Hybrid eye center localization using cascaded regression and robust circle fitting

Alex Levinshtein

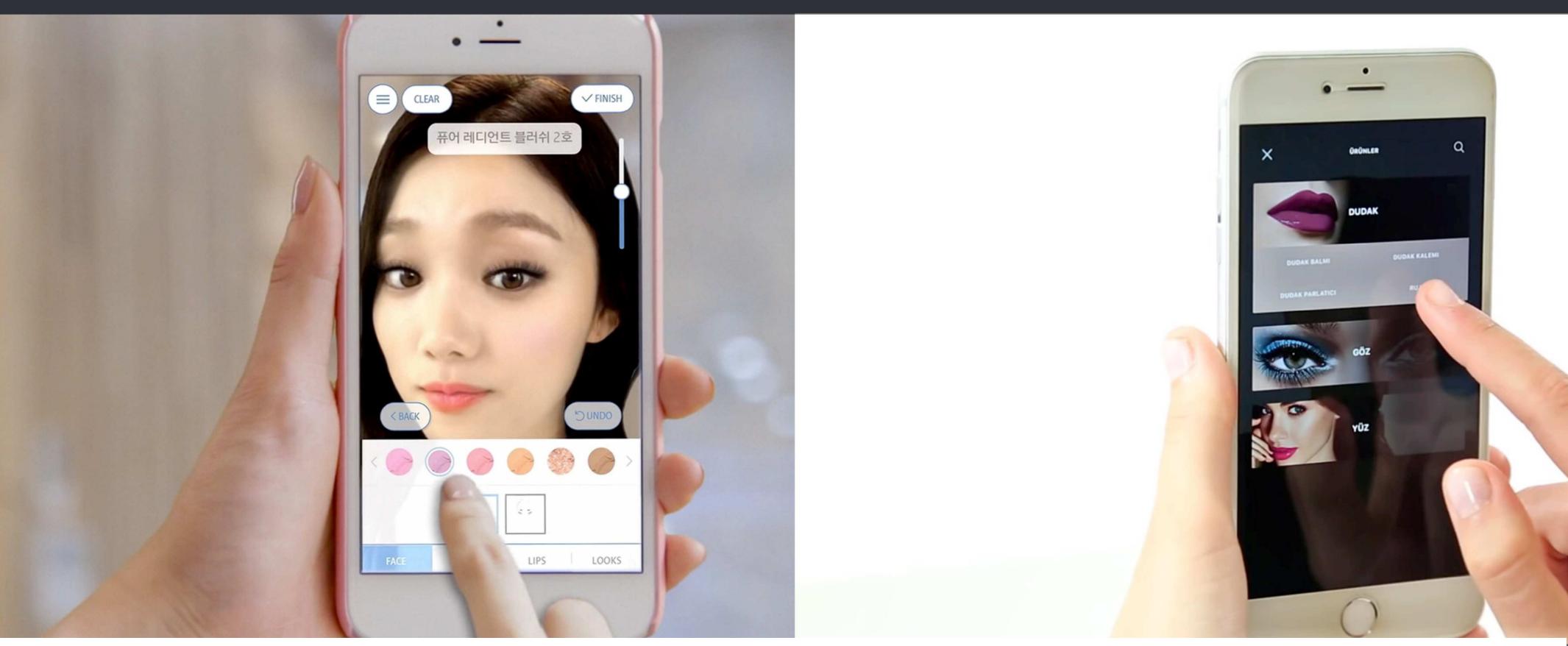
Edmund Phung

MODIFACE

Parham Aarabi



LANEÍGE



Customized Native iOS/Android/Web Apps

A V O N

The need for iris detection

Virtual contact lenses try-on



Gaze tracking

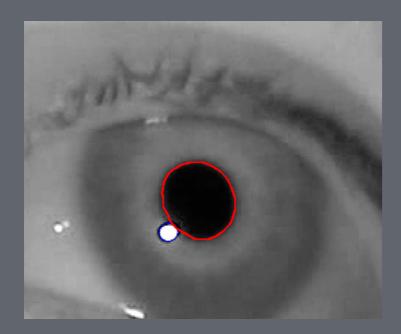


Iris recognition

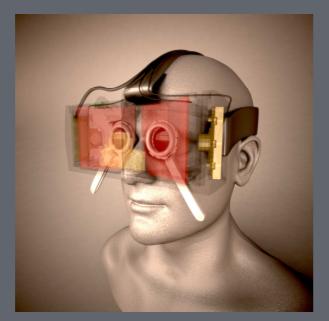


In-the-wild iris detection

Most methods use specialized devices



NIR images

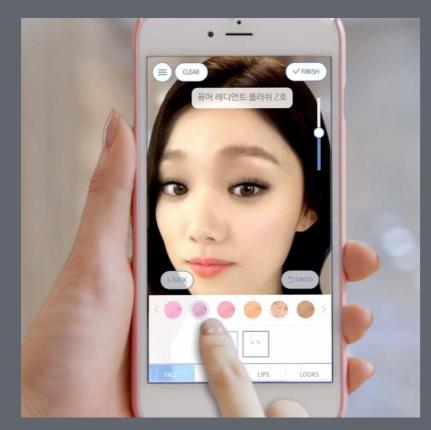


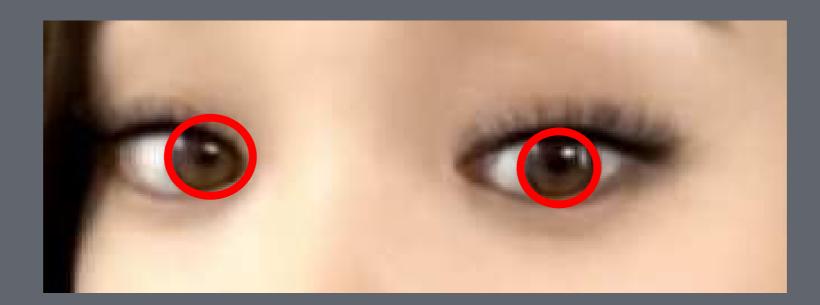


Head mounts

Iris scanners

Our focus: real-time detection on mobile devices using a standard camera





Related Work

Hand-crafted methods

Ahuja et al. 2016 Fuhl et al. 2015,2016 George and Routray 2016 Li et al. 2005 Skodras and Fakotakis 2015 Swirski et al. 2012 Timm and Barth 2011 Valenti and Gevers 2012 Wood and Bulling 2014

More robust but not accurate

Accurate but not robust

Learning-based methods

Markus et al. 2014 Tian et al. 2016

Zhou et al. 2015



Powerful regressors Simple features

Simple regressors Powerful features

Our contributions

- 1. Learning-based method using powerful regressors and powerful features
 - 2. Increased accuracy by combining #1 with robust circle fitting

ressors **and** powerful features with robust circle fitting

Method Overview

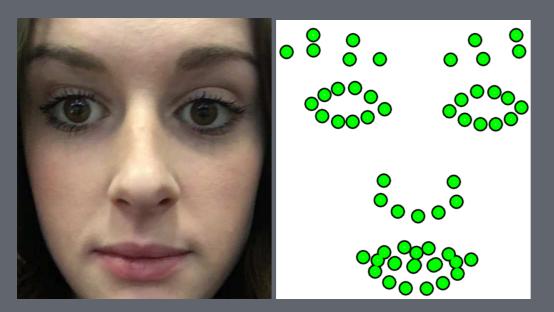
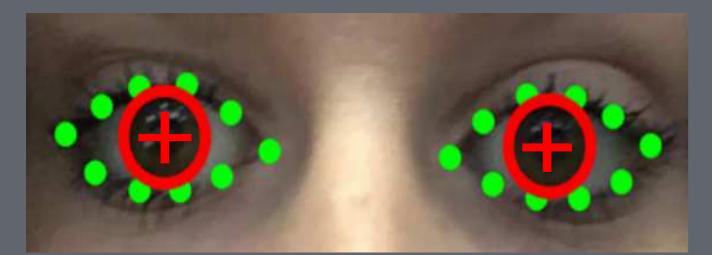
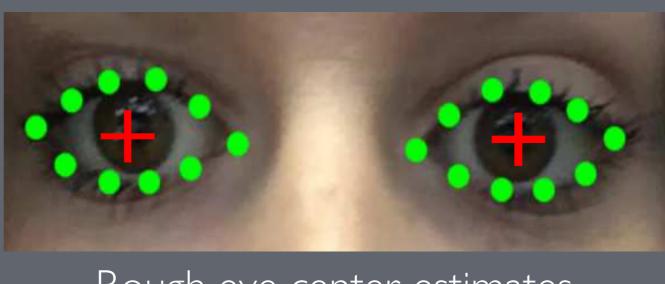


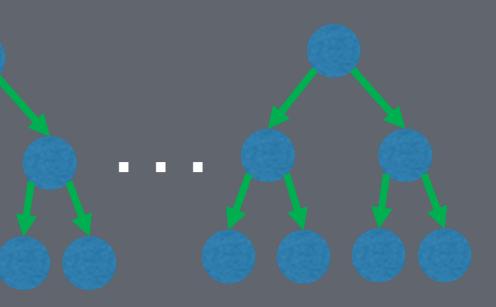
Image + Facial landmarks



Accurate eye center and iris radii estimates after circle fitting







Cascade of regression forests

Rough eye center estimates

Rough eye center detection

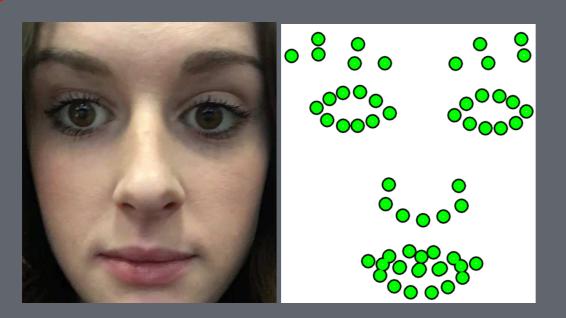
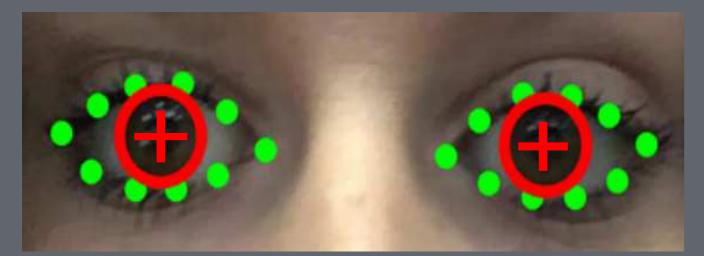
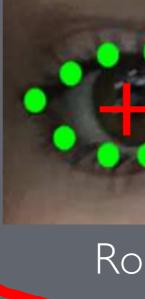


Image + Facial landmarks

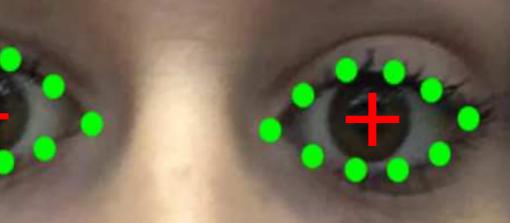


Accurate eye center and iris radii estimates after circle fitting





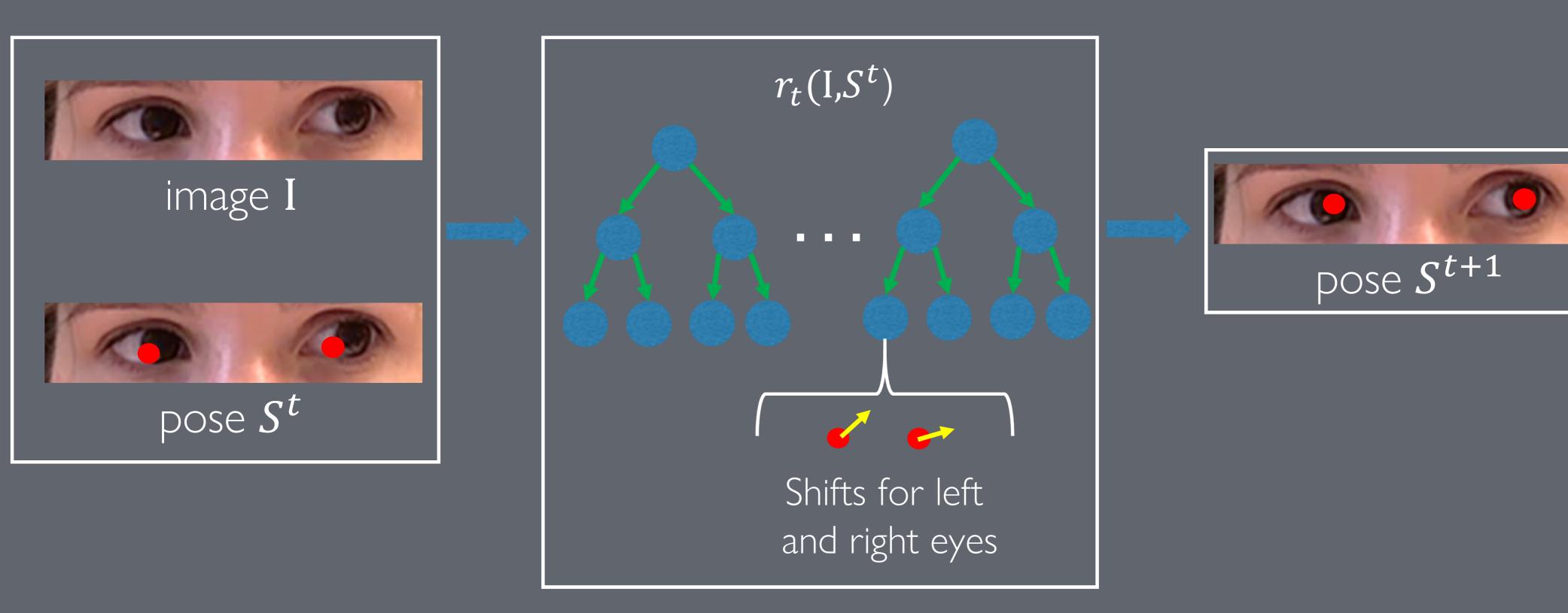
Cascade of regression forests



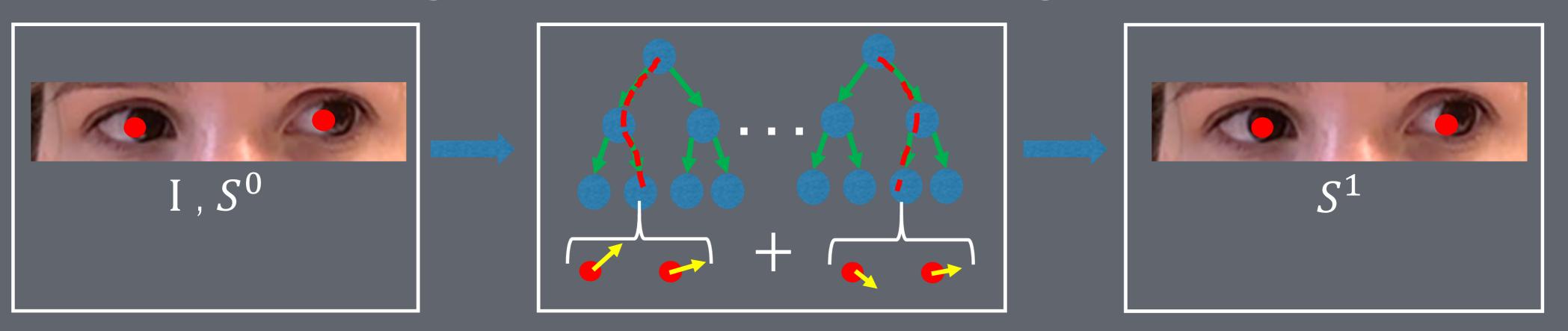
Rough eye center estimates

Cascade of gradient boosted regression forests

 $S^{t+1} = S^t + r_t(\mathbf{I}, S^t)$



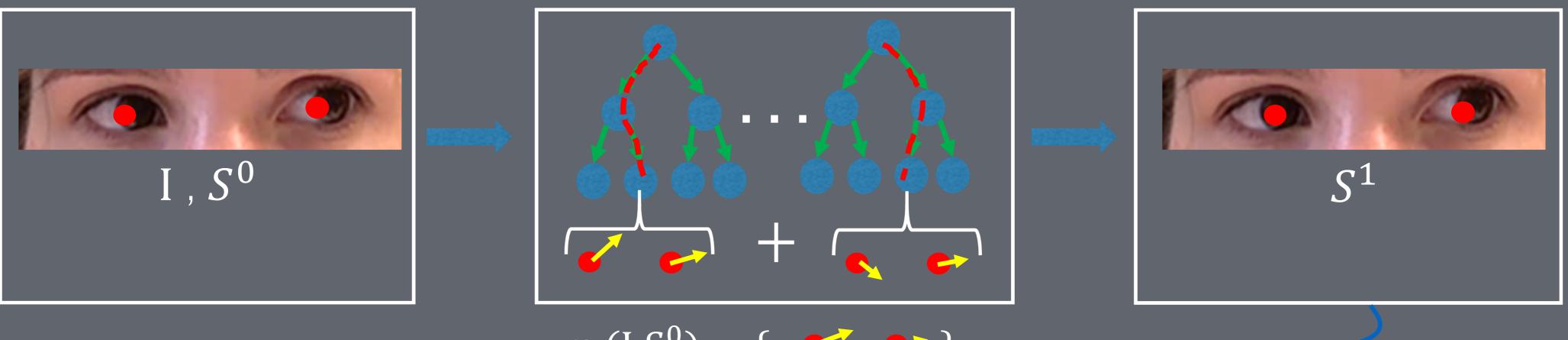
Cascade of gradient boosted regression forests



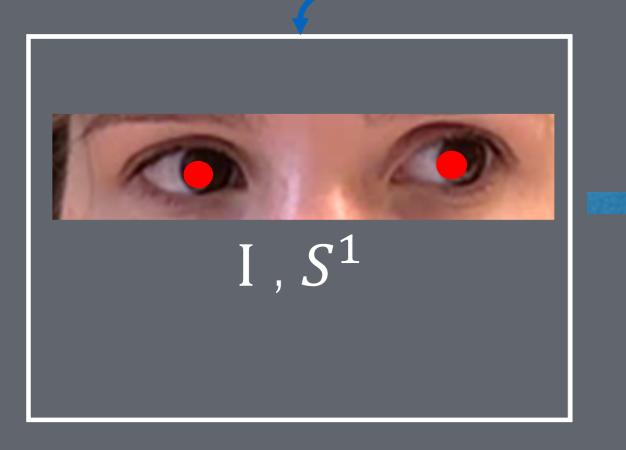
 $r_0(I,S^0) = \{ \bullet, \bullet \}$

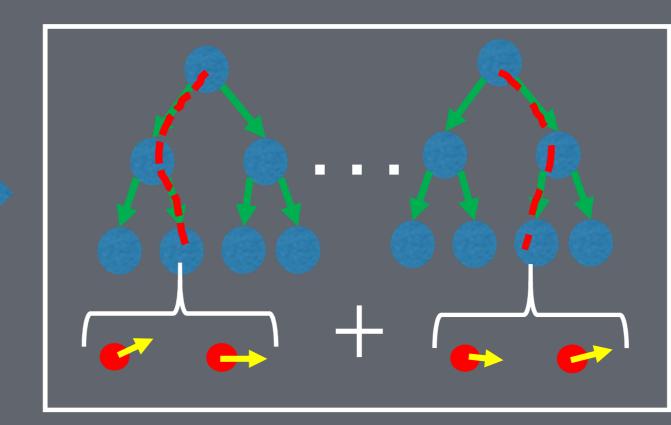


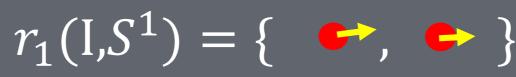
Cascade of gradient boosted regression forests



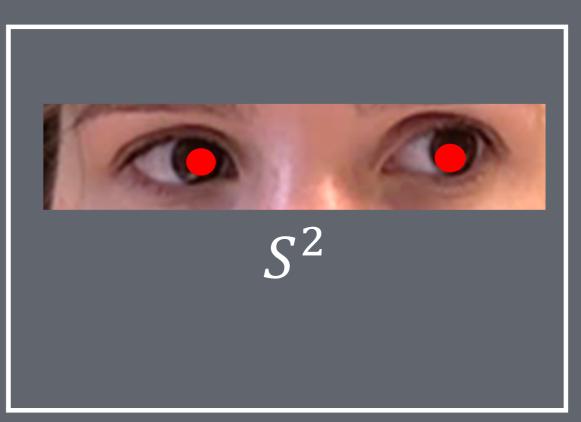
 $r_0(I,S^0) = \{ ~~,~~ \}$











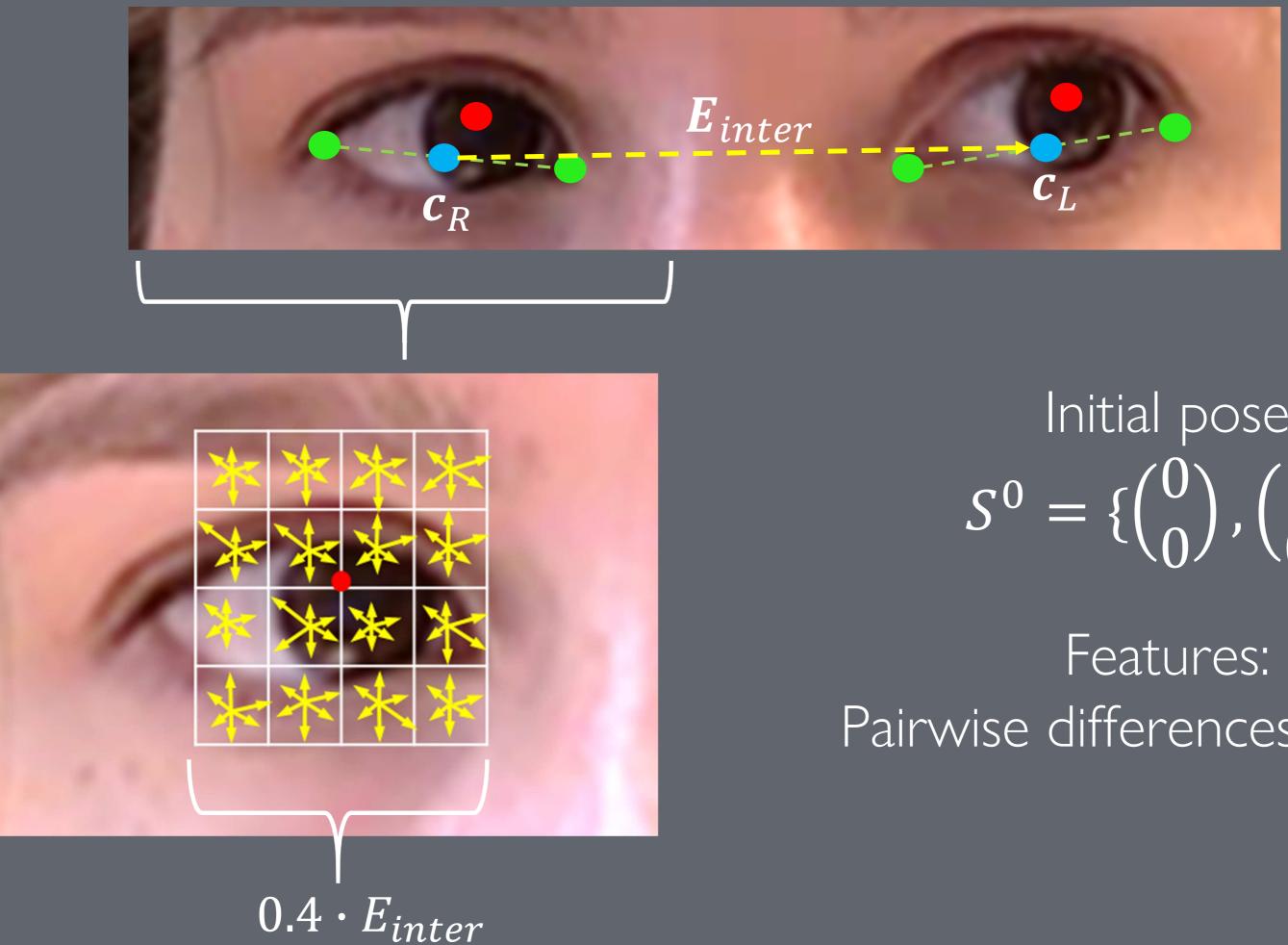


Beyond raw pixels in $r_t(I,S^t)$

1. Use powerful features, instead of raw pixels

2. Anchor the features to current eye center estimates

Normalized HoG features for iris detection



Initial pose $S^0 = \{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \}$

Pairwise differences of HoG

Iris pose refinement by circle fitting

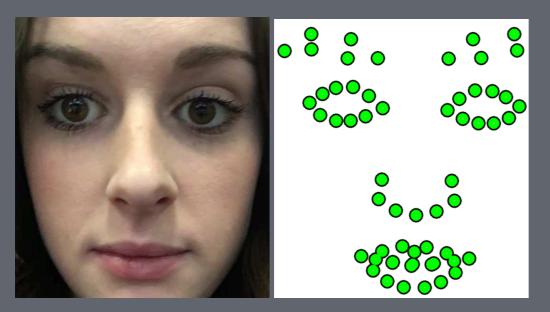
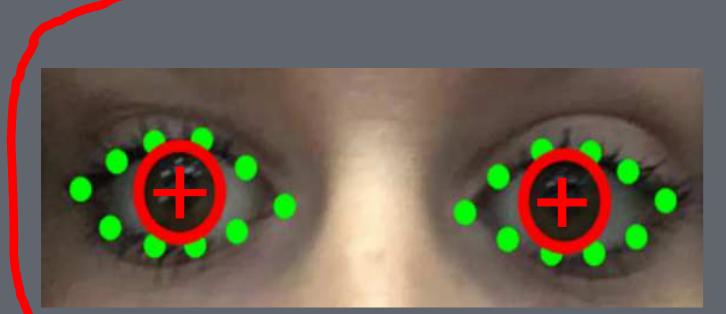
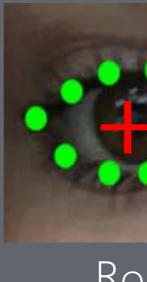


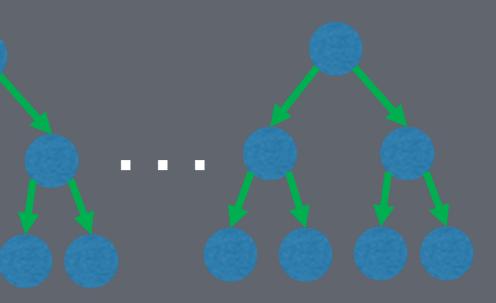
Image + Facial landmarks



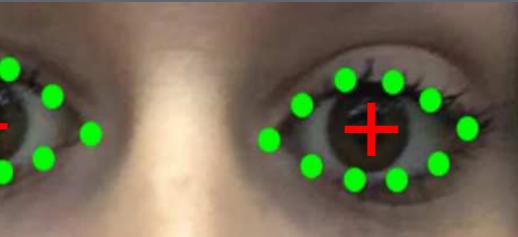
Accurate eye center and iris radii estimates after circle fitting



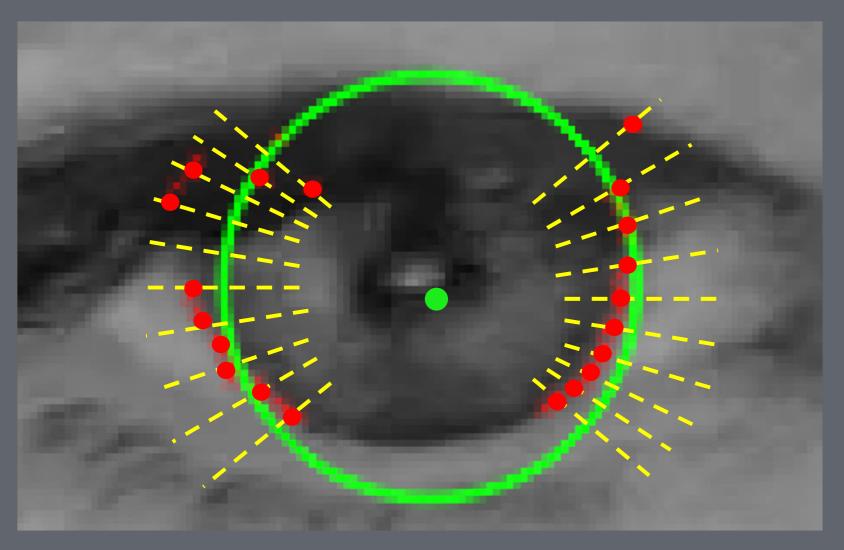




Cascade of regression forests



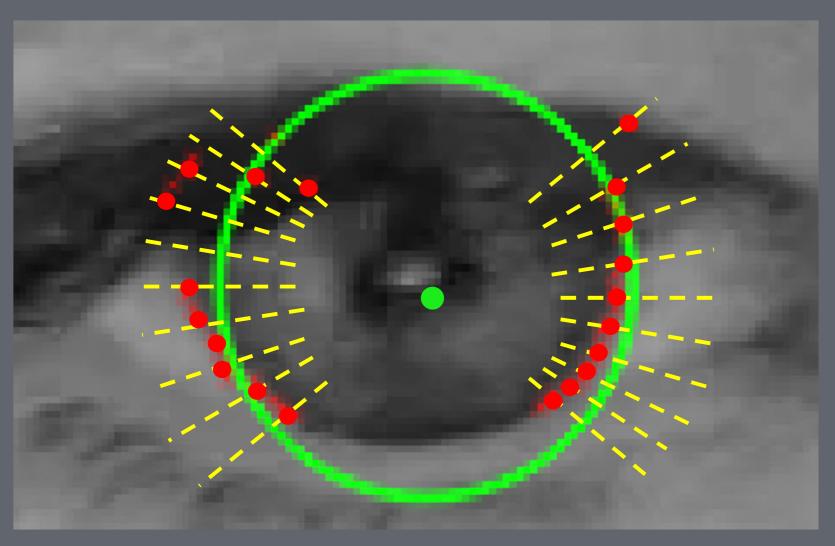
Rough eye center estimates



$$C_{1} = \sum_{i=1}^{N} \left(\sqrt{(e_{ix} - a)^{2} + (e_{iy} - b)^{2}} - a \right)^{2}$$

Fit iris using circle refinement

Start with (a, b) set to regressor output and *r* set to 10% of interocular distance

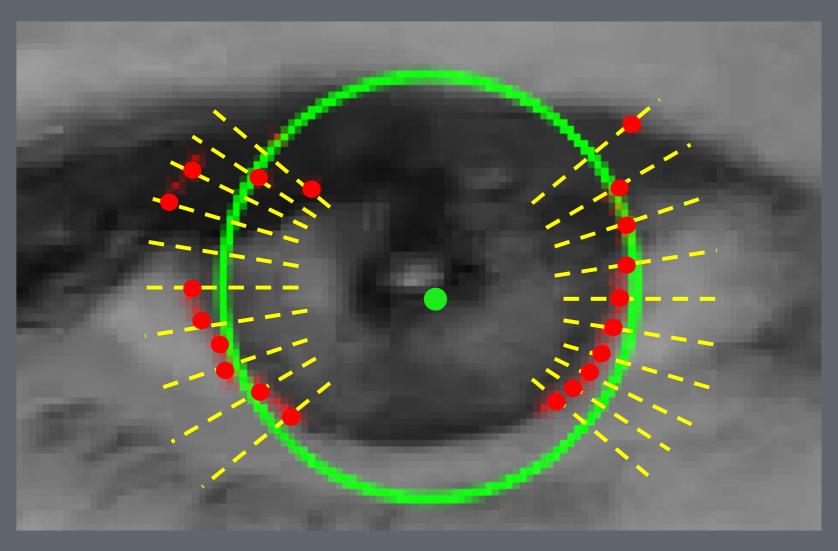


$$C_{1} = \sum_{i=1}^{N} \left(\sqrt{(e_{ix} - a)^{2} + (e_{iy} - b)^{2}} - \frac{1}{2} \right)^{2}$$

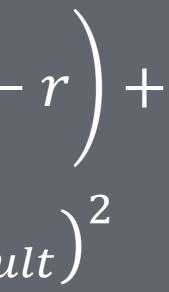
Issues:

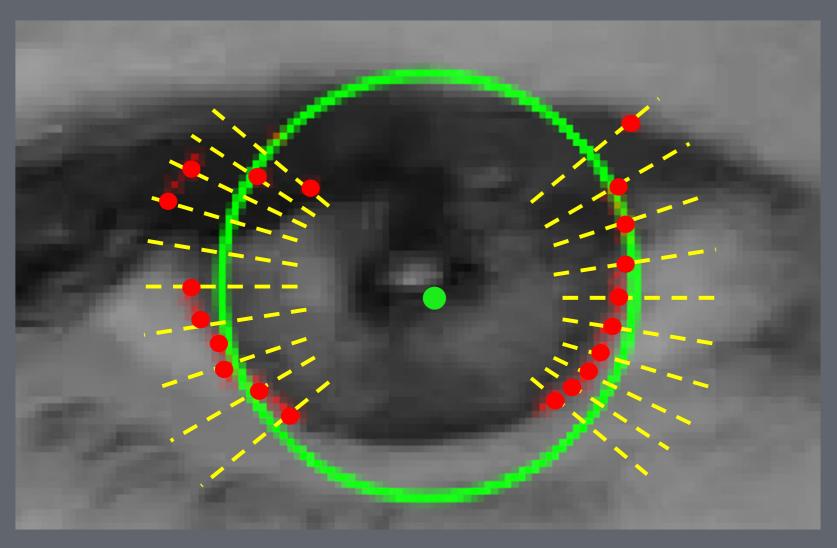
Not robust to outliers
Only uses regressor
output as initial guess





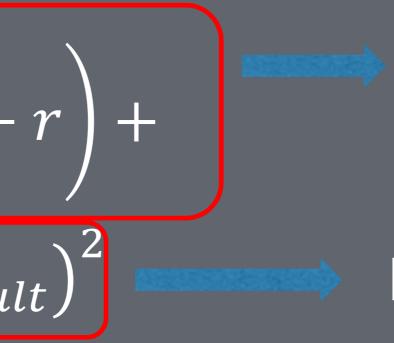
$$C_{2} = w_{1} \frac{1}{N} \sum_{i=1}^{N} \rho \left(\sqrt{(e_{ix} - a)^{2} + (e_{iy} - b)^{2}} - w_{2}(a - a_{0})^{2} + w_{2}(b - b_{0})^{2} + w_{3}(r - r_{defax})^{2} + w_{2}(b - b_{0})^{2} + w_{3}(r - r_{defax})^{2} + w_{3}(r - r_{def})^{2} + w_{$$





$$C_{2} = \left(w_{1} \frac{1}{N} \sum_{i=1}^{N} \rho \left(\sqrt{(e_{ix} - a)^{2} + (e_{iy} - b)^{2}} - w_{2}(a - a_{0})^{2} + w_{2}(b - b_{0})^{2} + w_{3}(r - r_{defax})^{2}\right)\right)$$

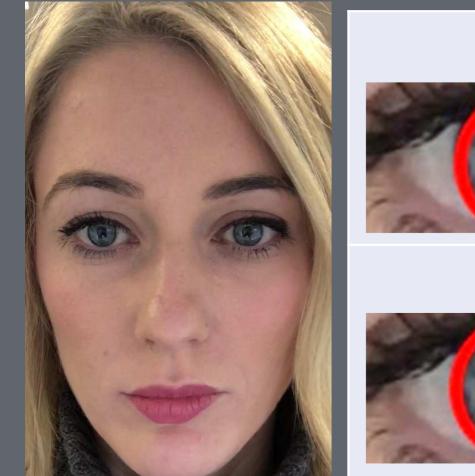
Robust to outliers Uses regressor output as initial guess and prior



Robust circle fitting cost

Prior terms

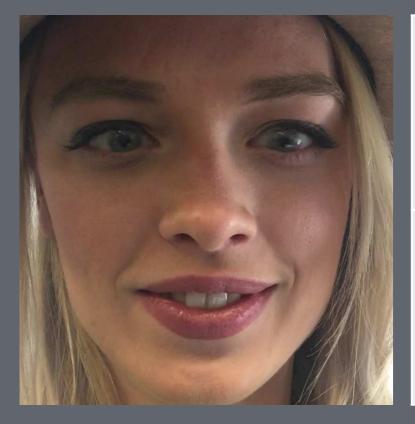
Results





REG-R







REG-R





REG



REG-R



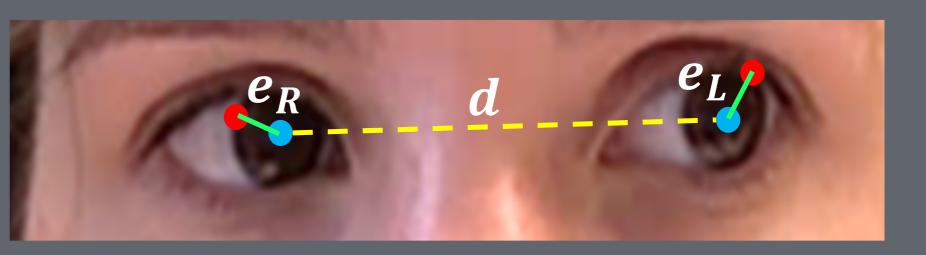
Results

Within the

iris

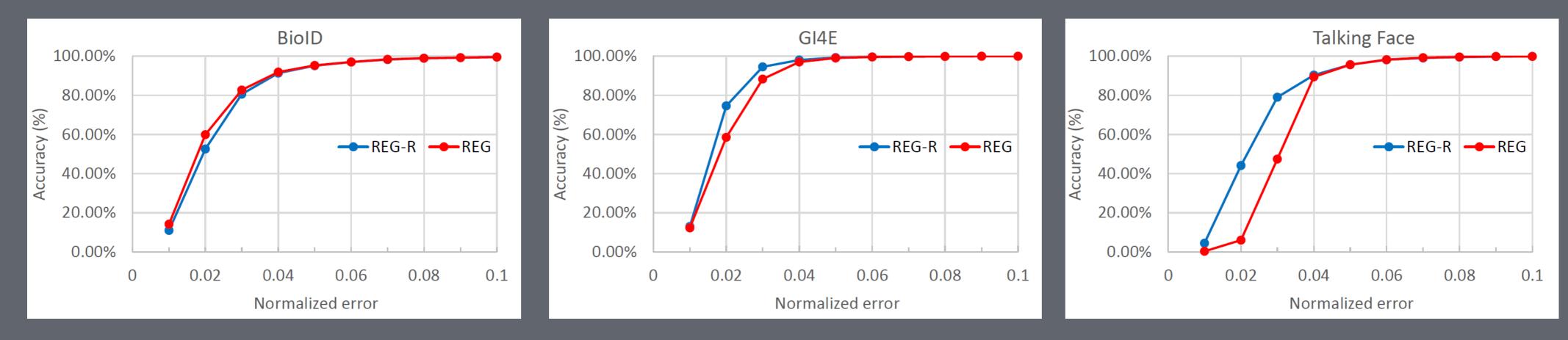
pupil

Method	e < 0.025	e < 0.05	e < 0.1	e < 0.25
BioID Dataset				
REG-R	68.13%	95.07%	99.59%	100%
REG	74.3%	95.27%	99.52%	100%
Timm [8]	$38\%^*$	82.5%	93.4%	98%
Valenti [9]	$55\%^*$	86.1%	91.7%	97.9%
Zhou [17]	$50\%^*$	93.8%	99.8%	99.9%
Ahuja [1]	NA	92.06%	97.96%	100%
Markuš [15]	$61\%^{*}$	89.9%	97.1%	99.7%
GI4E Dataset				
REG-R	88.34%	99.27%	99.92%	100%
REG	77.57%	99.03%	99.92%	100%
ELSE [3]	49.8%	91.5%	97.17%	99.51%
Anjith [4]	NA	89.28%	92.3%	NA
Talking Face Dataset				
REG-R	65.78%	95.68%	99.88%	99.98%
REG	18.7%	95.62%	99.88%	99.98%
ELSE [3]	59.26%	92%	98.98%	99.94%
Ahuja [1]	NA	94.78%	99%	99.42%



$e = \frac{1}{d} \max\{e_R, e_L\}$

Results



Increased fine-level accuracy due to circle refinement

Majority of methods are not even evaluated at e < 0.025

Summary

- Real-time iris detection system from standard images 1.
- 2. Eye center localization using cascades of boosted regression trees with HoG features
- 3. Accurate iris localization using robust circle fitting
- 4. State-of-the-art performance on multiple datasets



Questions?

