

HuMaINs: Human-Machine Inference Networks

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HuMAlNs

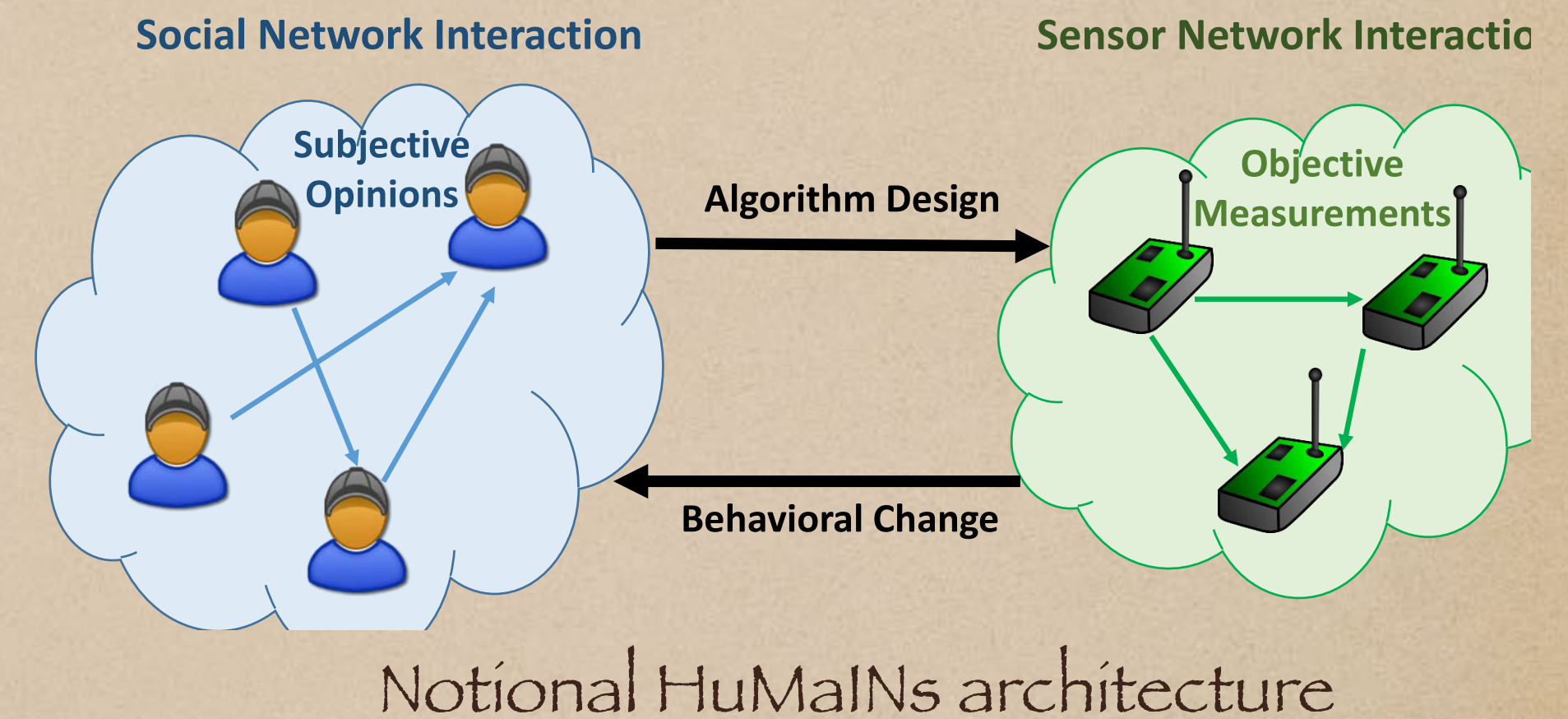
- ◆ Why?
- ◆ What?
- ◆ How?
- ◆ Where?

Motivation

- ◆ Problem solving has two steps: identify solution-space, and evaluate solutions
- ◆ **Bounded-rational** humans are cognitively limited and have limited time, information, and resources
 - ◆ Not fully aware of all possible choices
 - ◆ Sub-optimally evaluate consequences of choices
- ◆ Machines are **rational**
 - ◆ Stronger/larger memory for storing alternatives
 - ◆ Computational capability to accurately evaluate consequences
- ◆ Machines can aid humans in fast and accurate problem-solving → Human-Machine collaborative framework

Architecture

- ◆ HuMaIN = Social Network + Sensor/Machine Network
- ◆ Intelligent collaboration to exploit strengths of humans and machines
- ◆ Architecture governs interactions between agents in the networks
- ◆ Three architecture types:
 - ◆ Human controls autonomous system
 - ◆ Autonomous system monitor humans
 - ◆ Hybrid
- ◆ Relevant research problems:
 - ◆ Quantify human representation in decision-making tasks under uncertainty
 - ◆ Develop an estimator for model parameters
 - ◆ Provide common ontology for all agents to share information



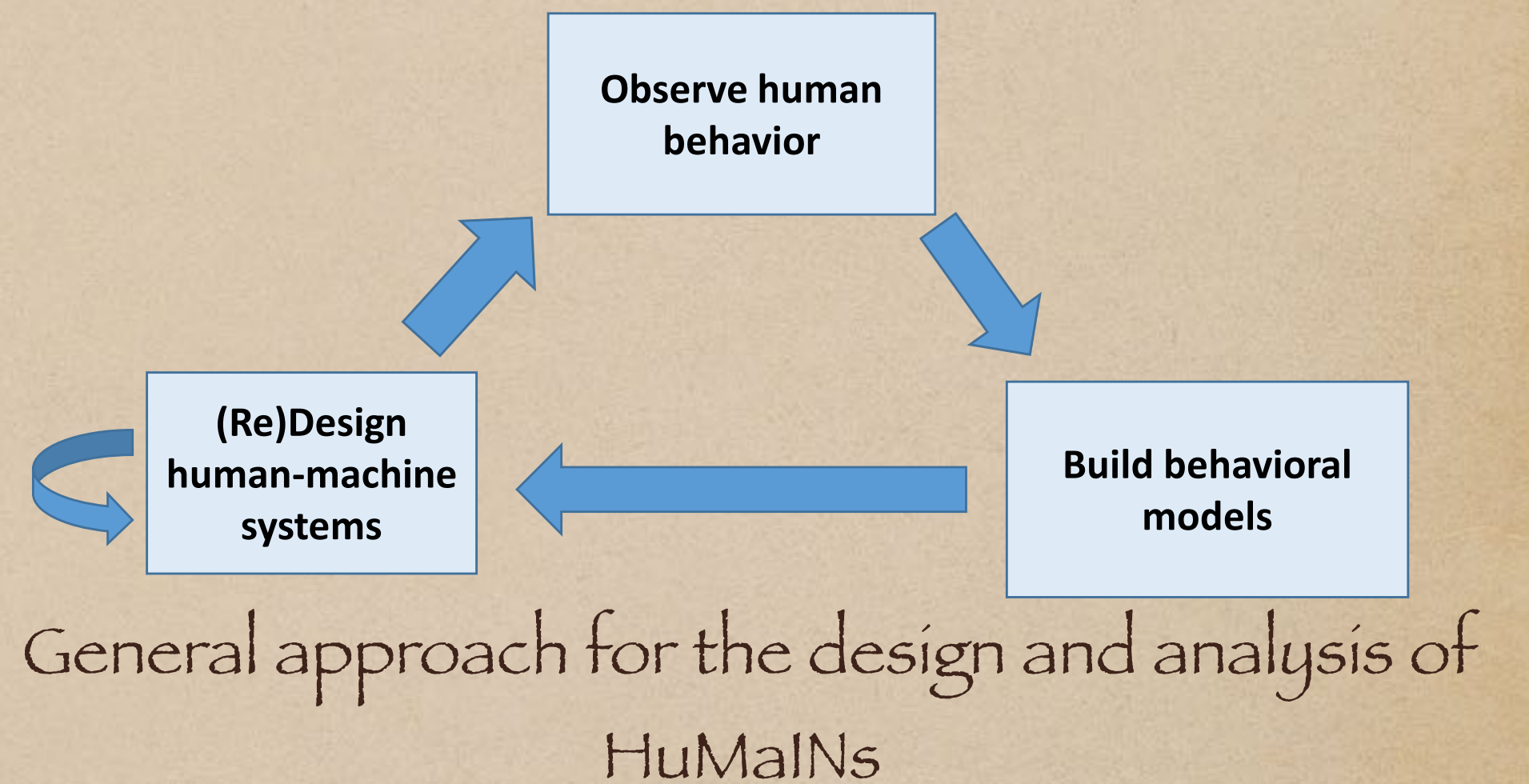
Recent Research

- ◆ W. Li, D. Sadigh, S. S. Sastry, and S. A. Seshia, "Synthesis for human-in-the-loop control systems," in TACAS2014, Apr. 2014, pp. 470–484.
- ◆ P. B. Reverdy, "Human-inspired algorithms for search: A framework for human-machine multi-armed bandit problems," Ph.D. dissertation, Princeton University, 2014.
- ◆ P. B. Reverdy, V. Srivastava, and N. E. Leonard, "Modeling human decision making in generalized Gaussian multiarmed bandits," Proceedings of the IEEE, vol. 102, iss. 4, pp. 544–571, 2014.
- ◆ P. Reverdy and N. E. Leonard, "Satisficing in Gaussian bandit problems," in IEEE 53rd Annual Conference on Decision and Control (CDC), 2014, pp. 5718–5723.

Human-in-the-loop Cyber-Physical System (HiLCPS),
Control Systems, Human-Computer Interface

Algorithms

- ◆ Development of new algorithms dealing with human behavioral data
- ◆ Collaborative integration of human expertise with automated processing
- ◆ Timely decision making and intervention
- ◆ Support but not supplant humans
- ◆ Relevant research problems:
 - ◆ Develop mathematical models of human decision making
 - ◆ Design robust fusion algorithms that handle potentially unreliable data



Recent Research

- ◆ S. Narayanan and P. G. Georgiou, "Behavioral signal processing: Deriving human behavioral informatics from speech and language," Proc. IEEE, vol. 101, no. 5, pp. 1203–1233, Feb. 2013.
- ◆ A. Vempaty, L. R. Varshney, G. J. Koop, A. H. Criss, and P. K. Varshney, "Experiments and Models for Decision Fusion by Humans in Inference Networks," IEEE Trans. Signal Process., 2018.
- ◆ A. Vempaty, L. R. Varshney, and P. K. Varshney, "Reliable crowdsourcing for multi-class labeling using coding theory," IEEE J. Sel. Topics Signal Process., vol. 8, no. 4, pp. 667–679, Aug. 2014.

Behavioral Signal Processing, Cognitive Psychology,
Mathematical Modeling, Robust Data Fusion

Applications

- ◆ Major driver of HuMaINs research
- ◆ Specific application nuances drive relevant architectural and algorithmic research
- ◆ Timely and important application areas:
 - ◆ Education
 - ◆ Autonomous Vehicles
 - ◆ Healthcare
 - ◆ Scientific Discovery

Education: Intelligent Tutoring Systems

- ◆ Provide immediate and customized instruction/ feedback to learners with teacher intervention
- ◆ Complement a human teacher
- ◆ Ensure personalized and adaptive learning at scale

ITS	HuMaIN
Domain model	Task
Student model	Human
Tutoring model	Machine/Robust fusion
User interface	Architecture

Autonomous Vehicles

- ◆ Sense and interact with physical world via sensors and actuators
- ◆ Fully autonomous makes them vulnerable to cyber-attacks
- ◆ Semi-autonomous vehicles: human-in-the-loop for safe and intelligent operation
- ◆ Require joint environment-driver state sensing, inference, and shared control and new metrics to characterize safety
- ◆ Communication among multiple self-driving cars can enable collective intelligence
- ◆ Requires design of robust communication protocols.

Healthcare

- ◆ Fully automated inference holds enormous potential to increase quality, efficacy, and efficiency of treatment and care
- ◆ Certain tasks with a small number of data sets or rare events, ML-approaches suffer from insufficient training samples
- ◆ Health decisions have serious consequences and necessitate human experts' domain knowledge
- ◆ Growing trend of litigation requires doctor-in-the-loop
- ◆ Need interpretable models that are transparent and earn experts' trust before being adopted in their workflow

Scientific Discovery

- ◆ Scientific research spans from screening of novel materials in material science, to tracking of extreme weather phenomena in climate science.
- ◆ Currently, machine role is limited to solving a well-defined task where the data and techniques are given by the scientists.
- ◆ Limits ability to tackle problems where data or task complexity itself challenge human capabilities to make discoveries.
- ◆ Advancing machine learning techniques for independent inquiry, proactive learning, and deliberative reasoning in the presence of hypotheses, domain knowledge, and insights provided by the scientists.

Session Details

- ◆ ARCHITECTURE:

- ◆ P. Reverdy and V. Srivastava, "Multi-armed bandits for human-machine decision making"

- ◆ ALGORITHMS:

- ◆ D. Seo, R. Raman, and L. R. Varshney, "Probability reweighting in social learning: Optimality and suboptimality"
- ◆ J. Rhim and V. Goyal, "Team decision making with social learning: Human subject experiments"
- ◆ S. Mourad and A. Tewfik, "Machine assisted human decision making"

- ◆ APPLICATIONS:

- ◆ R. Kokku, S. Sundararajan, P. Dey, R. Sindhgatta, S. Nitta, and B. Sengupta, "Augmenting classrooms with AI for personalized education"