

Time-Resolved Image Demixing

A Phase-Retrieval Approach for Reflection Canceling Cameras

Ayush Bhandari[†] Aurélien Bourquard[†] Shahram Izadi[‡] Ramesh Raskar[†]

[†]Massachusetts Institute of Technology • [‡]Microsoft Research

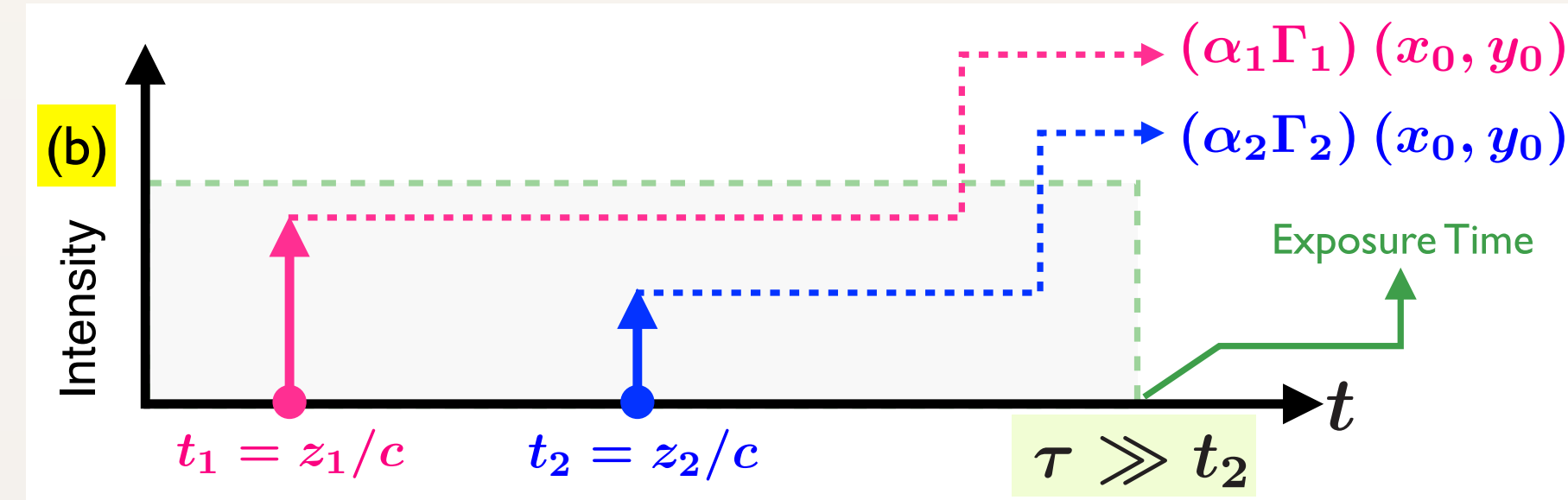
ayush@MIT.edu

Summary

Key Takeaways

- Demixing constituent components of an image mixture is a highly ill-posed problem.
- We approach the image-mixing problem from a time-resolved perspective by exploring the question: What if each photon is time-stamped?
- We propose a demixing algorithm based on phase-retrieval and our results are corroborated with experiments conducted using Microsoft Kinect ToF sensor.

Image Formation Model

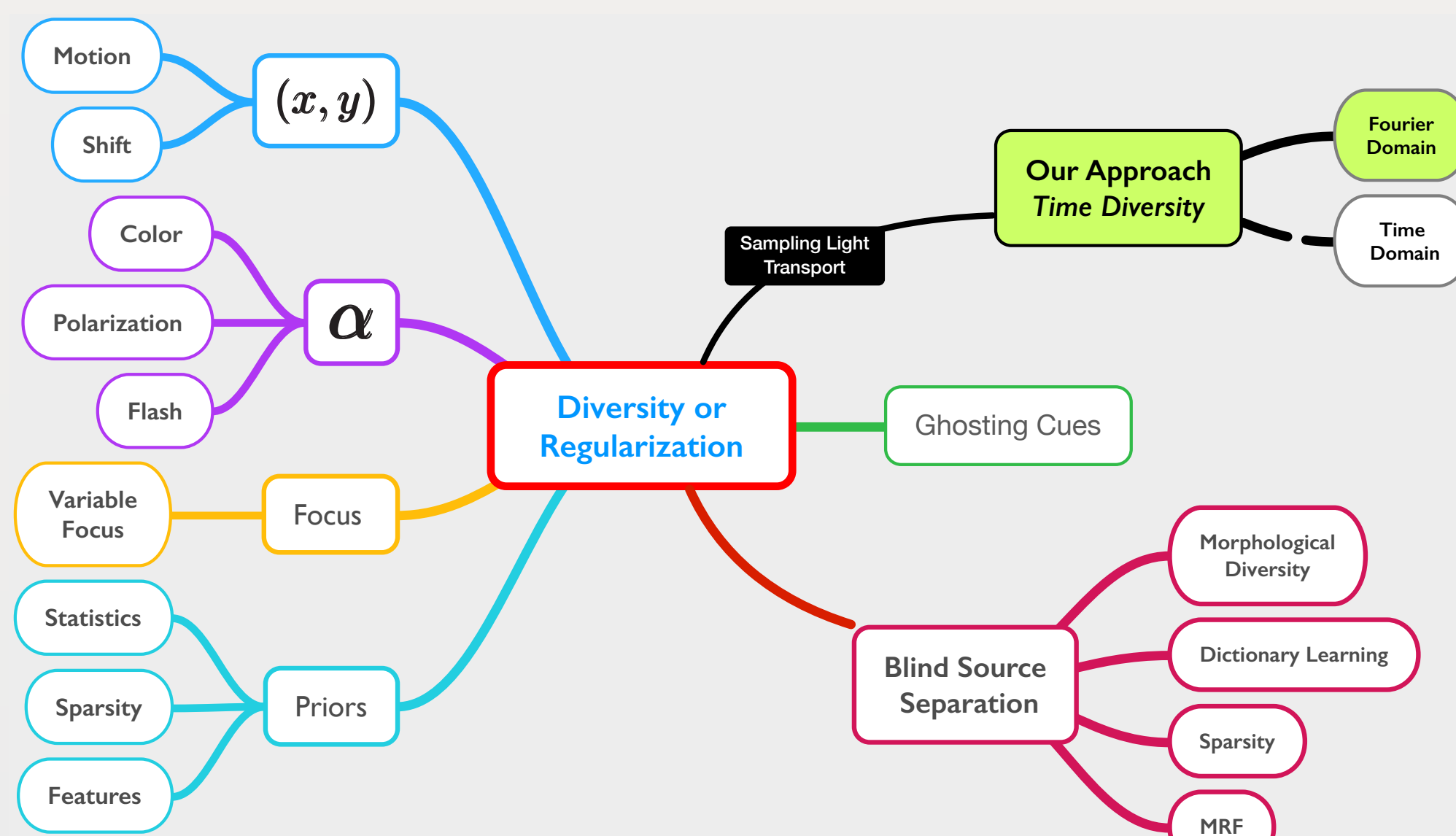


Transient $m(x, y, t) = \sum_{k=0}^{K-1} (\alpha_k \Gamma_k)(x, y) \delta(t - t_k)$

Conventional $m(x, y) = \sum_k (\alpha_k \Gamma_k)(x, y)$

Problem Statement

Problem: Given $m(x, y)$, identify $\{\Gamma_k(x, y)\}_{k=0}^{K-1}$



Frequency Domain Time-Resolved Imaging

Phase-Retrieval Approach for Image Demixing

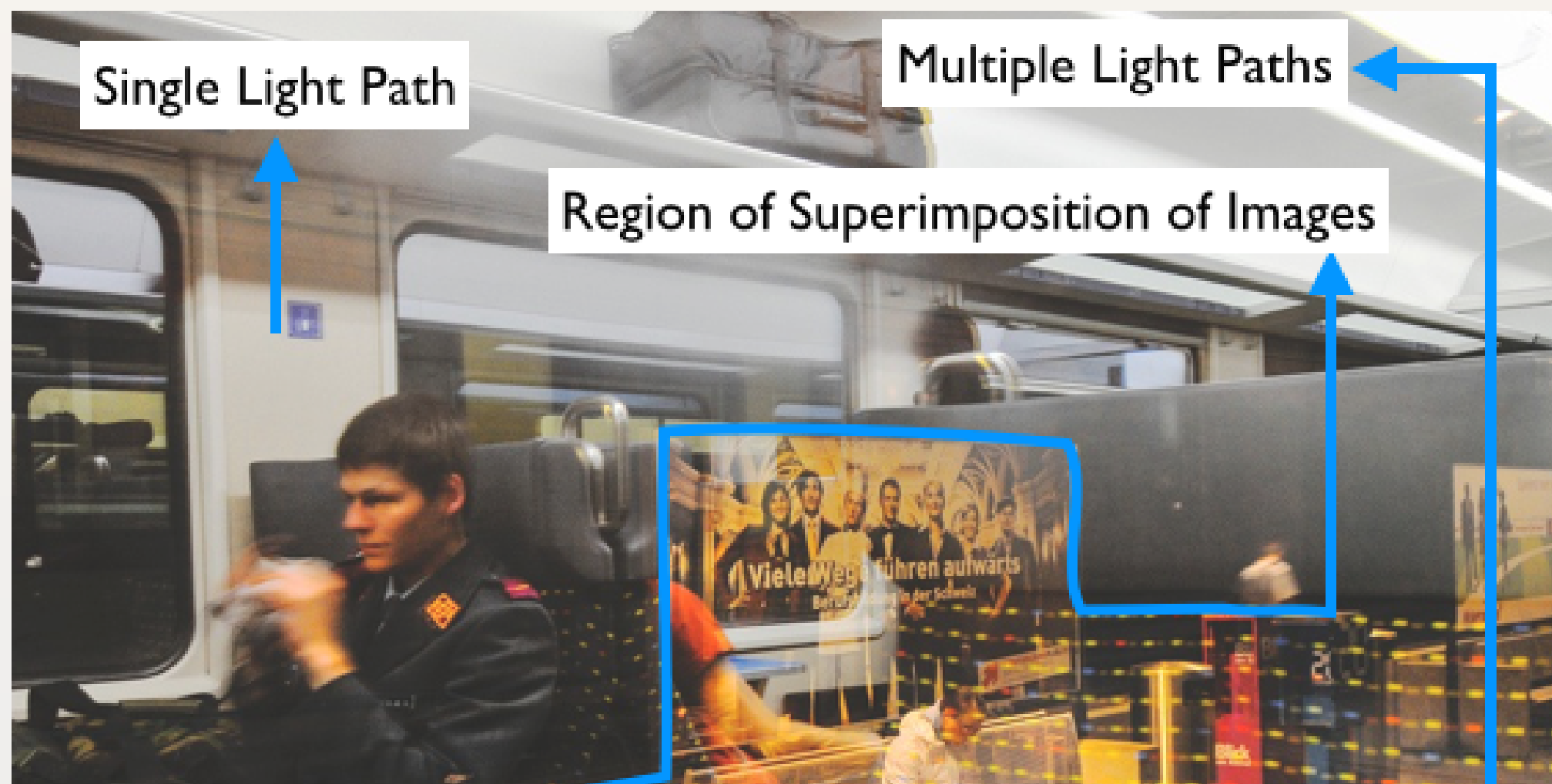
Conventional ToF sensor for single ToF, $h(t, \tau) = \Gamma_0 \delta(t - \tau - t_0)$, $t_0 = 2d_0/c$,

$$\Gamma_0 \left(1 + \frac{p_0^2}{2} \cos(\omega(t + t_0)) \right) \xrightarrow{\{m_\omega(\frac{k\pi}{2\omega})\}_{k=0}^3} \underbrace{z_\omega = \tilde{\Gamma}_0 e^{j\omega t_0}}_{\text{ToF Estimate}} \xrightarrow{|\cdot|^2} |\tilde{\Gamma}_0|^2$$

Our approach: Multiple image mixture. The SRF is $h(t, \tau) = \sum_{k=0}^{K-1} \Gamma_k \delta(t - \tau - t_k)$,

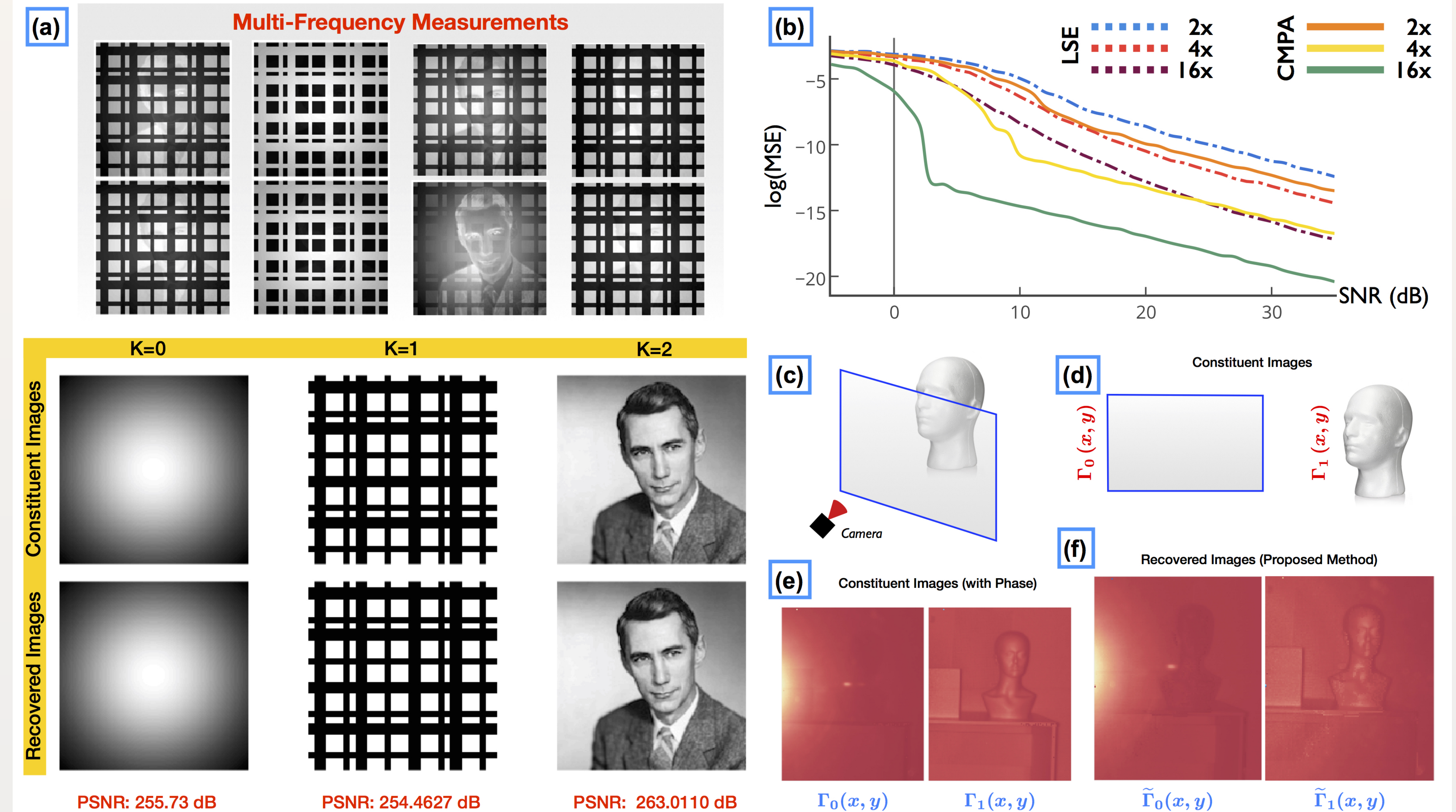
$$|z_\omega|^2 = \left| \sum_{k=0}^{K-1} \Gamma_k e^{-j\omega t_k} \right|^2 \equiv \sum_{k=-K_0}^{+K_0} \underbrace{\gamma_k}_{\text{Unknown}} e^{j\omega t_k}, \quad K_0 = (K^2 - K) / 2$$

Motivation



Can we recover images when multiple optical paths mix at the sensor or when there exists a many-to-one mapping between the scene and the pixel?

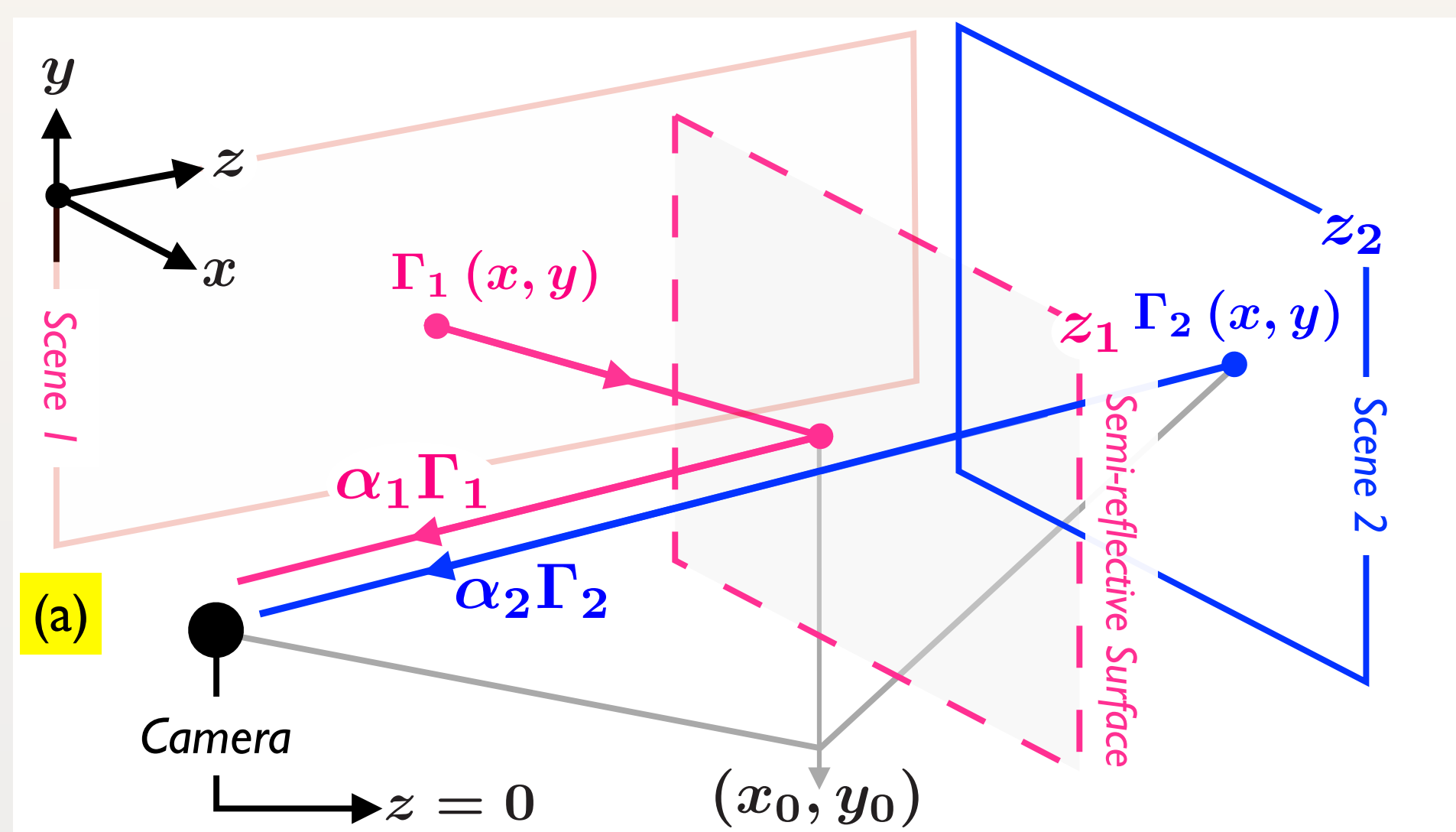
Results and Discussion



References

- H. Farid and E. H. Adelson. Separating reflections and lighting using independent components analysis. In *IEEE CVPR*, volume 1, 1999.
- Bronstein & Bronstein et. al. Sparse ICA for blind separation of transmitted and reflected images. *Intl. Journal of Imaging Sys. and Tech.*, 15(1):84-91, 2005.
- A. Bhandari et. al. Resolving multipath interference in time-of-flight imaging via modulation frequency diversity and sparse regularization. *Optics Letters*, 39(7), 2014.
- A. Levin and Y. Weiss. User assisted separation of reflections from a single image using a sparsity prior. *IEEE PAMI*, (9), 2007

Rethinking Image Formation



Conventional vs Transient Imaging.

Time-Resolved Imaging

$$p \rightarrow \boxed{h} \rightarrow r \rightarrow \otimes_p \rightarrow m \xrightarrow{\text{Sampling}} m_k = m(k\Delta)$$

Frequency Domain ToF Imaging

- Probing Function: $p(t) = \cos(\omega_0 t)$
- Scene Response: $h(t, \tau) = \sum_{k=0}^{K-1} \Gamma_k \delta(t - \tau - \frac{2d_k}{c})$
- Reflected Signal: $r(t) = (p * h)(t)$
- Measurements: $m_\omega(t) = \frac{p_0^2}{2} e^{j\omega t} \sum_{k=0}^{K-1} \Gamma_k e^{j\omega t_k}$

