

# PARAMETER ESTIMATION FROM HETEROGENEOUS/MULTIMODAL DATA SETS



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## Introduction

**Goal: fusion of non-linear estimators**

Example: measure precipitation from both wireless telecom [Messer2015] and rain gauges.

⇒ **We propose to study linear weighting of Maximum Likelihood (ML) estimators.**

**Problem:**

- find optimal weights
- for non-linear data model, the **optimal weights depend on the parameters** to be estimated

**Our approach:**

- derive heuristic weights from the optimal ones
- improve them iteratively

**Results:**

- proposition of optimal, heuristic weights
- conditions for heuristic weights to improve performance with respect to individual estimators

## Heterogeneous sensor networks

**Assumptions and notations:**

•  $\theta = (\theta_1, \dots, \theta_P)^t$  to be estimated from  $D$  data sets,

$$\mathbf{x}_i = \mathbf{s}_i(\theta) + \mathbf{n}_i, i = 1, \dots, D.$$

of size  $N_i$ ,  $N_i \geq P$ .  $\mathbf{n}_i$  follows  $\mathcal{N}(\mathbf{0}, \sigma_i^2 I_{N_i})$ .

•  $\mathbf{x}_i \Rightarrow$  ML estimator  $\hat{\theta}_i$  with covariance  $\text{Cov}(\hat{\theta}_i) \rightarrow$  FIM:  $F_i^{-1}(\theta) = \frac{1}{\sigma_i^2} G_i(\theta) G_i(\theta)^t = \frac{N_i}{\sigma_i^2} \tilde{F}_i^{-1}(\theta)$  asymptotically.

**Problem setting:**

We are looking for  $\alpha_i \geq 0$ ,  $\sum_{i=1}^D \alpha_i = 1$ ,

$$\hat{\theta}_\alpha = \sum_{i=1}^D \alpha_i \hat{\theta}_i$$

minimizing the asymptotical variance of  $\hat{\theta}_\alpha$ .

## Optimal weights for linear fusion

**Proposition 1** The weights minimizing  $\text{var}_\infty(\hat{\theta}_\alpha)$  are

$$\alpha_i^*(\theta) = \frac{1}{\sum_{j=1}^{D-1} \frac{\rho_i \lambda_i^*(\theta)}{\rho_j \lambda_j^*(\theta)} + \rho_i \lambda_i^*(\theta)}, i = 1, \dots, D-1 \quad (1)$$

with  $\lambda_i^*(\theta) = \frac{\text{tr}(\tilde{F}_i^{-1}(\theta))}{\text{tr}(\tilde{F}_D^{-1}(\theta))}$  and  $\rho_i = \frac{\sigma_i^2}{\sigma_D^2} \frac{N_D}{N_i}$ .

Unfortunately,  $\alpha^*(\theta)$  depend on the unknown  $\theta!$ <sup>a</sup>

For  $D = 2$ ,  $\alpha_1^*(\theta) = \frac{1}{1 + \rho_1 \lambda_1^*(\theta)} \in [\frac{1}{1 + \rho_1 \lambda_{\max}(\theta)}, \frac{1}{1 + \rho_1 \lambda_{\min}(\theta)}]$  where  $\lambda_{\min/\max}(\theta)$  are eigenvalues of  $\mathcal{F}(\theta) = \tilde{F}_2^{1/2}(\theta) \tilde{F}_1^{-1}(\theta) \tilde{F}_2^{1/2}(\theta)$ .

**Trends:**  $\rho_1 \gg 1 \Rightarrow \hat{\theta}_{\alpha^*} \approx \hat{\theta}_2$ ;  $\rho_1 \ll 1 \Rightarrow \hat{\theta}_{\alpha^*} \approx \hat{\theta}_1$ .

<sup>a</sup>Proof: in "Parameter estimation from heterogeneous/multimodal data sets", I. Fijalkow, E. Heiman, H. Messer, to appear in IEEE Signal Processing Letters, 2016.

## Proposed sub-optimal weights

We follow the "indication" of  $\rho_i \Rightarrow$  we propose the heuristic:

$$\alpha_i^h = \frac{1}{\sum_{j=1}^{D-1} \frac{\rho_i}{\rho_j} + \rho_i} \text{ for } i = 1, \dots, D-1$$

and  $\alpha_D^h = 1 - \sum_{i=1}^{D-1} \alpha_i^h = \frac{1}{1 + \sum_{i=1}^{D-1} \rho_i}$ .

## Conditions for improved performance

For  $D = 2$ , we know  $\text{var}(\hat{\theta}_{\alpha^*(\theta)}) \leq \text{var}(\hat{\theta}_{\alpha^h})$  and

$$\text{tr}((F_1(\theta) + F_2(\theta))^{-1}) \leq \text{var}(\hat{\theta}_{\alpha^*(\theta)}) \leq \text{var}(\hat{\theta}_i)$$

**Proposition 2** Asymptotically,  $\text{var}(\hat{\theta}_{\alpha^h}) \leq \text{var}(\hat{\theta}_i)$ , iff  $\frac{1}{2+\rho} \leq \lambda^*(\theta) \leq 2 + \frac{1}{\rho}$ .

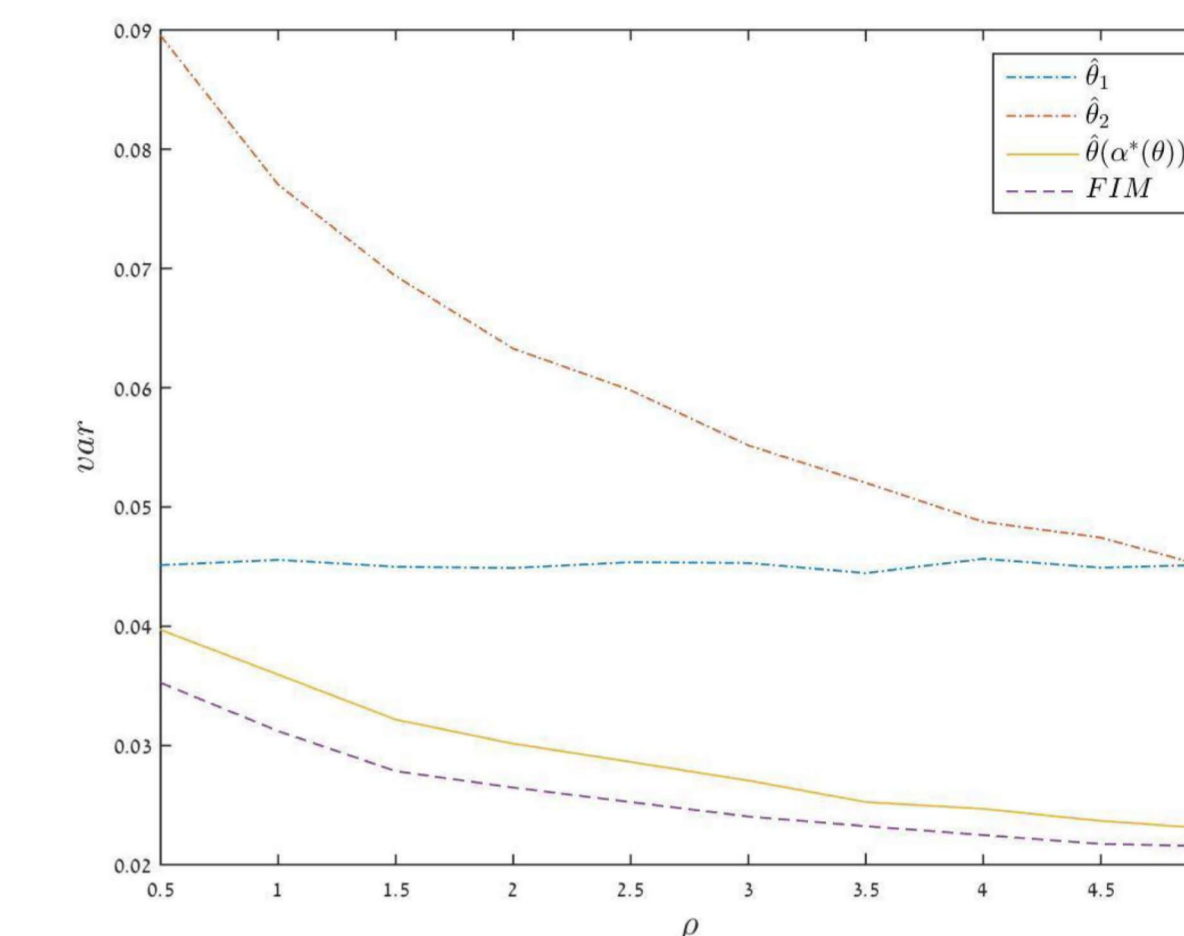
⇒ when  $1/2 \leq \lambda^*(\theta) \leq 2$ ,  $\hat{\theta}_{\alpha^h}$  overcomes  $\hat{\theta}_i$ .

## Numerical illustration

**Simulation settings satisfying Proposition 2 conditions:**  $P = 2$

- data set 1: linear,  $N_1 = 2$ ,  $\sigma_1 = 0.05$  and  $\text{tr}(F_1^{-1}) = 2$
- data set 2:  $\mathbf{s}_2(\theta) = H_2(\sin(\theta_1) + \sin(\theta_2), \cos(\theta_1) + \cos(\theta_2))^t$ ,  $\sigma_2 = 0.05$ ,  $N_2$  varies

Variance of  $\hat{\theta}_1, \hat{\theta}_2, \hat{\theta}(\alpha^*(\theta))$  and  $\text{tr}(\text{FIM})$  v.s  $\rho$ ,  $\theta = (\pi/4, \pi/8)^t$ :



**When Proposition 2 conditions are not satisfied:**

$N_2 = 2 \Rightarrow$  for  $\theta \approx (0, \pi/2)^t$   $\alpha^*(\theta) \approx 1$  whereas  $\alpha^h \approx 1/3$ :

⇒ **We want to approach  $\alpha^h$  numerically.**

## Numerical computation of weights

**Proposed iterative algorithm:**

- **Initialization:**  $\lambda_i^{(0)} = 1$  (implying  $\alpha^{(0)} = \alpha^h$ )

- **Iteration k:**

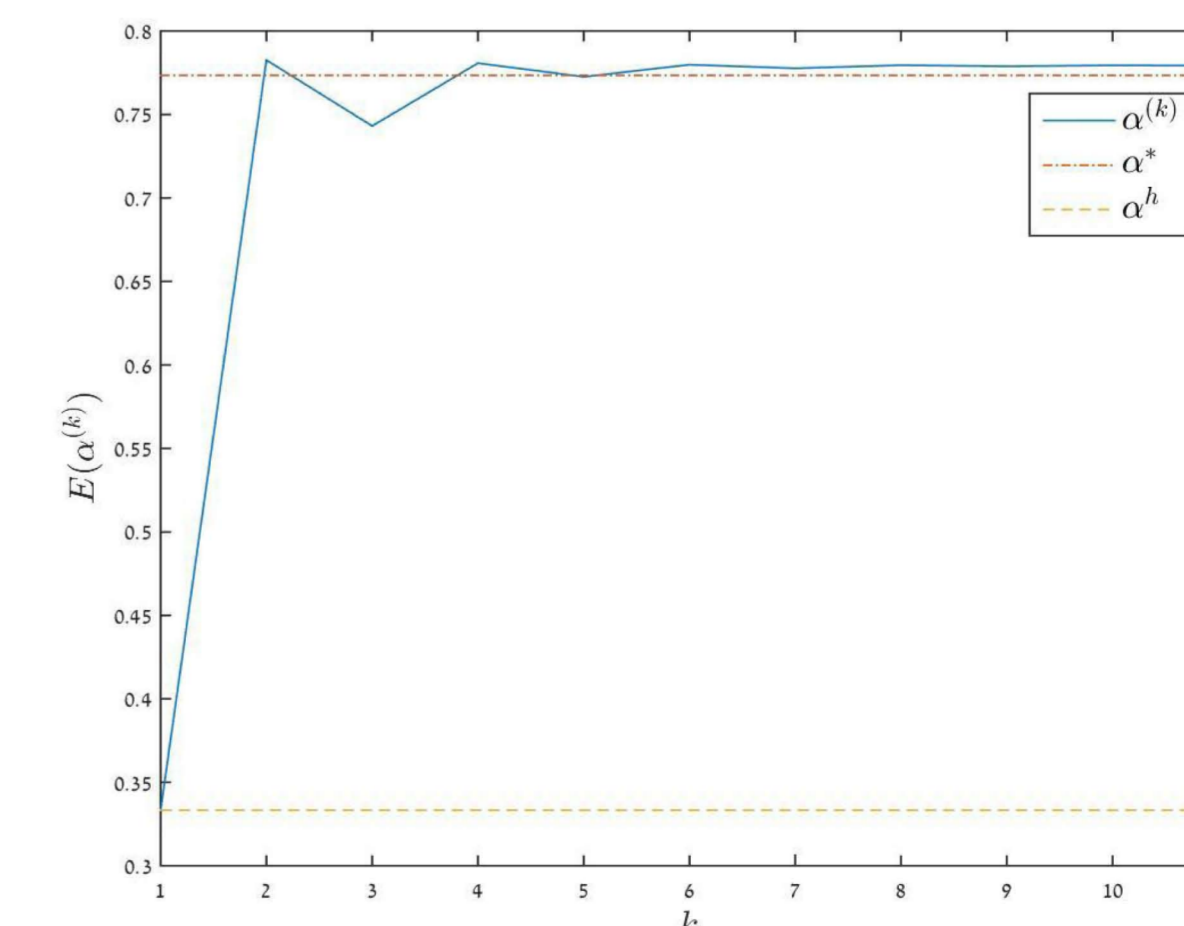
$$\alpha_i^{(k)} = 1 / (\sum_{j=1}^{D-1} \frac{\rho_i \lambda_j^{(k)}}{\rho_j \lambda_j^{(k)}} + \rho_i \lambda_i^{(k)}), i = 1, \dots, D-1$$

$$\hat{\theta}^{(k)} = \sum_{i=1}^{D-1} \alpha_i^{(k)} \hat{\theta}_i + (1 - \sum_{i=1}^{D-1} \alpha_i^{(k)}) \hat{\theta}_D$$

$$\lambda_i^{(k+1)} = \frac{\text{tr}(\tilde{F}_i^{-1}(\hat{\theta}^{(k)}))}{\text{tr}(\tilde{F}_D^{-1}(\hat{\theta}^{(k)}))}$$

- **Repeat until**  $|\lambda_i^{(k+1)} - \lambda_i^{(k)}| \leq \epsilon$ .

$\theta = (0, \pi/8)^t$ ,  $\rho = 2$ ,  $\rightarrow \alpha^h = 1/3$ ,  $\alpha^* = 0.7735$ .  $E[\alpha^{(k)}]$  vs  $k$ :



Convergence of proposed fixed point algorithm depends on non-linear functions  $\text{tr}(\tilde{F}_i^{-1}(\cdot))$ .