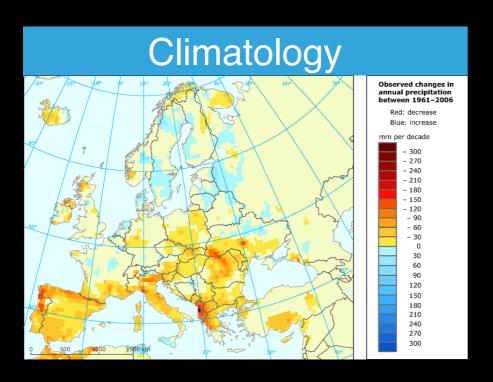
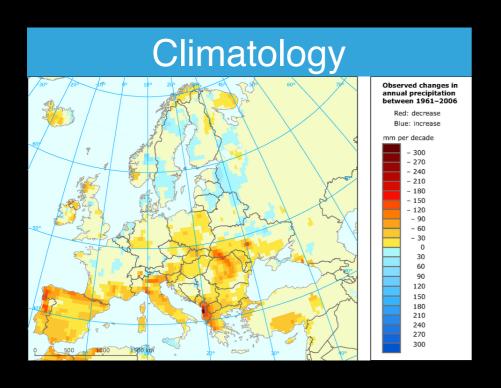
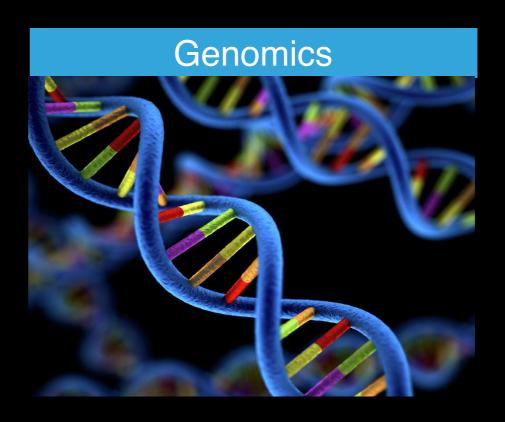
Subspace Clustering with Missing and Corrupted Data

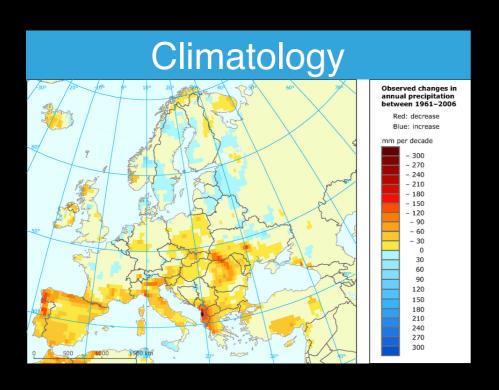
Zachary Charles (UW-Madison)

Joint with Amin Jalali and Rebecca Willett (UW-Madison)



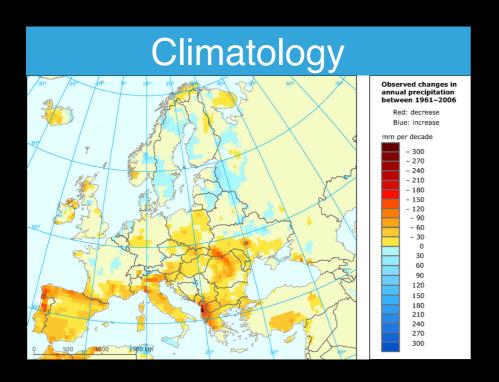










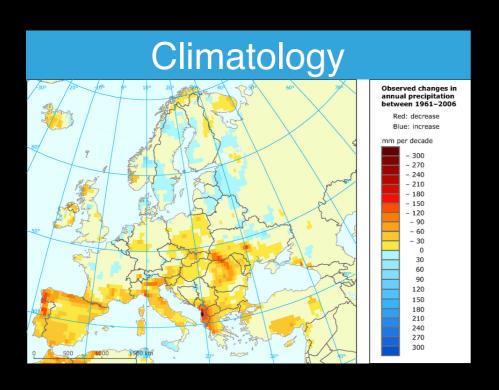






Recommender systems

amazon









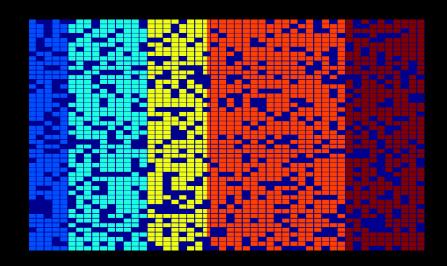
How do we remove noise and fill in missing values?

We assume the data is inherently low rank.

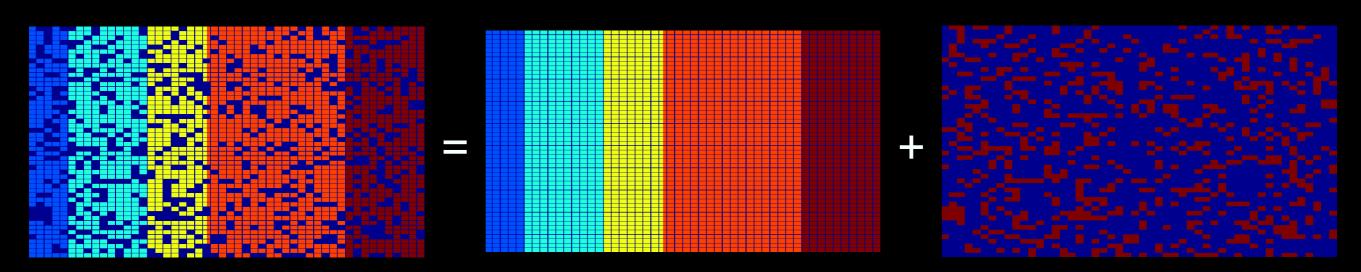
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http://perception.csl.illinois.edu/matrix-rank/home.html

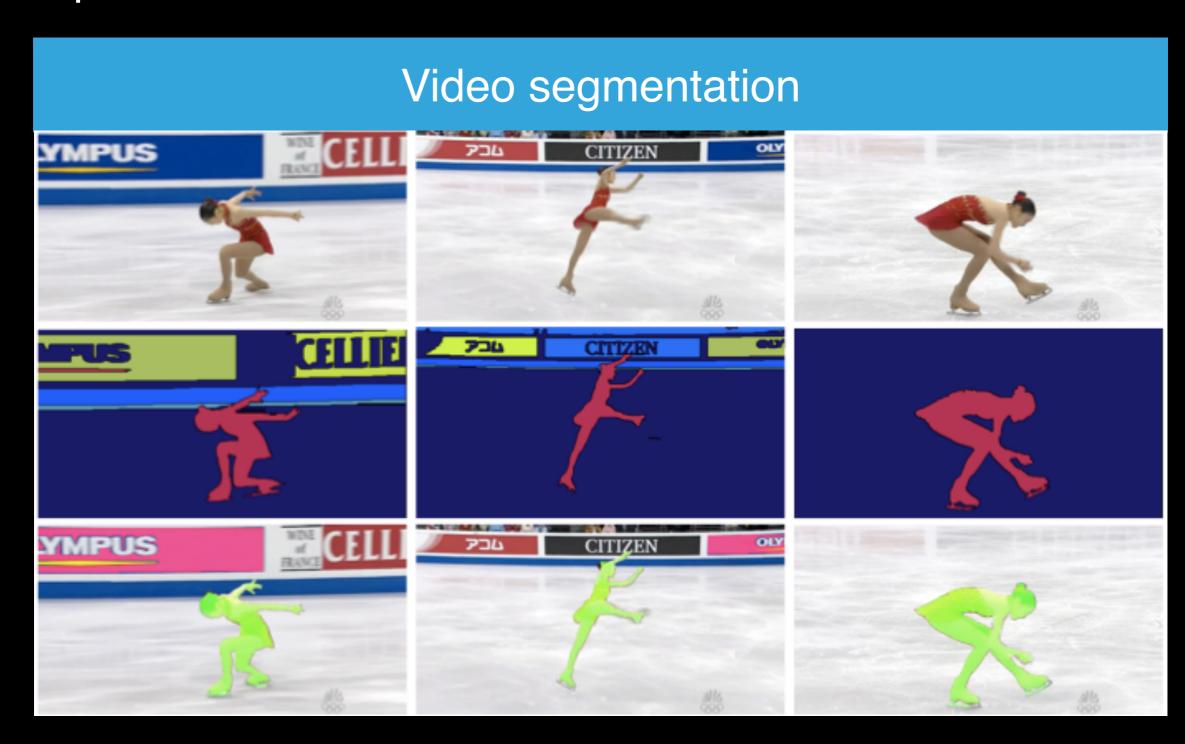
Issue: Most data is not low rank.

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New problem: Subspace clustering

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- Prior work focused on the amount of noise this can tolerate.
- Success criteria: no false positives.

Main results

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	δ	M
Wang, Xu	O(1/d)	$O(n/d^2)^*$
C., Jalali, Willett	$O(1/\sqrt{d})$	O(n/d)

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 - Randomly zeroing out entries = projecting on to random axis-aligned subspaces.
 - Apply Johnson-Lindenstrauss style results.

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By avoiding projection, we can better measure the affinity between the corrupted and the true subspaces.

$$\min_{c} \|c\|_1 + \frac{\lambda}{2} \|Xc - x_i\|_2^2$$

▶ LS-SSC can be used location agnostically.

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Open problems:

- How do we guarantee clustering accuracy?
- Information-theoretic limits?
- What about unions of low-dimensional non-linear spaces?

Fin.