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# What matters the most? Optimal Quick Classification of Urban Issue Reports by Importance

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## **Motivation**

- Civic engagement platforms
  - enable citizens to participate in collecting, analyzing and sharing knowledge about their local environments (e.g., measure air quality [Dutta2009])
  - interact with local governments to resolve urban issues, such as potholes and noise complaints (e.g. SeeClickFix [Mergel2012])



 Reported issues should be timely processed and addressed to maintain citizens' satisfaction with local governments





# **Related Work**



- Prior work
  - ignores citizens' implicit endorsement of urban issues that are "important" to them (e.g., [Budde2014])
  - requires large-scale annotation to achieve good accuracy (e.g., [Hirokawa2017])
  - relies on fixed set of features (e.g., [Budde2014], [Hirokawa2017])
  - ignores scalability and timeliness (e.g., [Budde2014], [Hirokawa2017])



- Currently, reported issues are acknowledged and assessed by a city official for routing to appropriate agency
  - We propose to classify importance of urban issues <u>as fast</u> <u>as possible without sacrificing accuracy</u> using optimal subset of features in an <u>online fashion</u>





## **Problem Formulation**

- Each urban issue *i* consists of
  - Title
  - Description
  - Address
  - Timestamp
  - Photo(s)
  - Comment(s)
  - Vote(s)

igstarrow feature vector  $\mathbf{f}_i = [f_1, f_2, \dots, f_K]^T$ 



• Urban issue importance: # of votes and comments received

extract

- Feature cost  $c_n > 0, n \in \{1, \dots, K\}$
- Misclassification costs  $M_{kj} \ge 0, k \in \{\mathcal{H}, \mathcal{L}\}, j \in \{1, \dots, L\}$  with L decision choices

#### **Optimization Problem**

• Goal: minimize number of features used for inferring importance of an issue without sacrificing accuracy



## **Optimal Classification Strategy**

• Rewrite the objective function using  $\pi_n$ 

$$J(R, D_R) = \mathbb{E}\left\{\sum_{n=1}^R c_n + \sum_{j=1}^L \left(M_{\mathcal{H}j}\pi_R + M_{\mathcal{L}j}(1-\pi_R)\right) \mathbf{1}_{\{D_R=j\}}\right\}$$
  
a posteriori probability

• Optimal classification strategy

$$D_R^{optimal} = \arg\min_{1 \le j \le L} \left[ M_{\mathcal{H}j} \pi_R + M_{\mathcal{L}j} (1 - \pi_R) \right]$$

Results to the smallest average cost

$$\widetilde{J}(R) \triangleq J(R, D_R^{optimal}) = \mathbb{E}\left\{\sum_{n=1}^R c_n + g(\pi_R)\right\}$$
  
where  $g(\pi_R) \triangleq \min_{1 \leq j \leq L} \left[M_{\mathcal{H}j}\pi_R + M_{\mathcal{L}j}(1-\pi_R)\right]$ 



 $\pi_n \triangleq P(H_{\mathcal{H}}|f_1,\ldots,f_n)$ 

## **Optimal Stopping Strategy**



• Optimal stopping strategy via dynamic programming

Last stage

$$\bar{J}_K(\pi_K) = g(\pi_K)$$

Any intermediate stage

$$\bar{J}_n(\pi_n) = \min \left[ g(\pi_n), c_{n+1} + \sum_{f_{n+1}} A_n(f_{n+1}) \bar{J}_{n+1} \left( \frac{p(f_{n+1}|H_{\mathcal{H}})\pi_n}{A_n(f_{n+1})} \right) \right]$$
Optimal cost-to-go
Cost of continuing

where 
$$A_n(f_{n+1}) \triangleq \pi_n p(f_{n+1}|H_{\mathcal{H}}) + (1-\pi_n)p(f_{n+1}|H_{\mathcal{L}})$$



## **ClvIC:** <u>Classify urban Issues into Importance Categories</u>



## **Case Study: The SeeClickFix Platform**

- Dataset
  - 2, 195 SeeClickFix issues
  - Metropolitan area surrounding Albany, NY
  - Jan 5, 2010 and Feb 10, 2018



- Features extracted from issues' title, description, address, and reported time
  - E.g., tokenized unigrams, logarithm of the number of words +1, exclamation marks +1, uppercase letters +1
- **Discretized importance** based on predefined thresholds
  - $H_{\mathcal{H}}$  if number of votes  $V > \bar{V}$  and number of comments  $C > \bar{C}$
  - Otherwise it belongs to  $H_{\mathcal{L}}$
- To verify robustness, we considered 4 scenarios of varying thresholds  $\, ar{V} \,$  and  $\, ar{C} \,$



- Baselines
  - Bayesian detection method that uses all features
  - Feature selection method: SVM–FS [Hirokawa2017]
  - Dimensionality Reduction method: SVM–PCA
  - Kernel based method: SVM classifier
  - Tree based classifiers: Random forest and XG-boosting



- ClvIC achieves same error probability as Bayesian detection with all features using only **104 out of 2594 features** on average
- On average **96% reduction** in the number of **features** used



#### Results

Method	Accuracy	Precision	Recall	Avg. # feat.
<b>CIvIC</b> $(c = 0.25)$	0.794	0.785	0.818	1.05
<b>CIvIC</b> $(c = 10^{-1})$	0.811	0.789	0.854	1.29
<b>CIVIC</b> ( $c = 10^{-2}$ )	0.814	0.783	0.873	4.19
<b>CIvIC</b> $(c = 10^{-3})$	0.833	0.801	0.889	104.10
<b>CIvIC</b> $(c = 10^{-4})$	0.830	0.807	0.870	189.78
<b>CIVIC</b> ( $c = 10^{-5}$ )	0.832	0.811	0.867	244.99
<b>CIvIC</b> ( $c = 10^{-6}$ )	0.835	0.819	0.864	289.59
$\mathbf{CIvIC} \ (c = 0)$	0.835	0.819	0.864	350.34
<b>Bayesian Detection</b>	0.833	0.819	0.860	<b>2,594</b>
SVM-FS	0.746	0.701	0.810	20
SVM-linear	0.806	0.801	0.815	2,594
SVM-Gaussian	0.796	0.739	0.916	<b>2,594</b>
SVM-PCA	0.825	0.791	0.886	208
<b>RF</b> (depth= $5$ )	0.815	0.779	0.883	2,594
<b>RF</b> (depth=10)	0.820	0.784	0.886	2,594
XG Boosting	0.827	0.801	0.873	2,594

 ClvIC uses on average 104 and 289 features and achieves same highest accuracy (83.3%) and precision (81.9%) as Bayesian detection with all features (i.e., 96% and 88.8% reduction)

 SVM–Gauss achieves highest recall (91.6%), but 25 times as many features for a mere 3% improvement compared to ClvIC

### **Contributions & Future Directions**

- Contributions
  - Optimal stopping theory framework to dynamically infer importance of incoming urban requests
  - Near-real-time algorithm that implements optimal solution
- Future directions
  - Extend framework to enable multi–valued importance recognition
  - Devise appropriate learning—to—rank approaches to dynamically order incoming urban issues requests
- Questions?

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