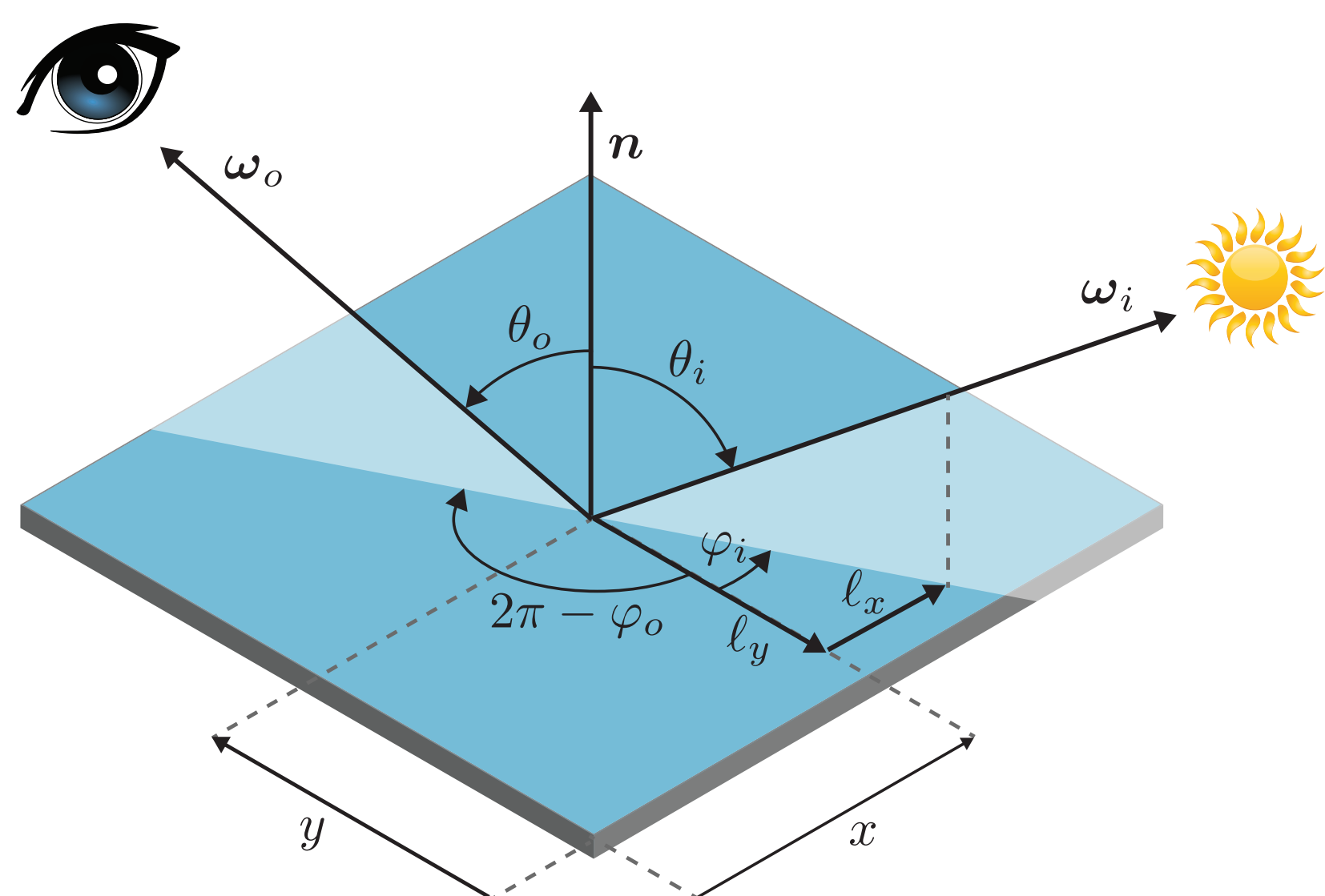


## Problem statement

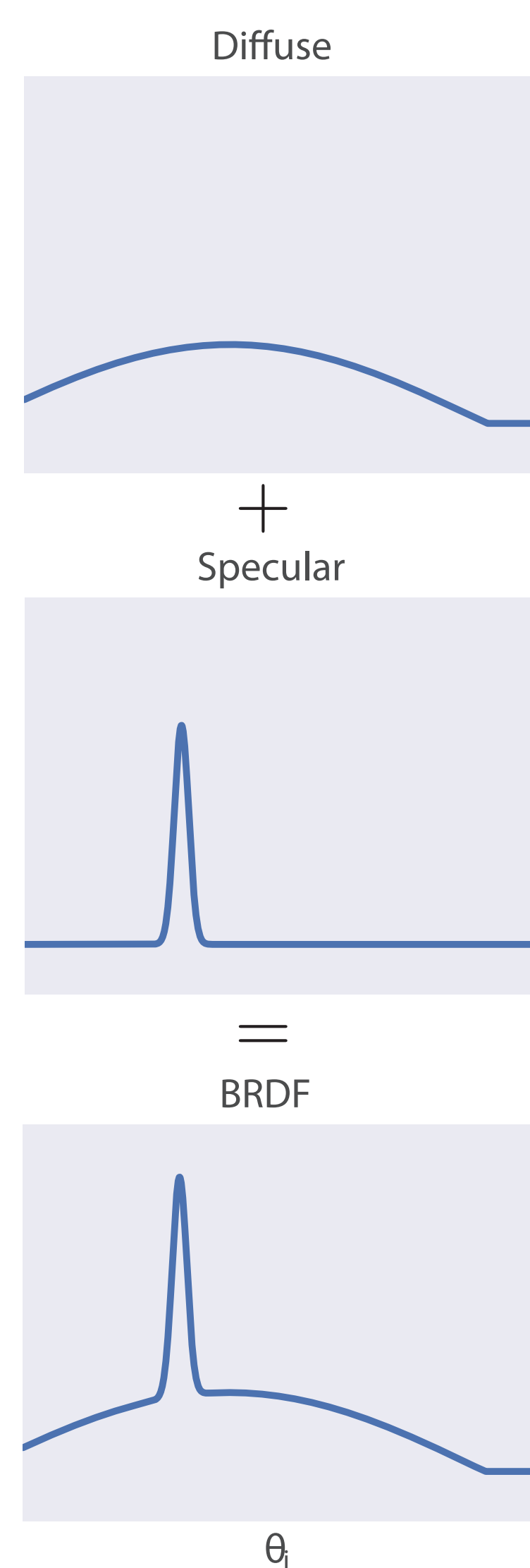
Acquire the specularity of reflectance functions with a few samples

## Background

Bidirectional Reflectance Distribution Function (BRDF):  $\rho(\omega_o, \omega_i)$ 

Symbol	Notation
$\omega_i = (\theta_i, \varphi_i)$	Incident light angle
$\omega_o = (\theta_o, \varphi_o)$	Viewing angle
$n$	Surface normal vector
$L_i(\omega)$	Incoming light at angle $\omega$
$L_o(\omega)$	Light reflected at angle $\omega$
$(l_x, l_y)$	Projection of $\omega_i$ onto the xy plane

## BRDF shape



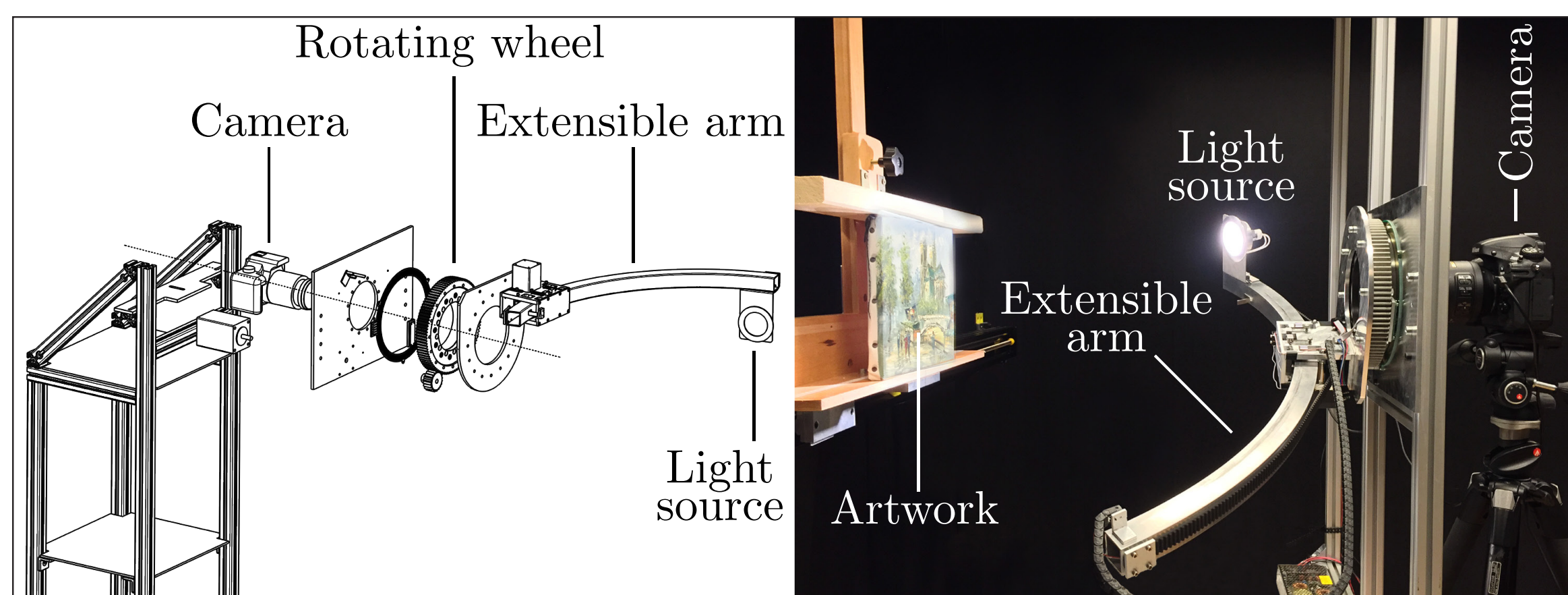
## BRDF acquisition

Reflection equation

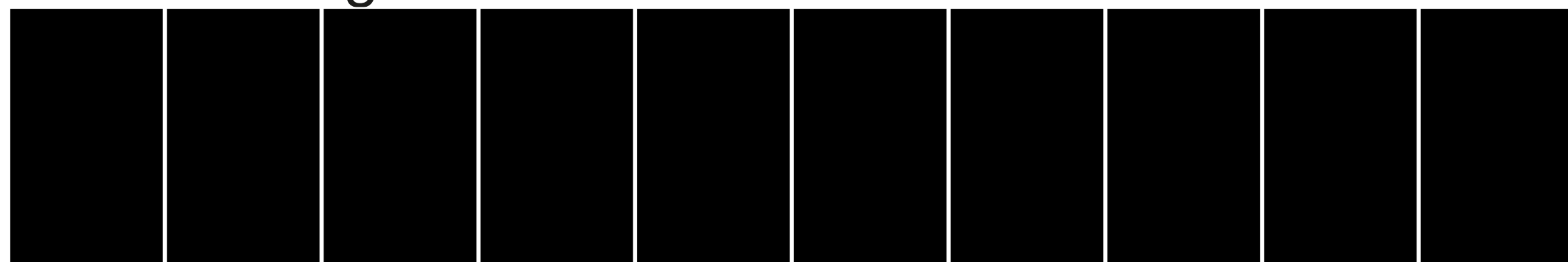
$$L_o(\omega_o) = \int_{\Omega} L_i(\omega) \rho(\omega, \omega_o) \langle n, \omega \rangle d\omega$$

BRDF acquisition

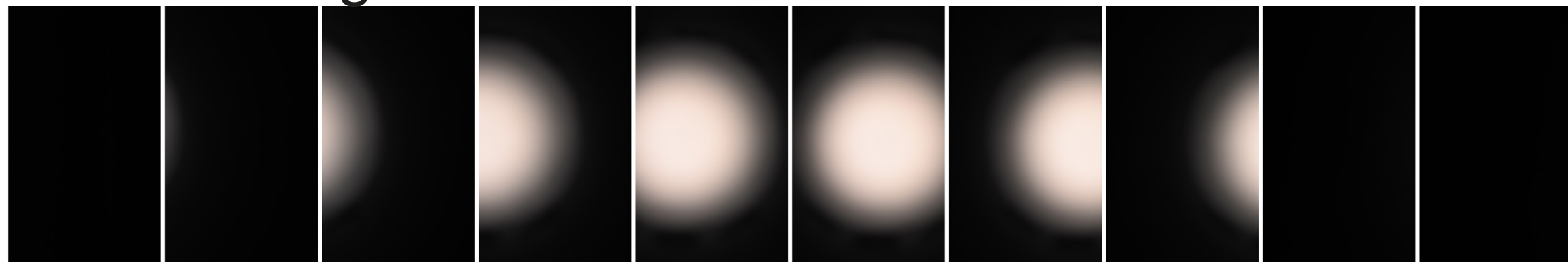
- Take several photographs of an object for different  $(\omega_o, \omega_i)$



Pointwise light source



Extended light source



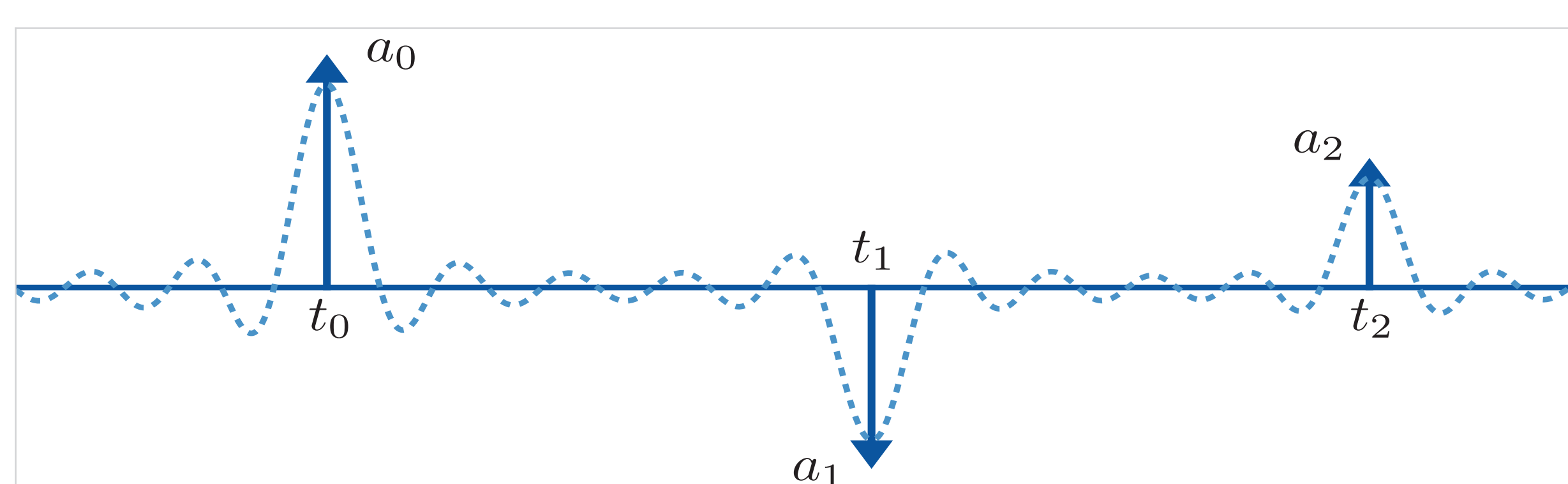
Proposed solution: use finite rate of innovation sampling with extended light and unknown pulse shape

## Finite Rate of Innovation (FRI) sampling [1]

Goal: sample and reconstruct signals with a finite number of parameters (innovations)

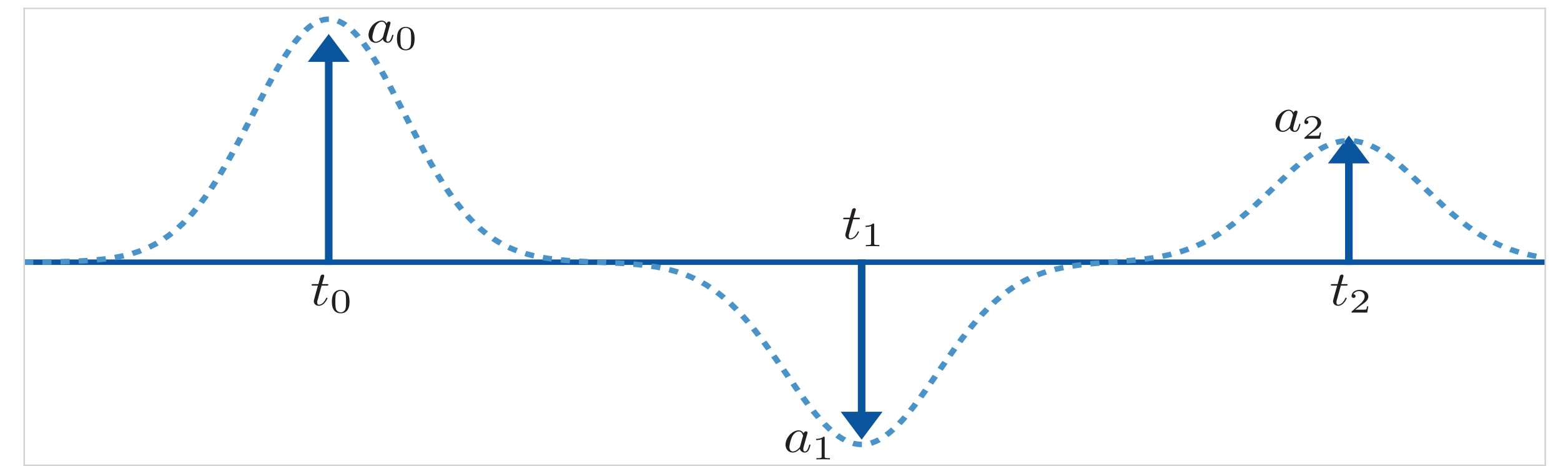
Example:  $\mathcal{T}$ -periodic stream of  $K$  Dirac pulses

$$X[m] = \frac{1}{\tau} \sum_{k=0}^{K-1} a_k e^{i2\pi t_k m / \tau}, \quad m \in \mathbf{Z}$$



## FRI with unknown sampling kernel

FRI Sampling kernels: Sinc, Gaussian [1], polynomial and exponential reproducing kernels [2]

Proposed model:  $X[m] = \frac{1}{\tau} \sum_{k=0}^{K-1} a_k e^{i2\pi t_k m / \tau} \Phi[m]$  (unknown shape)  $m \in \mathbf{Z}$ 

Parameters estimation as in the traditional case

- Find an annihilating filter  $A[m]$  for  $X[m]$

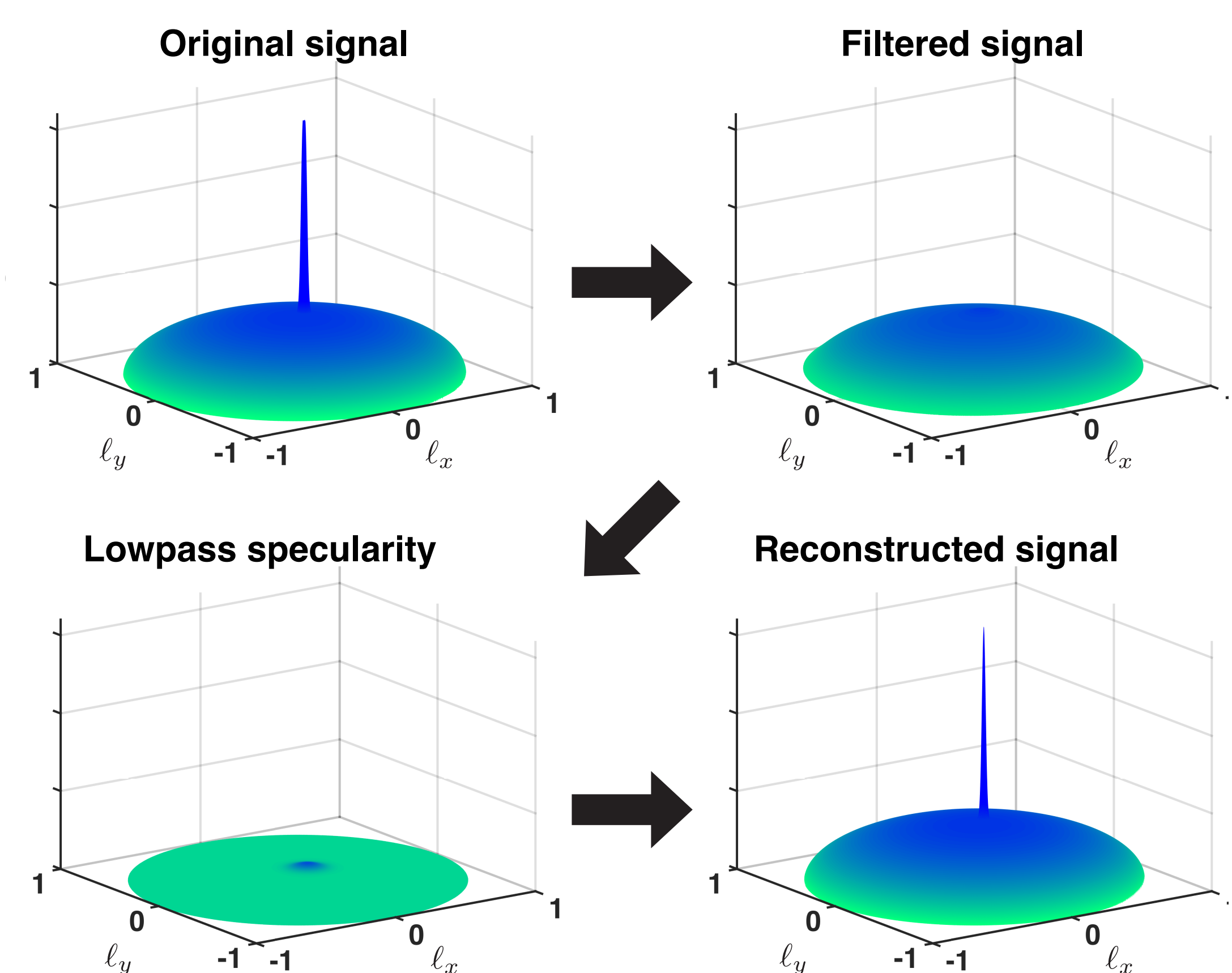
$$(A * X)[m] = 0, \quad \forall m \in \mathbf{Z}$$

Dirac locations  $\{t_k\}_{k=0}^{K-1}$  derived from the roots of  $A(z)$ 

- Amplitudes  $\{a_k\}_{k=0}^{K-1}$  estimated by matrix inversion

Assumptions: single pulse, symmetric sampling kernel

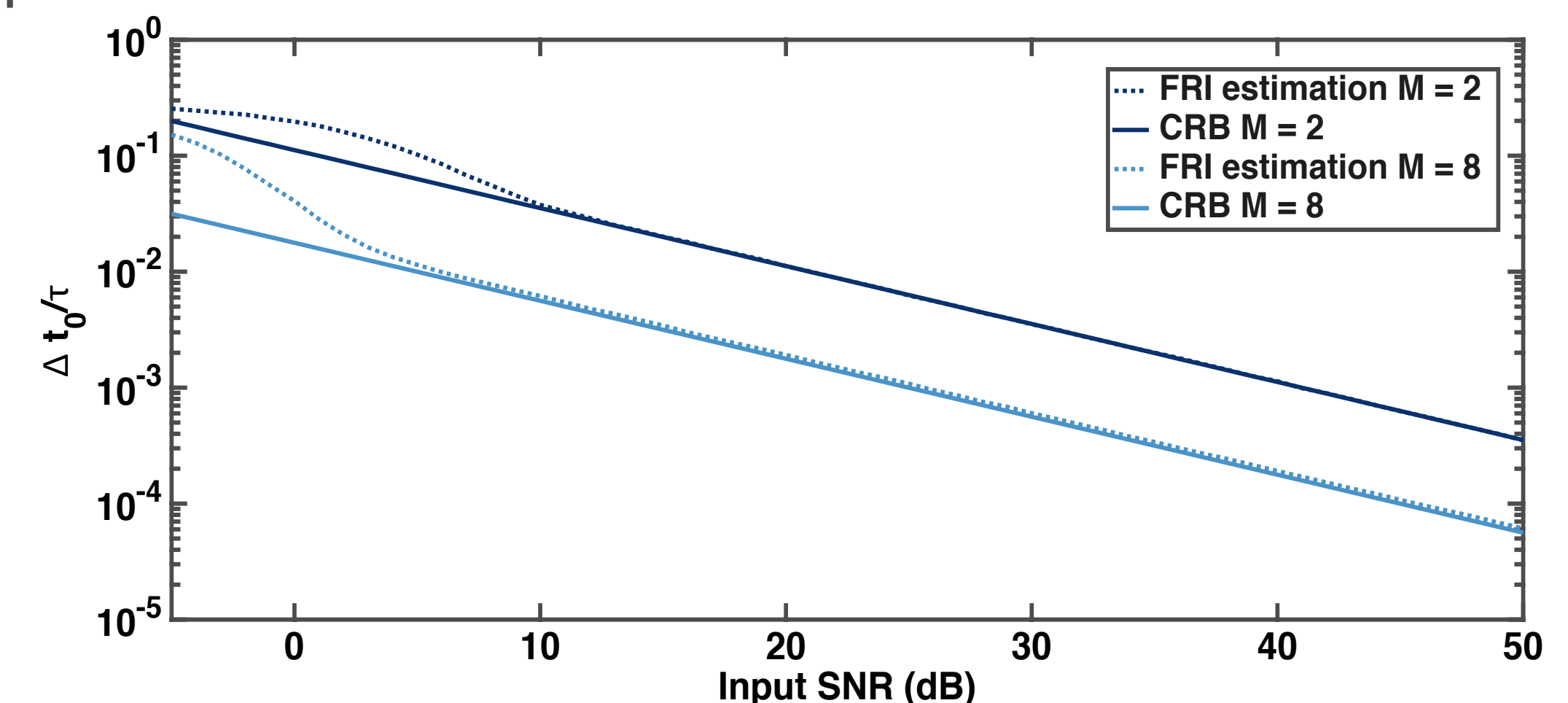
## Simulations



• SNR of reconstruction: 52.2 dB

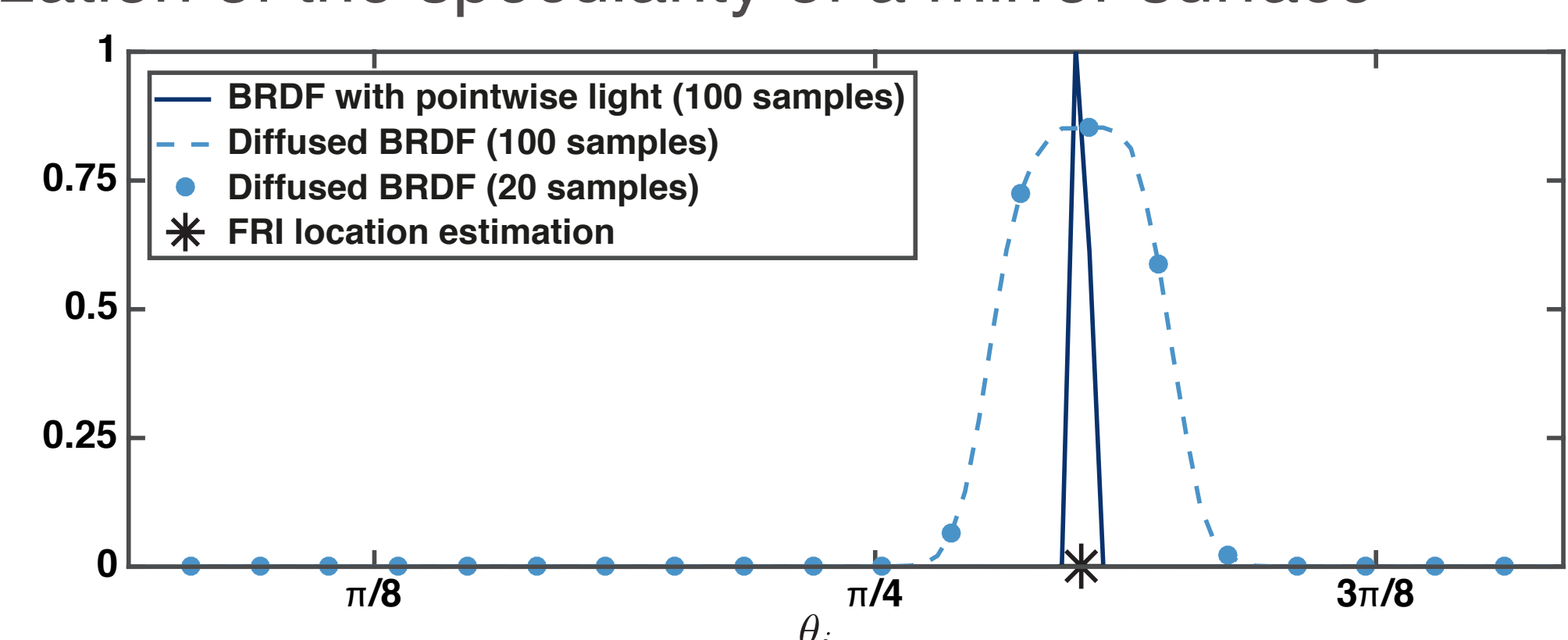
## Performance on noisy data

Comparison with Cramér-Rao lower bound



## Practical acquisition

Localization of the specularity of a mirror surface



## REFERENCES

- M. Vetterli, P. Marziliano, and T. Blu, "Sampling Signals with Finite Rate of Innovation," IEEE Trans. on Signal Processing, vol. 17, no. 6, pp. 1417–1428, 2002.
- P. L. Dragotti, M. Vetterli, and T. Blu, "Sampling Moments and Reconstructing Signals of Finite Rate of Innovation: Shannon meets Strang-Fix," IEEE Trans. on Signal Processing, vol. 55, no. 5, pp. 1741–1757, 2007.