

# Residual-based forensic comparison of video sequences

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[1] Christian Riess

# Increased prevalence of video content

## Creator's side

- Visual content simpler to create and share than ever before
- Easy-to-use tools for editing videos are already widely present

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- Some content is altered with malicious intents
- Few tools exist to automatically assess authenticity of video data



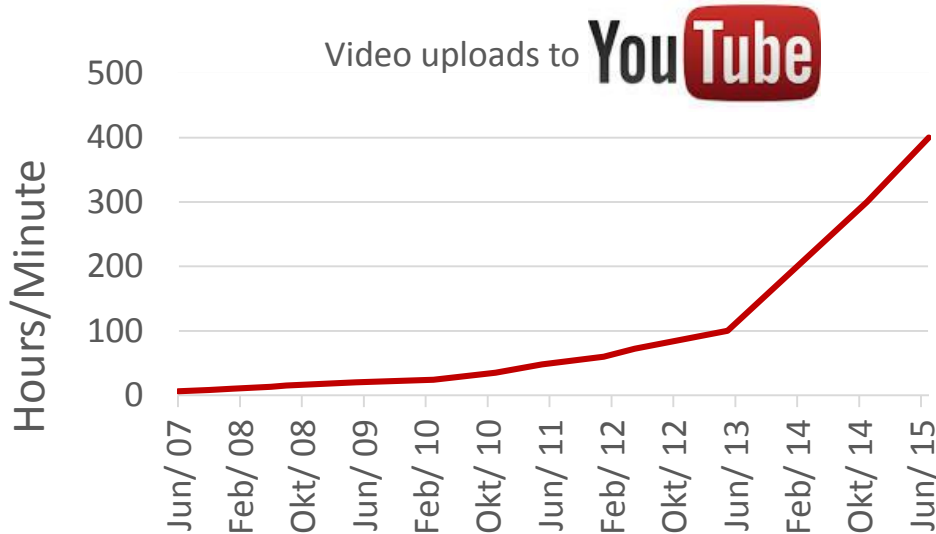
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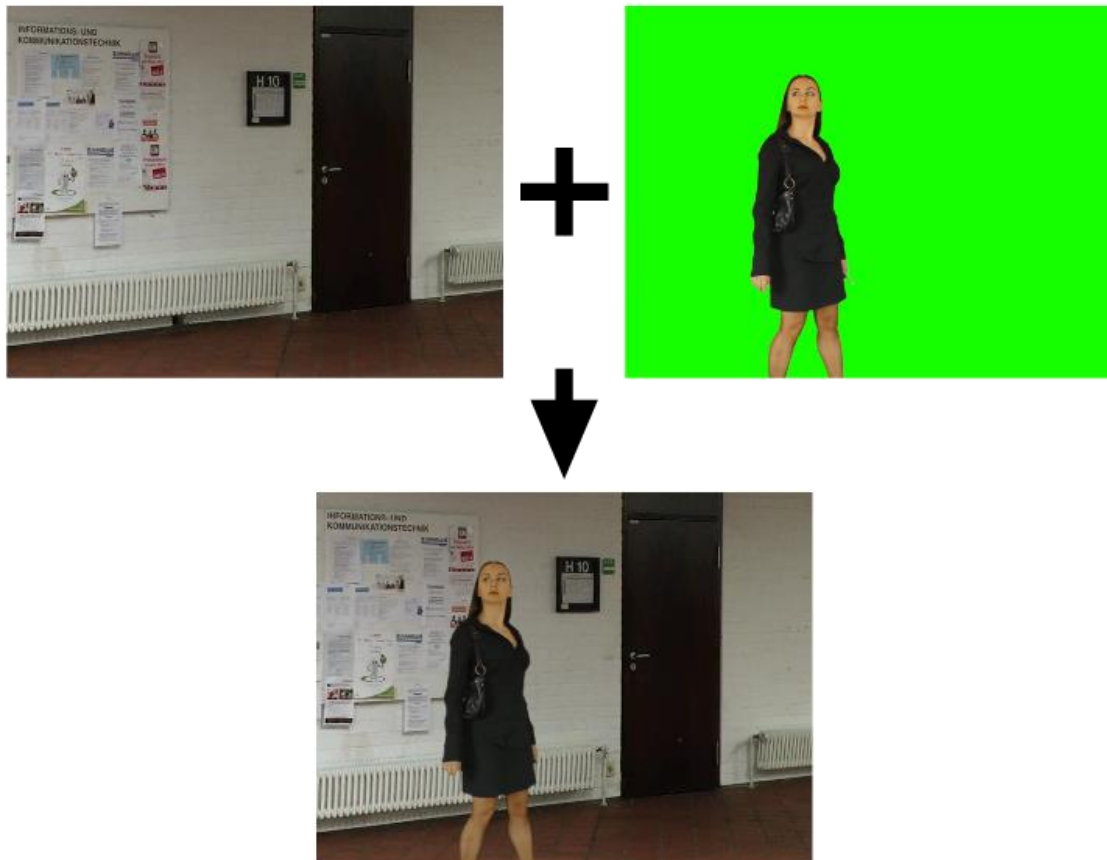
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source: mediathek.zdf.de

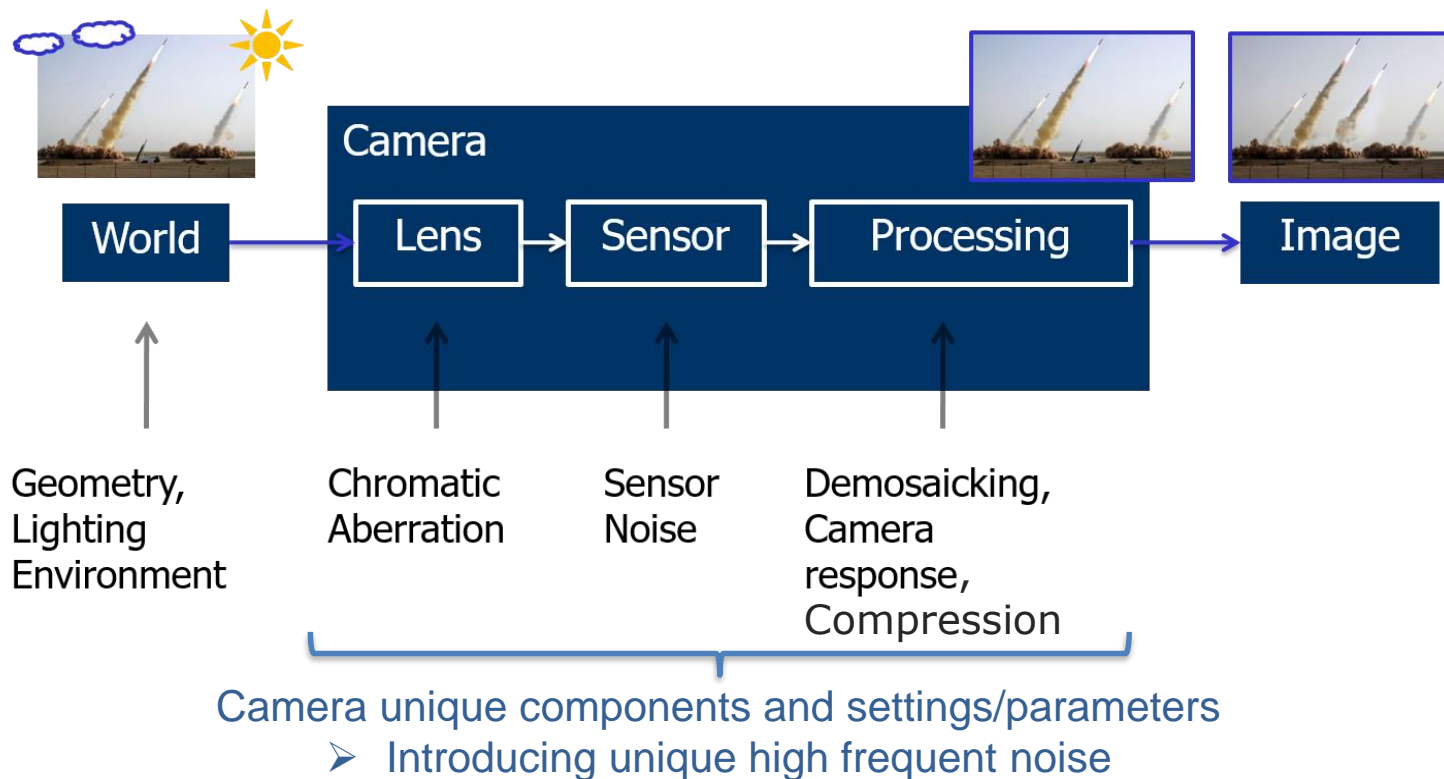
# Chroma keying

- One manipulation attack is chroma keying (e.g. greenscreening)
- If done well, forged video offers no visual clues on manipulation



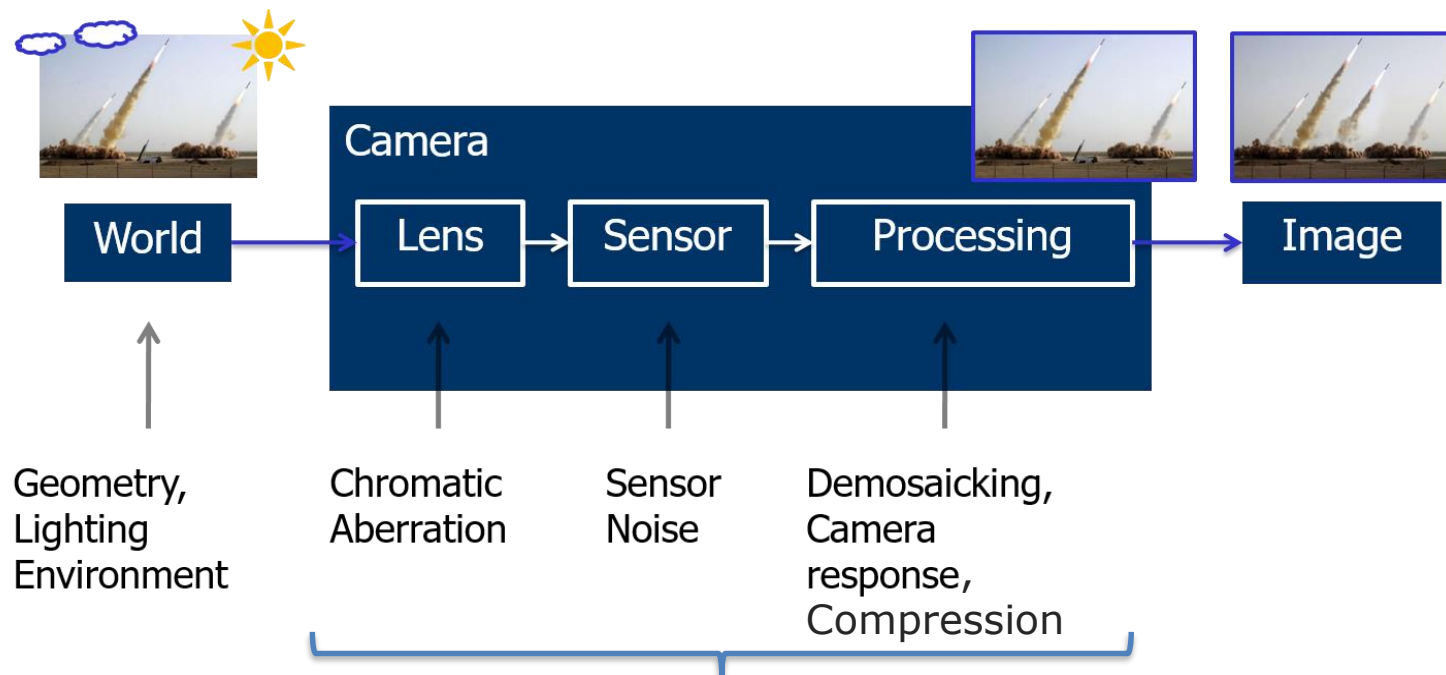
# Assumption

- Each camera has its own, unique, processing pipeline
- They introduce characteristic, high frequent noise, in each frame and over frames
- Often not visually perceivable



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- They introduce characteristic, high frequent noise, in each frame and over frames
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- **Manipulations break those statistics or make them inconsistent**



Camera unique components and settings/parameters

- Introducing unique high frequent noise



# Feature extraction from noise

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Inconsistencies in noise patterns well exploited in different fields:  
For example, in “steganography” [1] or “forgery detection in images” [2]

[1] J. Fridrich, J. Kodovský “Rich Models for Steganalysis of Digital Images”, in *IEEE Transactions on Information Forensics and Security*, June 2012

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Common algorithm:

1. High-pass filtering input image  $I$ , returning residual image  $R$ , where image  $I$  has pixels at  $I_{xy} \in [0|255]$   
→ retrieves noise domain

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→ large residuals (like edges) are all mapped to  $t$  or  $-t$   
→ the “interesting” coefficients lie between  $[-t + 1 | t - 1]$

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3. Build co-occurences of length  $d$ :  $C_{nm} = \{R_{xy}^*, R_{xy+1}^*, \dots, R_{xy+d}^*\}$   
→ incorporates neighborhood relationships

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# Descriptors applied to image forensics

Grayscale input frame



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High-pass  
[1,-3,3,-1]

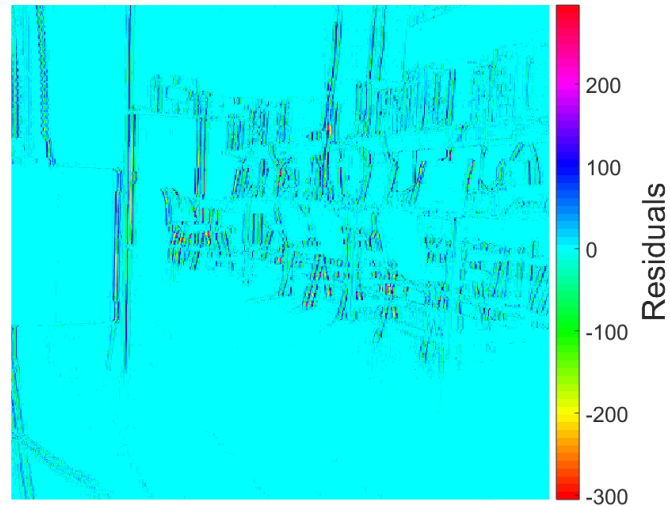


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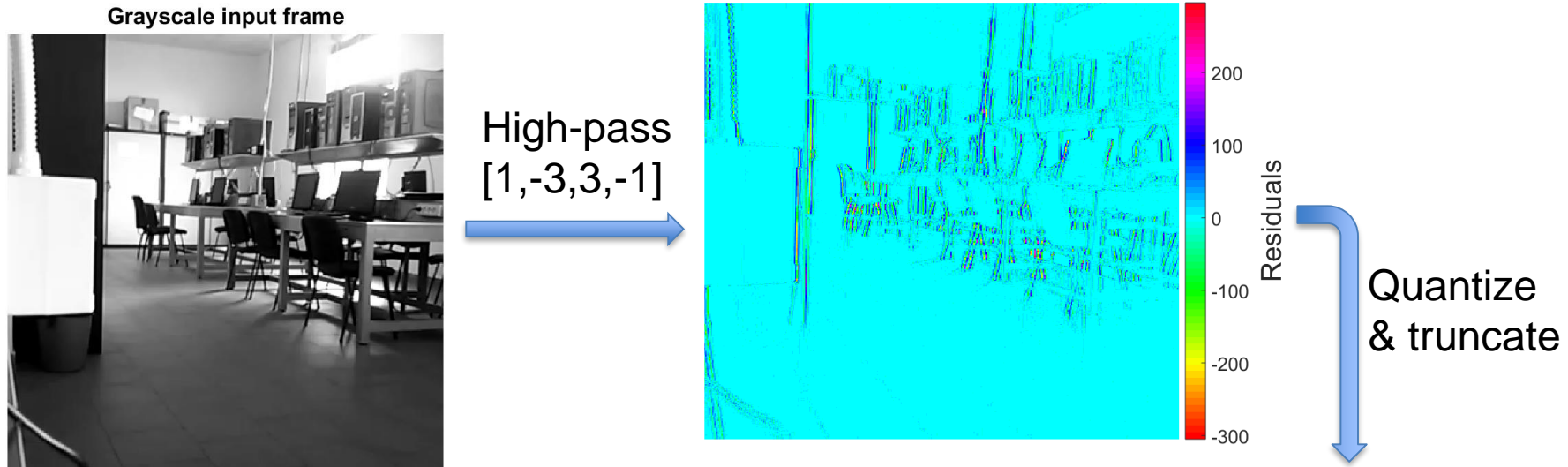
Grayscale input frame



High-pass  
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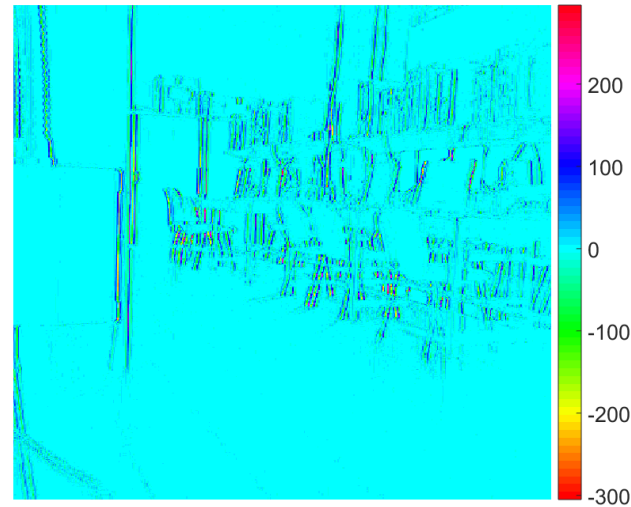




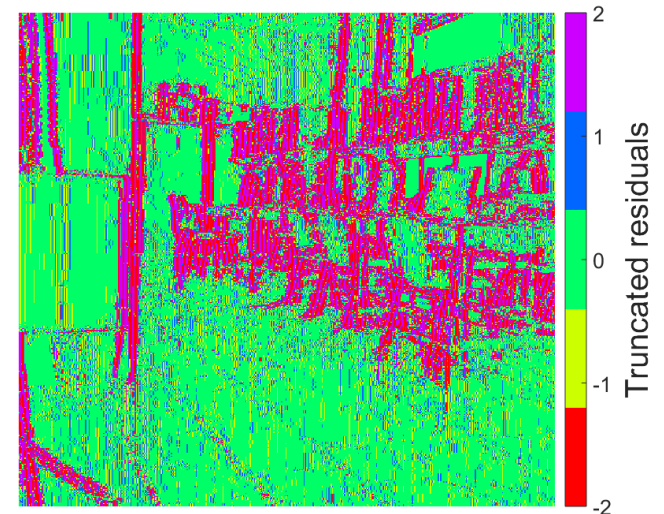
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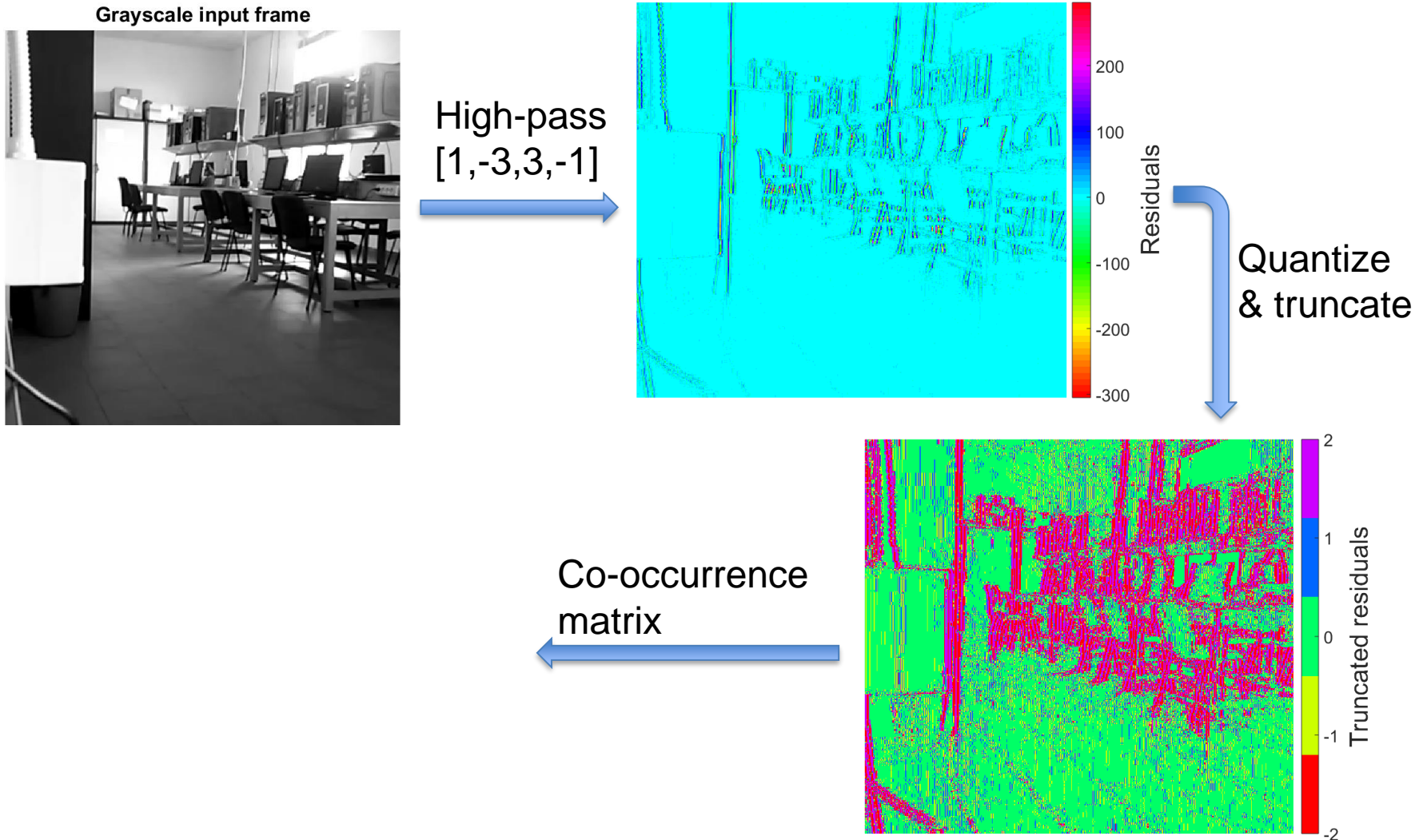
High-pass  
 $[1, -3, 3, -1]$



Quantize  
& truncate



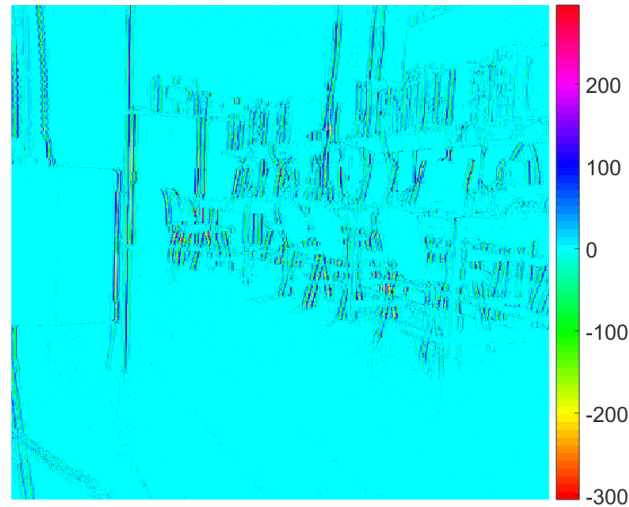
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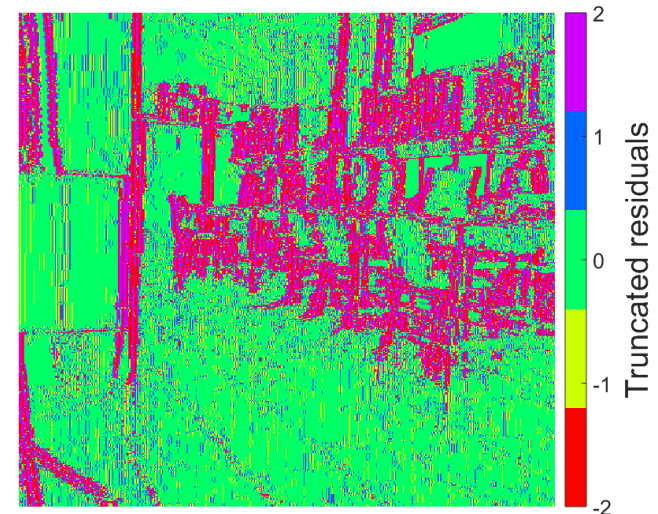
High-pass  
[1,-3,3,-1]



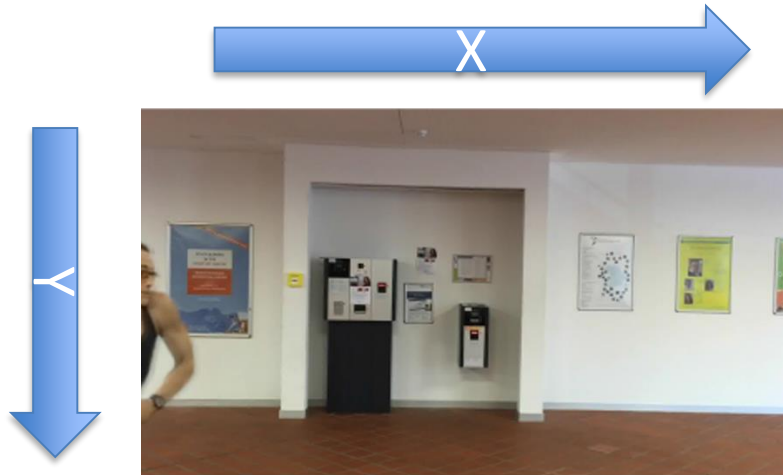
Quantize  
& truncate

	-2	-1	0	1	2
-2	8087	1256	2317	2713	15095
-1	1163	947	12097	11592	2600
0	2147	11892	84896	10277	2475
1	2732	11587	10317	854	1255
2	15340	2755	2182	1316	8208

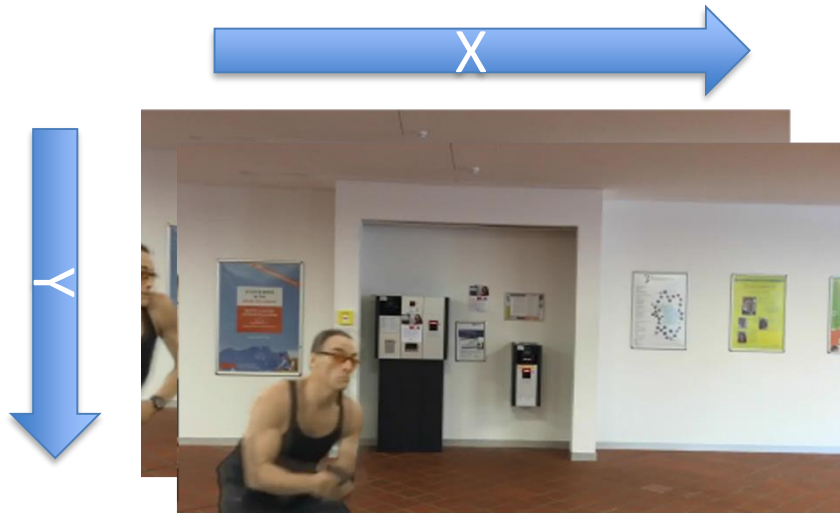
Co-occurrence  
matrix



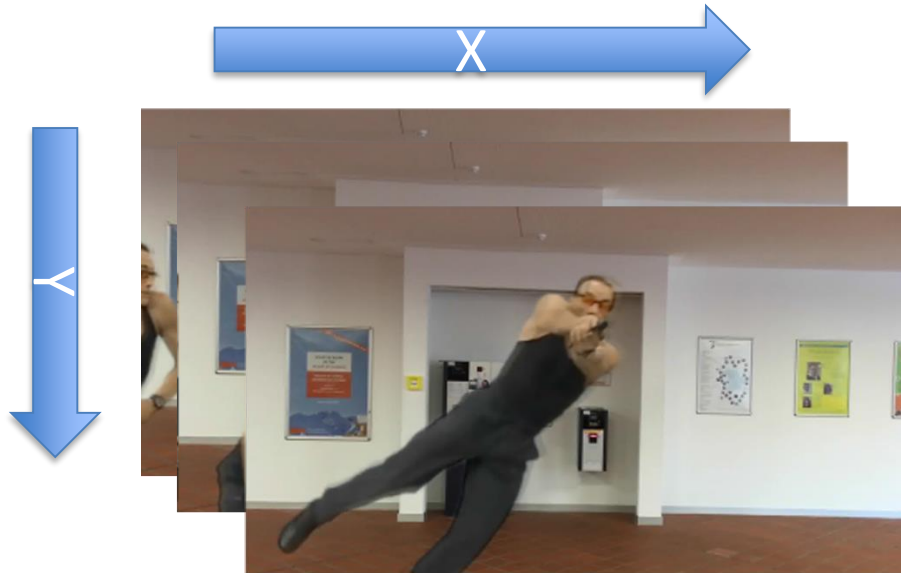
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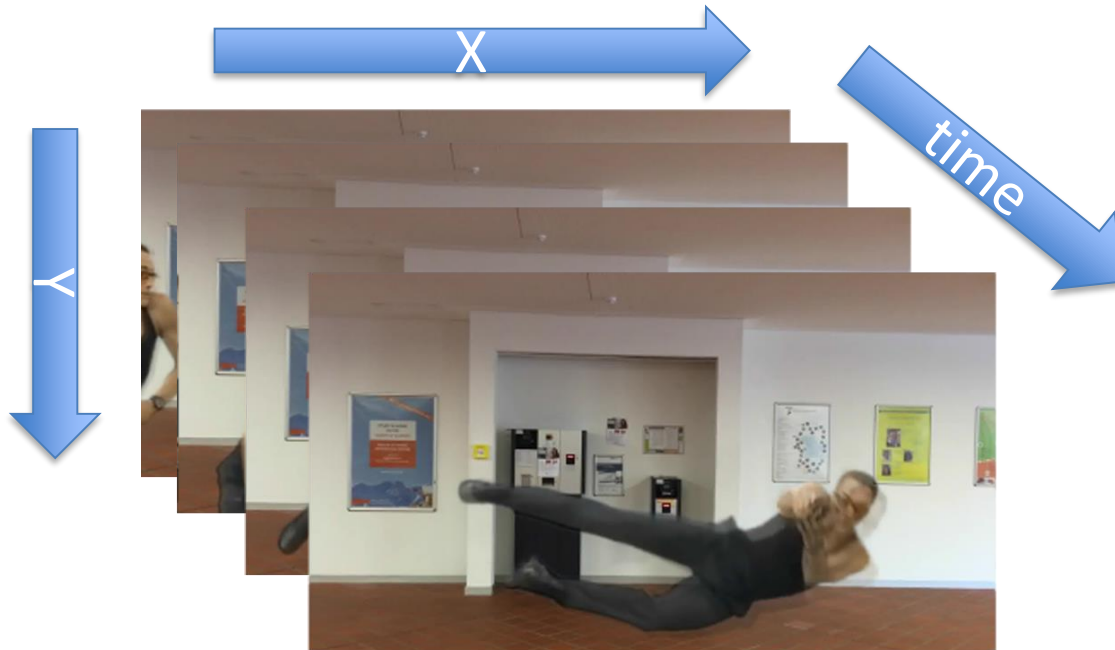


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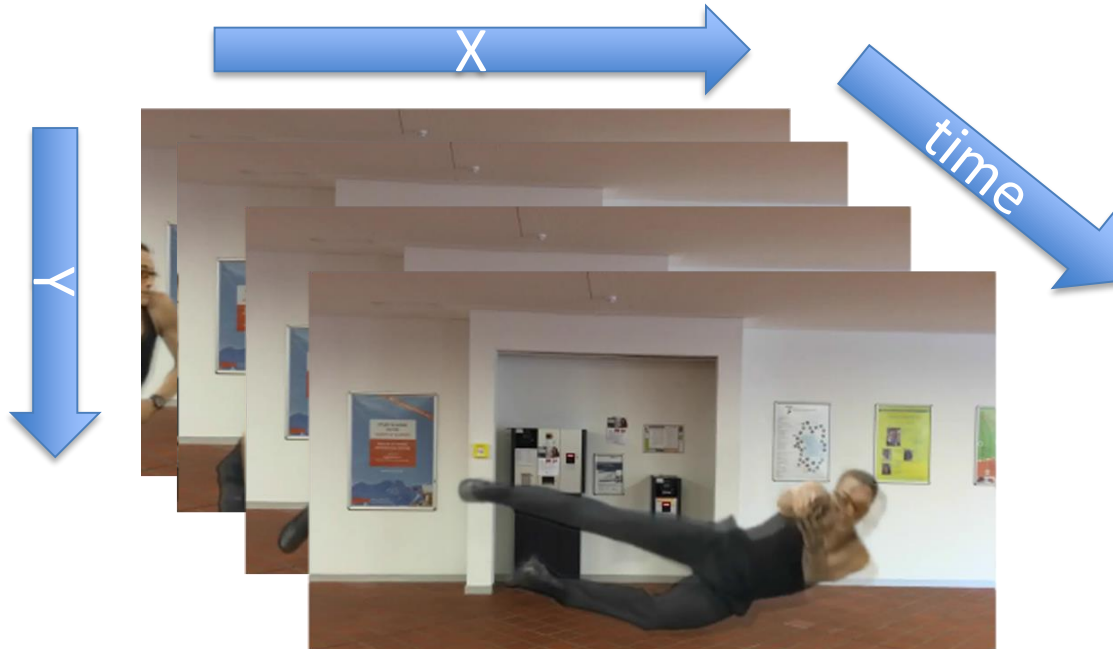




# Directions







## Video:

- Enlarges feature space  
→ time offers new, third dimension
- Can be used to track motion by optical flow  
→ to align slided windows of features

# Classification pipeline



## Feature Extraction

- Histogram of co-occurrence residuals
- In different directions
- On sliding windows
- Optional: align features by “optical flow”

## Classification

- Calculate mahalanobis distance
- Can be thresholded

## Decision

- Frame authentic?
- Frames from same camera?

## Training

Train on known pristine frames

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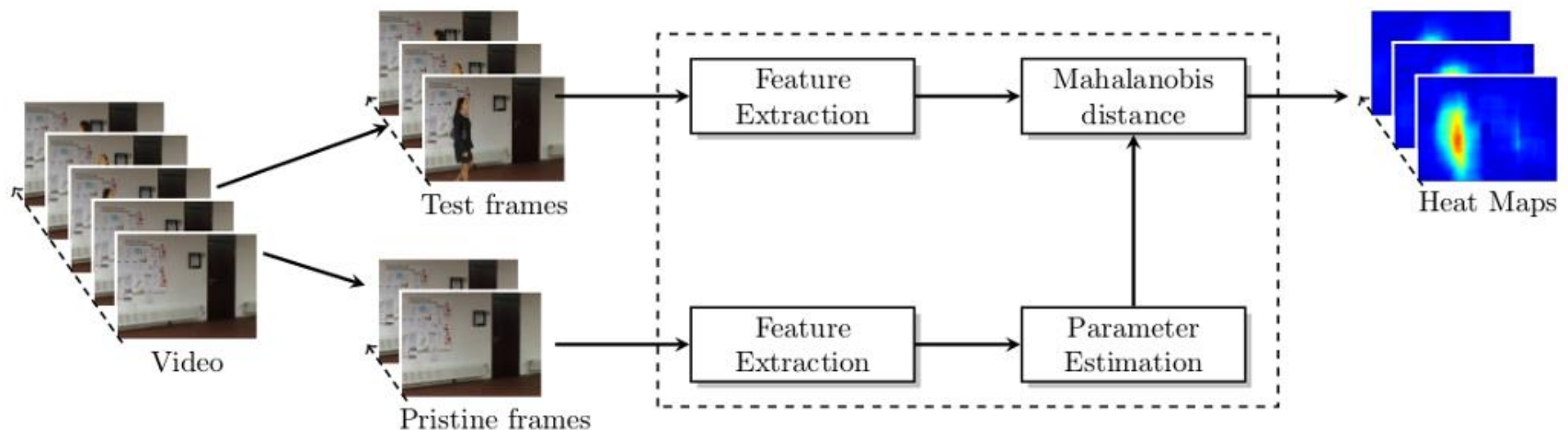
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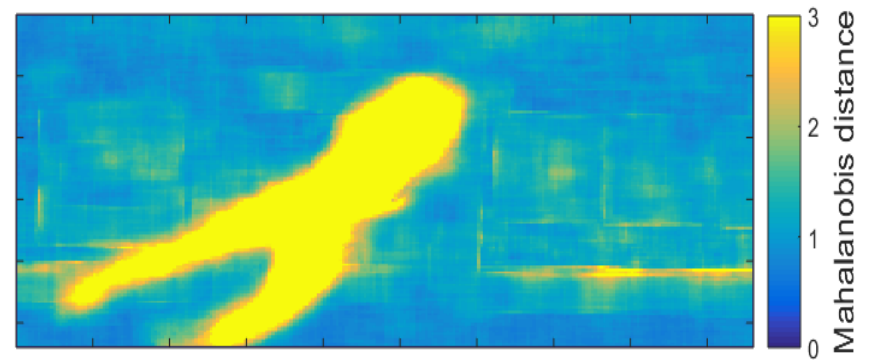
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Train on known pristine frames

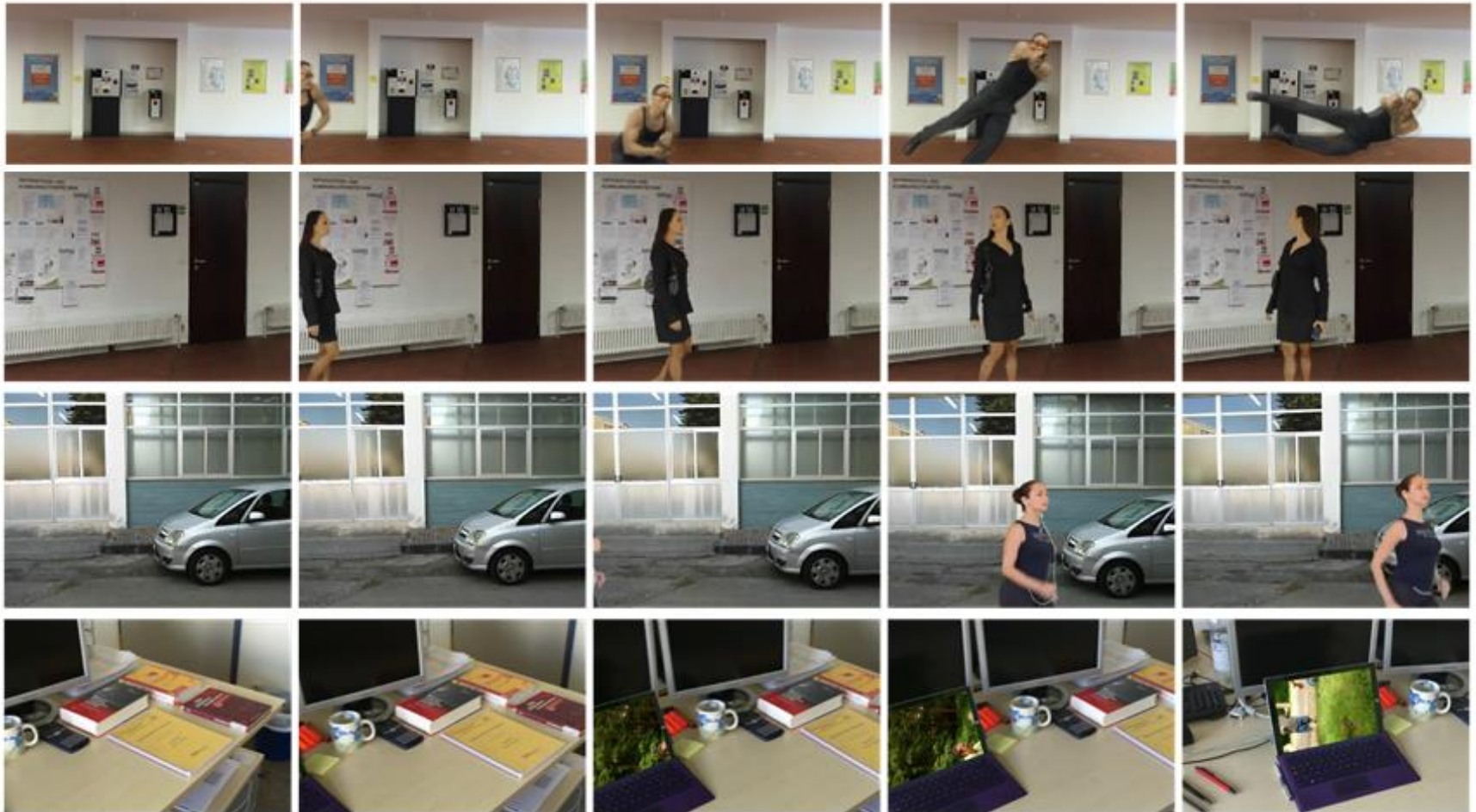


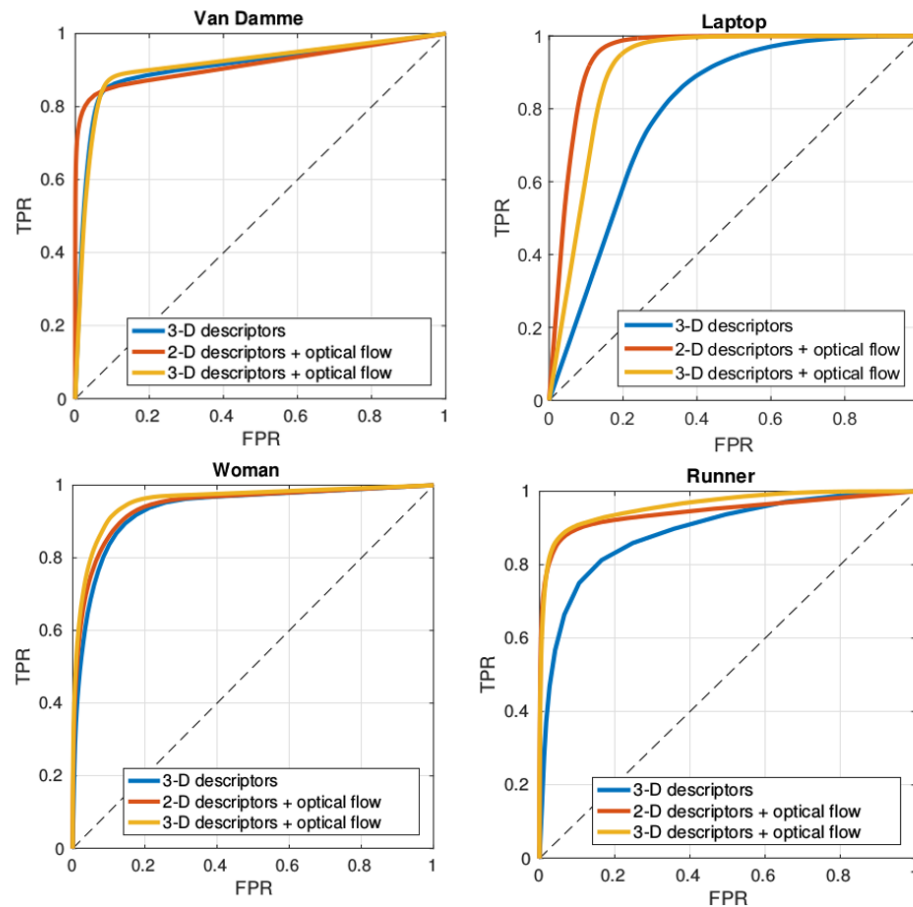
# Mahalanobis distance as heatmap

- Mahalanobis distances can be illustrated in heatmaps
- Objects spliced onto the background are revealed visually

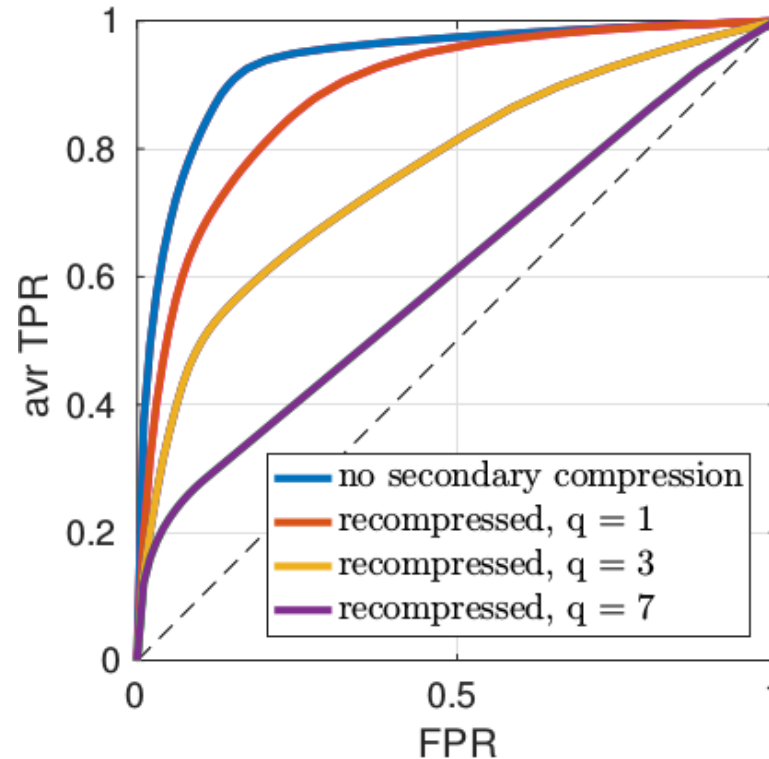


# Dataset





- Suggested method detects splicing reliable
- Incorporating optical flow to can improve results

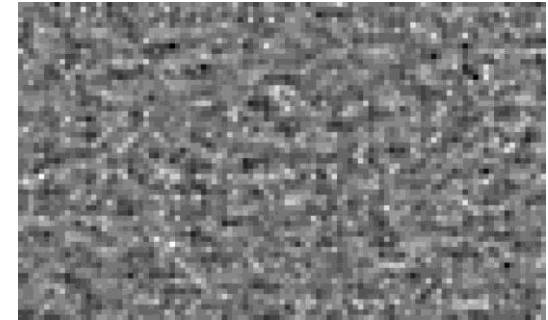


Secondary recompression of spliced material:

- Weakens its localization
- Detection results correlates (negatively) with compression factor



- Photo-response nonuniformity (PRNU) based:
  - PRNU is a profoundly unique pattern inherently present in any imaging device [1]
  - Also applied to localize video manipulations [2]

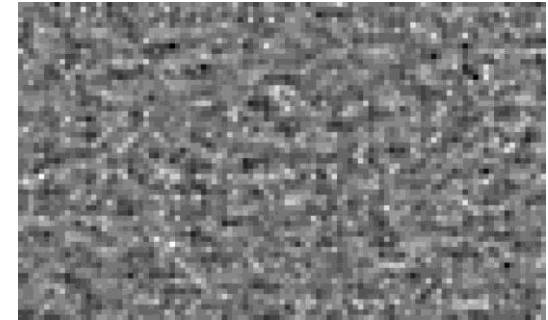


Example PRNU, amplified

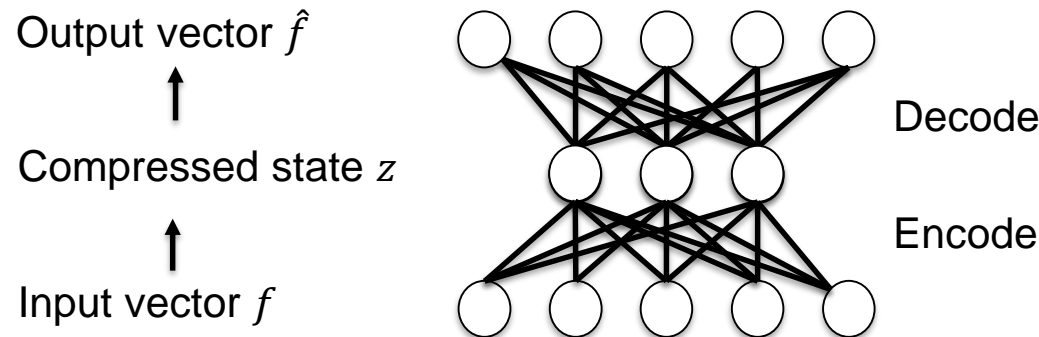
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- Photo-response nonuniformity (PRNU) based:
  - PRNU is a profoundly unique pattern inherently present in any imaging device [1]
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- Autoencoder (AE) based [3]:
  - AEs are a special neural network architecture
  - Training subject to reconstruct input from compressed state  $z$  with little error as possible:  $\min\{\mathcal{L}(f, \hat{f})\} \rightarrow$  If new input differs,  $\mathcal{L}$  becomes large

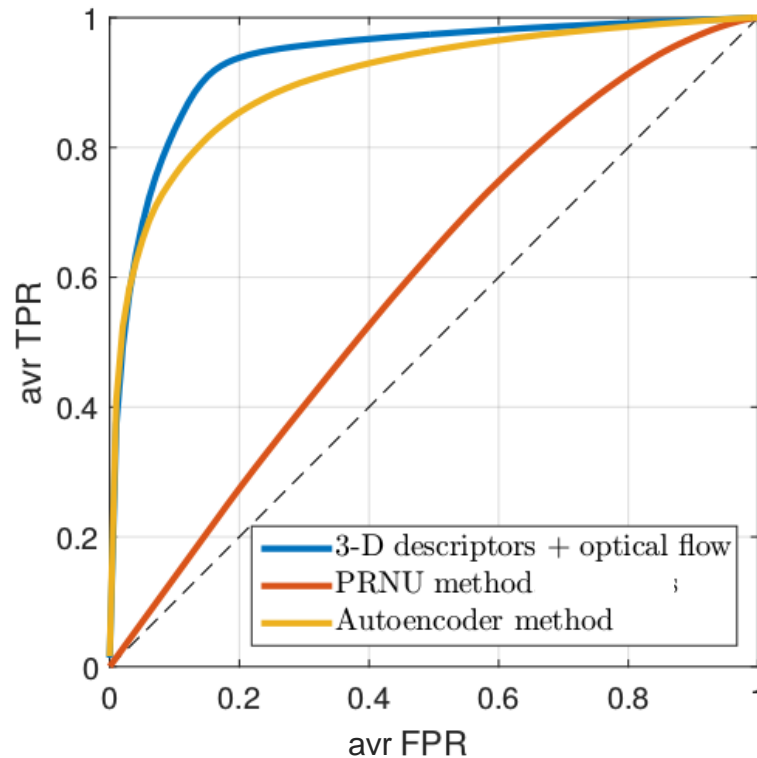


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# Comparison with other methods



- Suggested framework can produce better results than other works
- AE does not utilize information about movement in videos, like incorporating optical flow in the suggested framework
- PRNU might have difficulties to build a meaningful model from correlated frames

## Presented Algorithm:

- Distinguishes different noise distributions, present in a spliced video
- Tested successfully on green screen splicing
- Additional secondary compression influences performance

## Future Work:

- Build up bigger database
- Apply algorithms to different kinds of forgeries
- Also apply to video source identification (e.g. on non-forged videos)

The top portion of the slide features a dark blue background with a faint, semi-transparent image of the FAU building's facade and its statues. On the right side, a large, circular seal is visible, containing the word 'ACADEMIA' and a profile of a man's head.

**Thanks for your attention!**  
**Questions?**



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