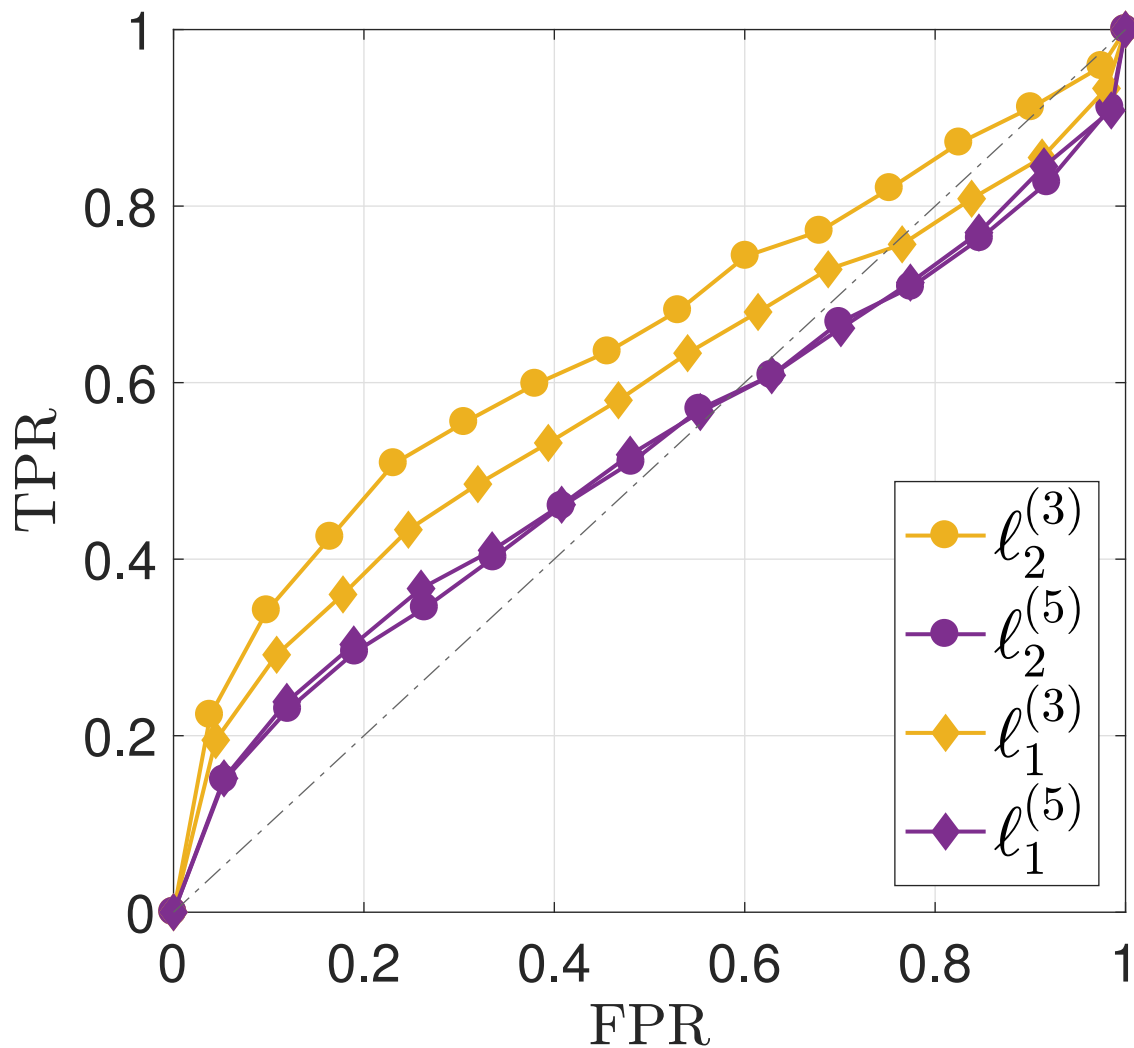


# Experiments and results

## Setup

- Dataset
  - 600 RAW uncompressed images
  - 512 x 512 pixels
  - Dresden Image Dataset
- Wavelet denoising
  - Camera PRNU estimation
  - Image noise residuals
- Performance evaluation in terms of
  - Receiver-Operating-Characteristic
  - Area-Under-Curve vs SNR
  - TPR vs SNR (at fixed FPR)





L2 norm  
3 pixel holes

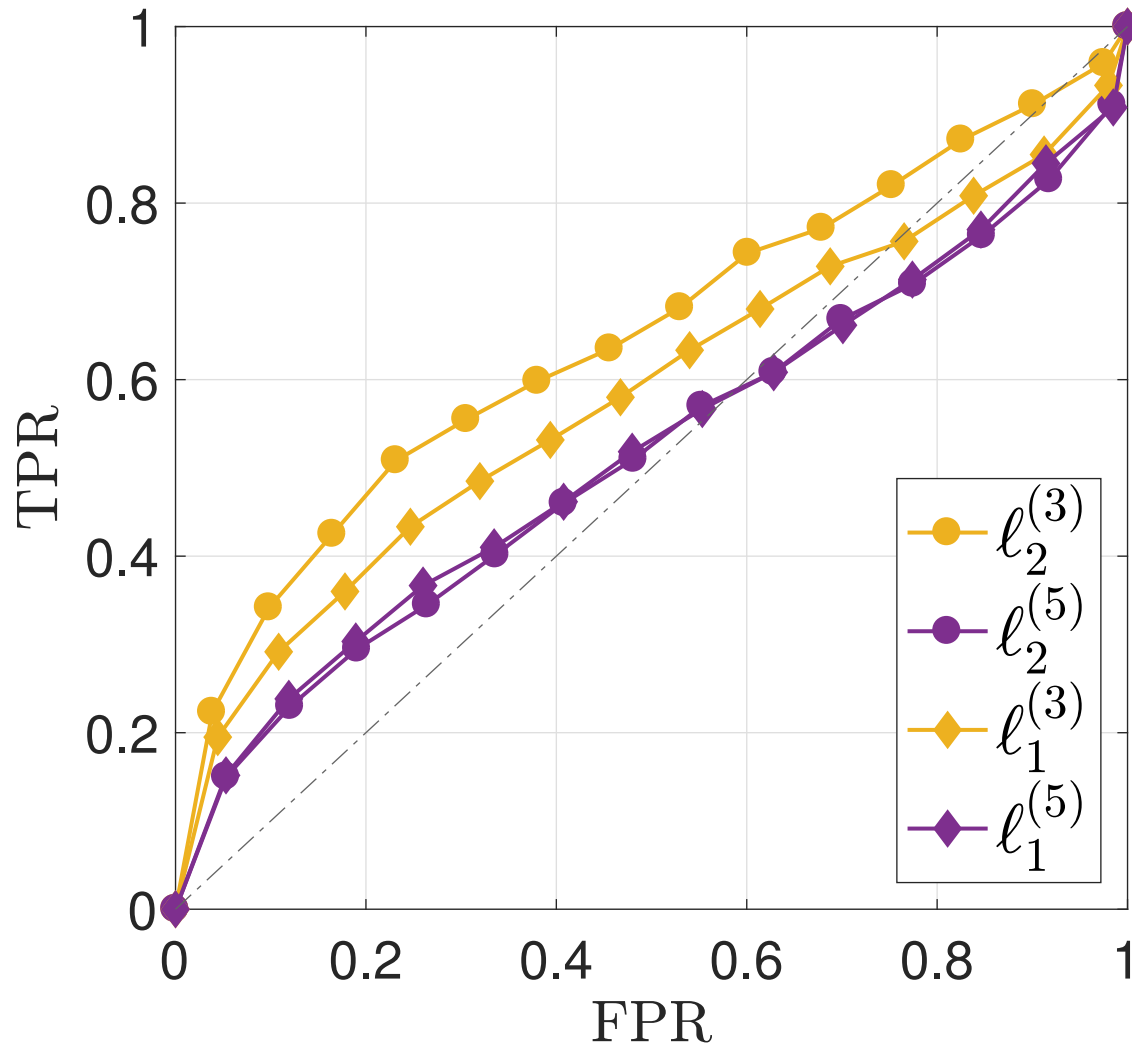
L2 norm  
5 pixel holes

L1 norm  
3 pixel holes

L1 norm  
5 pixel holes

# Experiments and results

## ROC



L2 norm  
3 pixel holes

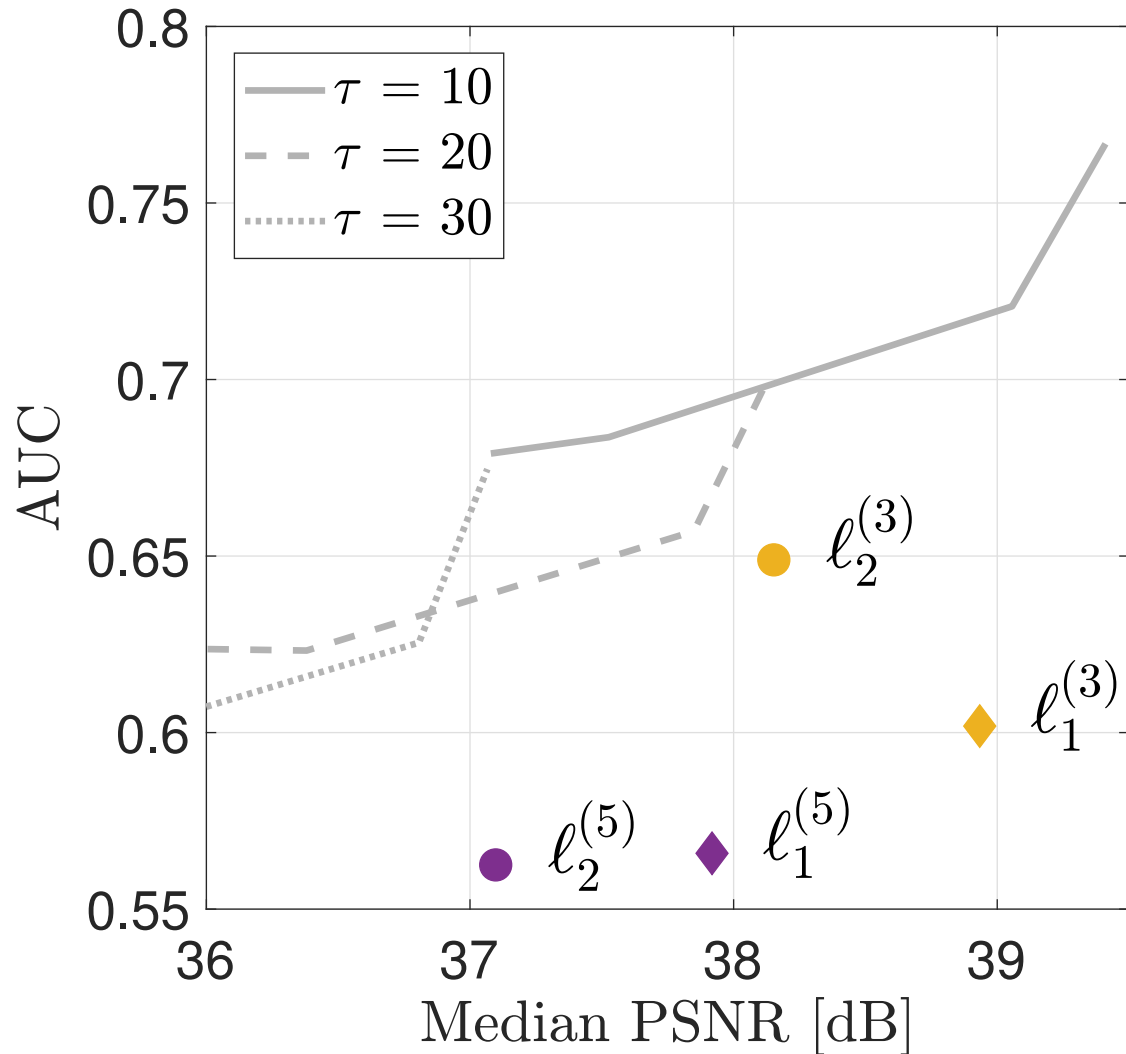
**L2 norm**  
**5 pixel holes**

L1 norm  
3 pixel holes

**L1 norm**  
**5 pixel holes**

# Experiments and results

## Comparison with SOTA



L2 norm  
3 pixel holes

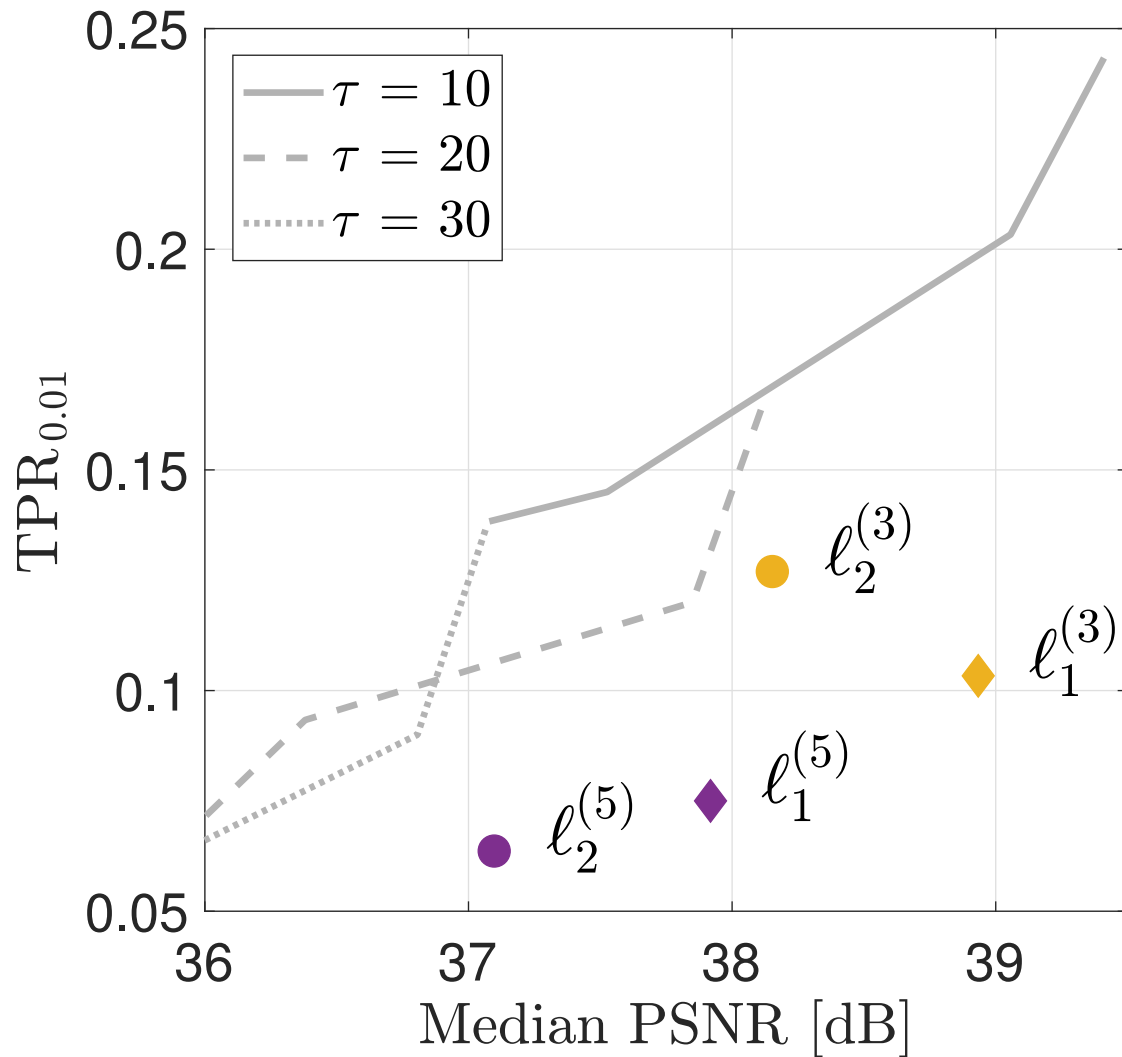
L2 norm  
5 pixel holes

**L1 norm**  
**3 pixel holes**

L1 norm  
5 pixel holes

# Experiments and results

## Comparison with SOTA



L2 norm  
3 pixel holes

L2 norm  
5 pixel holes

**L1 norm**  
**3 pixel holes**

L1 norm  
5 pixel holes

- *So far*
  - **Simple** anonymization strategy
  - Block-wise inpainting is easily **parallelizable**



- *So far*
  - **Simple** anonymization strategy
  - Block-wise inpainting is easily **parallelizable**
  
- *The future*
  - Investigate more **sophisticated** solutions
    - Take care of edge reconstruction at inpainting phase
  - Effectiveness on **JPEG** compressed images

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## Media Forensics Integrity Analytics

Space Coherence Analysis  
Integrity Analytics  
Forgery Localization  
Adversarial Setting  
Data-driven Solutions  
Multimedia Analytics  
Physical Integrity  
Electrical Network Frequency  
Forgery Detection  
Multimedia Phylogeny  
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