# **DNN-BASED WIRELESS POSITIONING IN AN OUTDOOR ENVIRONMENT**



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#### Introduction Project purpose □ System overview Estimate the location of a user using RSRP\* and the locations of Feature base stations with a DNN\* structure Raw DB extraction Data extraction - RSRP - Longitude Motivation To draw a coverage map, - Drive test is labor-intensive and costly - MDT\* allows the automatic monitoring of the radio status of UE\* $\Rightarrow$ important to identify the location of the UE Raw DB DNN is successful for modeling a non-linear relationship between radio signals and the user location **Data processing** $\bowtie$ . . . . Context windowing ۲ Background □ Fingerprint-based localization Match geographical signatures to a map of previously measured signatures Training phase PCI, RSRP, ... - Create a map represented by signature vector Latitude such as **RSRP** and **PCI**\* Matching phase - Determine best matching signature by calculating Euclidean distance among the grid unit Longitude

RSRP: Reference Signal Received Power, DNN: Deep Neural Network, MDT: Minimization of Drive Tests, UE: User Equipment, RSS: Received Signal Strength, BS: Base Station, PCI: Physical Cell Id, CDF: Cumulative Distribution Function



Normalization: zero mean, unit variance

- Prevent the problem of bias to certain parameters

- Use **past** and **future** features, as well as the **current** DNN input feature



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### Experiments

#### Database setup with field measurement

- Measurement environment
  - 1800 MHz LTE bands
- Data rate
  - Raw data: 77.01 (samples/sec)
  - Data connected to three BS: 3.83 (samples/sec)
- Median distance between UE and BS
  - 105.16 (m)

#### Network structure

Training	Data measured in detail	26,061 (Samsung Galaxy S5)	
		22,297 (Samsung Galaxy S3)	
		51,511 (LG G5)	
Test	Data measured	10,875 (Samsung Galaxy S5)	
	sparsely		
Input layer		$(9 \times \text{size of context window})$ dim.	
Output layer		2 dim.	
Weight initialization		Xavier	
Activation function		ReLU	
Optimizer		Adam	
Co	ost function	MSE	



Data measured in detail (Training)



Data measured sparsely (Test)

#### **Experiment results**

- Experiment by changing the size of context window
- Experiment to compare fingerprint-based localization and DNN-based localization

Method		Average distance	Distance err.	Distance err.
		err. (m)	for 70% (m)	for 90% (m)
Fingerprint-based localization		71.04	72.14	208.50
DNN-based localization	(0+1+0)	51.70	56.37	119.73
	(1+1+1)	43.51	42.33	<b>98.97</b>
	(2+1+2)	45.09	44.17	105.47
	(3+1+3)	45.78	46.41	102.19
Performance improvement		38.75%	41.32%	52.53%



## Conclusion

- Data used in those experiments were measured in a real communication field
- The average distance error of the proposed algorithm was reduced by 27.53 m in comparison to the conventional method



(The number of connected BS)



70%