

Introduction

Spectrum sensing scenario:



- Observations $\mathbf{x}[n]$ from *L* antennas
- Test whether or not a primary user is transmitting
- Digital communication signals are cyclostationary (CS)

$$\mathbb{E}\left[\mathbf{x}[n]\mathbf{x}^{H}[n-k]\right] = \mathbf{M}_{1}[n,k] = \mathbf{M}_{1}[n+\mathbf{P},k]$$

Noise is modeled as wide-sense stationary (WSS)

$$\mathbb{E}\left[\mathbf{x}[n]\mathbf{x}^{H}[n-k]\right] = \mathbf{M}_{0}[k]$$

- Existing test: CS vs. WSS [1]
- **Contribution**: Tests for more specific noise models:
 - temporally colored and spatially uncorrelated
 - II temporally white and spatially correlated
 - III temporally white and spatially uncorrelated

Problem formulation

- Cycle period *P* is integer-valued and known
- NP samples of $\mathbf{x}[n]$ are collected in

$$\mathbf{y} = \begin{bmatrix} \mathbf{x}^T [0] \dots \mathbf{x}^T [NP - 1] \end{bmatrix}^T$$

• Assuming $\mathbf{x}[n] \sim \mathcal{CN}$, the hypotheses are

$$egin{aligned} \mathcal{H}_1: \mathbf{y} &\sim \mathcal{CN}(\mathbf{0}, \mathbf{R}_1) \ \mathcal{H}_0: \mathbf{y} &\sim \mathcal{CN}(\mathbf{0}, \mathbf{R}_0) \end{aligned}$$

• Relation $\mathbf{M}[n, k] \leftrightarrow \mathbf{R}$

$$\mathbf{R} = \begin{bmatrix} \mathbf{M}[0,0] & \dots & \mathbf{M}[0,-NP+1] \\ \dots & \ddots & \dots \\ \mathbf{M}[NP-1,NP-1] & \dots & \mathbf{M}[NP-1,0] \end{bmatrix}.$$

• Test about the structure of the covariance matrix



- The exact values of the matrices are unknown
 - Composite hypothesis test: UMPIT, LMPIT, GLRT,...
 - no closed-form ML estimates of block-Toeplitz matrices

Detection of cyclostationarity in the presence of temporal or spatial structure with applications to cognitive radio

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Approximation

- Approximation $(N \to \infty)$: block-Toeplitz \simeq block-circulant
- Linear transformation $\mathbf{y} \mapsto \mathbf{z}$
- Asymptotically equivalent hypotheses

 $\mathcal{H}_1: \mathbf{z} \sim \mathcal{CN}(\mathbf{0}, \mathbf{S}_1)$ $\mathcal{H}_0: \mathbf{z} \sim \mathcal{CN}(\mathbf{0}, \mathbf{S}_0)$

• Covariance matrices are block-diagonal closed-form ML estimates exist







ML estimates

- $M \ge LP$ i.i.d. realizations \mathbf{z}_i
- Sample covariance matrix $\hat{\mathbf{S}} = \frac{1}{M} \sum_{i=1}^{M} \mathbf{z}_i \mathbf{z}_i^H$



- diag_B ($\hat{\mathbf{S}}$) returns the diagonal blocks of size $B \times B$
- the *k*th diagonal block of $\hat{\mathbf{S}}$ with size $L \times L$ is $\hat{\mathbf{S}}_k$

• Then the estimates are

• $\hat{\mathbf{S}}_1 = \operatorname{diag}_{LP}(\hat{\mathbf{S}})$

• case I:
$$\hat{\mathbf{S}}_0 = \operatorname{diag}_1(\hat{\mathbf{S}})$$

• case II:
$$\hat{\mathbf{S}}_0 = \mathbf{I}_{NP} \otimes \begin{bmatrix} \frac{1}{NP} \sum_{k=1}^{NP} \hat{\mathbf{S}}_k \end{bmatrix}$$

• case III: $\hat{\mathbf{S}}_0 = \mathbf{I}_{NP} \otimes \begin{bmatrix} \frac{1}{NP} \sum_{k=1}^{NP} \text{diag}_1(\hat{\mathbf{S}}_k) \end{bmatrix}$

k=1• Sample coherence matrix:

$$\hat{\mathbf{C}} = \hat{\mathbf{S}}_0^{-1/2} \hat{\mathbf{S}}_1 \hat{\mathbf{S}}_0^{-1/2}$$

Asymptotic GLRTs

$$\det(\hat{\mathbf{C}}) \mathop{\gtrless}\limits^{\mathcal{H}_0}_{\mathcal{H}_1} \eta$$



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Numerical results

• Observations are simulated as

$$\mathcal{H}_1 : \mathbf{x}[n] = (\mathbf{H} * \mathbf{s})[n] + \mathbf{w}[n]$$

 $\mathcal{H}_0 : \mathbf{x}[n] = \mathbf{w}[n],$

- QPSK signal $\mathbf{s}[n]$ with symbol length P = 4
- N = 16, M = 20
- Rayleigh fading channel H[n] with exponential power delay profile
- Noise $\mathbf{w}[n]$
 - ► if temporally colored: white noise filtered through moving average filter
- Probability of missed detection $(P_{\rm MD})$ at a false alarm rate of 10^{-3}
 - ► solid lines: proposed GLRT
 - ▶ dashed lines: GLRT from [1]



• ROC curve for case III at an SNR of $-8 \,\mathrm{dB}$



Bibliography

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