



System of quadratic equations

- Quadratic measurements obtained with high-rank measurement matrices arise in applications such as unassigned distance geometry problem.
- Most prior works focus on rank-1 psd measurement matrices or real measurements.
- Measurement Model:

$$y_i = \boldsymbol{x}^* \boldsymbol{A}_i \boldsymbol{x}, \quad i = 1, \cdots, m.$$

- $oldsymbol{x} \in \mathbb{C}^n$ is the complex signal.
- $y_i \in \mathbb{C}$ is the *i*-th complex quadratic measurement.
- $A_i \in \mathbb{C}^{n \times n}$ is the *i*-th complex random Gaussian measurement matrix.

Problem formulation

We minimize the following objective function $f(\boldsymbol{z})$:

$$f(\boldsymbol{z}) = rac{1}{m} \sum_{i=1}^{m} |\boldsymbol{z}^* \boldsymbol{A}_i \boldsymbol{z} - y_i|^2 ,$$

using gradient descent:

$$\boldsymbol{z}^{(t+1)} = \boldsymbol{z}^{(t)} - \eta \nabla f(\boldsymbol{z}) ,$$

where $\eta > 0$ is the step size.

- Nonconvex optimization problem.
- $\mathbf{x}e^{\mathbf{j}\phi}$ is a global minimum solution for all $\phi \in [0, 2\pi)$.
- The distance between the recovered z and a global minimum solution x is

$$\operatorname{dist}(\boldsymbol{z}, \boldsymbol{x}) = \min_{\boldsymbol{\phi} \in [0, 2\pi)} \left\| \boldsymbol{z} - \boldsymbol{x} e^{\boldsymbol{j} \boldsymbol{\phi}} \right\|_2$$

Figure 1:A good initialization is needed to solve a nonconvex optimization problem via gradient descent.

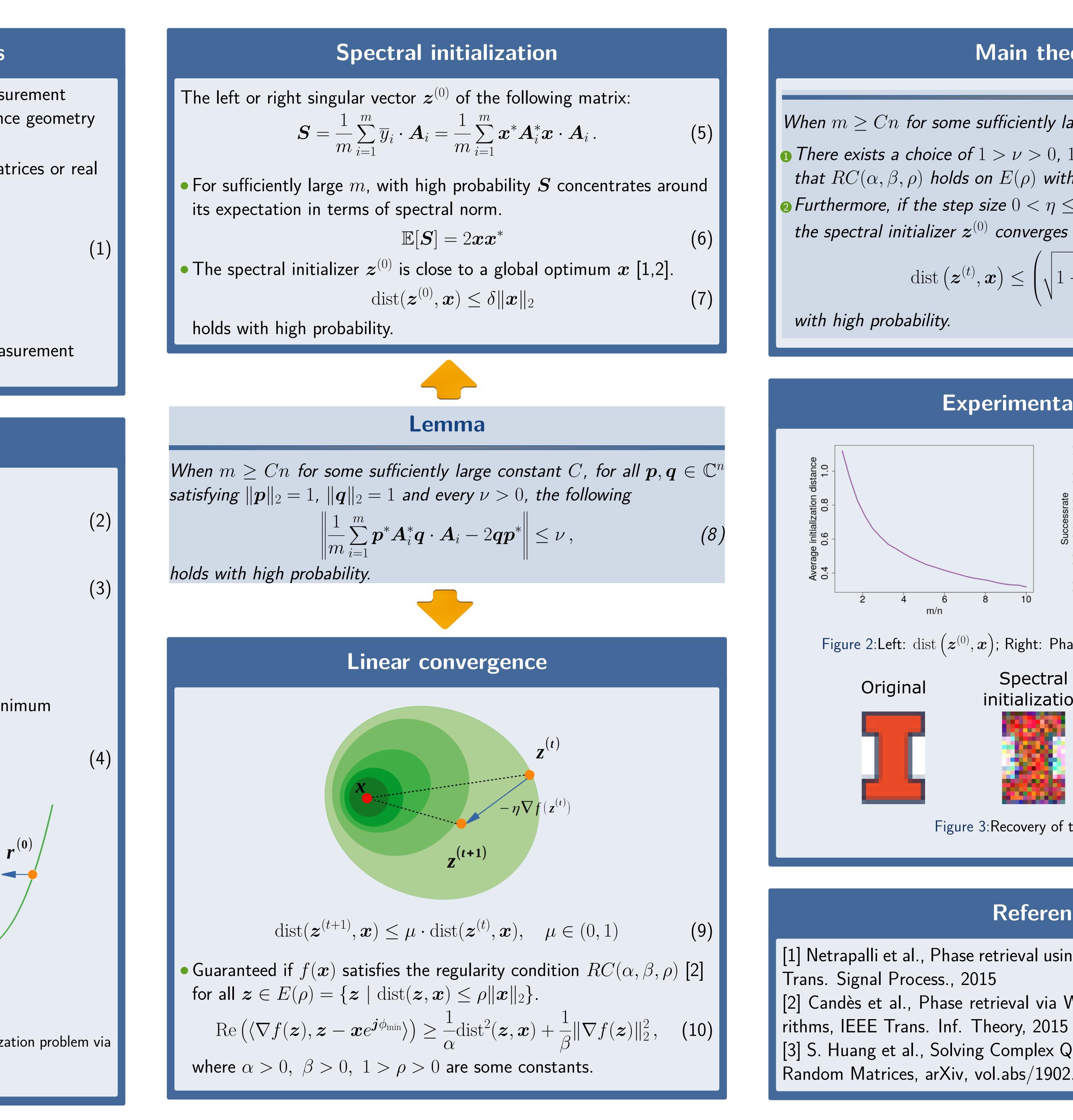
 $\mathbf{z}^{(\mathbf{0})}$

X

Solving Complex Quadratic Equations with Full-rank Random Gaussian Matrices

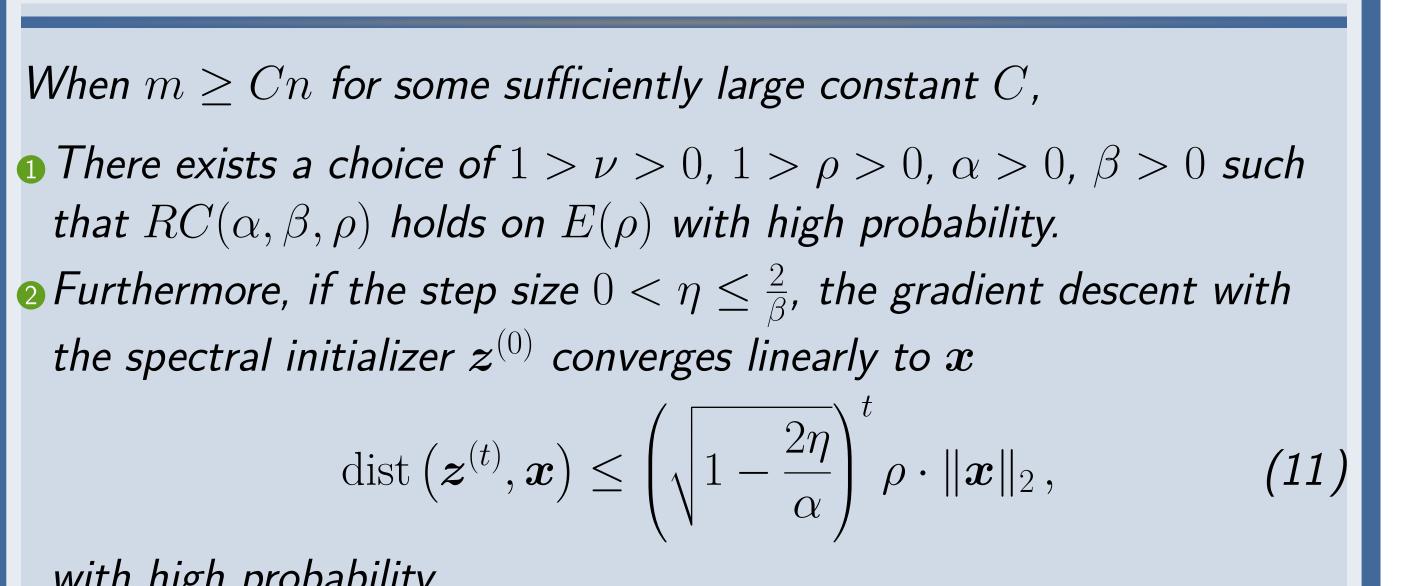
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Main theorem



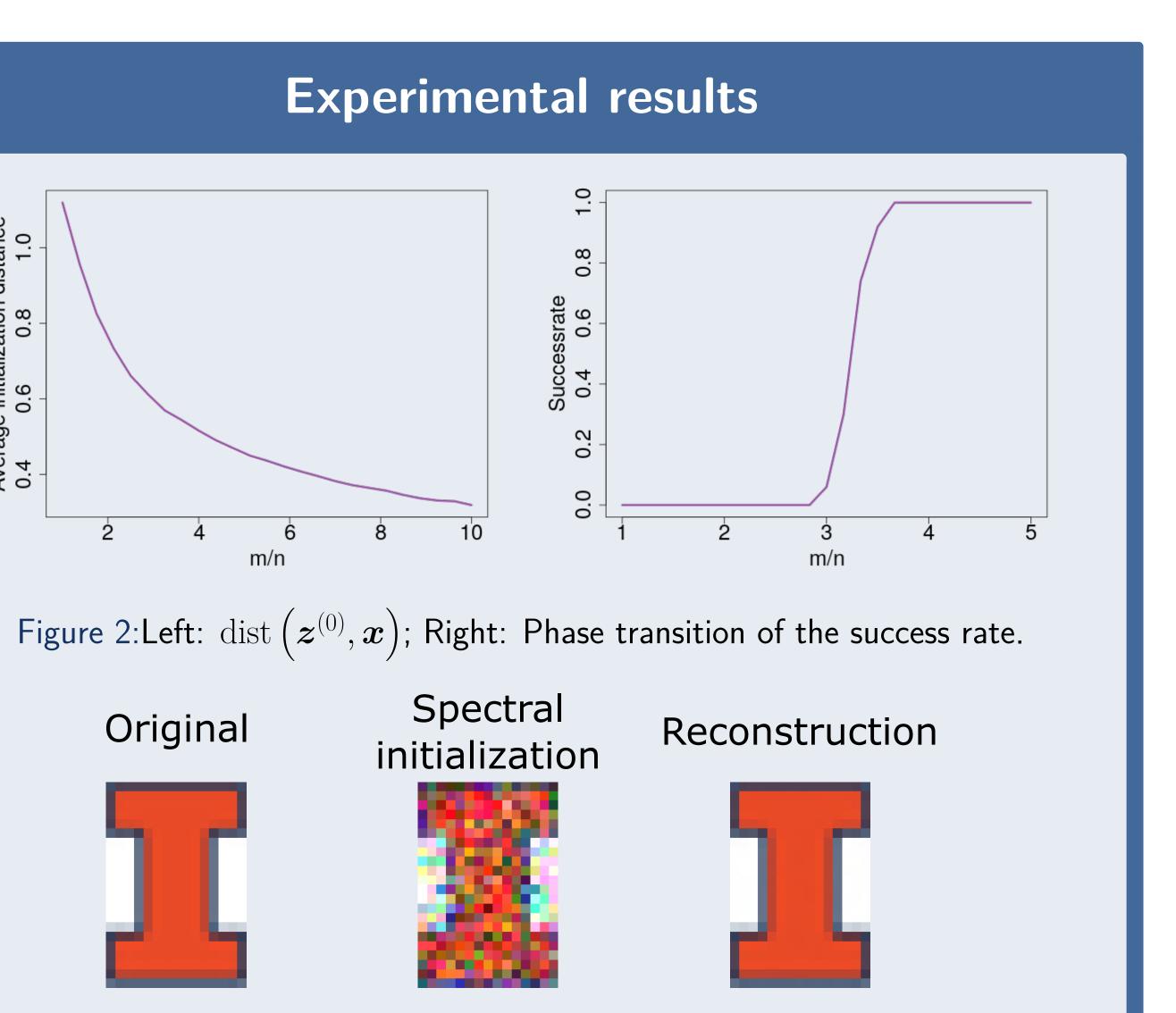


Figure 3: Recovery of the UIUC logo.

References

- [1] Netrapalli et al., Phase retrieval using alternating minimization, IEEE
- [2] Candès et al., Phase retrieval via Wirtinger flow: Theory and algo-
- [3] S. Huang et al., Solving Complex Quadratic Systems with Full-Rank Random Matrices, arXiv, vol.abs/1902.05612, 2019