

Objectives

▪ F, R convex functions over $\mathcal{X} = \mathbb{R}^d$

▪ **Problem:**

$$\min_{x \in \mathcal{X}} F(x) + R(x) \quad (1)$$

▪ ξ and ζ are random variables

▪ **Data fitting** term $F(x) = \mathbb{E}_{\xi}(f(x, \xi))$

▪ **Regularization** term $R(x) = \mathbb{E}_{\zeta}(r(x, \zeta))$

Example: Overlapping Group Regularizations

Structured sparsity:

$$F(x) = \sum_{i=1}^N f_i(x) \quad (2)$$

cost function associated with SVM or logistic regression

▪ \mathcal{G} is a set of **possibly overlapping** subsets of $\{1, \dots, d\}$

$$R(x) = \sum_{g \in \mathcal{G}} r_g(x) \quad (3)$$

▪ $\forall g \in \mathcal{G}$, $x|_g$ is the restriction of vector x to g (e.g if $g = 1, 2, 4$ then $x = (x_1, x_2, x_4)$)

▪ $r_g(x) = \|x|_g\|_1$

Douglas Rachford Algorithm

Proximal methods for solving (1) are known for numerical stability. Proximity operator

$$\text{prox}_{\gamma R}(x) = \arg \min_{y \in \mathcal{X}} \frac{1}{2\gamma} \|x - y\|^2 + R(y), \quad \gamma > 0$$

Standard method: Douglas-Rachford

$$\begin{aligned} y_{n+1} &= \text{prox}_{\gamma F}(x_n) \\ z_{n+1} &= \text{prox}_{\gamma R}(2y_{n+1} - x_n) \\ x_{n+1} &= x_n + z_{n+1} - y_{n+1} \end{aligned} \quad (4)$$

Theorem ([1]): $y_n \xrightarrow{n \rightarrow +\infty} \arg \min F + R$

▪ Related to ADMM

▪ Converges with a constant step $\gamma > 0$

▪ Splitting method

More splitting?

Sometimes we need more splitting for both F and R .

▪ In adaptive signal processing/online learning, F is unknown but revealed through i.i.d realizations of ξ

▪ Even if F is known, $\text{prox}_{\gamma F}$ is often intractable (e.g (2))

▪ In many cases (e.g (3)), $\text{prox}_{\gamma R}$ is also intractable

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Stochastic Douglas Rachford Algorithm

Takes advantage of the numerical stability without the iteration complexity.

$$\begin{aligned} y_{n+1} &= \text{prox}_{\gamma f(\cdot, \xi_{n+1})}(x_n^\gamma) \\ z_{n+1} &= \text{prox}_{\gamma r(\cdot, \zeta_{n+1})}(2y_{n+1} - x_n^\gamma) \\ x_{n+1}^\gamma &= x_n^\gamma + z_{n+1} - y_{n+1} \end{aligned} \quad (5)$$

where

▪ (ξ_n) (resp. (ζ_n)) are i.i.d copies of ξ (resp. ζ)

▪ Constant step $\gamma > 0$

The random functions $f(\cdot, \xi_{n+1})$ (resp. $r(\cdot, \zeta_{n+1})$) can be much simpler than F (resp. R), see (2)-(3) ([2]).

Dynamical Behavior

Constant step $\gamma > 0$: No a.s convergence. Stochastic approximation technique [3]:

$$x_\gamma(t) = x_n^\gamma + (t - n\gamma) \frac{x_{n+1}^\gamma - x_n^\gamma}{\gamma}, \quad (6)$$

where $n > 0$, $n\gamma \leq t < (n+1)\gamma$.

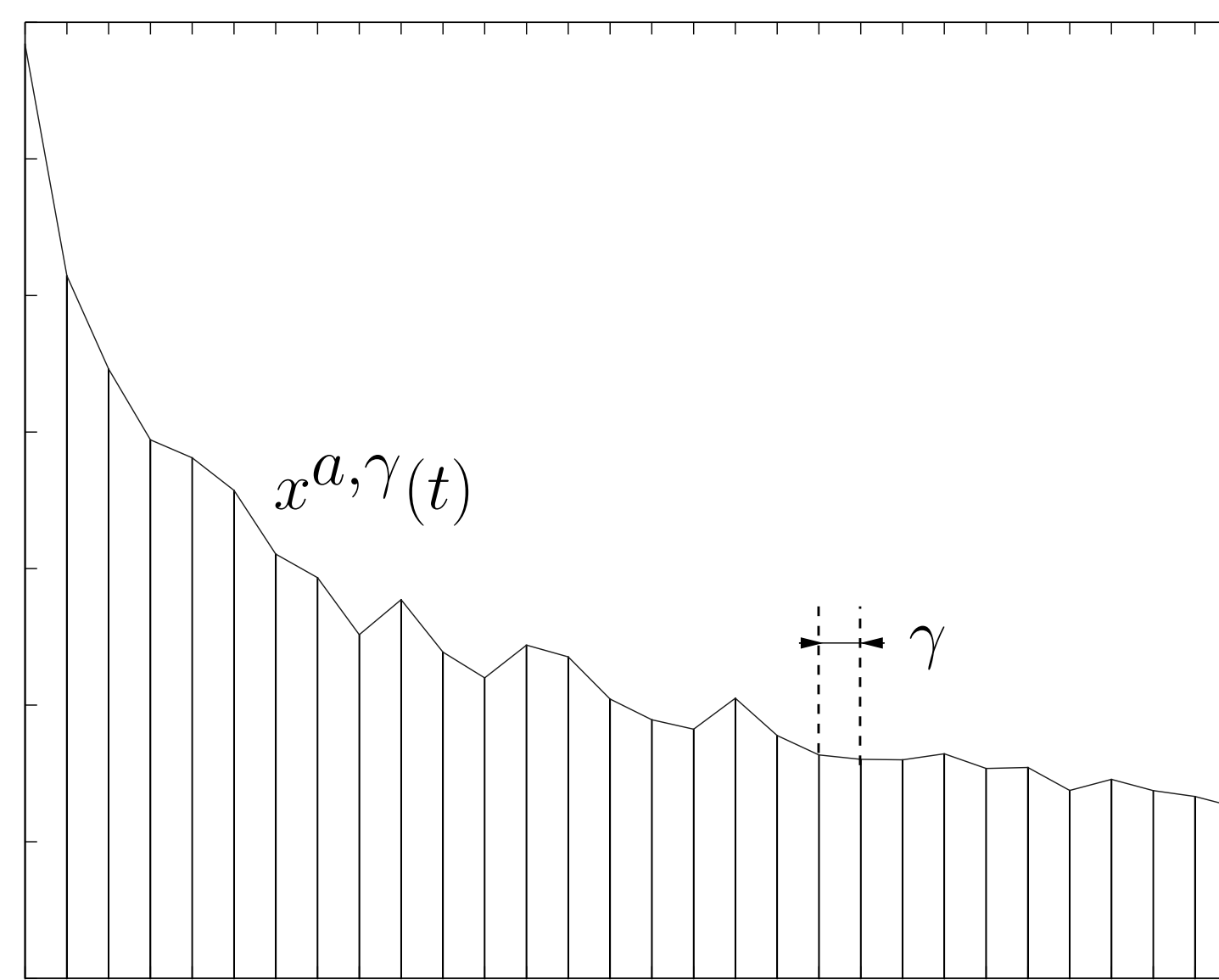


Figure 1: The linearly interpolated process of order γ : x_γ

Theorem

Under mild assumptions,

$$x_\gamma \xrightarrow{\gamma \rightarrow 0} x,$$

weakly where x satisfies the Differential Inclusion ([4])

$$\dot{x}(t) \in \nabla F(x(t)) + \partial R(x(t)), \quad t \geq 0.$$

Long-run behavior

Known fact :

$$x(t) \xrightarrow{t \rightarrow +\infty} \arg \min F + R$$

We would like x_γ to "inherit" this property. OK under stability of the Markov chain (x_n^γ) .

Theorem

Assume moreover

- $F(x) + R(x) \xrightarrow{\|x\| \rightarrow +\infty} +\infty$
- $\nabla f(\cdot, \xi)$ is Lipschitz continuous.

Then, for every $\varepsilon > 0$,

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n \mathbb{P}(d(x_k^\gamma, \arg \min(F + R)) > \varepsilon) \xrightarrow{\gamma \rightarrow 0} 0.$$

Return to the Overlapping Group Lasso

Two Douglas Rachford strategies to solve the problem defined by (1)–(3).

First, Partially Stochastic Douglas Rachford

① Sample $i_{n+1} \sim U(\{1, \dots, N\})$

② Compute $\text{prox}_{\gamma f_{i_{n+1}}}$ using [2]

③ Compute $\text{prox}_{\gamma R}$ using [5]

Second, Stochastic Douglas Rachford

① Sample $i_{n+1} \sim U(\{1, \dots, N\})$

② Sample $g_{n+1} \sim U(\mathcal{G})$

③ Compute $\text{prox}_{\gamma f_{i_{n+1}}}$ using [2]

④ Compute $\text{prox}_{\gamma r_{g_{n+1}}}$ (easy, soft thresholding)

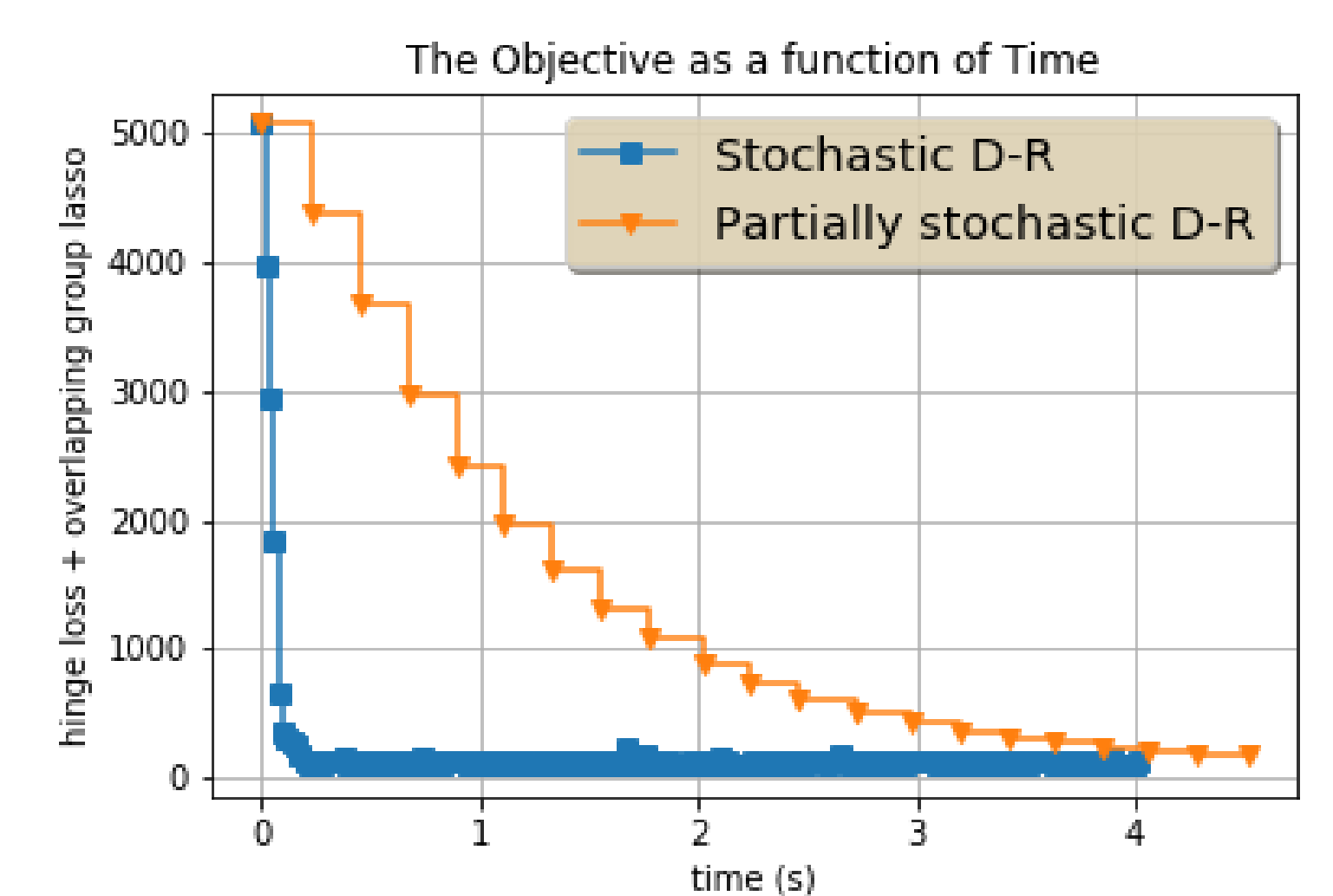


Figure 2: $F + R$ as a function of time for the Stochastic Douglas Rachford and the Partially Stochastic Douglas Rachford algorithms

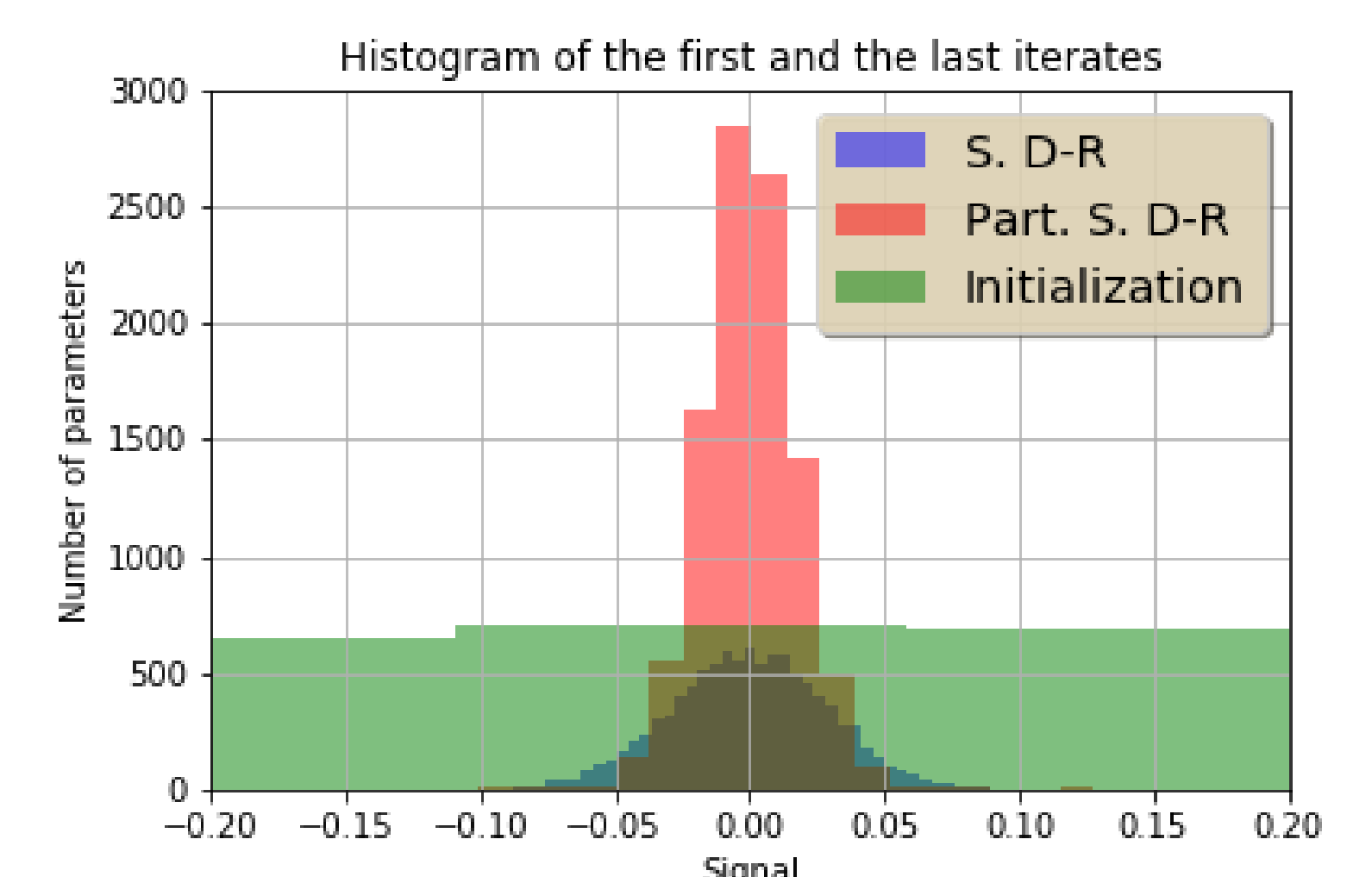


Figure 3: Histogram of the initialization and the last iterates of the two algorithms

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