



GlobalSIP 2015 – Monday 14.12. 2015

**“Channel-Robust Compressed Sensing via Vector
Pre-Quantization in Wireless Sensor Networks”**

*Markus Leinonen, Marian Codreanu, Markku Juntti

Centre for Wireless Communications (CWC), University of Oulu, Finland

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Background: Wireless Sensor Network Monitoring

- Measuring & monitoring WSN applications
- Resource-limited sensors
 - Wireless access is energy-consuming
 - Limited computation power → ***simple encoding needed***
- Source compression for minimizing the information rate
- Real-world WSN signals ***sparse***, e.g., in surveillance, fault detection and spectrum sensing applications
- Signals typically continuous-valued
- ***Quantization*** inevitable for finite-rate communications

Background: Design Approaches

- Compressed sensing (CS)
 - Retrieve a high-dimensional sparse vector from few linear measurements
- Vector quantization (VQ)
 - Block source coding (cf. Shannon's source coding theory)
- Channel-optimized VQ (COVQ)
 - Joint source-channel coding (JSCC)
 - Source-channel separation theorem: infinitely long block lengths
 - ❑ A practical method with constrained delay and complexity

System Model (1/2)

Fixed measurement matrix

- Noisy CS measurements [M] of K -sparse signal [N]: $\mathbf{y} = \Phi \mathbf{x} + \mathbf{w}$
- Pre-quantization of measurement space into V cells $\{\mathcal{S}_1, \dots, \mathcal{S}_V\}$ with rate $\bar{R} = \log_2 V$ and indices $\mathcal{V} \triangleq \{1, \dots, V\}$

$$\text{PQ}(\mathbf{y}) = v, \text{ if } \mathbf{y} \in \mathcal{S}_v, v \in \mathcal{V}$$

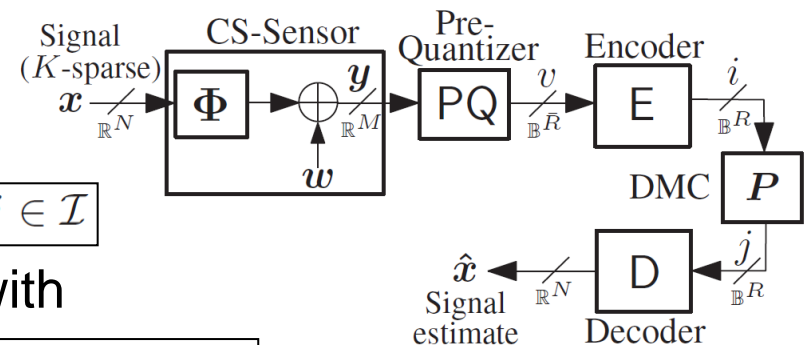
- Encoder is an index mapping $\pi : \mathcal{V} \mapsto \mathcal{I}$, $\pi = \{\pi(1), \dots, \pi(V)\}$ with rate $R = \log_2 I$, $R \leq \bar{R}$, and indices $\mathcal{I} \triangleq \{1, \dots, I\}$

$\pi(v) \in \mathcal{I}$: encoding index of v :th cell

$\pi^{-1}(i) = \{v | \pi(v) = i\}$: cell indices assigned to i :th encoding index

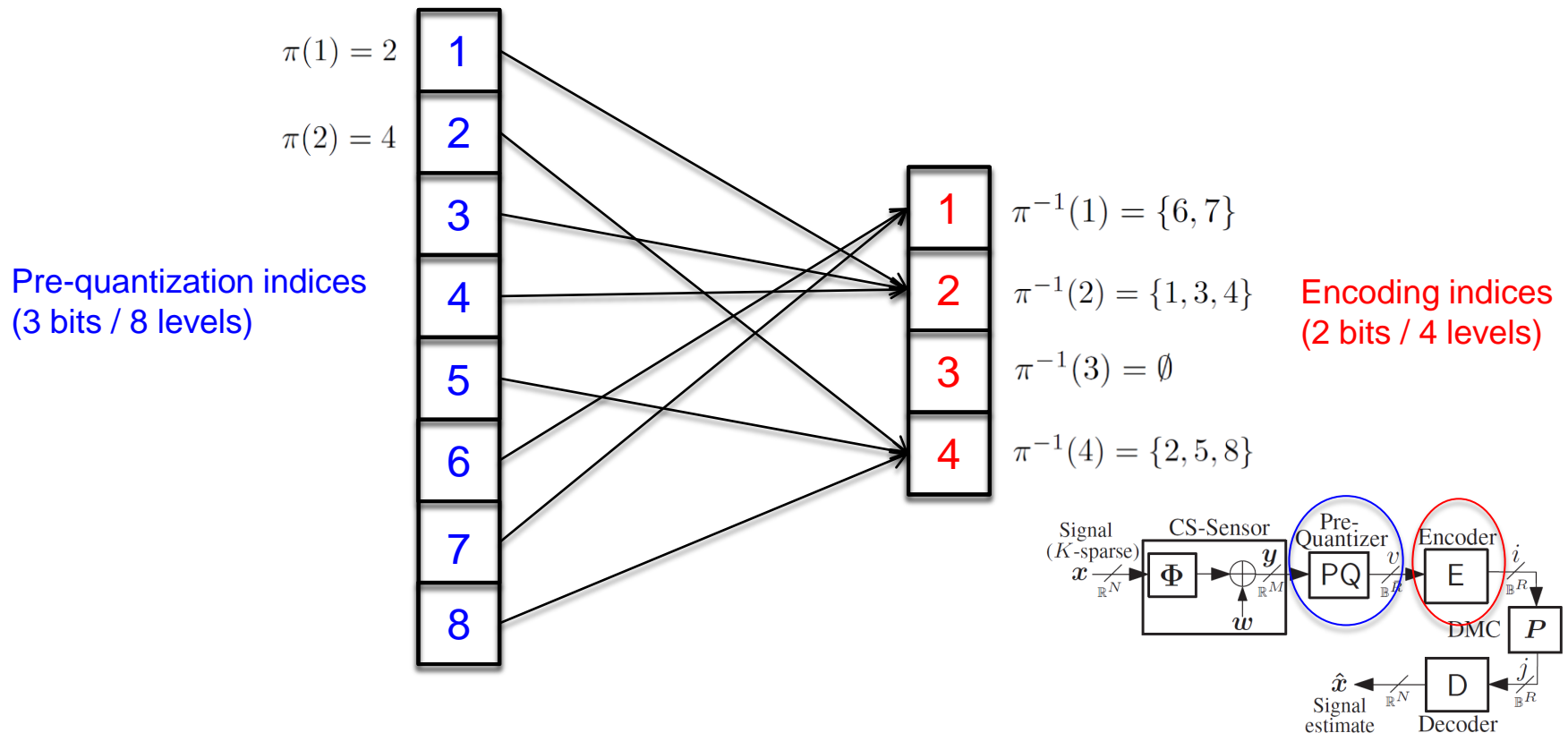
$$\text{E}(v) = i, \text{ if } \pi(v) = i, i \in \mathcal{I}$$

- Discrete memoryless channel is a mapping $I \rightarrow I$ with $p_{ij} = \Pr(j|i), i, j \in \mathcal{I}$
- Decoder is a mapping $D : \mathcal{I} \rightarrow \mathcal{C}$ with codevectors $\mathcal{C} \triangleq \{c_1, \dots, c_I\}$, i.e., $D(j) = c_j \in \mathcal{C}$



System Model (2/2)

- Illustration of assignment of pre-quantization cells into encoding indices with $\bar{R} = 3$ and $R = 2$



Problem Formulation

- Minimization of the end-to-end MSE distortion $D \triangleq \mathbb{E}[\|\mathbf{x} - \hat{\mathbf{x}}\|_2^2]$
 - 1) Quantization error 2) Channel error 3) Reconstruction error
- Additional constraint for PQ, i.e., VQ with codebook $\mathcal{G} \triangleq \{g_1, \dots, g_V\}$ and codepoints $g_v \in \mathbb{R}^M$:
 - Nearest-neighbor coding to enforce **controlled encoding complexity**
- Marginalize over the PQ, E and D indices:

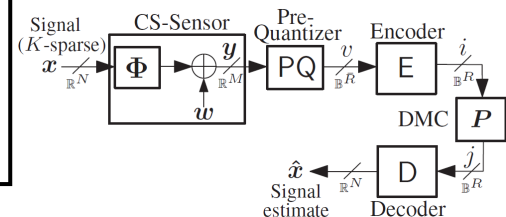
$$\begin{aligned}
 D &= \sum_{v,i,j} \Pr(v,i,j) \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | v,i,j] \\
 &= \sum_{i,j} \sum_{v \in \pi^{-1}(i)} p_{ij} \Pr(v) \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | v,i,j] \\
 &= \sum_{v,i,j} \delta_\pi(v,i) p_{ij} \Pr(v) \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | v,i,j]
 \end{aligned}$$

Markov property
 $v \rightarrow i \rightarrow j$

- Joint optimization problem:

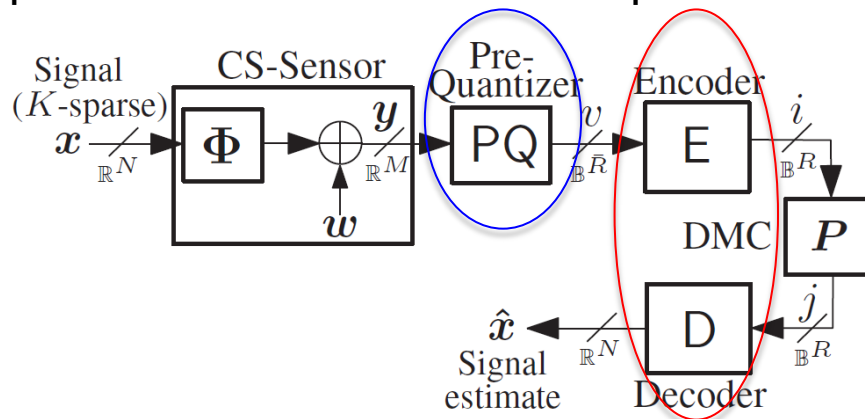
$$\begin{aligned}
 \min. \quad & \sum_{v,i,j} \delta_\pi(v,i) p_{ij} \Pr(v) \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | v,i,j] \\
 \text{s.t.} \quad & \pi(v) \in \mathcal{I}, v \in \mathcal{V} \\
 & \mathcal{S}_v = \left\{ \mathbf{y} : \|\mathbf{y} - \mathbf{g}_v\|_2^2 \leq \|\mathbf{y} - \mathbf{g}_{v'}\|_2^2, \forall v' \neq v \right\}, v \in \mathcal{V}
 \end{aligned}$$

with optimization variables $\{g_v\}_{v=1}^V$, π , and $\{c_j\}_{j=1}^I$



Optimization Approach

- The integer constraint makes the problem intractable
- Split the optimization into two **separate** steps:
 1. Optimization of **PQ** via $\{g_v\}_{v=1}^V$
 2. Optimization of **E-D pair** via π and $\{c_j\}_{j=1}^I$
- Alternating optimization in the spirit of the iterative Lloyd algorithm used in both steps
 - Optimize partition for fixed codevectors
 - Optimize codevectors for fixed partition



Pre-Quantization Optimization

- A reasonable choice is to minimize the MSE distortion induced by the measurement space discretization:

$$\tilde{D} \triangleq \sum_{v=1}^V \Pr(v) \mathbb{E} [\|\mathbf{y} - \mathbf{g}_v\|_2^2 | v]$$

- Due to the MSE distortion criterion, the alternating optimization for PQ results in the traditional VQ with

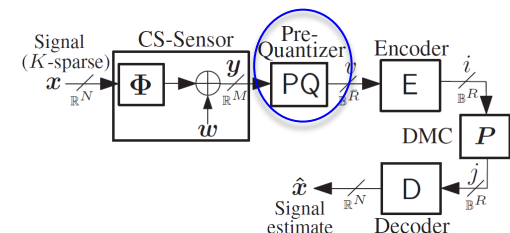
- Optimal partition (nearest-neighbor condition):

$$\mathcal{S}_v^* = \left\{ \mathbf{y} : \|\mathbf{y} - \mathbf{g}_v\|_2^2 \leq \|\mathbf{y} - \mathbf{g}_{v'}\|_2^2, \forall v' \neq v \right\}, v \in \mathcal{V}$$

- Optimal codepoints (centroid condition):

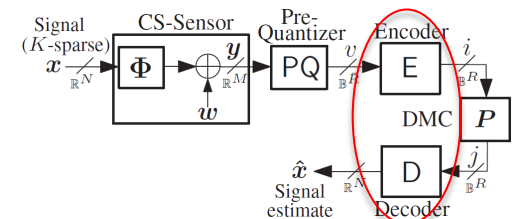
$$\mathbf{g}_v^* := \mathbb{E}[\mathbf{y} | \mathbf{y} \in \mathcal{S}_v] = \frac{1}{\Pr(v)} \int_{\mathcal{S}_v} \mathbf{y} f(\mathbf{y}) d\mathbf{y}, v \in \mathcal{V}$$

VQ training via the iterative Lloyd algorithm by successively applying the necessary optimality conditions



Joint Encoder-Decoder Optimization (1/3)

- Optimize E-D for a fixed PQ, i.e., fixed PQ cells $\{\mathcal{S}_v\}_{v \in \mathcal{V}}$
- Minimum mean-square error (MMSE) estimator of the source given noisy CS measurements: $\hat{\mathbf{x}}(\mathbf{y}) \triangleq \mathbb{E}[\mathbf{x}|\mathbf{y}] \in \mathbb{R}^N$
 - Closed-form solution available
 - Exponential complexity proportional to the number of supports $\binom{N}{K}$
- Alternating optimization of E and D
 - Practical training via the principles of the iterative Lloyd algorithm



Joint Encoder-Decoder Optimization (2/3)

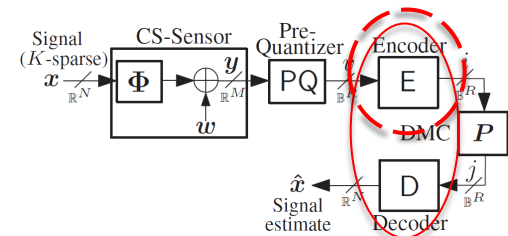
- The optimization of E separates into V subproblems, namely

$$\begin{aligned}
 D &= \sum_{v,i,j} \delta_{\pi}(v,i) p_{ij} \int_{\mathbf{y}} \Pr(v|\mathbf{y}) \mathbb{E}[d_j|v,i,j,\mathbf{y}] f(\mathbf{y}) d\mathbf{y} \\
 &= \sum_{v,i,j} \delta_{\pi}(v,i) p_{ij} \int_{\mathcal{S}_v} \mathbb{E}[d_j|v,i,j,\mathbf{y}] f(\mathbf{y}) d\mathbf{y} \\
 &= \sum_{v,i} \delta_{\pi}(v,i) \boxed{D(v,i)} \longrightarrow \text{Distortion when } v\text{:th cell is} \\
 &\hspace{15em} \text{assigned to } i\text{:th encoding index}
 \end{aligned}$$

- Optimal encoder index:

$$\begin{aligned}
 \pi_v^* &:= \operatorname{argmin}_{i \in \mathcal{I}} \left\{ \sum_j p_{ij} \int_{\mathcal{S}_v} \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | v, i, j, \mathbf{y}] f(\mathbf{y}) d\mathbf{y} \right\} \\
 &:= \operatorname{argmin}_{i \in \mathcal{I}} \left\{ \sum_j p_{ij} \int_{\mathcal{S}_v} \left(\|\mathbf{c}_j\|_2^2 - 2\mathbf{c}_j^T \mathbb{E}[\mathbf{x}|\mathbf{y}] \right) f(\mathbf{y}) d\mathbf{y} \right\} \\
 &:= \operatorname{argmin}_{i \in \mathcal{I}} \left\{ \sum_j p_{ij} \int_{\mathcal{S}_v} \left(\|\mathbf{c}_j\|_2^2 - 2\mathbf{c}_j^T \hat{\mathbf{x}}(\mathbf{y}) \right) f(\mathbf{y}) d\mathbf{y} \right\}
 \end{aligned}$$

- Weighted nearest-neighbor condition



Joint Encoder-Decoder Optimization (3/3)

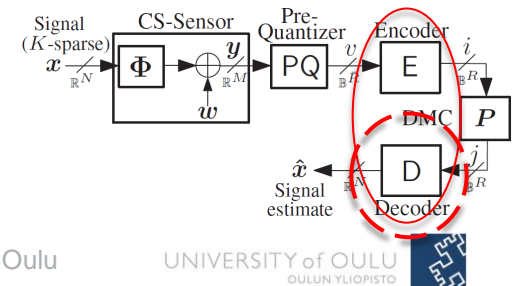
- The MSE marginalized over channel output indices as

$$\sum_j \Pr(j) \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | j] \text{ results in } \mathbf{c}_j^* := \operatorname{argmin}_{\mathbf{c}_j} \mathbb{E}[\|\mathbf{x} - \mathbf{c}_j\|_2^2 | j]$$

- The optimal codevector:

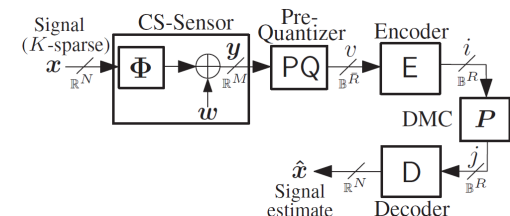
$$\begin{aligned} \mathbf{c}_j^* &= \mathbb{E}[\mathbf{x} | j] \\ &= \sum_v \sum_i \int_{\mathbf{y}} \Pr(v, i | j) \mathbb{E}[\mathbf{x} | v, i, j, \mathbf{y}] f(\mathbf{y} | v, i, j) d\mathbf{y} \\ &= \sum_{v, i} \int_{\mathbf{y}} \Pr(i | j) \Pr(v | i) \hat{\mathbf{x}}(\mathbf{y}) f(\mathbf{y} | v, i) d\mathbf{y} \\ &= \sum_{v, i} \int_{\mathbf{y}} p_{ij} \frac{\Pr(i) \Pr(v | i) \Pr(v, i | \mathbf{y})}{\Pr(j) \Pr(v, i)} \hat{\mathbf{x}}(\mathbf{y}) f(\mathbf{y}) d\mathbf{y} \\ &= \frac{1}{\Pr(j)} \sum_{i=1}^I p_{ij} \sum_{v \in \pi^{-1}(i)} \int_{\mathcal{S}_v} \hat{\mathbf{x}}(\mathbf{y}) f(\mathbf{y}) d\mathbf{y} \end{aligned}$$

- A weighted centroid condition

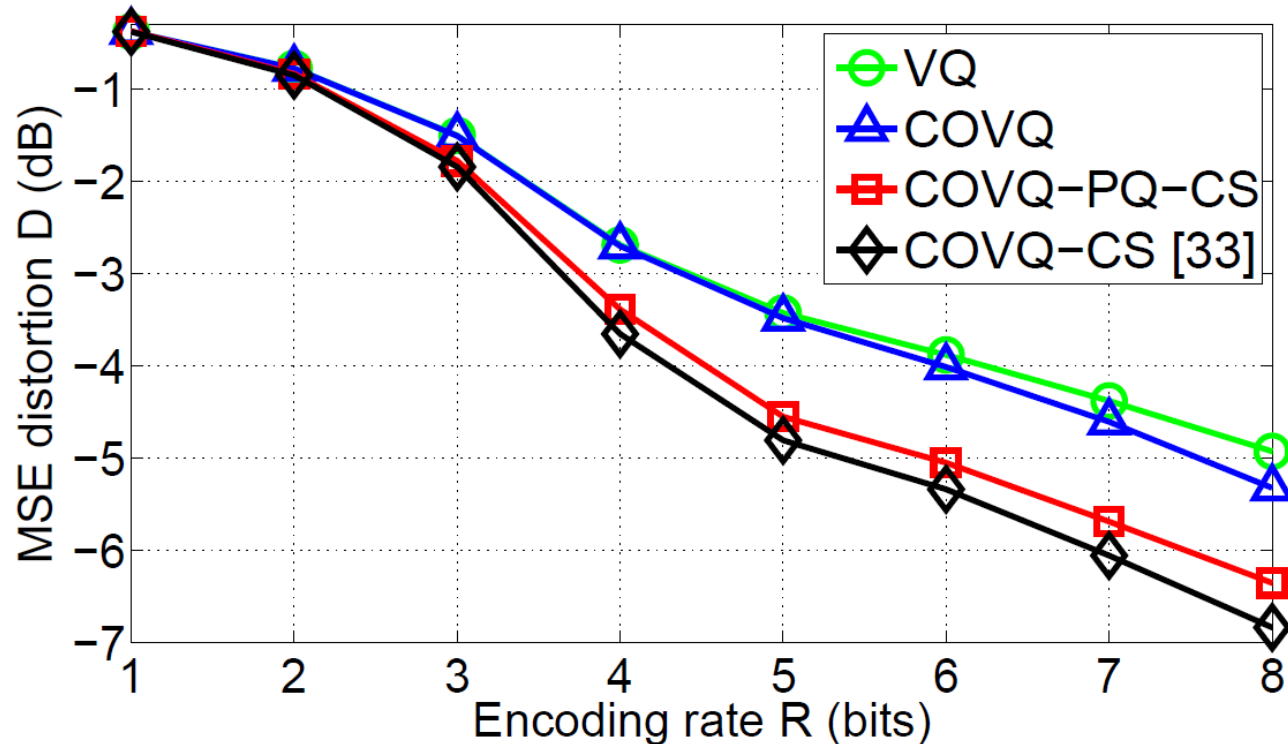


Algorithm Implementation

- Encoding of each measurement vector requires
 1. Table look-ups (V) at PQ: $v^* := \operatorname{argmin}_{v \in \mathcal{V}} \{\|\mathbf{y} - \mathbf{g}_v^*\|_2^2\}$ using codebook $\mathcal{G}^* = \{\mathbf{g}_1^*, \dots, \mathbf{g}_V^*\}$
 2. A simple reference at E: $i^* = \pi^*(v)$ using $\pi^* = \{\pi^*(1), \dots, \pi^*(V)\}$
- Tolerable encoding complexity via adjusting the PQ rate
 - Higher PQ rate refines the approximation of measurement space \rightarrow smaller end-to-end distortion
 - Lower PQ rate decreases the encoding complexity
- Decoding of each received index j requires
 - A simple reference $D(j) = \mathbf{c}_j \in \mathcal{C}$ using $\mathcal{C}^* = \{\mathbf{c}_1^*, \dots, \mathbf{c}_I^*\}$



Numerical Results (1/2)



Average MSE distortion for varying values of encoding rate R with $\sigma_w^2 = 0.008$ and $p_\epsilon = 0.99$ for $N = 7$, $M = 5$, and $K = 2$.

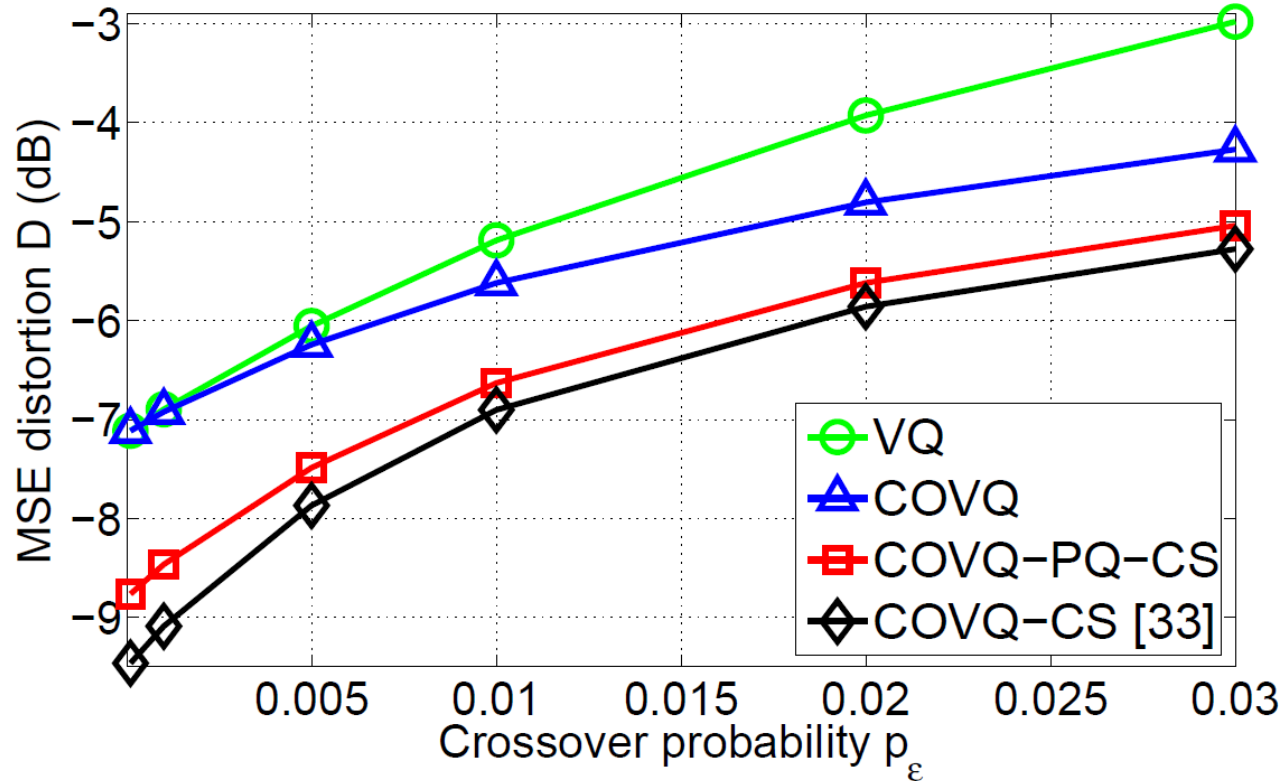
VQ: CS-blind & Channel-blind

COVQ: CS-blind & Channel-aware

COVQ-PQ-CS (Proposed): CS-aware & Channel-aware with controlled encoding complexity

COVQ-CS: CS-aware & channel-aware with "full" encoding complexity

Numerical Results (2/2)



Average MSE distortion for varying values of crossover probability p_ϵ with $R = 8$ and $\sigma_w^2 = 0$ for $N = 8$, $M = 6$, and $K = 2$.

VQ: CS-blind & Channel-blind

COVQ: CS-blind & Channel-aware

COVQ-PQ-CS (Proposed): CS-aware & Channel-aware with controlled encoding complexity

COVQ-CS: CS-aware & channel-aware with "full" encoding complexity

Conclusions

- We proposed a novel finite-rate communication method for efficient and robust acquisition of sparse sources over noisy channels with controlled encoding complexity
- The results illustrated that the sparse signal structure and the existence of channel noise, respectively, necessitates
 - ❖ ***CS-awareness***
 - ❖ ***Channel-awareness***

Thank You For Your Interest!
Questions?