

• When the segments represent HMM states, a state-level error $E_s(s_i)$ can be minimised:

$$E_s(s_j) = -CM(s_j) = \frac{\sum_{t=b(s_j)}^{e(s_j)} \mathbb{KL}\left(\mathbf{y}_{s_j} \parallel \mathbf{z}_t\right)}{e(s_j) - b(s_j) + 1}$$

• When the segments represent phone units, a phone-level error $E_{ph}(ph_k)$ can minimised:

$$E_{ph}(ph_k) = \frac{1}{N_{ph_k}} \sum_{n=1}^{N_{ph_k}} E(s_{j+n})$$
; where ph_k comprises N_{ph_k} sta

Priors $P(a^d)$ are estimated from the state segment counts instead of frame label counts.

5 Data Sets and Experimental Setup

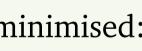
	AMI	Mediaparl German	Mediaparl French	TIMIT
Training hours	77.3	14.5	16.1	3.1
Phone set count	176	57	38	48
Vocabulary size	52.5k	16.7k	12.4k	48
LM order	3-gram	2-gram	2-gram	2-gram
Features	fMLLR+spk-iVec MFCC			
Tools	Kaldi+Keras/Tensorflow			
Alignments	From HMM-SGMM systems			
Training	E_f , E_s or E_{ph} , followed by sMBR			

Segment-level training based on Confidence Measures for Hybrid HMM/ANN Speech Recognition

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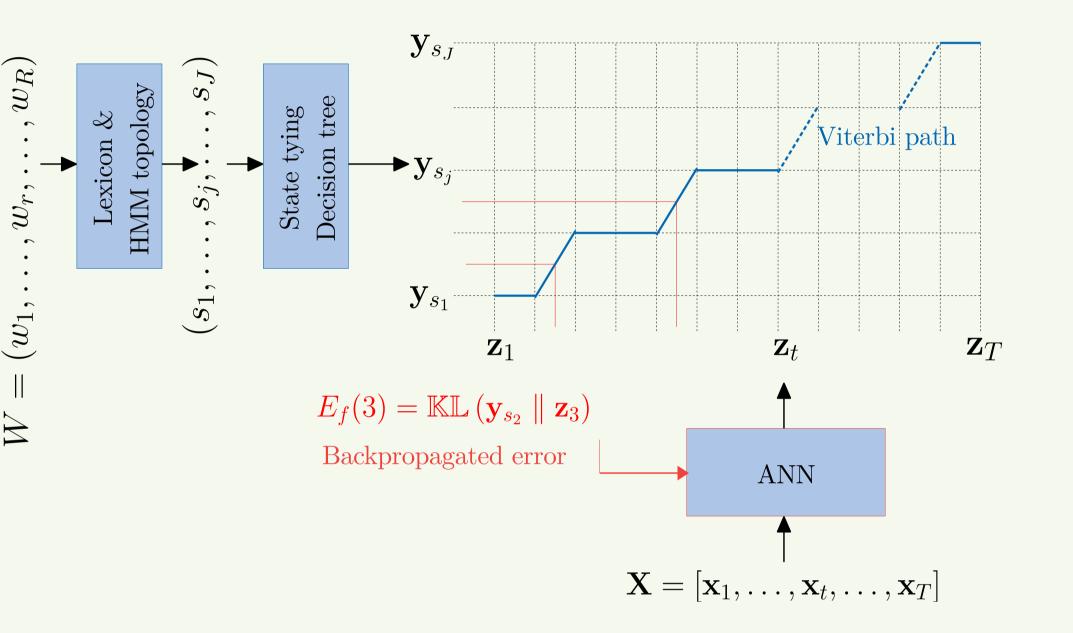
(2) Background: Conventional Hybrid HMM/ANN Systems

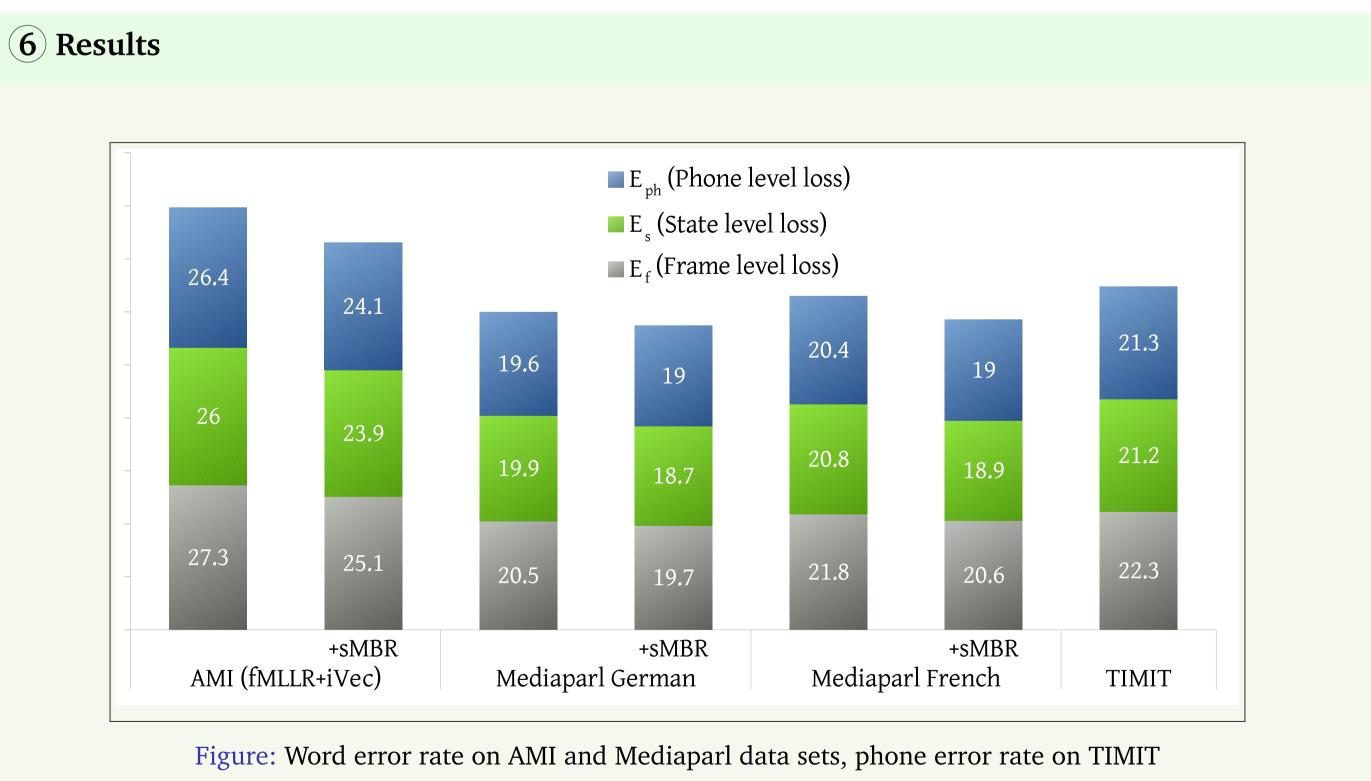
In hybrid hidden Markov model (HMM) based speech recognition, the *scaled likelihood* of an acoustic observation \mathbf{x}_t given a HMM state q_t at time t, labelled l^i , is estimated as:

$$\frac{p(\mathbf{x}_t|q_t = l^i)}{p(\mathbf{x}_t)} = \sum_{d=1}^{D} \frac{p(\mathbf{x}_t|a^d)}{p(\mathbf{x}_t)} P(a^d|q_t = l^i) = \sum_{d=1}^{D} \frac{P(a^d|\mathbf{x}_t)}{P(a^d)} P(a^d|q_t = l^i)$$

Oconventionally, given the *segmentation*, the artificial neural network (ANN) is trained using one hot encodings of the targets and minimising frame level cross-entropy. This can be expressed as:

$$E_{f}(t) = \mathbb{KL}\left(\mathbf{y}_{s_{j}} \| \mathbf{z}_{t}\right) \stackrel{(s_{j}=l^{j}) \mapsto a^{d'}}{=} \mathbb{KL}\left(\delta_{d'} \| \mathbf{z}_{t}\right) = -\log\left(P(a^{d'} | \mathbf{x}_{t})\right)$$
(1)





Acknowledgements HASLERSTIFTUNG

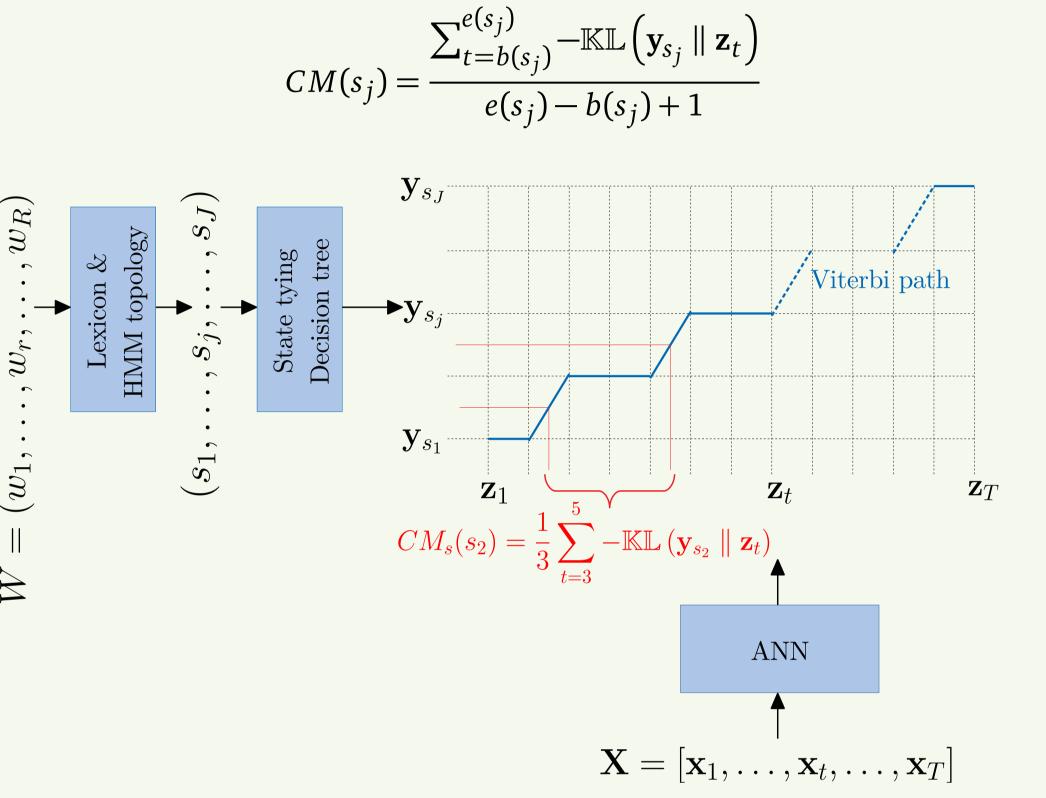
carried out at the Idiap Research Institute.

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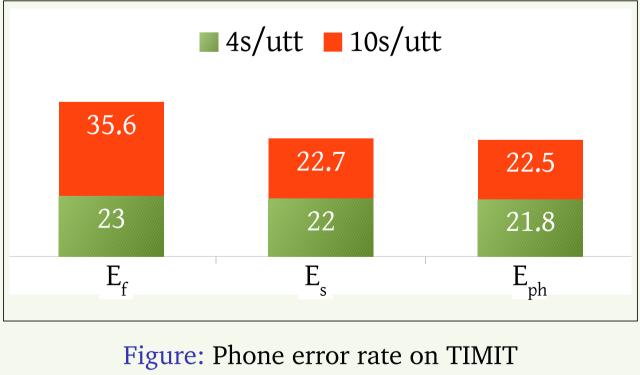
3 Confidence Estimation using Local Posteriors

$$CM(s_{j}) = \frac{\sum_{t=b(s_{j})}^{e(s_{j})} \log \left(P(q_{t} = l^{j} | \mathbf{x}_{t}) \right)}{e(s_{j}) - b(s_{j}) + 1} \quad l^{j} \stackrel{\text{def}}{=} \frac{\sum_{t=b(s_{j})}^{e(s_{j})} \log \left(P(a^{d'} | \mathbf{x}_{t}) \right)}{e(s_{j}) - b(s_{j}) + 1}$$

Z with a local cost based on Kullback-Leibler (KL) divergence:



(7) Analysis: Effect of Silence Duration on the Training



(8) Conclusion

- yields better systems than using frame-level cross-entropy.
- adds to the efficacy of further sequence discriminative training.
- improves robustness to duration variations in the training data set.



• Given an alignment between **X** and *W* and the local posterior probability estimates, a confidence measure $CM(s_i)$ can be estimated by rescoring the segment of s_i at $t = \{b(s_i), \dots, e(s_i)\}$ as

Solution Based on (1), we can express the state level confidence $CM(s_i)$ estimation as a matching of Y and

• Here we show how increasing the silence duration affects training using the three cost functions. Silence was artificially added at the beginning and end of each training and test utterance.

The proposed linguistic-segment-level training of ANNs based on confidence measures



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