

# CHANNEL ESTIMATION FOR CROSSTALK CANCELLATION IN WIRELESS ACOUSTIC NETWORKS



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# 1. Crosstalk Canceller (CC) over a WASN

WASN: Wireless Acoustic Sensor Network

#### **ORIGINAL SOUNDS**

- $s_1(n)$ : (e.g. Male speech)
- $s_2(n)$ : (e.g. Female speech)

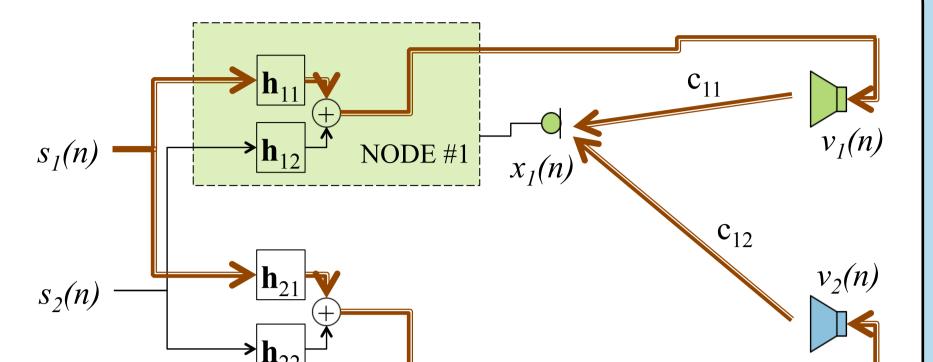
#### **CC DESIRED RESPONSE**

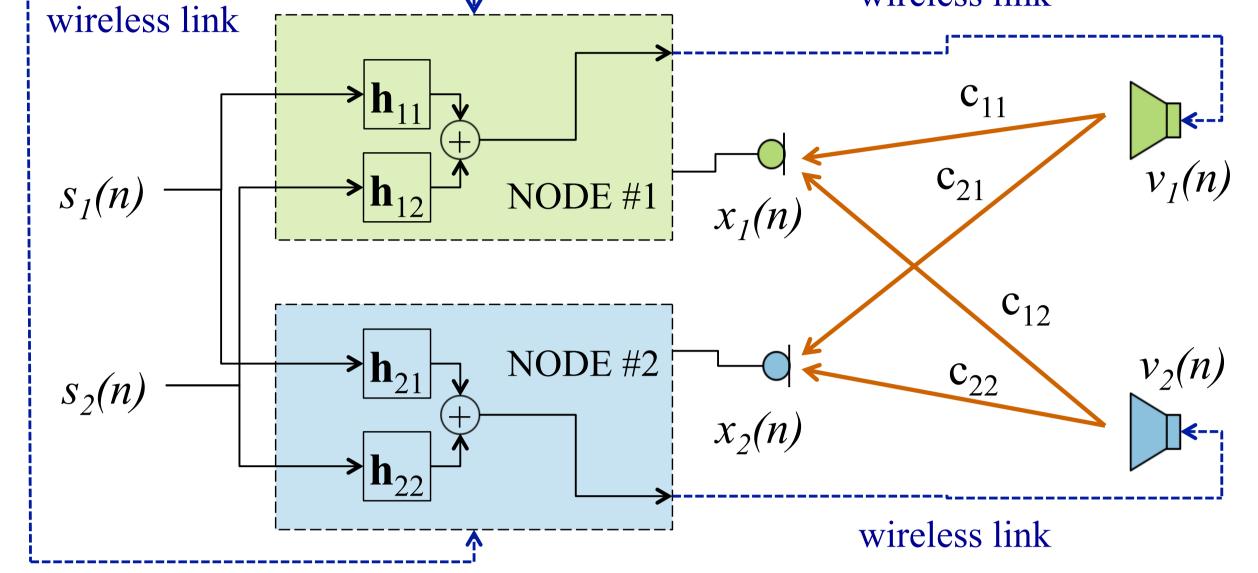
•  $x_1(n) \approx s_1(n)$ •  $x_2(n) \approx s_2(n)$ 

wireless link

## 2. Adaptive identification of the acoustic channels

Let us define the **Global Impulse Response (GIR)**  $a_{11}$  of NODE #1 as the impulse response between  $s_1(n)$  and  $x_1(n)$ :





**Step 1)** > Estimate the electro-acoustic channels (also called Room Impulse Responses, **RIR**)  $\mathbf{c}_{ij}$  using maximum length sequences (MLS) [1].  $\mathbf{c}_{ij} = \begin{bmatrix} c_{ij}(0) & c_{ij}(1) & \cdots & c_{ij}(L_c - 1) \end{bmatrix}^T$ 

**Step 2)** > Design the **CC filters**  $h_{ii}$  [2].

**Step 3)** > Filter original signals  $s_1(n)$  and  $s_2(n)$  through filters  $\mathbf{h}_{ii}$  to obtain  $v_1(n)$ and  $v_2(n)$ . Provide the desired signals  $x_1(n)$  and  $x_2(n)$  at the mic locations.

## Some challenges due to the use of WASNs:

- $\succ$  Lack of perfect synchronization between the nodes [3].
- $\triangleright$  Requirement of low communication burden between nodes, thus, no

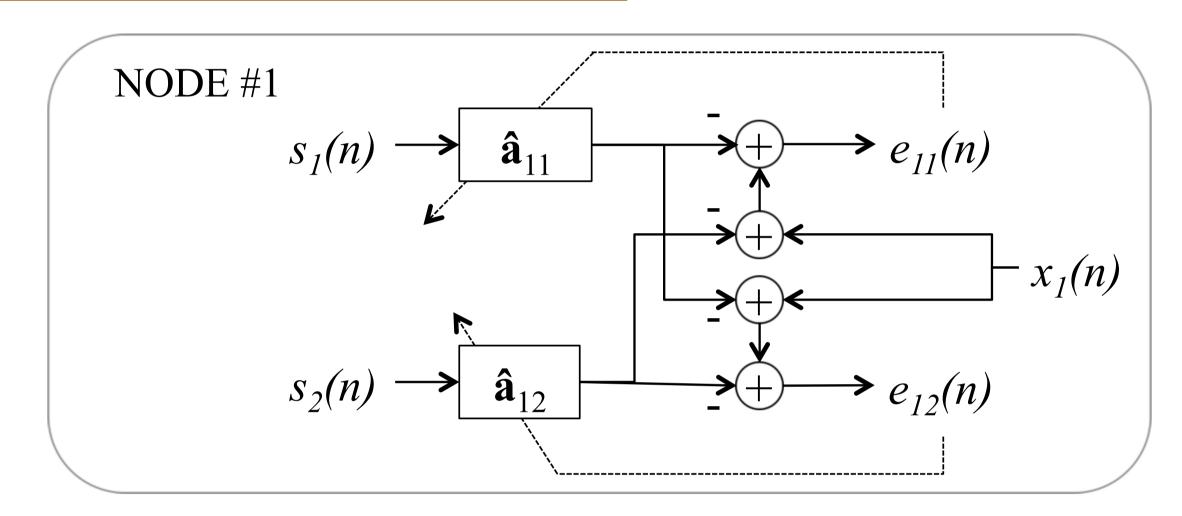
 $\mathbf{a}_{11} = \mathbf{c}_{11} * \mathbf{h}_{11} + \mathbf{c}_{12} * \mathbf{h}_{21}$ 

We define in the same way the GIR between  $s_2(n)$  and  $x_1(n)$  as:

 $\mathbf{a}_{12} = \mathbf{c}_{11} * \mathbf{h}_{12} + \mathbf{c}_{12} * \mathbf{h}_{22}$ 

 $x_1(n) = \mathbf{a}_{11} * s_1(n) + \mathbf{a}_{12} * s_2(n)$ Therefore:

## **Adaptive estimation of the GIRs**





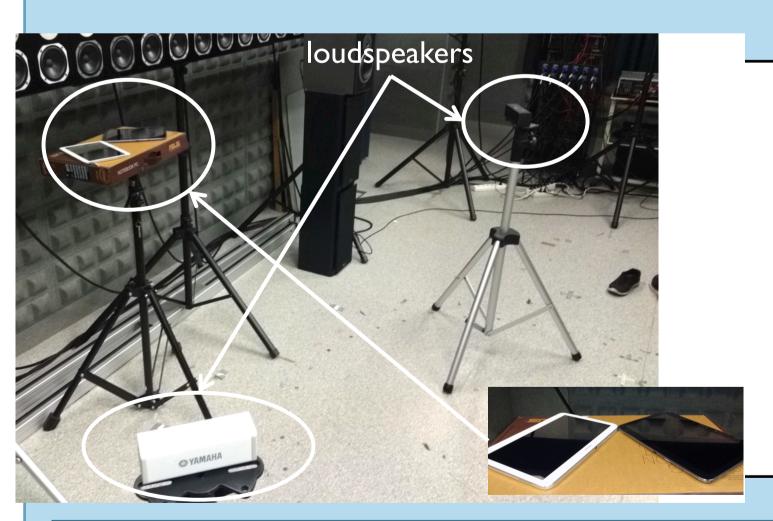
> The estimation of the GIRs related to NODE #1 is carried out minimizing the mean square of the following error signals:  $e_{11}(n) = [x_1(n) - \hat{\mathbf{a}}_{12} * s_2(n)] - \hat{\mathbf{a}}_{11} * s_1(n)$ 

exchange of signals  $x_i(n)$  or  $v_i(n)$  is allowed.

## $\succ$ The acoustic channels $c_{ii}$ can vary their coefficients due to changes in the location of the nodes.

[1] J. Vanderkooy, "Aspects of MLS measuring systems," J. Audio Eng. Soc, vol. 42, no. 4, pp. 219–231, 1994. [2] O. Kirkeby et al., "Fast deconvolution of multichannel systems using regularization," *IEEE Trans. on Speech and Audio* Processing, vol. 6, no. 2, pp. 189-194, Mar 1998.

[3] G. Piñero et al., "Sound-field reproduction system over a two-node acoustic network of mobile devices," Proc. IEEE 2nd World Forum on Internet of Things (WF-IoT), Milan, 2015, pp. 652-657.



# **3. Simulation Results**

- Real acoustic channels measured between two Bluetooth loudspeakers & two tablets (Android OS). - Number of RIR coefficients:  $L_c = 1200$ .
- Sampling frequency  $f_s$ =11025 Hz.
- $s_1(n)$  and  $s_2(n)$  are uncorrelated white noise.

 $e_{12}(n) = [x_1(n) - \hat{\mathbf{a}}_{11} * s_1(n)] - \hat{\mathbf{a}}_{12} * s_2(n)$ 

#### Similar procedure to estimate the GIRs associated to NODE #2 where:

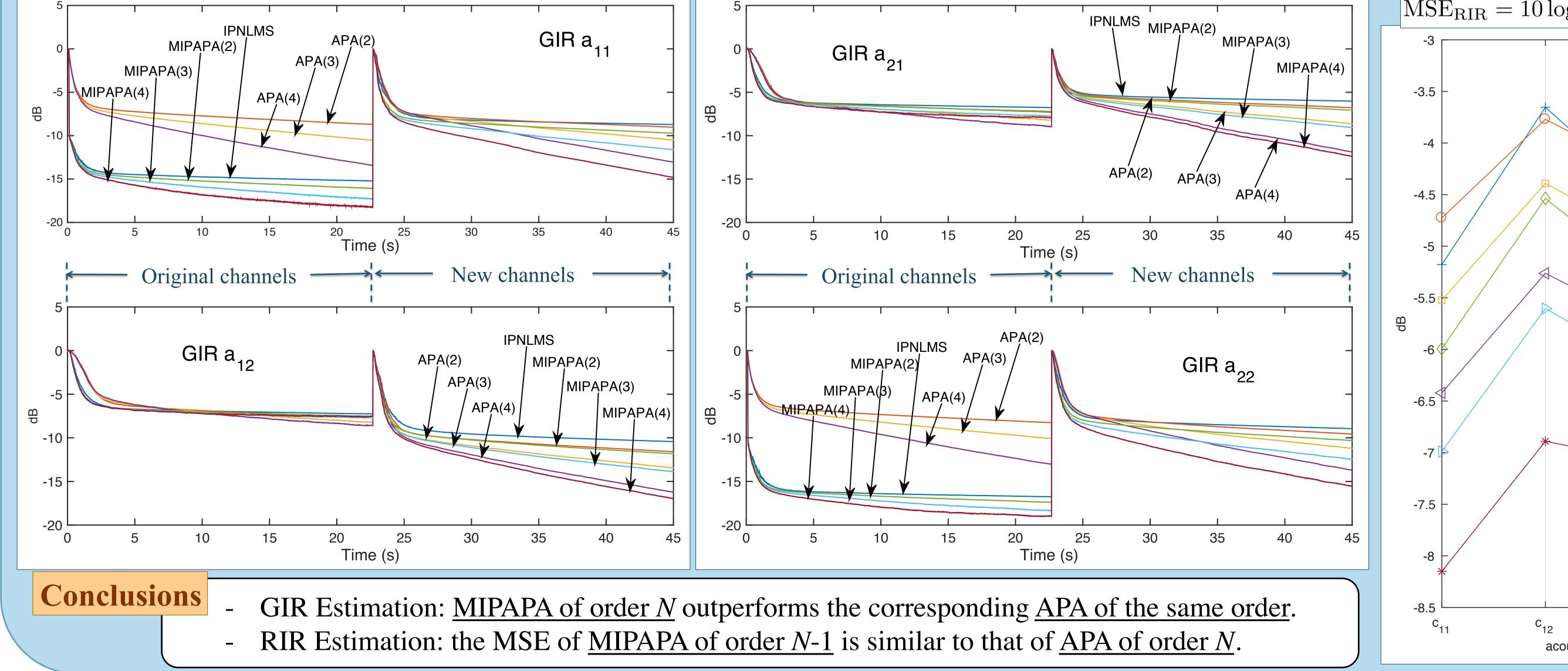
 $\mathbf{a}_{21} = \mathbf{c}_{21} * \mathbf{h}_{11} + \mathbf{c}_{22} * \mathbf{h}_{21}$ ,  $\mathbf{a}_{22} = \mathbf{c}_{21} * \mathbf{h}_{12} + \mathbf{c}_{22} * \mathbf{h}_{22}$ 

- > Once the GIRs have been estimated, the corresponding RIRs Step 2) are estimated at each node through a least squares (LS) solution.
- > Follow steps 2) and 3) of the CC algorithm to design the new Step 3) filters and provide signals  $v_1(n)$  and  $v_2(n)$  to the loudspeakers.

### **Implemented algorithms**

- For sparse Affine projection algorithm (APA), N=2,3,4 GIRs
- Improved proportionate NLMS (IPNLMS) <sup>∠</sup>
- Memory-improved proportionate APA (MIPAPA), N=2,3,4

 $\|\mathbf{a}_{ij} - \hat{\mathbf{a}}_{ij}(n)\|_2$  $Misalignment = 20 \log_{10}$  $\|{f a}_{ij}\|_2$ 



 $MSE_{RIR} = 10 \log_{10} \{ \|\mathbf{c}_{ij} - \hat{\mathbf{c}}_{ij}(n)\|^2 \}$ - IPNLMS — APA(2) - APA(3) MIPAPA(2) MIPAPA(3) - MIPAPA(4)

