

An Expectation-Maximization Eigenvector Clustering Approach to Direction of Arrival Estimation of Multiple Speech Sources

presented by

<u>Xiong Xiao¹</u>, Shengkui Zhao², Thi Ngoc Tho Nguyen², Douglas L. Jones², Eng Siong Chng^{1,3}, Haizhou Li^{1,3,4}

¹Temasek Lab@NTU, Nanyang Technological University, Singapore.
²Advanced Digital Sciences Center, Singapore.
³School of Computer Engineering, Nanyang Technological University, Singapore.
⁴Department of Human Language Technology, Institute for Infocomm Research, Singapore.

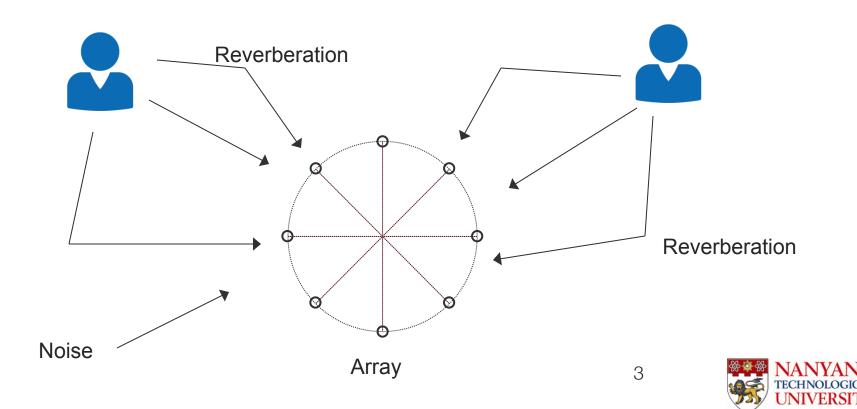
Outline

- Task definition and literature review
- Proposed EM-based eigenvector clustering
 - Time-frequency (TF) bins selection
 - Extraction of eigenvectors
 - Generative modeling of eigenvectors
 - EM-based eigenvector clustering
- Experiments
- Conclusions



Task definition

- Detect the direction-of-arrival (DOA) of multiple speakers simultaneously in noisy and reverberant environments.
- We use a circular array: Diameter = 20cm, 8 microphones



Review on Multiple Source Localization

- Angular spectrum based approach
 - Define an angular spectrum that is a function of DOA/TDOA.
 - Find the peaks in angular spectrum, one peak for one source. and then estimate the DOA/TDOA from the peaks.
 - Example: MUSIC [1], GCC-PHAT [2].
- Clustering based approach
 - Assume sparsity in time-frequency (TF) spectrogram representation of speech --every TF bin is dominated by only 1 source.
 - Cluster the TF bins into several clusters. One cluster represent one source. Then estimate DOA/TDOA for each cluster.
 - Examples: normalized observation vector clustering [3], MESSL [4]

[1] R. Schmidt, Multiple emitter location and signal parameter estimation, IEEE Transactions on Antennas and Propagation 34 (3) (1986) 276–280.

[2] C. Knapp, G. Carter, The generalized cross-correlation method for estimation of time delay, IEEE Transactions on Acoustics, Speech and Signal Processing 24 (4) (1976) 320–327.

[3] S. Araki, H. Sawada, R. Mukai, and S. Makino, "DOA estimation for multiple sparse sources with normalized observation vector clustering," in *ICASSP 2006.*

[4] MichaelMandel,RonJWeiss,DanielPWEllis,etal., "Model- based expectation-maximization source separation and localization," *IEEE Transactions on Audio, Speech, and Language Processing*, vol. 18, no. 2, pp. 382–394, 2010.



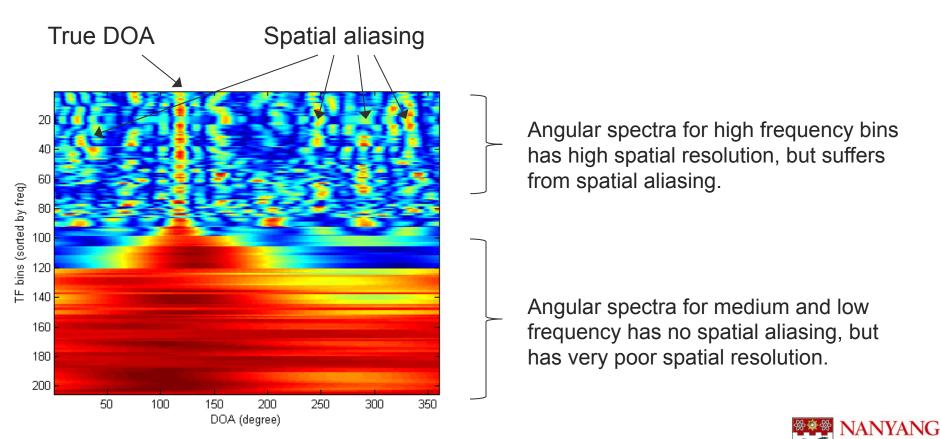
Issue 1: The correctness of the sparsity assumption

- The sparsity assumption of TF representation is not realistic for reverberant and noisy scenarios.
 - Reverberation will cause the power of the sources to spread to many future frames.
 - Ambient noise affects large proportion of TF bins.
- One solution is to model the reverberation and noise explicitly in clustering.
- We argue that it may be easier to just ignore the TF bins in poor condition (i.e. low SNR, higher reverberation).
- We propose to first select TF bins in good condition, and then apply the TF bin clustering algorithm.



Issue 2: Comparing different frequency bins

- Angular spectra at high and low frequency bins have their strength and limitation. They need to be combined to achieve accurate and robust DOA estimation.
- However, the TF bins at different frequencies cannot be compared directly. Even normalizations [3] cannot deal with spatial aliasing.
- In this work, we design an EM framework that can deal with all frequencies naturally.



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[3] S. Araki, H. Sawada, R. Mukai, and S. Makino, "DOA estimation for multiple sparse sources with normalized observation vector clustering," in *ICASSP 2006.*

Outline

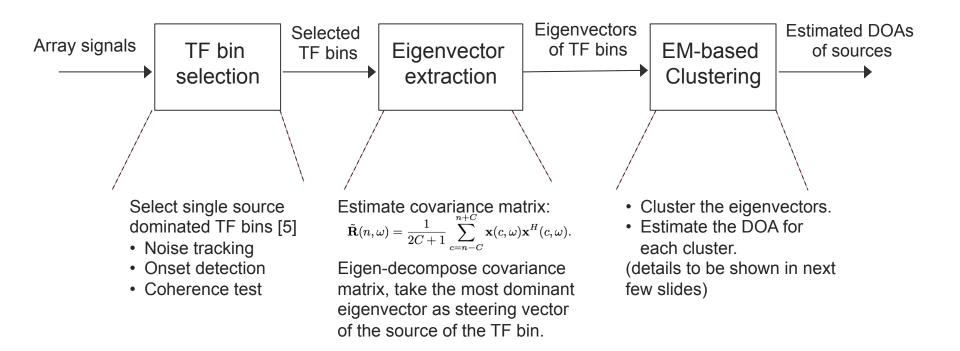
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System Diagram

The proposed method consists of 3 steps:

- Step 1: select TF bins with low reverberation and high SNR, and dominated by one source [5].
- Step 2: estimate the spatial covariance for the selected TF bins, get the dominant eigenvector.
- Step 3: perform EM-based clustering of the TF bins using the eigenvectors as features.



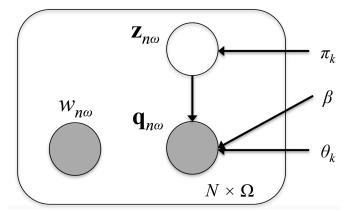


Generative modeling of eigenvectors

- Assume there are K sources
- We model the distribution of the TF bin eigenvectors by a mixture density function with K component density functions.

$$p(w_{n\omega}, \mathbf{q}_{n\omega}; \Theta) = \sum_{k=1}^{K} p(z_{n\omega k} = 1) p(w_{n\omega}, \mathbf{q}_{n\omega} | z_{n\omega k} = 1; \theta_k)$$

- One component of the mixture represents one source. The clustering process is equal to the maximizing of the likelihood of the observations (the eigenvector and its reliability measure).
- $\mathbf{q}_{n\omega}$ is the eigenvector (observation) at frame n and frequency $\boldsymbol{\omega}$.
- $\mathcal{W}_{n\omega}$ is a reliability measure of $\mathbf{q}_{n\omega}$. It is also an observation.
- $\mathbf{Z}_{n\omega}$ is a latent variable that denotes the cluster membership of $\mathbf{q}_{n\omega}$.
- N: total number of frames, Ω : number of frequency bins.
- K is the number of sources.



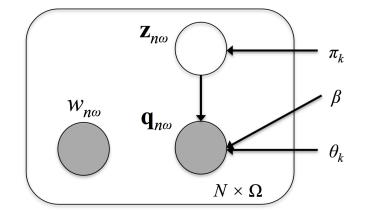
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Definition of component densities

Component weights

$$p(z_{n\omega k} = 1) = \pi_k, \quad k \in [1, K],$$
$$\sum_{k=1}^{K} \pi_k = 1.$$



• Component density function

$$p(w_{n\omega}, \mathbf{q}_{n\omega}|z_{n\omega j} = 1; \theta_j) =$$

$$rac{\exp(eta w_{n\omega} | \mathbf{q}_{n\omega}^H \mathbf{e}_{j\omega} |)}{\mathcal{E}(eta, heta_j)}$$

- $-|\mathbf{q}_{n\omega}^{H}\mathbf{e}_{j\omega}|$ measures how much the eigenvector agrees with steering vector $\mathbf{e}_{j\omega}$.
- The more the eigenvector agrees with the steering vector, the higher the likelihood. - $\mathcal{E}(\beta, \theta_j) = \int_{\mathbf{q}_{n\omega}, w_{n\omega}, \omega} \exp(\beta w_{n\omega} |\mathbf{q}_{n\omega}^H \mathbf{e}_{j\omega}|) d\mathbf{q}_{n\omega} dw_{n\omega} d\omega$ is the normalization term and ensures that the distribution integrates to 1.
- We assure that the normalization term is independent of the DOA for simplicity.
- Mixture density function

$$p(w_{n\omega}, \mathbf{q}_{n\omega}; \Theta) = \sum_{k=1}^{K} \pi_k \frac{\exp(\beta w_{n\omega} |\mathbf{q}_{n\omega}^H \mathbf{e}_{k\omega}|)}{\mathcal{E}(\beta)} \quad 10$$



EM-based clustering – iterative algorithm

- We maximize the auxiliary function of EM.
- E-step: compute the membership function of TF bins

$$\gamma_{n\omega k} = p(z_{n\omega k} = 1 | w_{n\omega}, \mathbf{q}_{n\omega}; \Theta') = \frac{\pi_k \exp(\beta w_{n\omega} | \mathbf{q}_{n\omega}^H \mathbf{e}_{k\omega} |)}{\sum_{j=1}^K \pi_j \exp(\beta w_{n\omega} | \mathbf{q}_{n\omega}^H \mathbf{e}_{j\omega} |)}$$

- For efficient implementation, we can use "winner take all" membership function, i.e. each TF bin is assigned to one and only one cluster.
- M-step: estimate the DOA for each cluster based on the TF bins that are assigned to the cluster by the membership function:

$$\hat{ heta}_k = rg\max_{ heta_k \in [0,359]} \sum_{\{n,\omega\} \in \Psi} \gamma_{n\omega k} eta w_{n\omega} |\mathbf{q}_{n\omega}^H \mathbf{e}_{k\omega}|$$

- A grid search (0-359 degrees) can be performed to find the optimal DOA.
- With "winner take all" membership function, the EM algorithm becomes like kmeans clustering. However, a key difference is that we use a set of template steering vectors for each cluster. 11

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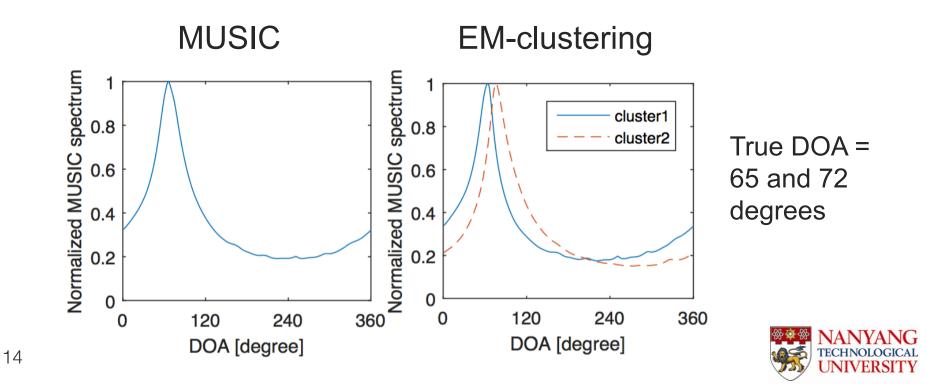
Experiments – Data Description

- Array geometry: 8-microphones circular, 20cm diameter.
- 2D DOA estimation, 0-359 degrees
- 16kHz sampling rate, 512 FFT length
- Simulated test data
 - Synthesized by convolving clean speech signal from WSJCAM0 to simulated room impulse response. Additive noise is added later.
 - T60 times from 0.3s to 0.9s. SNR from 0dB to 20dB.
- Real test data
 - Three scenarios: small meeting room (4mx3mx2.5m, T60=0.34s), pantry room (6mx5mx2.5m, T60=0.47s), and lift lobby (8mx4m,3m, T60=1.07s).
 - A male speaker's voice was recorded at 0, 45, 90 degrees.
 - A female speaker's voice was recorded at 135, 180, 225 degrees.
 - Various mixtures can be simulated by combining these recordings.
 - All test utterances are 6s in length.



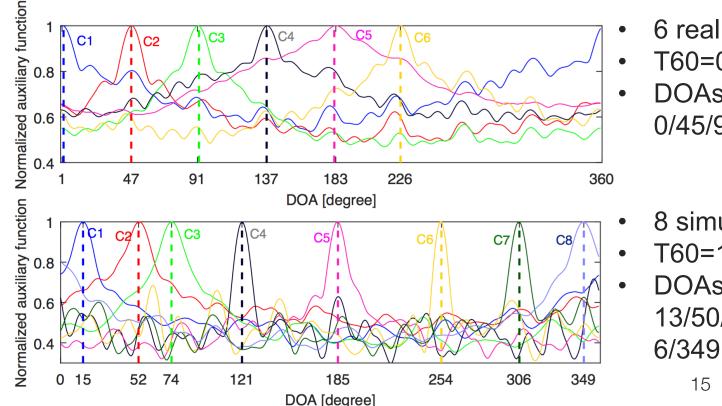
Ability to resolve closely spaced speakers

- MUSIC spatial spectrum is not able to resolve two closely spaced speakers (65 and 72 degrees). Only one peak in the spectrum.
- The proposed EM based clustering produces two clusters, each corresponds to one source.



Ability to detect multiple sources

 The proposed EM-based clustering is able to detect up to 6 real sources and 8 simulated sources accurately.



Plot of normalized auxiliary function of clusters

- 6 real sources,
- T60=0.47s.
- DOAs = 0/45/90/135/180/225
- 8 simulated sources,
- T60=1.0s, SNR = 20dB
- DOAs =

13/50/74/118/186/254/30



Results on Simulated Data (2 sources)

- MUSIC: angular spectrum based method
- Algorithm [14]: k-means clustering of TF bins proposed in [15]. (Typo in the paper)
 - Select TF bins (same as this work).
 - Find DOA of each TF bin, then cluster the DOAs.
 - Due to spatial aliasing, only uses TF bins below 1700Hz.
- Proposed: the EM-based eigenvector clustering proposed in this paper.

Room	Method	SNR=20dB	SNR=10dB	SNR=0dB
Small	MUSIC	15.51	18.30	23.76
	Algorithm[14]	14.26	18.41	20.50
	Proposed	2.78	2.84	6.75
Medium	MUSIC	13.67	9.41	12.37
	Algorithm[14]	18.19	10.97	14.12
	Proposed	3.76	5.15	3.07
Large	MUSIC	7.87	4.99	14.94
	Algorithm[14]	11.70	10.10	11.49
	Proposed	1.17	2.04	9.47

The numbers are root mean square of DOA estimation errors are compared.

[15] TNT Nguyen, S. Zhao, and Douglas L. Jones, "Robust DOA estimation of multiple speech sources," in *ICASSP 2014.*



Results on Real Data (2 sources)

- DOA ground truth is obtained by using MUSIC for each singlesource recordings individually.
- Significant improvement over MUSIC and the k-means algorithm.

		Testing Environment		
		small	pantry	lift
Method	MUSIC	33.43	28.7	62.66
	Algorithm[14]	40.74	42.92	70.02
	Proposed	1.7	0.92	13.02

T60 of small room = 0.34sT60 of pantry room = 0.47sT60 of lift = 1.07s

Conclusions

- We propose an EM-based eigenvector clustering methods for multi-source DOA estimation.
 - Selection of TF bins that are dominated by one source.
 - Multiple steering vectors for each cluster to use information in all frequency bins.
- Significant improvement can be obtained compared to MUSIC and a k-means clustering method.
- Future work
 - Automatic determination of number of sources
 - Better modeling of eigenvectors
 - Extend to source separation (cluster all TF bins)



Thank you!

