# Fully Supervised Speaker Diarization Say Goodbye to clustering

## Overview

- Most existing speaker diarization systems are based on unsupervised clustering approaches, such as k-means or hierarchical clustering.
- We propose UIS-RNN, a trainable model for segmenting and clustering temporal data by learning from examples.
- New state-of-the-art on CALLHOME, while decoding is online.



## **Baseline Diarization System**



Fig. Multi-layer LSTM network as speaker Fig. Baseline diarization system using d-vectors and unsupervised clustering. encoder

- Speaker encoder is trained with "Generalized End-to-End Loss for Speaker Verification", ICASSP 2018. Proven to be better than softmax or triplet loss.
- Speaker embeddings (d-vectors) are extracted on sliding windows of length 240ms with 50% overlap, using log-mel-filterbank energies as features.
- Window-wise d-vectors are aggregated on non-overlapping segments. Segments are determined by VAD and a maximal length limit of 400ms.
- A modified version of spectral clustering on segment-wise embeddings, using eigen-gap for number of speakers, produces state-of-the-art performance.
- This baseline system is described in "Speaker Diarization with LSTM", ICASSP 2018. A lecture is available on **> YouTube**













### I would like to sort of buy needle interrupt

Speaker2

I would like to sort of buy needle interrupt



without supervised or temporal information.



**Clustering is Not Good Enough Experiment Results** Datasets: NIST SRE 2000 Disk-8 (CALLHOME), Disk-6, and ICSI. How many clusters UIS-RNN requires training, so we evaluated with three different setups: indomain training, off-domain training, and in-domain plus off-domain training. In-domain 5-fold Fold 2 evaluation trair Off-domain Disk-8 Disk-6 ICSI evaluation **UIS-RNN** Disk-8 Fold 1 Fold 2 Fold 3 Fold 4 Fold 5 All data 5-fold  $\times 5$ Disk-6 ICSI We model the **generative process** of the speaker embedding sequence: evaluation  $p(\mathbf{x}_t, y_t, z_t | \mathbf{x}_{[t-1]}, y_{[t-1]}, z_{[t-1]})$  $\{\mathbf{x}_t\}$ : embedding sequence **Conclusions:** Table. DER (%) on NIST SRE 2000 Disk-8  $= p(\mathbf{x}_t | \mathbf{x}_{[t-1]}, y_{[t]}) \cdot p(y_t | z_t, y_{[t-1]}) \cdot p(z_t | z_{[t-1]})$  { $y_t$ }: label sequence CALLHOME), compared with other teams' work  $\{z_t\}$ : binary speaker changes VB for Variational Bayesian resegmentation. speaker change speaker assignment sequence generation we have in-domain training data with Method Training data DER (%) Speaker assignment **Speaker change** timestamped speaker labels. 12.3 k-means • Speaker labels are assigned using • I.I.D. coin flipping distribution: spectral • What is learned by UIS-RNN: (1) 8.8 Chinese restaurant process (CRP) **UIS-RNN** 5-fold 8.5  $p(z_t = 0 | z_{[t-1]}, \boldsymbol{\lambda}) = p_0$ Dialogue styles; (2) Domain-specific Disk-6 + ICSI **UIS-RNN** 8.2 hints for speaker turns. **UIS-RNN** 5-fold + Disk-6 + ICSI 7.6 Castaldo et al. 13.7 E. Shum *et al.* 14.5 12.1 Senoussaoui et al. Sell *et al.* (+VB) 13.7 (11.5) Sequence generation to further improve quality. Garcia-Romero et al. (+VB) 12.8 (9.9) Each speaker is modeled by an RNN instance, all sharing same parameters. **More Information** Each instance has its own states. States of different speakers interleave in the time domain. Core algorithm on **GitHub** Full lecture is available on **> YouTube** Each embedding follows a Gaussian, where the mean is this speaker's average RNN output so far. Google I... 📮 google / uis-rnn **Data:**  $\mathbf{X}^{test} = (\mathbf{x}_1^{test}, \mathbf{x}_2^{test}, \dots, \mathbf{x}_T^{test})$ Fig (Left). Four Pull requests 0 Pulse Communi **Result:**  $\mathbf{Y}^* = (y_1^*, y_2^*, \dots, y_T^*)$ possible generative **Fully Supervised Speaker Diarization** initialize  $\mathbf{x}_0 = \mathbf{0}, \mathbf{h}_0 = \mathbf{0};$ paths in an example Say Goodbye to clustering for t = 1, 2, ..., T do python 3 sequence. o the paper Fully Supervised Speaker Diarization.  $(y_t^*, z_t^*) = \arg \max_{(y_t, z_t)} (\ln p(z_t))$ Aonan Zhang, Quan Wang, Zhenyao Zhu, ttps://arxiv.org/abs/1810.0471  $+ \ln p(y_t | z_t, y^*_{[t-1]})$ John Paisley, Chong Wang codecov Fig (Right). Online  $+ \ \ln p(\mathbf{x}_t | \mathbf{x}_{[t-1]}, y^*_{[t-1]}, y_t))$ Quan Wang Presented by: greedy MAP upervised-learning update  $N_{k,t-1}$  and GRU hidden states; ► ► • • 0:00 decoding algorithm.

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- Supervised diarization is helpful, when
- Future work: (1) Speaker change: coin flipping  $\rightarrow$  RNN; (2) Unlabeled data as part of training set; (3) Offline decoding



