

Non-negative TD regularization with an augmented Lagrangian

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1 Motivation

- Nonuniform sampling and interpolation of spectral envelopes for speech signals by temporal decomposition.
- Non-negative matrix factorization (NMF) applies naturally to difference event vectors and functions in TD.
- TD constraints: line spectral frequency (LSF) ordering in event vectors and monotonic event functions.

2 Goals

- Third constraint: Event function complementarity.
- Inclusion of third constraint in NMF starting from penalty condition.

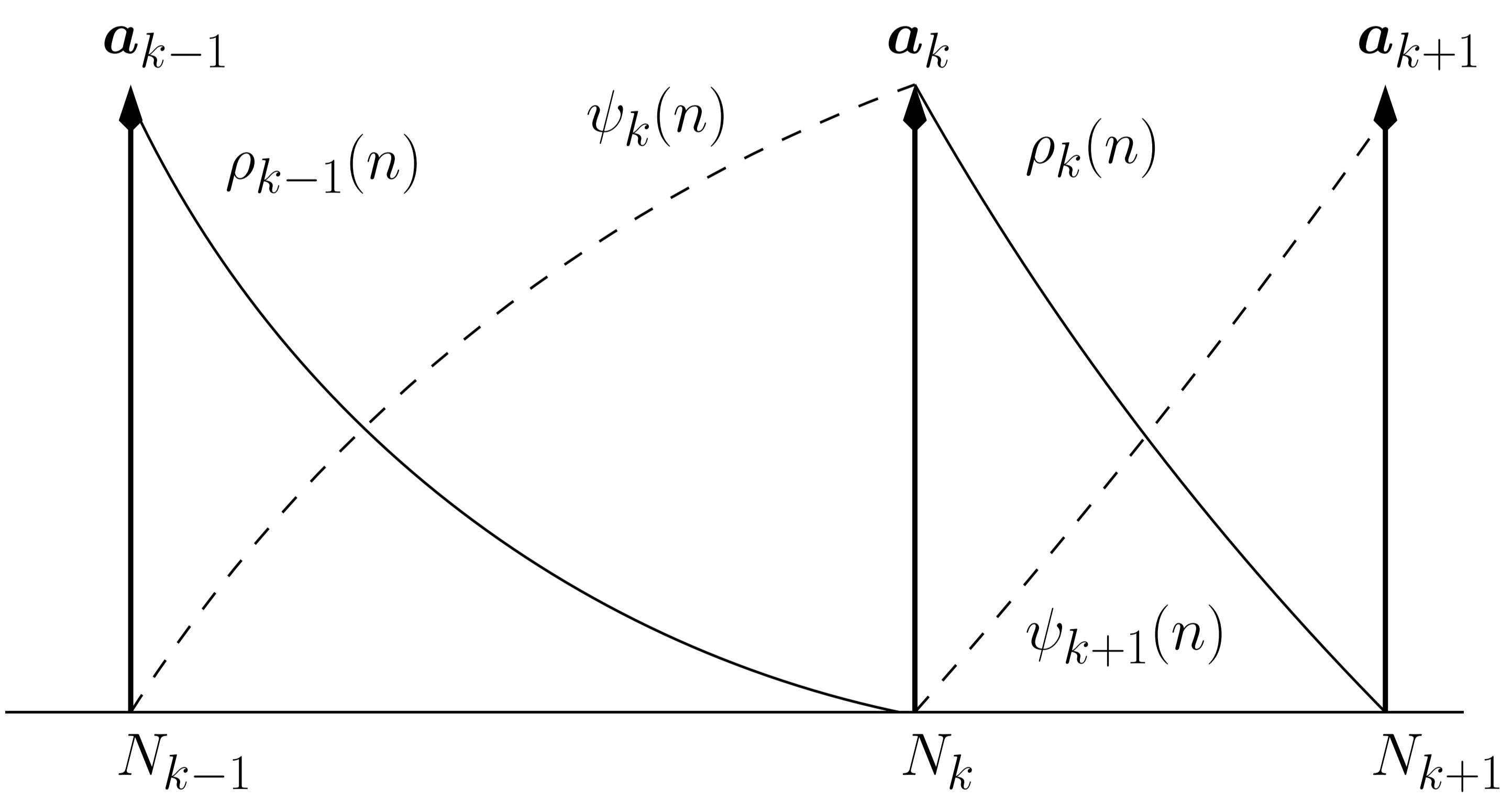
3 Temporal decomposition (TD)

$$\hat{\mathbf{Y}} = \mathbf{A}\Phi \quad (1)$$

$$\hat{y}_i(n) = a_{i,k-1}\phi_{k-1}(n) + a_{i,k}\phi_k(n) \quad (3)$$

$$\hat{y}_i(n) = a_{i,k-1}\rho_{k-1}(n) + a_{i,k}\psi_k(n) \quad (4)$$

4 Temporal decomposition in adjacent superframes



5 Model fitting stages

1. Event locations N_k and the number of events K are determined. Triangular interpolation spectral measure (TRISM) is used.
2. Half event functions $\rho_{k-1}(n)$ and $\psi_k(n)$ and right event vector a_k are determined minimizing cost function.

6 Cost functions and augmented Lagrangian

$$J_0 = \sum_{n=N_{k-1}}^{N_k} \sum_{i=1}^p [y_i(n) - a_{i,k-1}\rho_{k-1}(n) - a_{i,k}\psi_k(n)]^2 \quad (6)$$

$$J_1 = J_0 + \sum_{n=N_k+1}^{N_{k+1}} \sum_{i=1}^p [y_i(n) - a_{i,k}\rho_k(n) - a_{i,k+1}\psi_{k+1}(n)]^2$$

$$J = J_1 + \frac{\mu}{2} \sum_{n=N_{k-1}}^{N_k} [\rho_{k-1}(n) + \psi_k(n) - 1]^2 \\ + \sum_{n=N_{k-1}}^{N_k} \lambda_n [\rho_{k-1}(n) + \psi_k(n) - 1] \quad (17)$$

7 Non-negative difference LSF event vector

$$d_{i,k} = \begin{cases} a_{i,k} & \text{if } i = 1 \\ a_{i,k} - a_{i-1,k} & \text{if } 1 < i \leq p. \end{cases} \quad (12)$$

8 Non-negative difference half event functions

$$\delta_{k-1}(n) = \begin{cases} \rho_{k-1}(n) & \text{if } n = N_k \\ \rho_{k-1}(n) - \rho_{k-1}(n+1) & \text{if } N_{k-1} \leq n < N_k \end{cases}$$
$$\gamma_k(n) = \begin{cases} \psi_k(n) & \text{if } n = N_{k-1} \\ \psi_k(n) - \psi_k(n-1) & \text{if } N_{k-1} < n \leq N_k. \end{cases} \quad (13)$$

9 Update rule for Lagrange multipliers

$$0 = \nabla J_1 + \sum_{n=N_{k-1}}^{N_k} \underbrace{[\lambda_n + \mu [\rho_{k-1}(n) + \psi_k(n) - 1]]}_{\mu} \nabla [\rho_{k-1}(n) + \psi_k(n) - 1] \quad (18)$$

$$\lambda_n \leftarrow \frac{\mu}{\lambda_n + \mu [\rho_{k-1}(n) + \psi_k(n)]} \lambda_n. \quad (20)$$

10 Update rules for difference event functions and event vector

$$\delta_{k-1}(n) \leftarrow \frac{\sum_{m=N_{k-1}}^n [2 \sum_{i=1}^p a_{i,k-1} y_i(m) + \mu]}{\sum_{m=N_{k-1}}^n \{2 \sum_{i=1}^p [a_{i,k-1} a_{i,k} \psi_k(m) + a_{i,k-1}^2 \rho_{k-1}(m)] + \mu [\rho_{k-1}(m) + \psi_k(m)] + \lambda_m\}} \delta_{k-1}(n) \quad (21)$$

$$\gamma_k(n) \leftarrow \frac{\sum_{m=n}^{N_k} [2 \sum_{i=1}^p a_{i,k} y_i(m) + \mu]}{\sum_{m=n}^{N_k} \{2 \sum_{i=1}^p [a_{i,k-1} a_{i,k} \rho_{k-1}(m) + a_{i,k}^2 \psi_k(m)] + \mu [\rho_{k-1}(m) + \psi_k(m)] + \lambda_m\}} \gamma_k(n) \quad (21)$$

$$d_{i,k} \leftarrow \frac{2 \left\{ \sum_{n=N_{k-1}}^{N_k} \sum_{j=i}^p \psi_k(n) y_j(n) + \sum_{n=N_k+1}^{N_{k+1}} \sum_{j=i}^p \rho_k(n) y_j(n) \right\}}{2 \left\{ \sum_{n=N_{k-1}}^{N_k} \sum_{j=i}^p [a_{j,k-1} \rho_{k-1}(n) \psi_k(n) + a_{j,k} \psi_k^2(n)] + \sum_{n=N_k+1}^{N_{k+1}} \sum_{j=i}^p [a_{j,k+1} \rho_k(n) \psi_{k+1}(n) + a_{j,k} \rho_k^2(n)] \right\}} d_{i,k} \quad (15)$$

11 Experimental setup

- 210 speech signals from TIMIT test partition
- Spectrogram: TANDEM-STRAIGHT at 200 frame/s
- LSF vector generation: Wiener-Khinchin theorem and Linear Predictive analysis of order $p = 16$
- Event rate: 12.32 ev/s

12 Performance of non-negative TD (NTD) with several regularizations.

Method	SD (dB)	μ_c ($\times 10^{-3}$)	c_{\min} ($\times 10^{-3}$)	c_{\max} ($\times 10^{-3}$)	e_m (%)	e_o (%)
(ρ, ψ, a)	1.15	0.225	-170.8	185.1	0.27	0.012
(ρ, ψ, d)	1.28	0.219	-173.3	184.1	0.26	0
(δ, γ, a)	1.22	0.222	-118.8	107.5	0	0.012
(δ, γ, d)	1.35	0.231	-120.7	107.8	0	0
(ρ, ψ, a, λ)	1.34	-2.77	-6.69	0	0	0.012
(ρ, ψ, d, λ)	1.49	-2.76	-6.69	0	0	0
$(\delta, \gamma, d, \lambda)$	1.49	-0.502	-6.42	4.22	0	0

- SD: mean log spectral distortion
- ordering error at k if, for any i , $a_{i,k} - a_{i-1,k} \leq 0$
- e_o : percentage of event vectors with ordering errors
- monotonicity error at k if ρ_{k-1} or ψ_k nonmonotonic
- e_m : percentage of frames with monotonicity error
- complementarity deviation: $c(n) = \rho(n) + \psi(n) - 1$
- μ_c : mean value of complementarity deviation
- c_{\min} : minimum complementarity deviation
- c_{\max} : maximum complementarity deviation

13 Conclusion

Baseline • Difference LSF event vectors provide stable synthesis filters.

- Non-negative difference event functions make event functions monotonic.
- Regularization of event function complementarity includes a quadratic penalty term as previous NMF TD.

Proposed • Smoother TANDEM-STRAIGHT spectral envelopes improve NMF for TD of speech.

- Adaptive regularization of event function complementarity by means of a linear term;
- linear term adjustable by Laplace multipliers (LMs);
- multiplicative rule updates LMs.

Result • This approach has eliminated ordering and monotonicity errors and greatly reduced the amplitude of complementarity errors.

14 Thanks

