## JOINT DEMOSAICING AND DENOISING OF NOISY BAYER IMAGES WITH ADMM

### PROBLEM

Bayer image  $b \in R^n$  and RGB  $x = [r^T, g^T, b^T]^T \in R^{3n}$ . The image formation model

$$b = Ax + \eta \tag{1}$$

where  $A \in \mathbb{R}^{n \times 3n}$  is the mosaic matrix which down samples RGB image x to Bayer image b, and  $\eta \in \mathbb{R}^n$  is the noise vector.

Joint demosaicing and denoising can be viewed as the inverse problem of (1)

$$\min_{x} \|Ax - b\|_{2}^{2} + T(x)$$
(2)

where T(x) represents the prior functions.

This is a difficult problem due to limited information, that is only 1/3 pixels are known.

### METHOD

The image recovery model is specialized as

$$\min_{x} \|Ax - b\|_{2}^{2} + \lambda_{tv} \|\nabla x\|_{1} + \lambda_{bm3d} bm3d(x) + \lambda_{cc} \|Cx\|_{1} + \lambda_{dm} demosaic(x)$$

The above equation consists of one data term and four priors: total variation [3], bm3d denoising term [4], cross-channel prior [5] and demosaicing prior [6]. Suppose we have a minimization problem with *J* terms

$$\min_{z \in \mathbb{R}^d} \sum_{j=1}^J g_j(z)$$

where  $g_j : R^{p_j} \to R$  are functions with closed form,  $H^{(j)} \in R^{p_j \times d}$  are matrices and  $p = p_1 + \cdots + p_J$ . The general steps solving problem (4) are

. Initialize  $u_0, d_0, \mu$  with zero vectors.

1: 
$$\zeta_k^{(j)} \leftarrow u_k^{(j)} + d_k^{(j)}, \quad j = 1, \cdots, J$$
  
2:  $\gamma_k \leftarrow \sum_{j=1}^J (H^{(j)})^T \zeta_j^{(j)}$ 

2. 
$$j_k \sim \sum_{j=1}^{J} (II \sim ) \leq_k$$
  
3.  $z_{k+1} \leftarrow [\sum_{j=1}^{J} ((H^{(j)})^T H^{(j)})]^{-1} \gamma_k$ 

4: for 
$$j = 1$$
 to  $J$  do

5: 
$$\nu_{k}^{(j)} \leftarrow H^{(j)} z_{k+1} - d_{k}^{(j)}$$

6: 
$$u_{k+1}^{(j)} \leftarrow \operatorname{argmin}_{v\frac{1}{2}} \|v - \nu_k^{(j)}\|_2^2 + g_j(v)$$

7: end for  
$$I(j) = I(j) = (TT(j)) = (j)$$

8:  $d_{k+1}^{(j)} \leftarrow d_k^{(j)} - (H^{(j)}z_{k+1} - u_{k+1}^{(j)}), \quad j = 1, \cdots, J$ 

Line 6 corresponds to a restoration problem with v as the data term and  $g_i(v)$  as the prior term, which suggests ADMM split a complicated minimization problem with multiple prior terms into multiple simple minimization problems with only one prior term.

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- $(H^{(j)}z)$



Fig. 1 Visual Results. The first row and the last two rows of images are from Kodak and McMaster datasets, respectively. Each image is divided into four rectangular parts: Top-left, bottom-left, bottomright and top-right correspond to noise levels  $\sigma = 0, 5, 15, 25$ , respectively.

Data

Kod (24)1ma

(3)

(4)

BayerNoisy

FlexISP

DeepJoint

Table 1 Average PSINK Comparison on Two Datasets (db)								
Noise	FlexISP	Deep	ADMM	Dataset	Noise	FlexISP	Deep	ADMM
Level	[1]	Joint	(Ours)		Level	[1]	Joint	(Ours)
		[2]					[2]	
0	34.98	33.88	31.63	Mc-	0	35.18	32.49	32.66
5	31.31	33.07	31.60	Master	5	31.17	32.01	32.63
15	26.67	30.40	30.16	(18	15	26.55	29.89	30.50
25	23.90	25.88	28.38	images)	25	23.73	26.13	28.20
-	Noise         Level         0         5         15         25	Noise       FlexISP         Level       [1]         0       34.98         5       31.31         15       26.67         25       23.90	NoiseFlexISPDeepLevel[1]Joint[2]034.9833.8833.88531.3133.071526.6730.402523.9025.88	NoiseFlexISPDeepADMM (Ours)Level[1]Joint [2](Ours)034.9833.8831.63531.3133.0731.601526.6730.4030.162523.9025.8828.38	Noise         FlexISP         Deep         ADMM         Dataset           Level         [1]         Joint         (Ours)         Image         Im	Noise         FlexISP         Deep         ADMM         Dataset         Noise           Level         [1]         Joint         (Ours)         Level         Level           0         34.98         33.88         31.63         Mc-         0           5         31.31         33.07         31.60         Master         5           15         26.67         30.40         30.16         (18         15           25         23.90         25.88         28.38         images)         25	Noise         FlexISP         Deep         ADMM         Dataset         Noise         FlexISP           Level         [1]         Joint         (Ours)         Level         [1]	Noise         FlexISP         Deep         ADMM         Dataset         Noise         FlexISP         Deep           Level         [1]         Joint         (Ours)         Level         [1]         Joint         [2]           0         34.98         33.88         31.63         Mc-         0         35.18         32.49           5         31.31         33.07         31.60         Master         5         31.17         32.01           15         26.67         30.40         30.16         (18         15         26.55         29.89           25         23.90         25.88         28.38         images)         25         23.73         26.13



ADMM(Ours)

Groundtruth

Table 1 Average DCNIP Comparison on Two Datacate (dR)