TV-DCT: Method to impute Gene Expression data using DCT based Sparsity and Total Variation Denoising



Introduction

- High dimensional genomics data such as microarray gene expression data and RNA sequencing data, generally suffers from missing values. • Incomplete data can adversely affect the downstream analysis for
- diagnostics and treatment.
- Several methods to impute missing values in gene expression data have been developed, but most of these work at high levels of observability.
- Interdependence between the expression levels of genes in gene expression data leads to a highly correlated data matrix (of subjects versus genes). Gene expression matrix can be considered as a low rank matrix embedded into a lower dimensional linear subspace. Further, missing value imputation in genomics can be viewed as a matrix completion problem.
- We propose a novel 2-stage method, namely, TV-DCT method for predicting missing values in gene expression data using Discrete Cosine Transform DCT based sparsity in Stage-1 and Total Variation (TV) denoising in Stage-2 .

Proposed Method

Proposed TV-DCT method for completing the gene expression matrix is a 2-stage method.

Stage-1: Compressive Sensing Framework

- Columns of gene expression matrix are highly sparse in the DCT domain because every column represents the expression values of a particular gene across subjects that would be biologically similar and hence, data within any column would be slowly varying in nature.
- Hence, we propose to recover missing data column-wise, i.e., by applying CS framework on each column of the matrix **Y**. The sensing matrix Φ_i of size $r_i \times m$ is constructed for every ith column, where r_i denotes the number of observed entries in that column.
- Every ith column of matrix **Y** using the CS-based reconstruction with the sparsity constraint on the column in the DCT domain as

$$\min_{\tilde{\mathbf{x}}_i}(||\mathbf{y}_i - \Phi_i \tilde{\mathbf{x}}_i||_2^2 + \lambda_1 ||\mathbf{D}\tilde{\mathbf{x}}_i||_1)$$

• Since DCT is an orthogonal transform, we transformed it to synthesis prior formulation as $\min_{\tilde{\mathbf{z}}_i}(||\mathbf{y}_i - \Phi_i \mathbf{D}^T \mathbf{z}_i||_2^2 + \lambda_1 ||\mathbf{z}_i||_1)$ (2)

Stage-2: Denoising Framework

• Recovered matrix from stage-1 is assumed to be the noisy version of the original matrix and denoising is used in Stage-2. Total Variation (TV) based denoising is used in Stage-2 and is formulated as-

$$\min_{\mathbf{x}_i}(||\mathbf{x}_i - \tilde{\mathbf{x}}_i||_2^2 + \lambda_2 ||\mathbf{A}\mathbf{x}_i||_1)$$

where i ranges from 1 to n (number of columns/ genes).

• A is a difference operator defined as

$$\mathbf{A} = \begin{bmatrix} -1 & 1 & & & \\ & -1 & 1 & & \\ & & \ddots & \\ & & & -1 & 1 \end{bmatrix}$$

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(1)

(3)

• It maps a vector x, to

$$(\mathbf{A}\mathbf{x}_{i}^{k}) = \mathbf{x}_{i}^{k} - \mathbf{x}_{i}^{k+1}$$
 (4)
used to solve the optimization framework (because

 Dual formulation of above is u non-differentiability of L₁-norm) as

$$\min_{\mathbf{x}_i} \max_{|\mathbf{w}_i| \le 1} (||\mathbf{x}_i - \tilde{\mathbf{x}}_i||_2^2 + \lambda_2 \mathbf{w}_i^T \mathbf{A} \mathbf{x}_i)$$
(5)

where w_i is an auxiliary vector such that

$$||\mathbf{x}_i||_1 = \max_{|\mathbf{w}_i| \le 1} (\mathbf{w}_i^T \mathbf{x}_i)$$
(6)

• TV denoising problem is minimized using iterative clipping algorithm with update equations as given in algorithm where,





Fig. 2: Classification Accuracy and F₁ score obtained on imputed matrices of ALLAML dataset at varying sampling ratios.

Table 1:. Classification accuracy and F₁ scores on different samp recovered/imputed matrix using proposed TV-DCT method for A

	Classification Accuracy				F ₁ score			
Classifier	Random Forest		Linear SVM		Random Forest		Linear SVM	
SR	Observed	Imputed	Observed	Imputed	Observed	Imputed	Observed	Imputed
20	0.65	0.96	0.67	0.90	0.77	0.96	0.79	0.90
30	0.65	0.96	0.67	0.93	0.77	0.96	0.80	0.95
40	0.69	0.97	0.72	0.94	0.79	0.97	0.82	0.95
50	0.71	0.97	0.74	0.97	0.80	0.97	0.83	0.98
60	0.75	0.97	0.81	0.98	0.83	0.97	0.87	0.99
70	0.77	0.96	0.86	0.99	0.84	0.97	0.90	0.99
80	0.80	0.95	0.91	0.99	0.86	0.96	0.93	0.99
90	0.85	0.95	0.94	0.99	0.88	0.96	0.96	0.99

ling percentage of incomplete matrix and th	าе
ALLAML dataset	

Algorithm

- 1 Stage 1 Matrix Recovery Input: Y (Input incomplete matrix), DCT matrix D
- 2 for loop from $i = 1, \dots, n$
- 3 Calculate Φ_i for all *i* using \mathbf{y}_i
- 4 while converge: $\mathbf{z}_{i}^{k+1} = soft\left\{\mathbf{z}_{i}^{k} + \frac{1}{\alpha}(\mathbf{D}\Phi_{i}^{T})(\mathbf{y}_{i} - \Phi_{i}\mathbf{D}^{T}\mathbf{z}_{i}^{k}), \frac{\lambda_{1}}{2\alpha}\right\}$
- 5 end while
- 6 $\tilde{\mathbf{x}}_i = \mathbf{D}^T \mathbf{z}_i$
- 7 end for
- 8 Obtain X from $\tilde{\mathbf{x}}_i$
- Output: X (Recovered Matrix) 9 Stage 2 - Denoising
- Input: X(Noisy matrix), A (Difference Operator)
- 10 for loop from $i = 1, \dots, n$
- 11 while converge:
- 12 $\mathbf{x}_i^{k+1} = \tilde{\mathbf{x}}_i \mathbf{A}^T \mathbf{w}_i^k$
- 13 $\mathbf{w}_i^{k+1} = clip\left\{\mathbf{w}_i^k + \left(\frac{1}{\alpha}\right)\mathbf{A}\mathbf{x}_i^{k+1}, \frac{\lambda_2}{2}\right\}$
- 14 end while
- 15 end for
- 16 Obtain X from \mathbf{x}_i
- 17 $\mathbf{x}_{j,i} = \hat{\mathbf{x}}_{j,i}, if \ \Omega_{j,i} = 1$ **Output:** X (Recovered Matrix)

Evaluation metric is Normalized Root Mean Square Error defined as

NRMSE =

Conclusion

- classification accuracy.

References

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(a) Dark Blue color shows missing values



(b) Imputed Matrix

Fig. 1: 16x16 patch of Incomplete and Imputed matrix.

 $||\mathbf{X}(original) - \mathbf{X}(recovered)||_F$ $||\hat{\mathbf{X}}(original)||_{F}$

(7)

• In this study, we have presented novel TV-DCT method that is a 2-stage matrix imputation method and we have investigated the performance of our proposed method at low as well as high observability of data.

• The comparative performance of TV-DCT method is observed to be superior to three state-of-the-art matrix completion methods in terms of NRMSE and

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