

MAXIMALLY SEPARATED AVERAGES PREDICTION FOR HIGH FIDELITY REVERSIBLE DATA HIDING

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1. Background

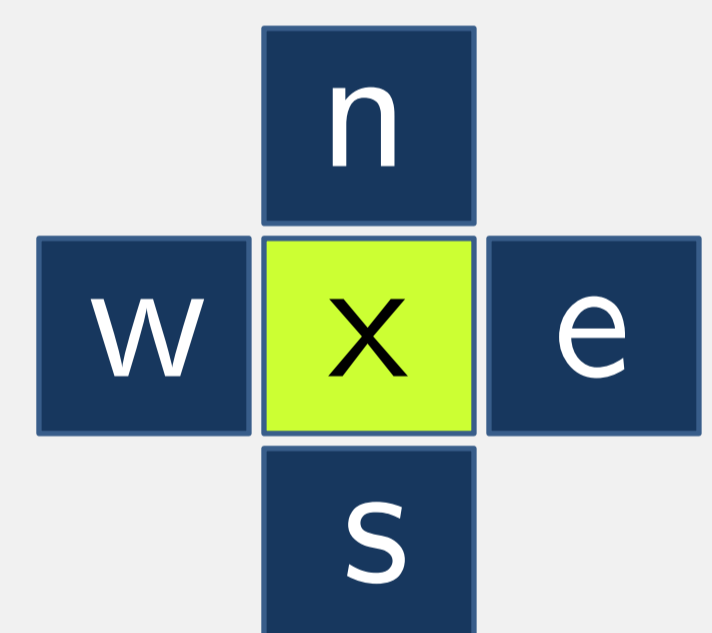
- ✓ Prediction-error histogram (PEH) sharpness (often estimated by how low PEH entropy is) is an important determinant of performance (embedding distortion minimization) of prediction-error expansion based reversible data hiding (RDH).
- ✓ Common approaches for low entropy PEH generation in RDH are:

Pixel sorting (PS): use smooth pixels for PEH generation **Pixel pairing (PP):** pair up correlated pixels for sharper 2D PEH generation **Better Prediction:** improve prediction accuracy to obtain sharper PEH

- ✓ Some recent RDH schemes including [2], [3] have utilized PS and PP simultaneously to achieve high performance.
- ✓ To perform PS and flexible PP, such schemes limit the prediction context to the 4-neighbour pixels and use rhombus 4-neighbour average) predictor (introduced in [1]).
- ✓ Predictors better than rhombus exist (e.g., [4]), but cannot be easily used with the 4-neighbour prediction context.

Motivation: To design a sharp-PEH-generating predictor that can be used together with pixel pairing and pixel sorting to achieve high RDH performance.

2. Maximally Separated Averages (MSA) Predictor



4-neighbour prediction context

Step 2: Compute the values:
 $v_L = \min S$ and
 $v_H = \max S$

Step 1: Compute the set of two-neighbour averages

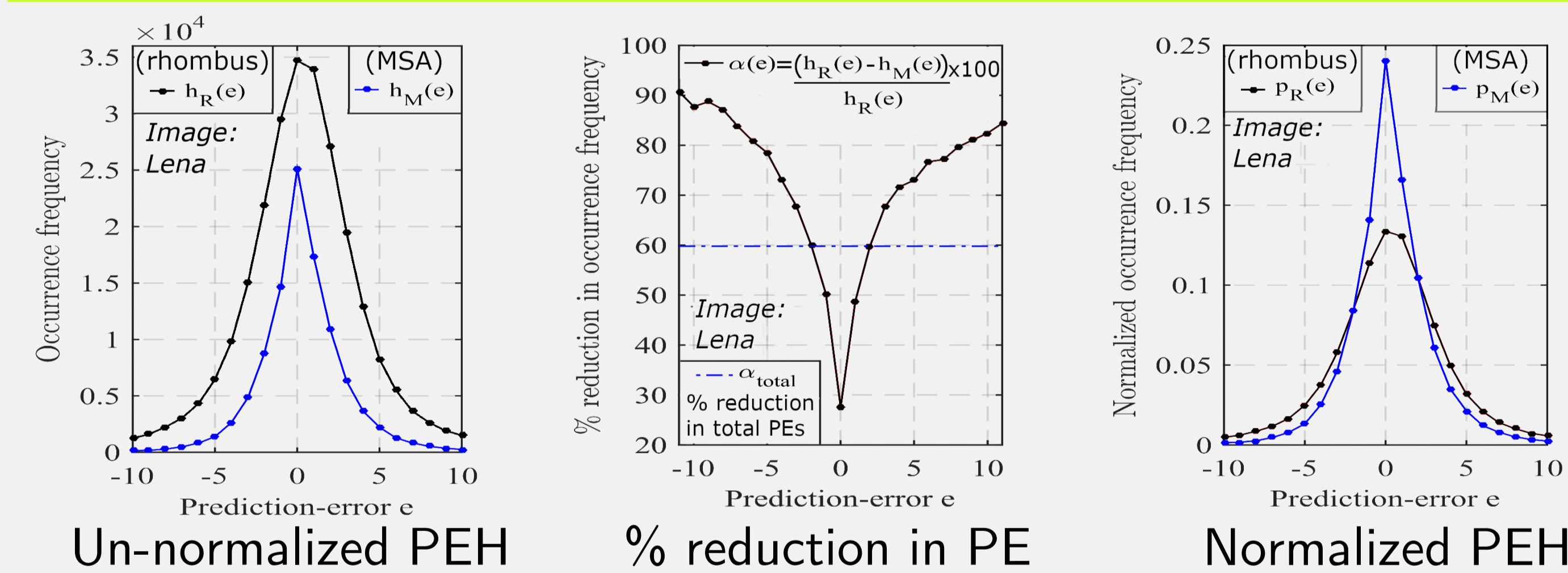
$$S = \left\{ \frac{n+s}{2}, \frac{w+e}{2}, \frac{n+e}{2}, \frac{e+s}{2}, \frac{s+w}{2}, \frac{w+n}{2} \right\}$$

Step 3: Compute prediction value

Cases	Prediction value
$x \geq v_H$	v_H
$x < v_L$	v_L
$v_L \leq x < v_H$	Unpredictable Pixel Location (UPL)

Using the 4 neighbour pixels, 11 (${}^4C_2 + {}^4C_3 + {}^4C_4$) averages can be computed. Among these, the two most separated averages are from the set S as the two-neighbour averages have the lowest common neighbours (either 0 or 1). Hence, we call $\max S$ and $\min S$ as the maximally separated averages.

Reduction in PEH entropy due to UPLs



After PEH generation using non-UPLs, it can be observed that $h_R(e) > h_M(e)$. As $|e|$ increases from 0, change in $h_R(e) \gg$ change in $h_R(e) - h_M(e)$. Hence, % reduction of PE in MSA w.r.t rhombus, $\alpha(e)$, increases (except a few local inconsistencies) with increase in $|e|$. Let $\alpha_{total} =$ % reduction in total PEs in MSA w.r.t rhombus. If $\alpha(e) < \alpha_{total}$ ($\alpha(e) > \alpha_{total}$) then $p_M(e) > p_R(e)$ ($p_M(e) < p_R(e)$). Hence, PEH entropy decreases due to exclusion of UPLs.

The two maximally separated averages are chosen in step 2 to maximize the number of UPLs for high PEH entropy reduction.

3. Results

Performance gain by using our MSA predictor in [1],[2],[3]

- ✓ Performance (embedding distortion) is evaluated by PSNR between marked & cover images.
- ✓ [1] is a popular benchmark RDH scheme that employs pixel sorting and rhombus predictor.
- ✓ [2], [3] are state-of-the-art RDH schemes based on rhombus predictor, pixel pairing & sorting.

PSNR gains (dB) in schemes (averaged over payloads ranging from 1kbits to max embedding capacity with steps of 1kbits)	USC-SIPI test images						
	Lena	Baboon	F16	Barbara	Lake	Boat	Average
[1]	1.29	1.16	1.41	1.36	0.74	1.16	1.187
[2]	1.08	1.02	1.15	1.29	0.50	0.94	0.997
[3]	0.92	0.83	0.64	1.04	0.46	0.83	0.787

Increase in PEH sharpness i.e. decrease in PEH entropy

PEH entropy	Lena	Baboon	F16	Barbara	Lake	Boat
Rhombus predictor	4.108	5.967	3.864	5.111	4.963	4.811
MSA predictor	3.415	5.313	2.612	4.337	4.314	4.094
Predictor of [4]	3.939	5.696	3.722	4.040	4.869	4.432

4. Conclusion

High prediction-error histogram sharpness

- ✓ Better than rhombus predictor and comparable to the highly efficient predictor of [4].

Flexible choice of prediction contexts

- ✓ Compatible with the 4-neighbour prediction context and extendable to any other context.

Simultaneous usage with pixel pairing and pixel sorting

- ✓ Further performance improvement can be achieved in high performance RDH schemes employing pixel pairing and pixel sorting by using the proposed MSA predictor.

References

- 1) V. Sachnev, H. J. Kim, J. Nam, S. Suresh, and Y. Q. Shi, "Reversible watermarking algorithm using sorting and prediction," *IEEE Trans. Circuits Syst. Video Techn.*, vol. 19, no. 7, pp. 989–999, 2009.
- 2) B. Ou, X. Li, Y. Zhao, R. Ni, and Y.-Q. Shi, "Pairwise prediction-error expansion for efficient reversible data hiding," *IEEE Trans. Image Process.*, vol. 22, no. 12, pp. 5010–5021, 2013.
- 3) B. Ou, X. Li, W. Zhang, and Y. Zhao, "Improving pairwise pee via hybrid-dimensional histogram generation and adaptive mapping selection," *IEEE Trans. Circuits Syst. Video Techn.*, to be published, doi:10.1109/TCSVT.2018.2859792.
- 4) I.-C. Dragoi and D. Coltuc, "Local-prediction-based difference expansion reversible watermarking," *IEEE Trans. Image Process.*, vol. 23, no. 4, pp. 1779–1790, 2014.