

A VIDEO DEHAZING SYSTEM BASED ON FAST AIRLIGHT ESTIMATION

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OUTLINE

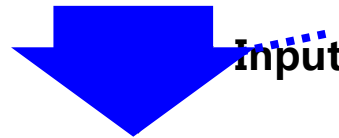
- ▶ **Introduction**
 - ▶ Dehazing
- ▶ **Background**
 - ▶ Hazy imaging model
 - ▶ DCP-based dehazing method
- ▶ **Proposed dehazing system**
 - ▶ Fast airlight estimation
 - ▶ Proposed dehazing system
- ▶ **Evaluation**
- ▶ **Conclusion**

INTRODUCTION

▶ Dehazing

▶ Hazy images

- ▶ Image quality is degraded by haze



Dehazing: The signal processing used to remove haze

▶ Recovered images

- ▶ Enhance the image quality by removing the haze

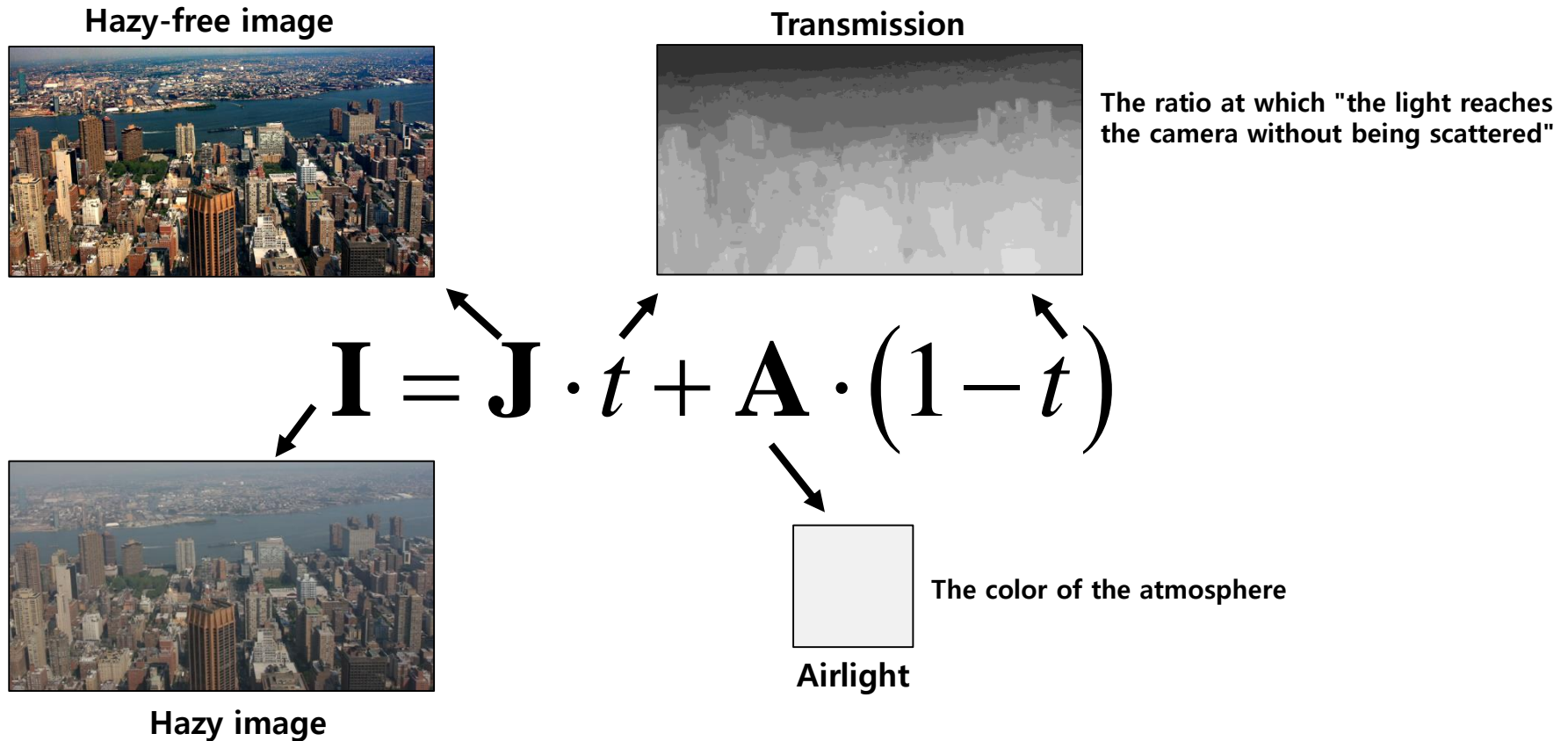
Computer vision systems



Undesired output

BACKGROUND

▶ Hazy imaging model¹⁾

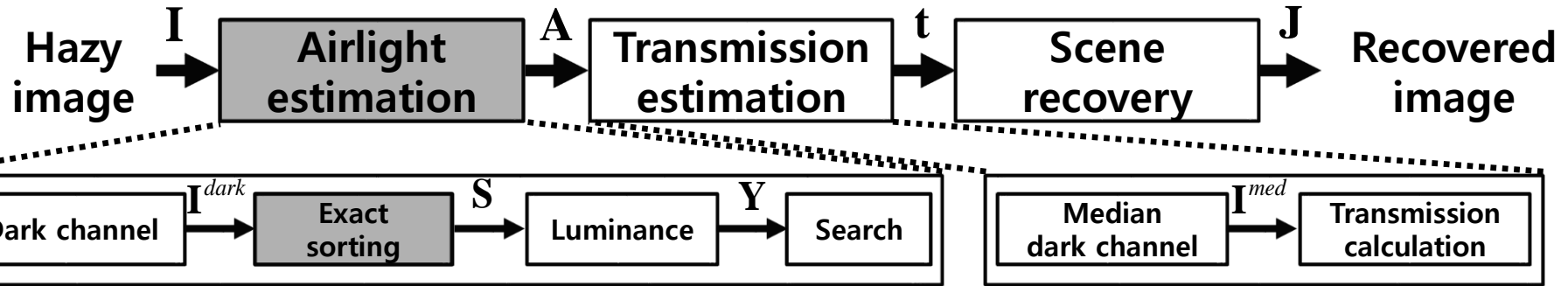


→ Goal of dehazing is to obtain \mathbf{J} by estimating \mathbf{A} and t using given \mathbf{I}

1) S. G. Narasimhan and S.K. Nayar. "Chromatic frame work for vision in bad weather", IEEE Conference on Computer Vision and Pattern Recognition(CVPR), volume 1, pages 598-605, June 2000.

BACKGROUND

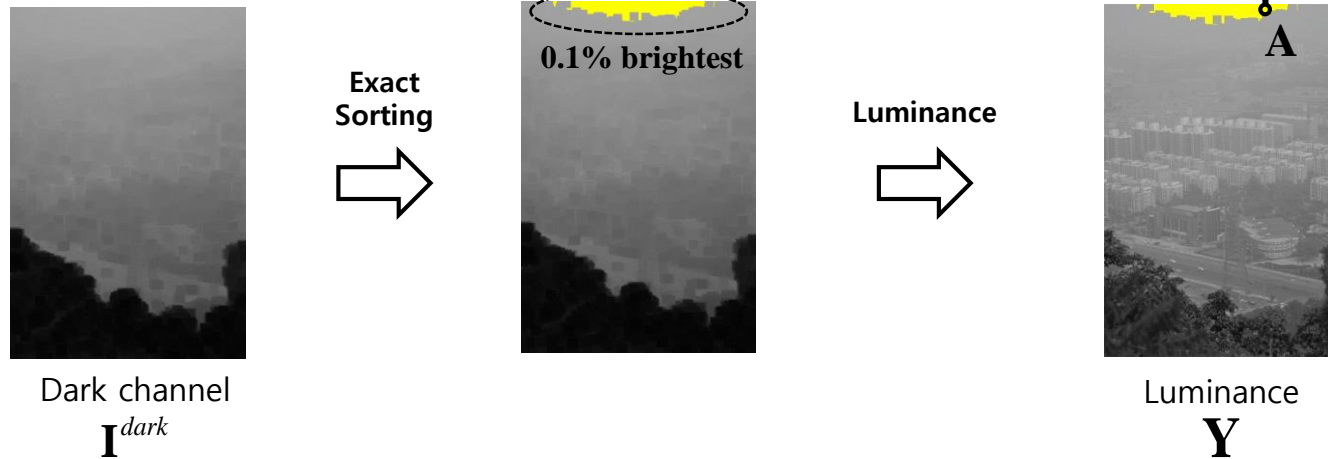
▶ DCP-Based Dehazing¹⁾



▶ Airlight Estimation

S : Candidate locations for the airlight pixel

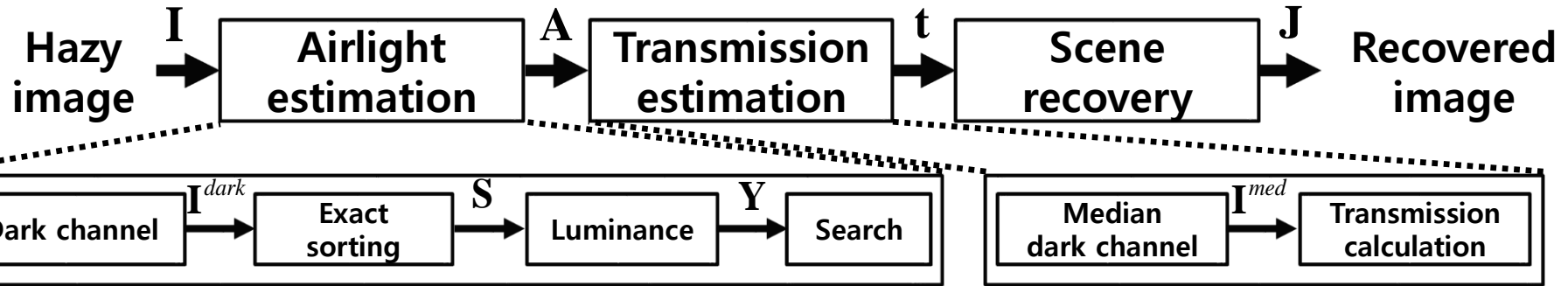
Airlight pixel: Brightest pixel in luminance Y for S



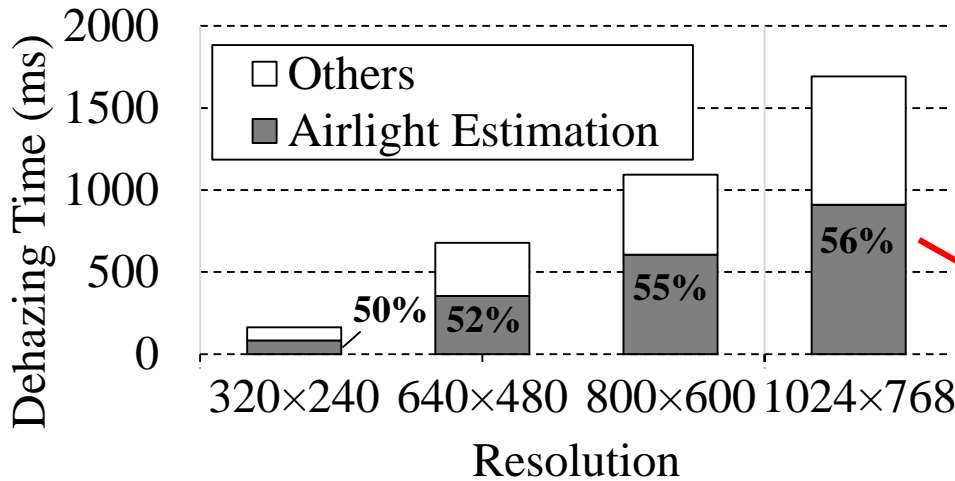
1) K. He, J. Sun, and X. Tang, "Single image haze removal using dark channel prior," IEEE Trans. Pattern Analysis & Machine Intelligence, vol. 33, no. 12, pp. 2341–2353, Dec. 2011.

BACKGROUND

▶ DCP-Based Dehazing¹⁾



▶ Profiling results of software simulation ✓ 800MHz ARM Processor

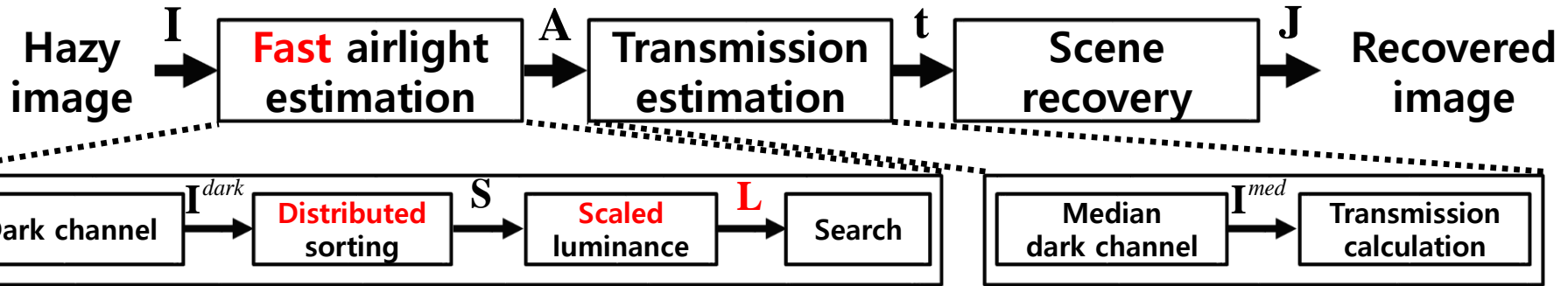


Takes **more than 50%** of total dehazing time due to **Exact sorting** of the entire pixels.

1) K. He, J. Sun, and X. Tang, "Single image haze removal using dark channel prior," IEEE Trans. Pattern Analysis & Machine Intelligence, vol. 33, no. 12, pp. 2341–2353, Dec. 2011.

PROPOSED DEHAZING SYSTEM

Fast Airlight Estimation



Distributed sorting with scaled luminance

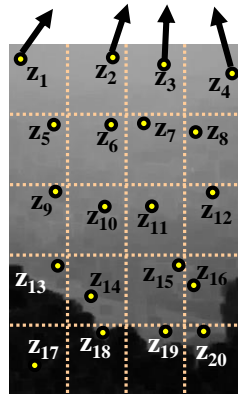
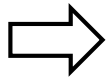
S: Brightest pixel locations in each sub-region

Airlight pixel: Brightest pixel in **L** for S

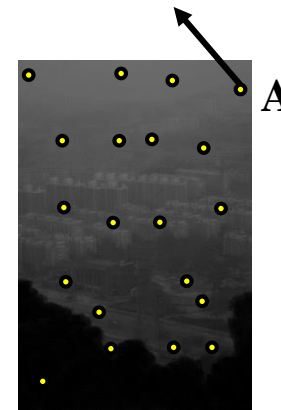
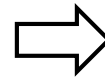


Dark channel
 I^{dark}

Distributed
sorting



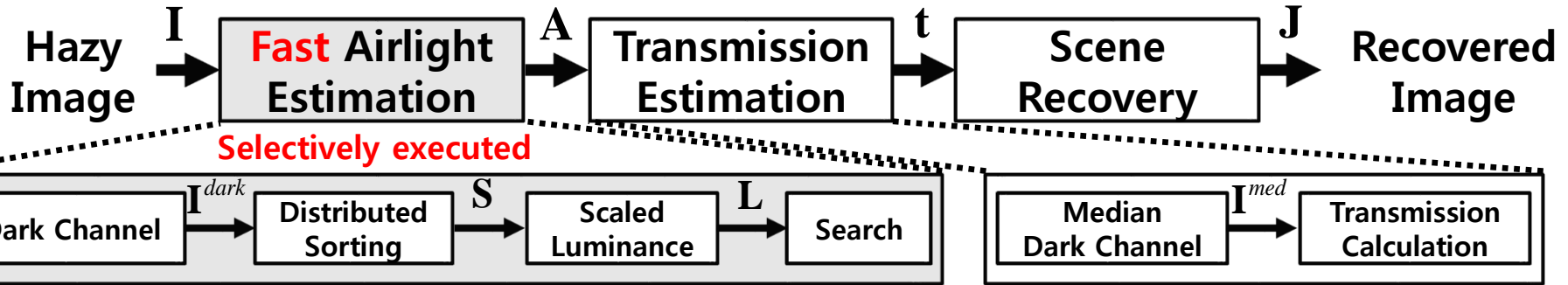
Scaled
luminance



Scaled luminance
 $L = Y \cdot I^{dark}$

PROPOSED DEHAZING SYSTEM

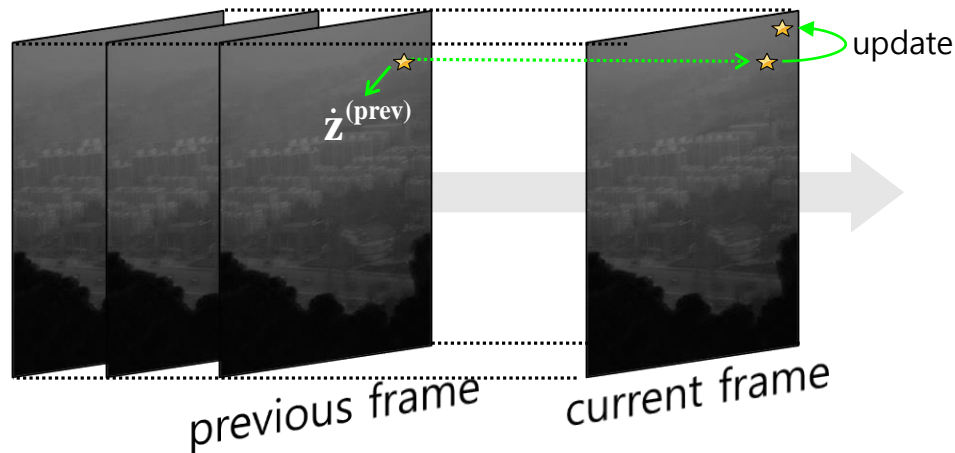
Fast Airlight Estimation



Selective Airlight Estimation

- Coherence between successive video frames is presented.

$$|L^{(prev)}(\dot{z}^{(prev)}) - L^{(current)}(\dot{z}^{(prev)})| > L_{th}$$



PROPOSED DEHAZING SYSTEM

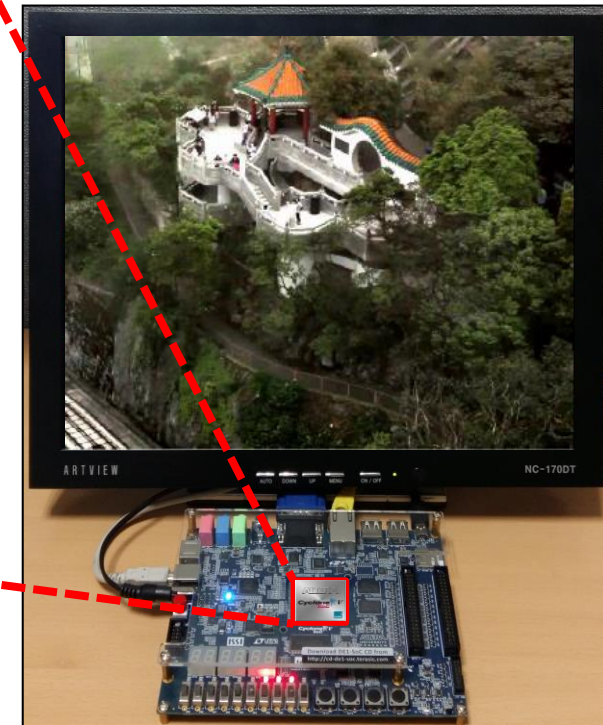
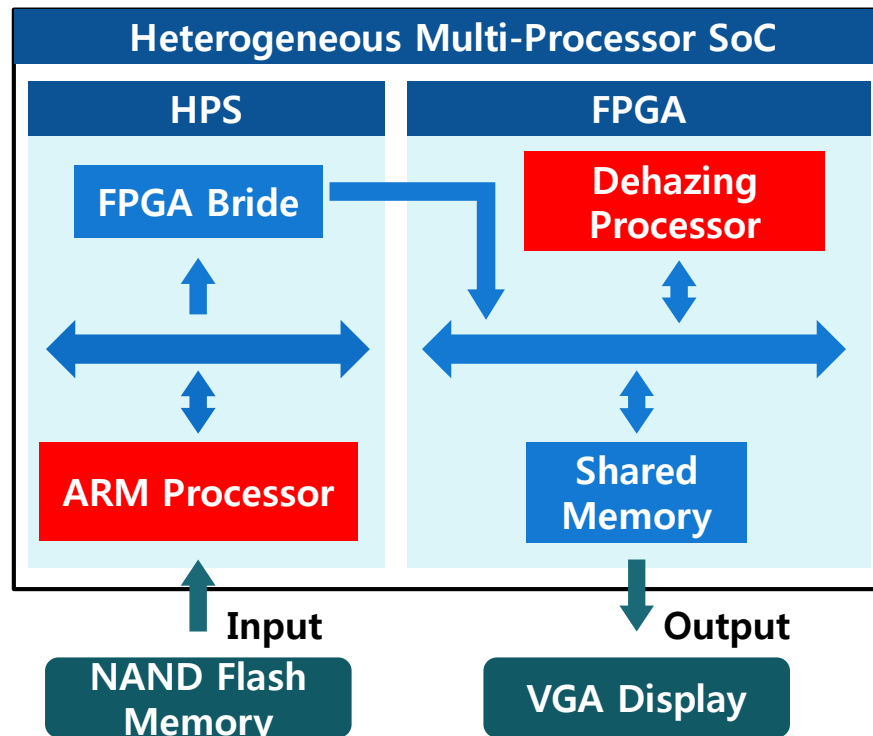
▶ Overall Architecture

▶ ARM Processor in HPS

- ▶ Control process

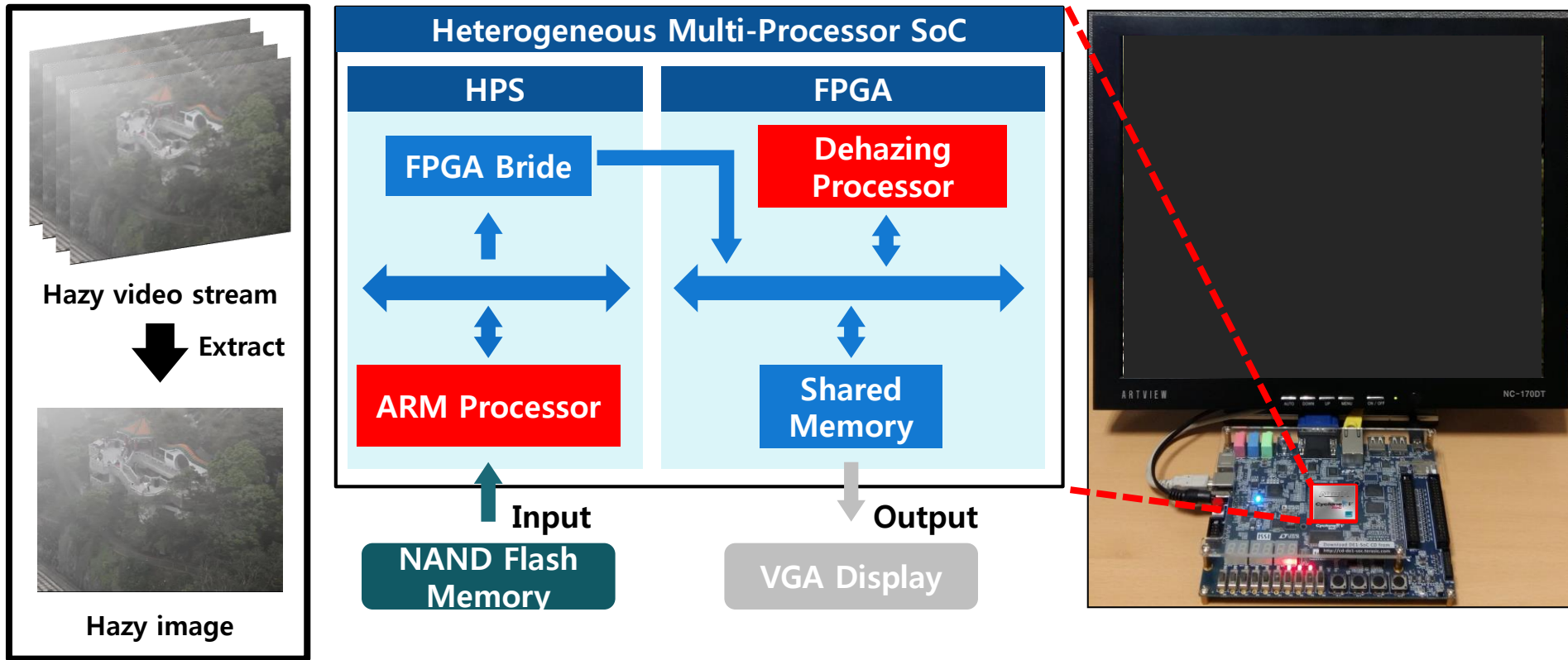
▶ Dehazing Processor in FPGA

- ▶ Overall dehazing process with fast airlight estimation



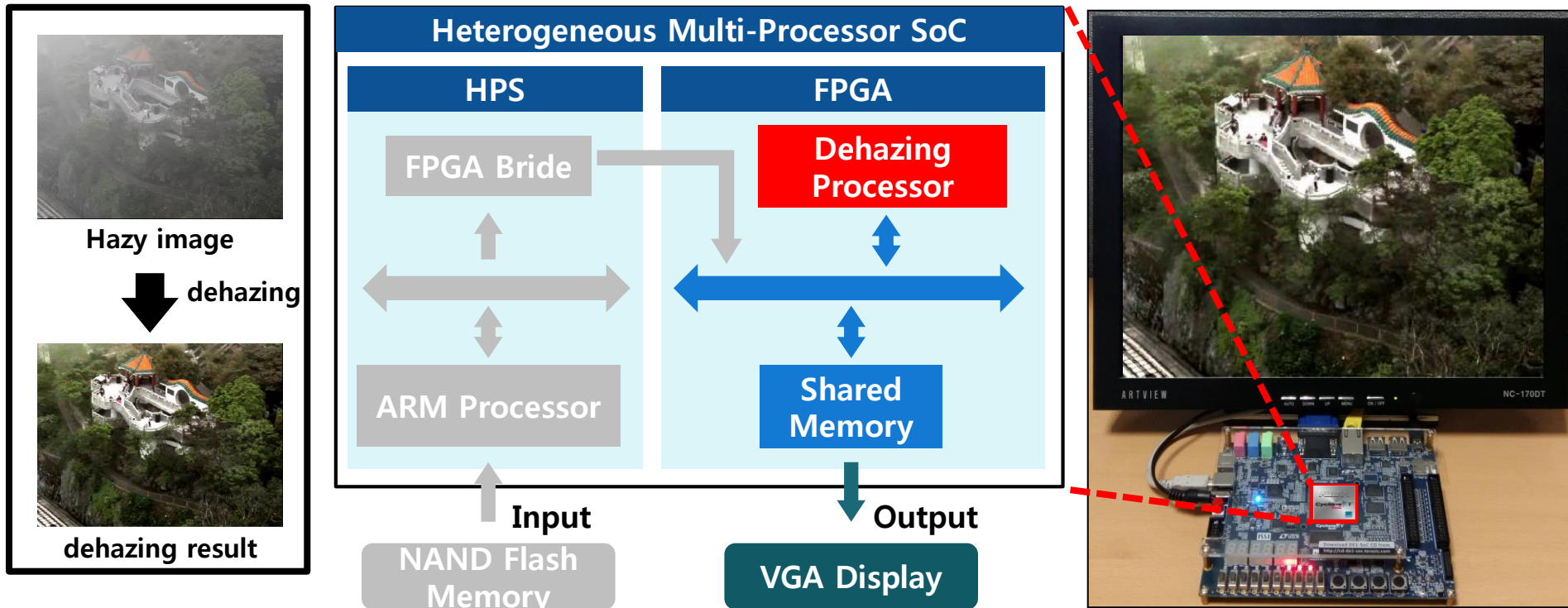
PROPOSED DEHAZING SYSTEM

- ▶ Operating mechanism
 - ▶ Read the hazy video stream from the NAND flash memory.
 - ▶ Extract a hazy image from the hazy video stream.
 - ▶ Feed it to the dehazing processor through the FPGA bridge.



PROPOSED DEHAZING SYSTEM

- ▶ Operating mechanism
 - ▶ The dehazing processor performs the overall dehazing process.
 - ▶ The dehazing result is displayed through the VGA output.

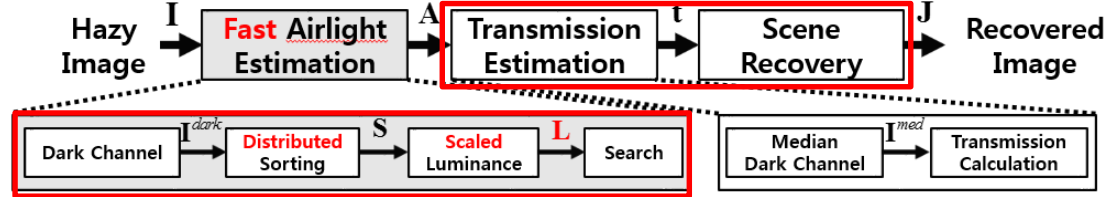


PROPOSED DEHAZING SYSTEM

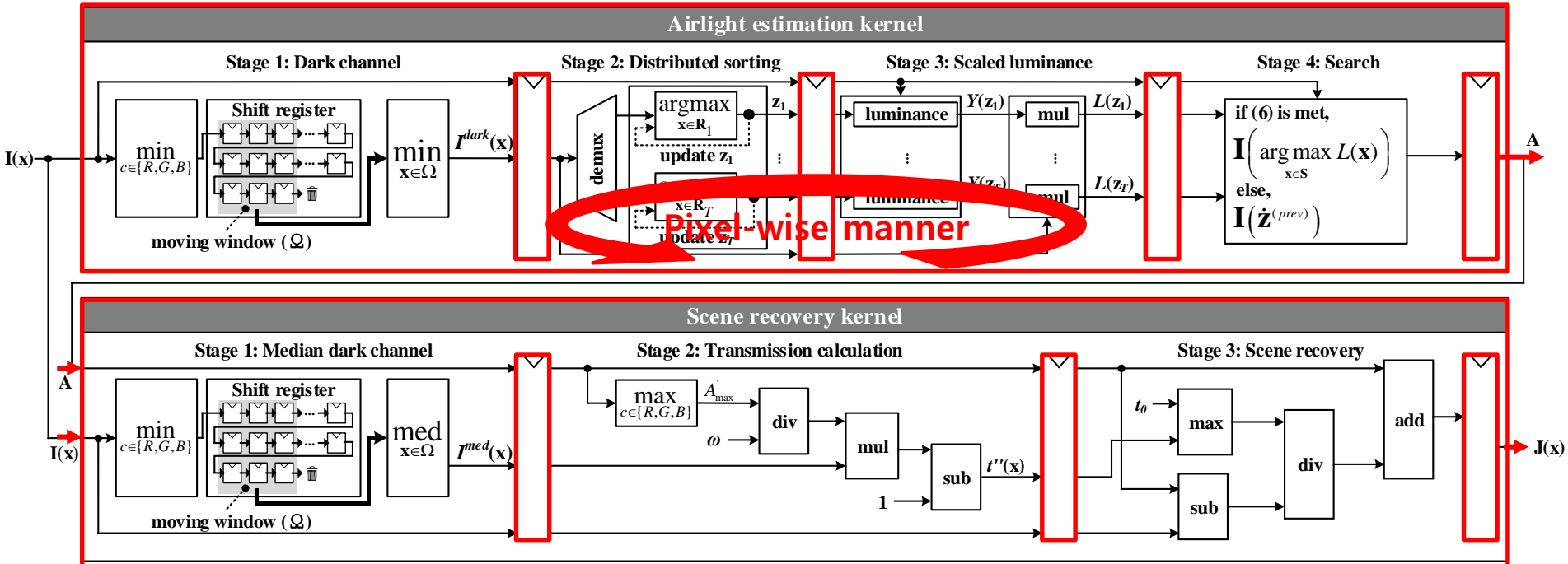
Dehazing processor

Two OpenCL kernels

- Airlight estimation kernel
- Scene recovery kernel



Pixel-wise manner

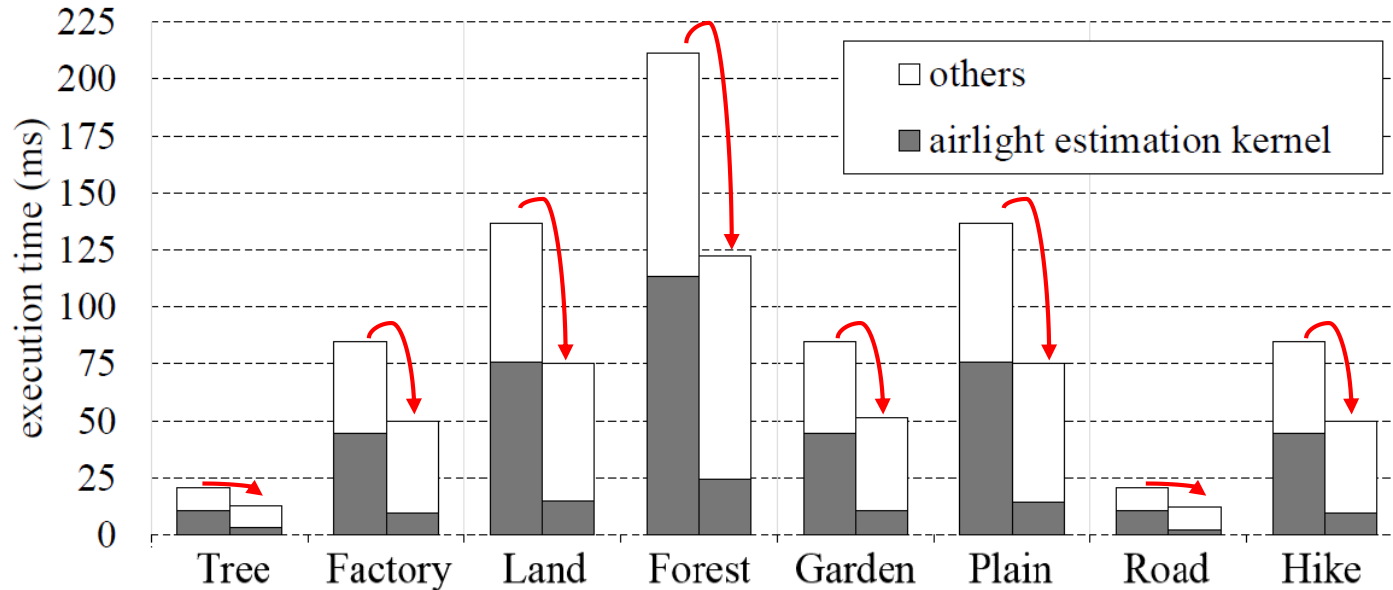


Pixel-wise manner

EVALUATION

▶ Dehazing time

40% reduction in average



▶ FPGA resource utilization

		320×240	640×480	800×600
resource utilization	ALMs	21.3k	28.2k	32.0k
	registers	43.0k	46.6k	53.4k
	DSPs	26	36	42
	memory (bits)	1.2M	2.5M	3.2M
frequency (MHz)	HPS	800	800	800
	FPGA	86.3	88.2	88.7

EVALUATION

▶ Dehazing Quality



Hazy Images

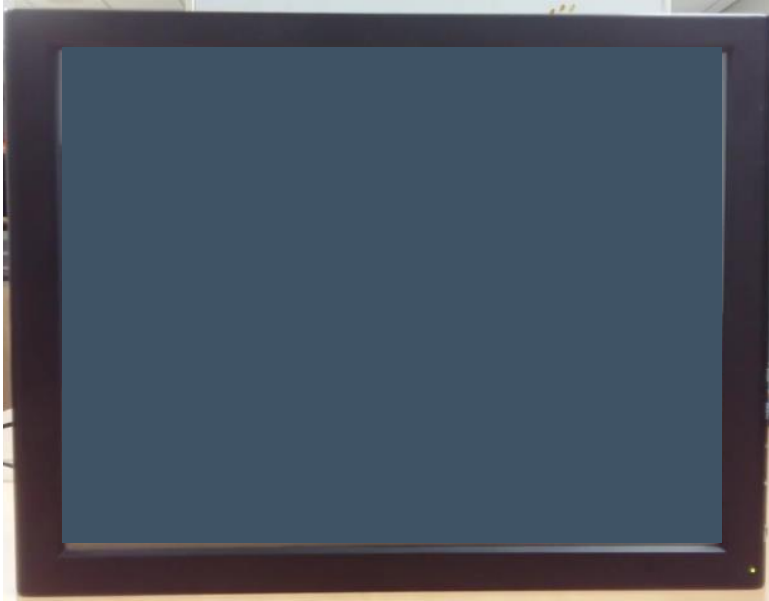
**Dehazing results
(referential)**

**Dehazing results
(proposed)**

EVALUATION

- ▶ Demo

- ▶ Hazy video stream



Real-time
dehazing

- ▶ Proposed dehazing system



CONCLUSION

- ▶ Main Contribution
 - ▶ Low-complexity dehazing method based on fast airlight estimation
 - ▶ Distributed sorting with scaled luminance
 - ▶ Selective airlight estimation
 - ▶ Efficient dehazing system based on low-complexity dehazing method
 - ▶ The overall dehazing time is reduced by 40% in average