

# Counting Plants With Deep Learning

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# Introduction

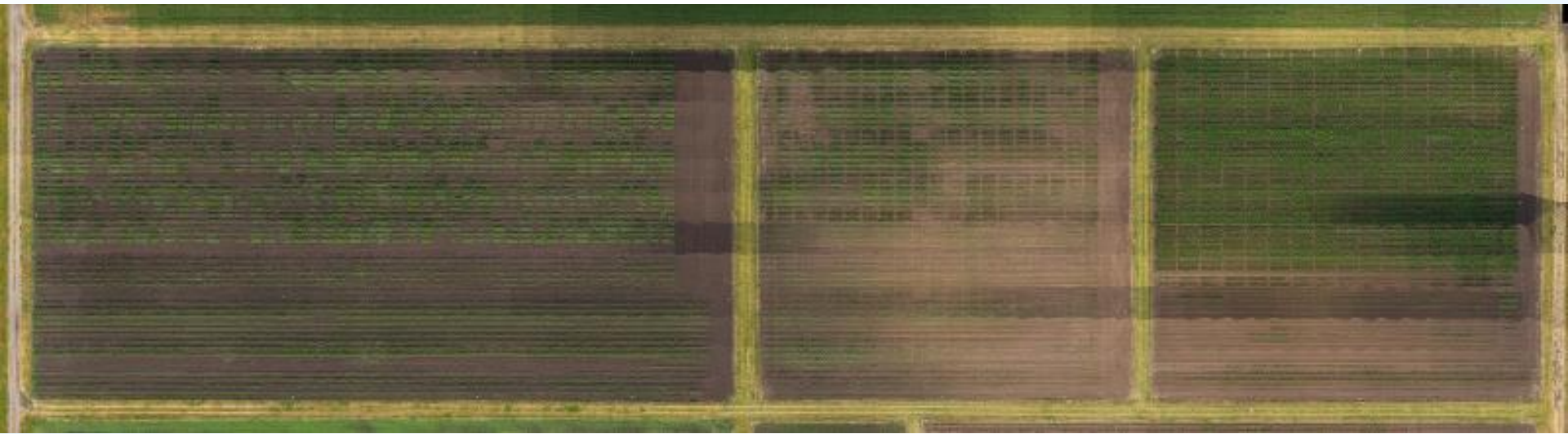
- **Agronomists and farmers need to know the number of plants in their crops to predict future yield**
- **Can we count without locating?**
- **We count plants in a crop field without knowing where they are**
- **We build our plant dataset from a single image of the entire crop field**
- **We describe a method to extract images sections or “plots” from an orthorectified image**



# 1. Plot Extraction



# Dataset



**420 meters ~ 4 football fields**

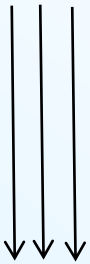
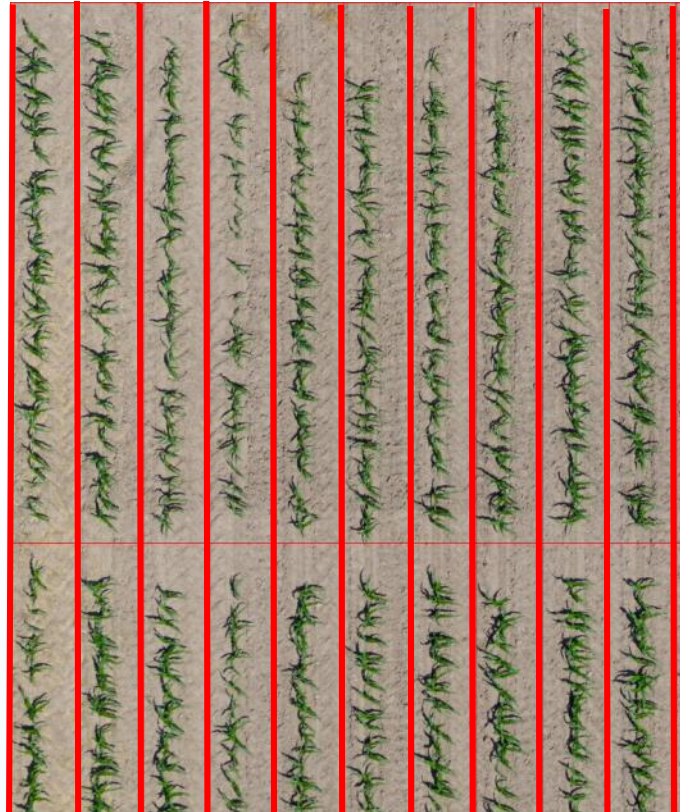
# Dataset

1,240 images were extracted



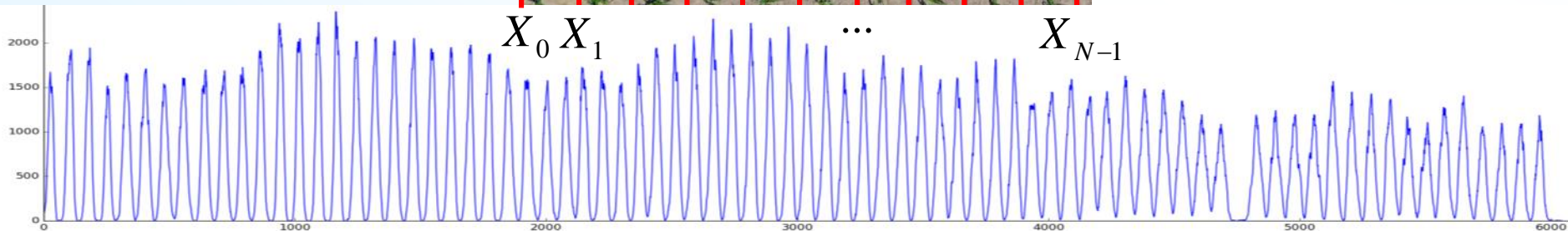
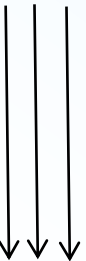
420 meters ~ 4 football fields

# Vertical Projection



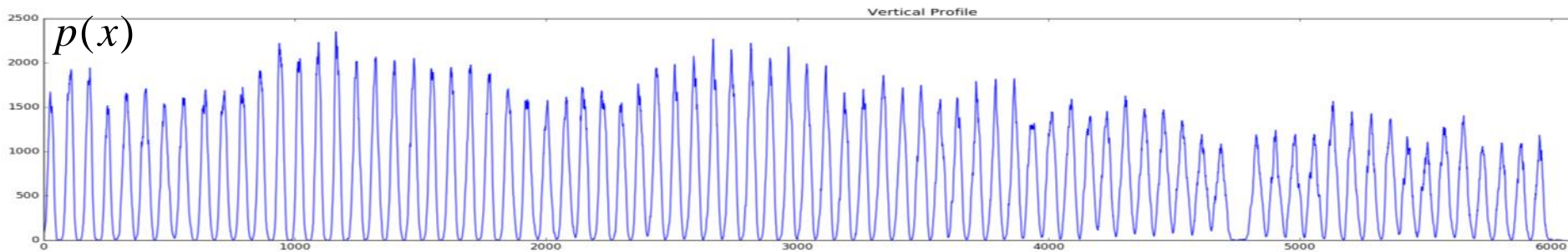
...

...



# Profile Function

- **Vertical profile over the entire crop field:**



$$\hat{X}_0, \Delta\hat{X} = \arg \min_{x_0, \Delta x} \sum_{n=0}^{N-1} p(x_0 + n\Delta x)$$

**Row  
harvested?**

- **$N$  : # lines**
- **$X_0, \dots, X_{N-1}$  : Coordinates of each plot-separating line**
- **$X_n = X_0 + n\Delta X \quad n = 0, 1, \dots, N-1$**

# The Cost Function

- It does not seem appropriate for gradient descent:





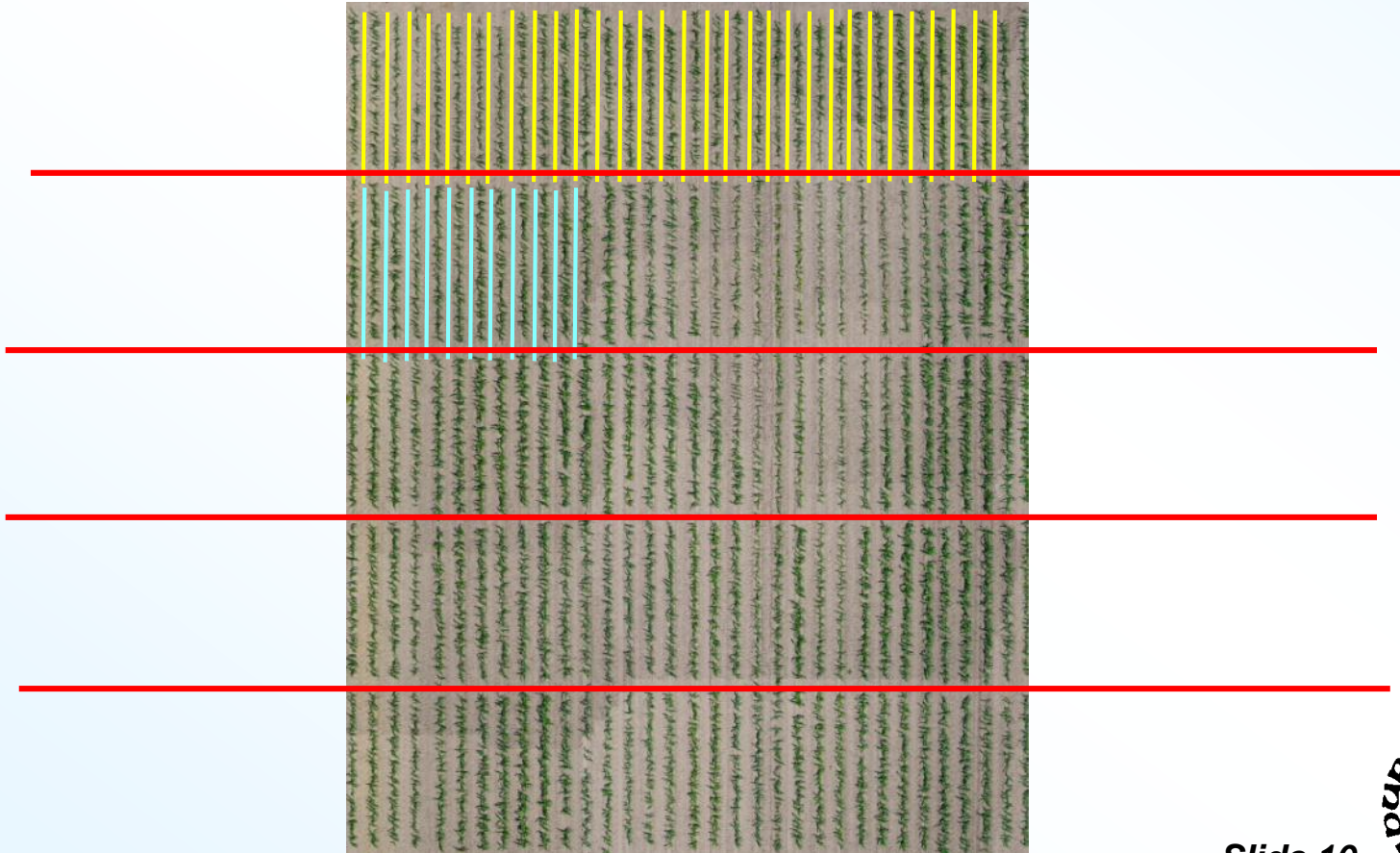
# Method

1. User provides: (a) number of rows and (b) number of ranges
2. Find range-separating lines:



# Method

3. For each range, find row-separating lines:



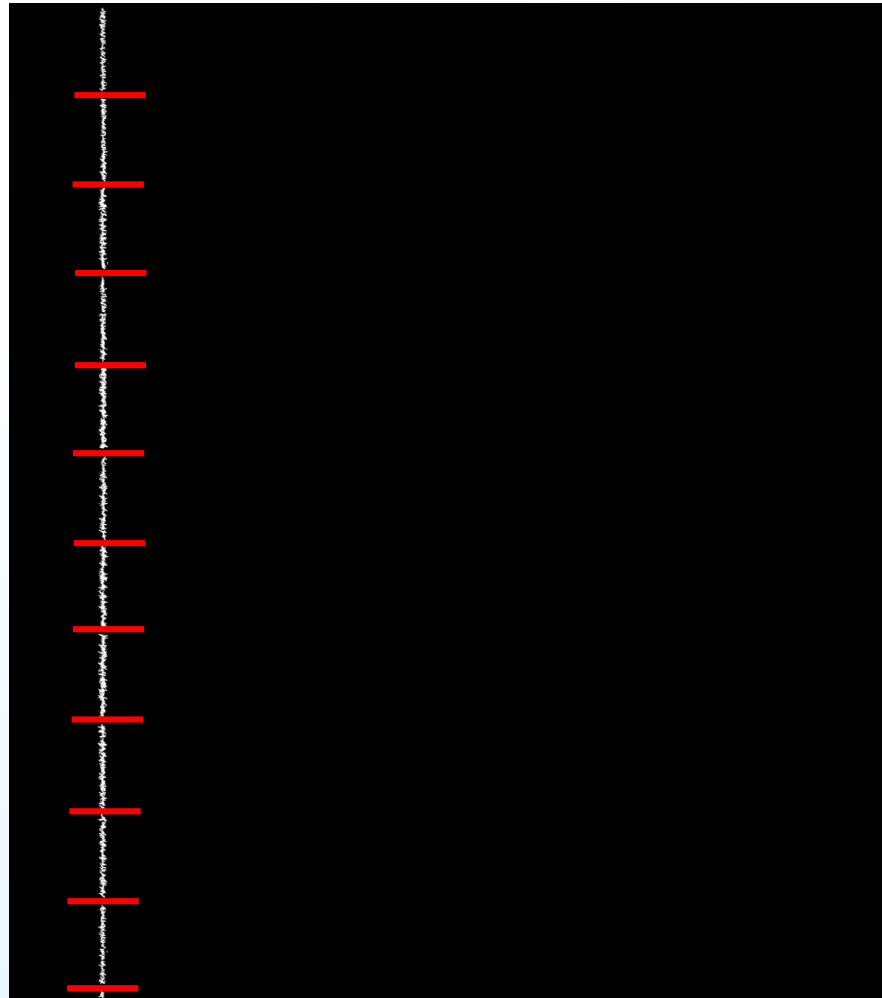
# Method

4. Select the  $n$ -th row of each range



# Method

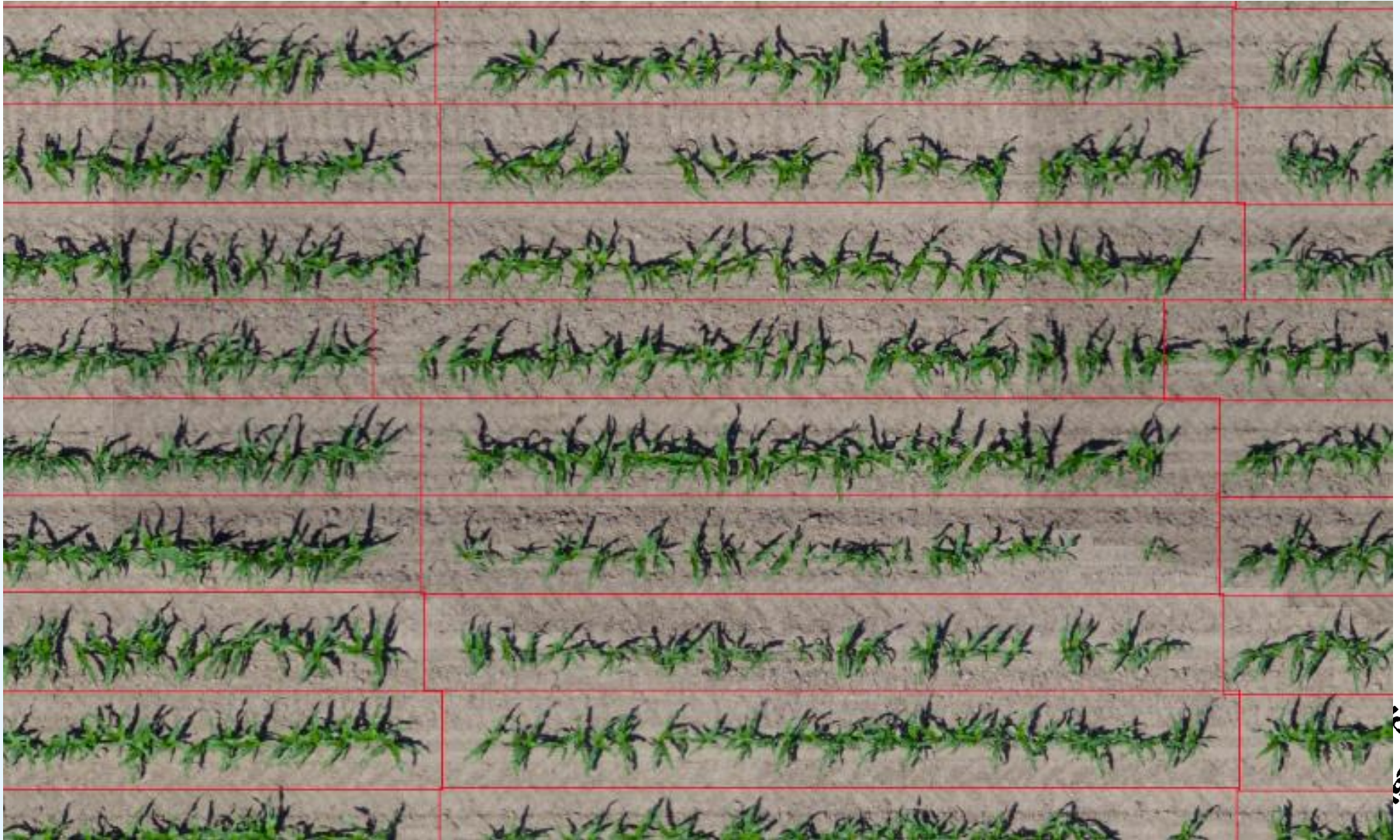
## 4. Find range-separating lines for the $n$ -th row



# Resulting Cropped Images

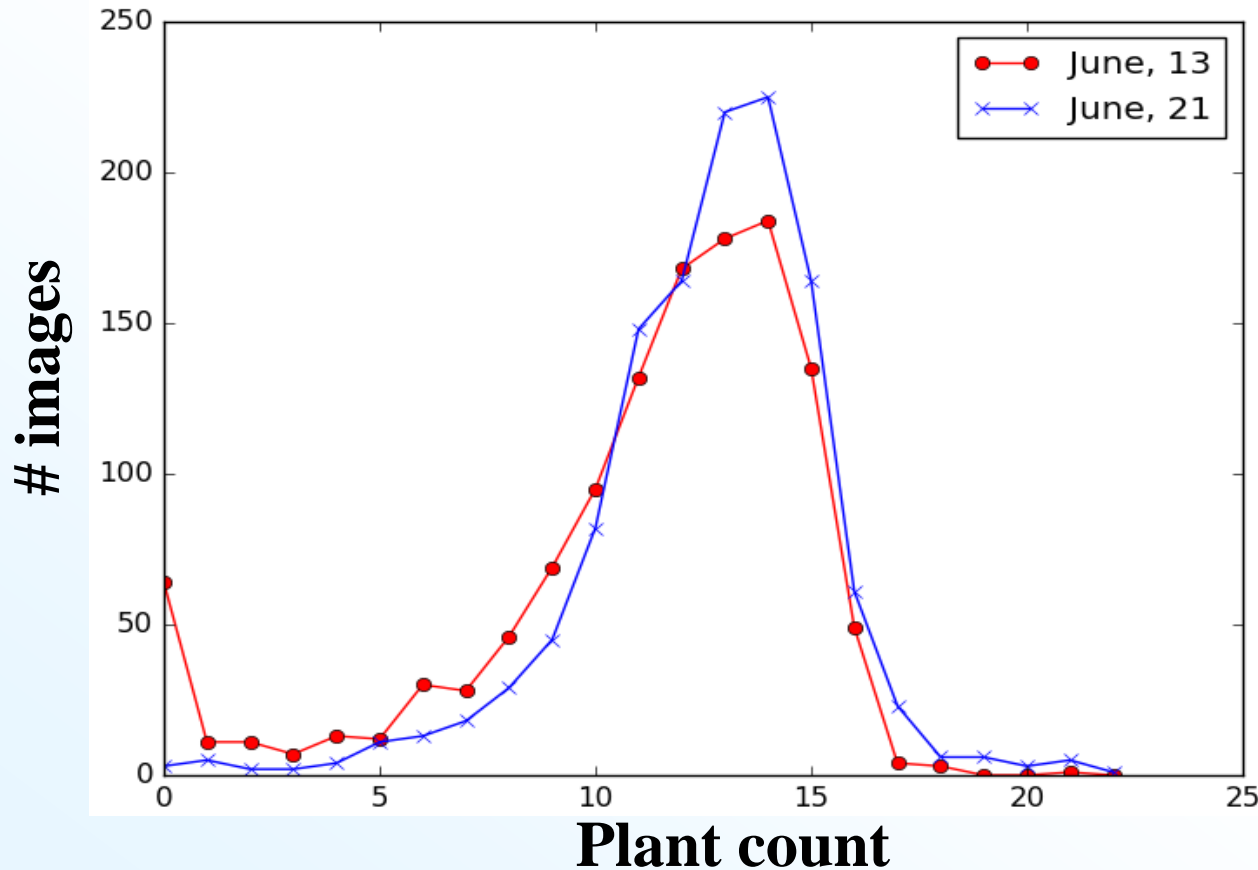


# Resulting Cropped Images



# Dataset

- We groundtruthed 2,480 labeled images
  - 80% for training, 10% for validation, 10% for testing



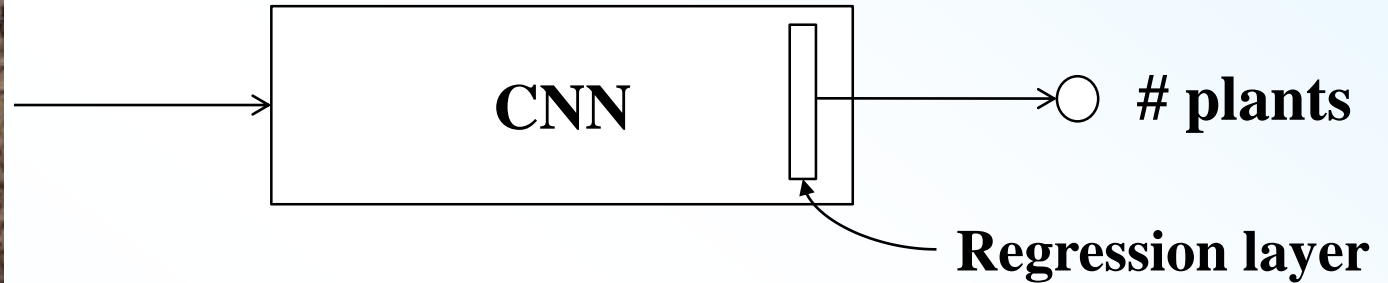
**Example image**  
**Plant count: 15**

## 2. Plant Counting





# Counting Plants With Deep Learning



**Compared CNNs:**

- AlexNet-v2
- Inception-v2
- Inception-v3
- Inception-v4

**With minimal modification  
to adapt to image size**

# Cost Function

- **Most research uses cross entropy as cost function, which reduces to**

$$H(p, q) = -\log q(C)$$

**where  $q(x)$  are the activations of the last layer, and  $C$  is the true number of plants**

- **This cost function is not appropriate when the classes are not independent, and there is label noise**
- **We want to count, not classify**
- **We propose to use the  $L_p$  norm**

$$L_p(x, \hat{x}) = |x - \hat{x}|^p$$

**and test which value of  $p$  provides the lowest error**

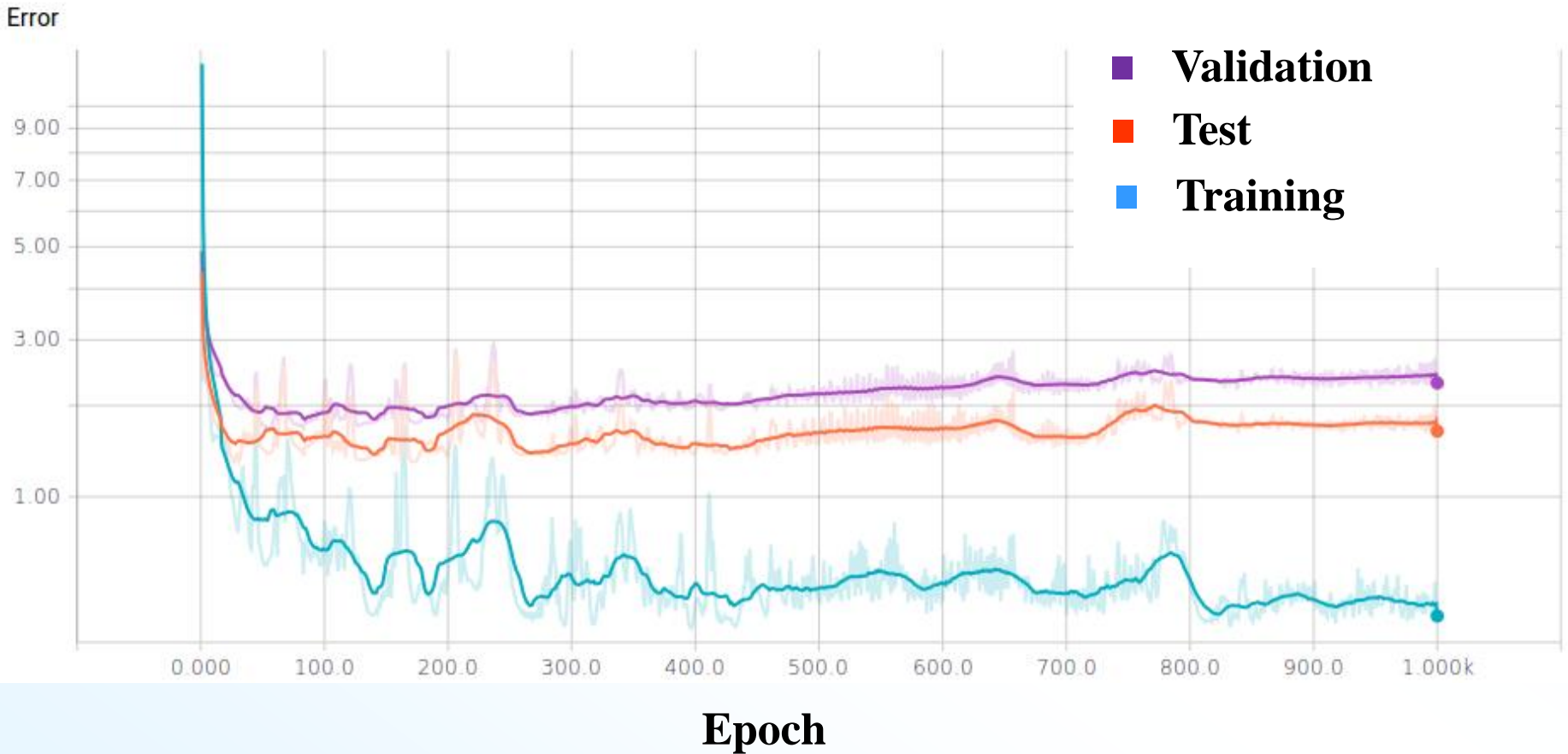


# Network Architectures

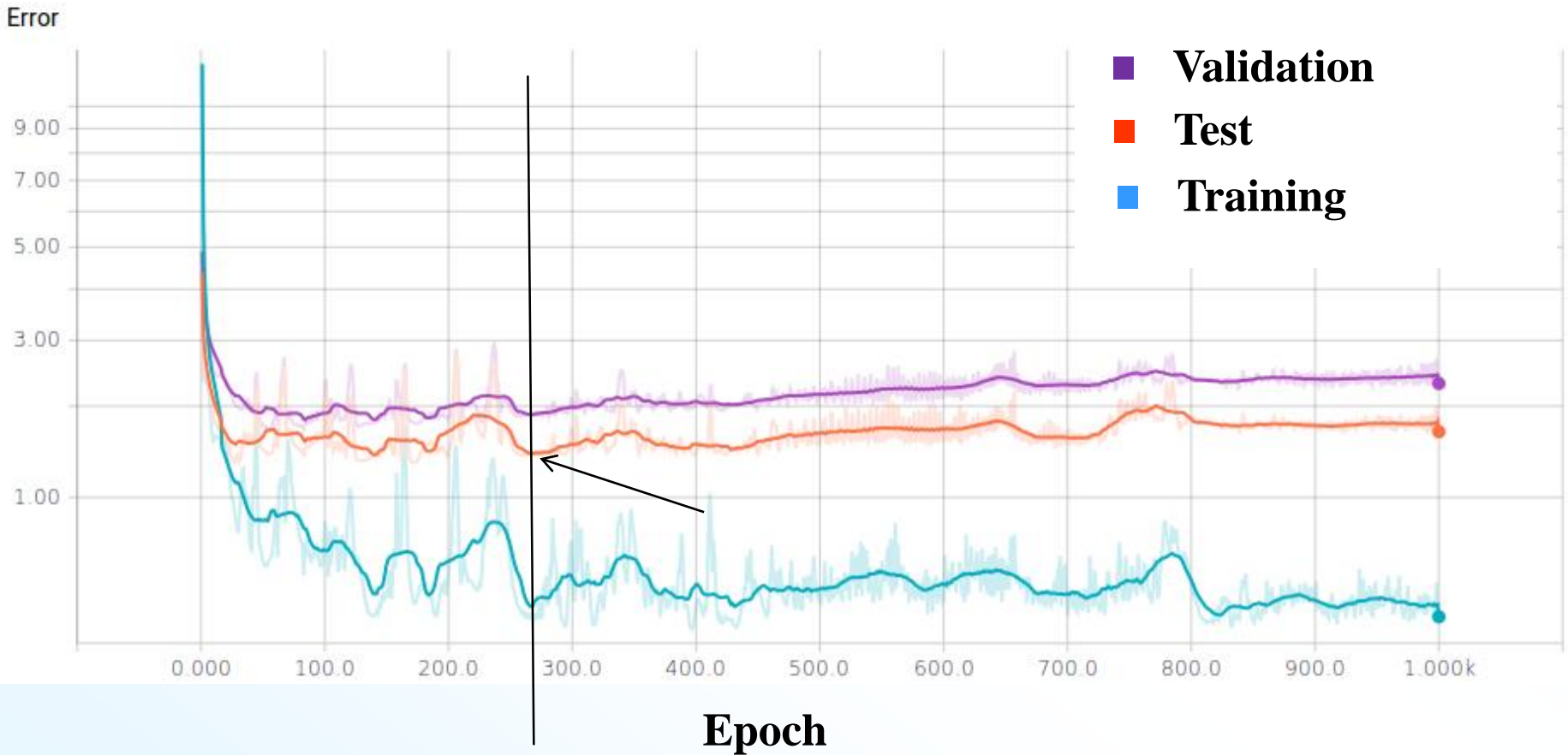
- **We examined several CNN architectures:**
  - **Alexnet**
  - **Inception-v2**
  - **Inception-v3**
  - **Inception-v4**
- **We modify the last layers to be able to process non-rectangular images (of size  $546 \times 103$ )**



# Stopping Criteria



# Stopping Criteria



# Value For $p$

- Our metric for testing is Mean Average Percentage Error

$$MAPE = 100 \frac{|\hat{x} - C|}{C}$$

- Effect of  $p$  on the error, evaluated using AlexNet

$p$	MAPE
2	8.2%
1.8	8.4%
1.5	8.5 %
1	7.9 %



# Results

- Performance of different architectures was evaluated

Network	MAPE (w/o data augm)	MAPE (w/ data augm)
AlexNet	8.3%	7.9%
Inception-v2	8.2%	6.7%
Inception-v3	7.1%	6.7%
Inception-v4	12.4%	11.4%



- (using  $p=1$ )



# Conclusions

- **We presented a CNN-based method to count plants without locating them**
- **We presented a method to segment (or extract) image sections, or plots, from an orthorectified image**
- **Future work will include investigating loss functions more stable than the L1, such as the smooth L1, and training with larger datasets**

