



Tropical Modeling of Transducer Algorithms on Graphs

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group



paper



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CVSP: <http://cvsp.cs.ntua.gr>

IRAL: <https://robotics.ntua.gr>

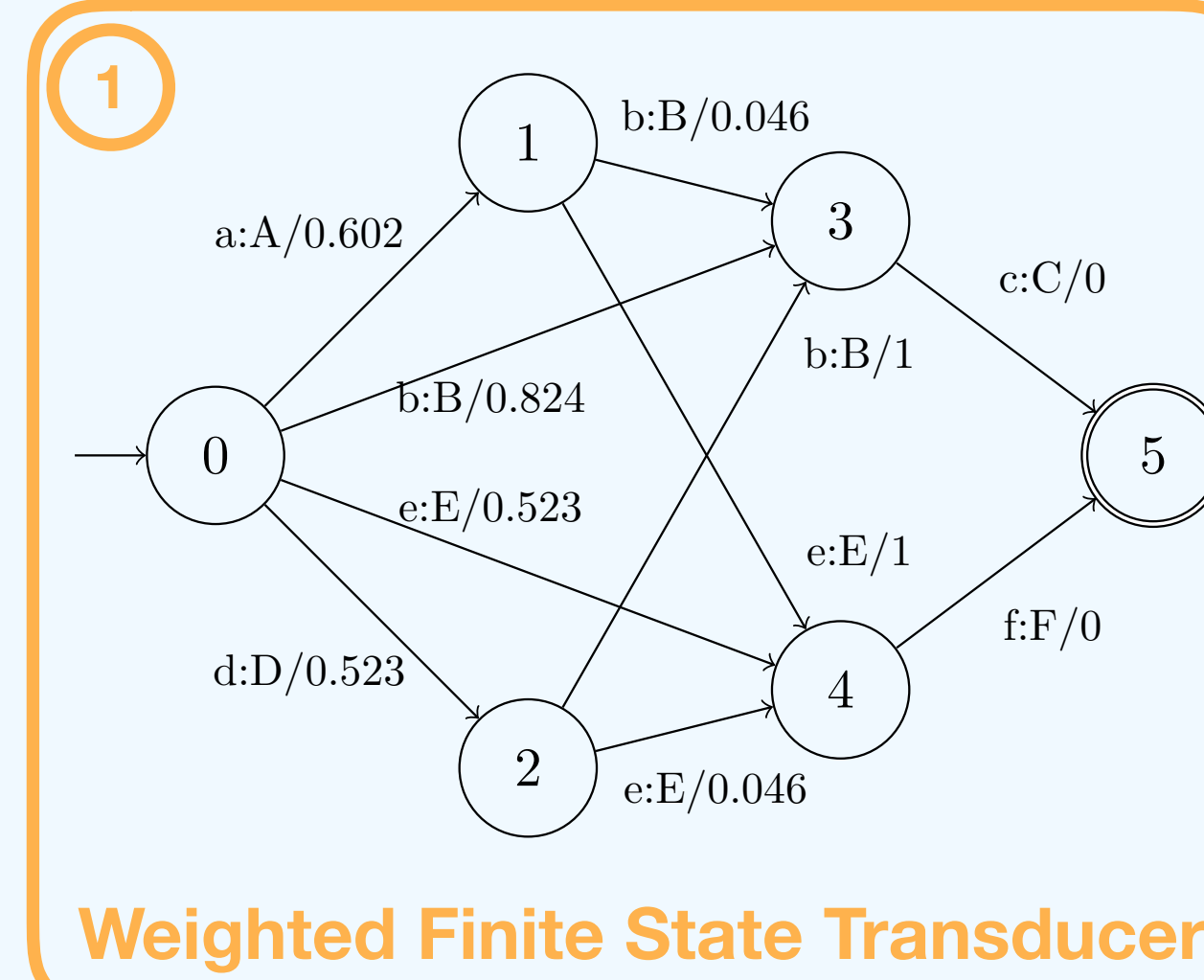
1. Introduction

Why WFST?

- extensive application in **SLP**
- tropical operations, but conventional calculations

Why tropical?

- emerging field with **novel** results
- piecewise linear solution space
- connection to **tropical geometry**
- nonlinear** vector spaces
- unified common framework



2. Tropical Algebra and Geometry

- like **linear algebra**, but $(+, x) \rightarrow (\wedge, +)$
- matrix/vector multiplication:

$$(\mathbf{A} \boxplus \mathbf{B})_{ij} = \bigwedge_{k=1}^n A_{ik} + B_{kj}$$

- neutral elements are ∞ for the minimum and 0 for the addition
- example:

$$\begin{bmatrix} \infty & 4 \\ -6 & 11 \end{bmatrix} \boxplus \begin{bmatrix} 7 \\ 0 \end{bmatrix} = \begin{bmatrix} \min(\infty + 7, 4 + 0) \\ \min(-6 + 7, 11 + 0) \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

- transitive closures:

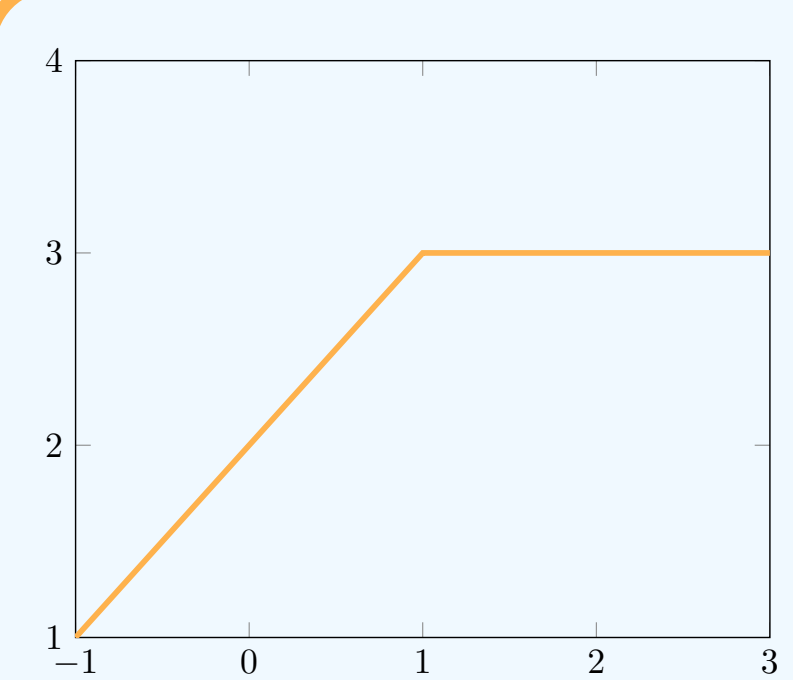
$$\Gamma(\mathbf{A}) = \mathbf{A} \wedge \mathbf{A}^2 \wedge \dots \wedge \mathbf{A}^n \wedge \dots$$

$$\Delta(\mathbf{A}) = \mathbf{I} \wedge \mathbf{A} \wedge \mathbf{A}^2 \wedge \dots \wedge \mathbf{A}^n \wedge \dots$$

solutions to eigenvalue problems

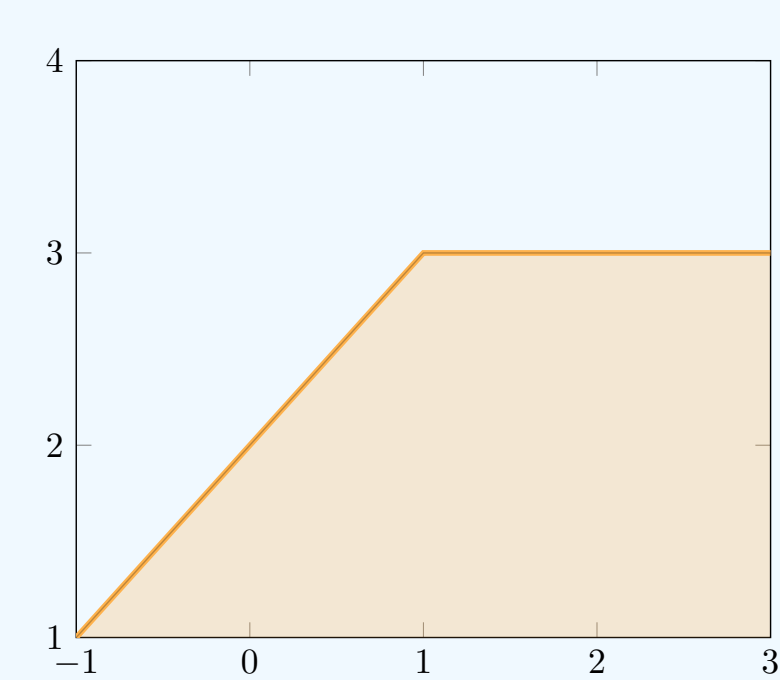
- tropical line:

$$y = \alpha + x \wedge \beta = \min(\alpha + x, \beta)$$



tropical line

$$y = 2 + x \wedge 3$$



tropical halfspace

$$y \le 2 + x \wedge 3$$

polytope: bounded intersection of halfspaces

3. Modeling

3.1 Weight pushing

- single step update:

$$\mathbf{v}_{i+1} = \mathbf{v}_i \wedge \mathbf{A} \boxplus \mathbf{v}_i$$

- final potential vector:**

$$\mathbf{v}_\infty = \rho \wedge \mathbf{A} \boxplus \rho \wedge \mathbf{A}^2 \boxplus \rho \wedge \dots = \Delta(\mathbf{A}) \boxplus \rho$$

- define:

$$\mathbf{\Lambda} = \text{diag}(\lambda)$$

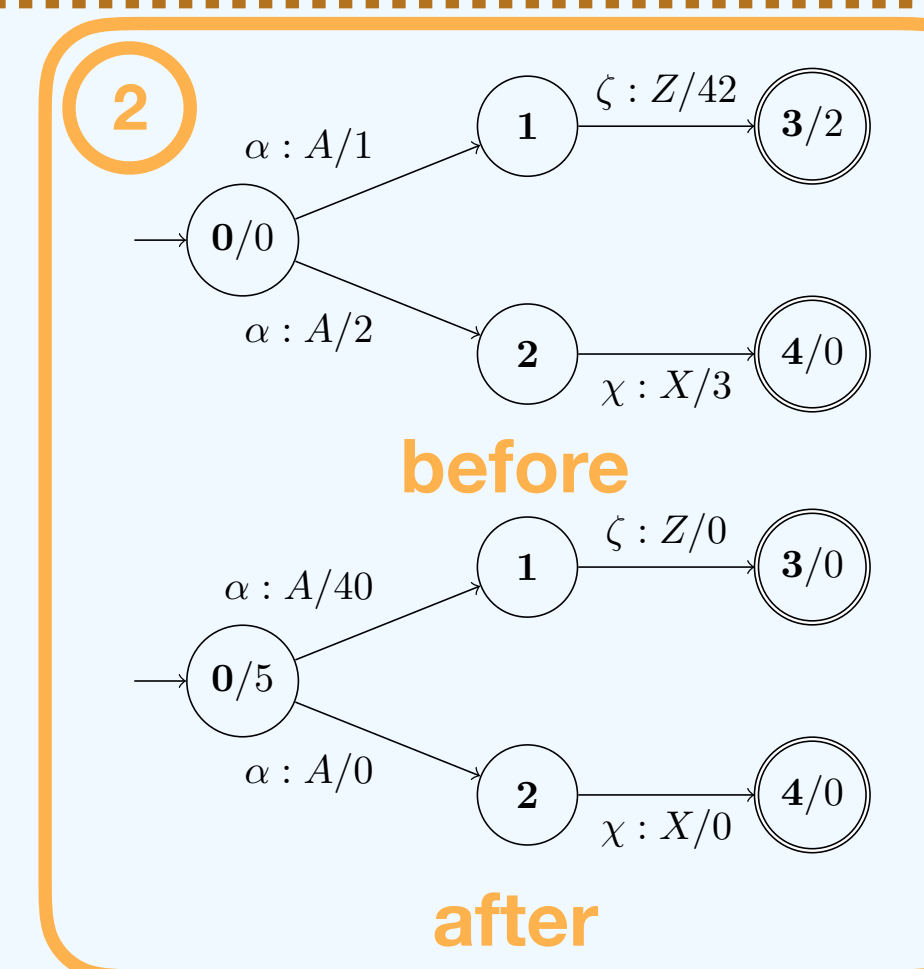
$$\mathbf{V}^+ = \text{diag}(\mathbf{v}_\infty)$$

$$\mathbf{V}^- = \text{diag}(-\mathbf{v}_\infty)$$

$$\mathbf{P} = \text{diag}(\rho)$$

- new system model:**

$$\lambda' = \mathbf{\Lambda} \boxplus \mathbf{v}_\infty, \quad \rho' = \mathbf{P} \boxplus (-\mathbf{v}_\infty), \quad \mathbf{A}' = \mathbf{V}^- \boxplus \mathbf{A} \boxplus \mathbf{V}^+$$



\mathbf{A} : transition matrix
 λ : input vector
 ρ : emission vector

3.2 Epsilon removal

- decompose:

$$\mathbf{A} = \mathbf{A}_\epsilon \wedge \mathbf{E}$$

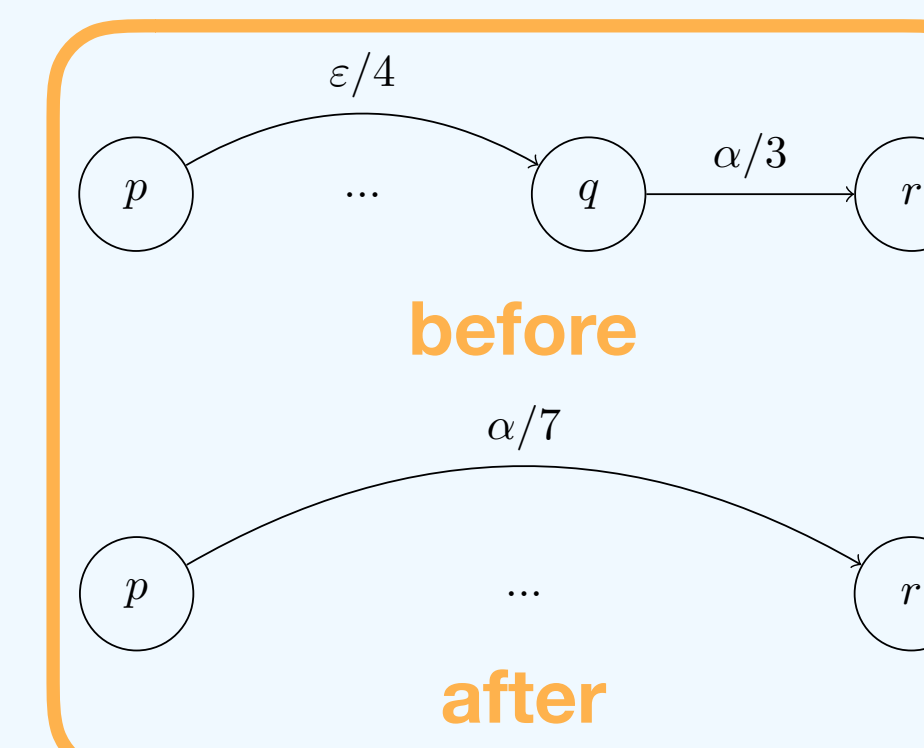
- epsilon closure** of WFST:

$$\Gamma(\mathbf{E}) = \mathbf{E} \wedge \mathbf{E}^2 \wedge \dots \wedge \mathbf{E}^n \wedge \dots$$

- new system model:**

$$\mathbf{A}' = \mathbf{A}_\epsilon \wedge (\Gamma(\mathbf{E}) \boxplus \mathbf{A}_\epsilon) = \Delta(\mathbf{E}) \boxplus \mathbf{A}_\epsilon$$

$$\rho' = \rho \wedge (\Gamma(\mathbf{E}) \boxplus \rho) = \Delta(\mathbf{E}) \boxplus \rho$$



Σ_i : input symbols
 Σ_o : output symbols

3.3 Viterbi pruning

- tropical Viterbi:**

$$\mathbf{x}(t) = \mathbf{P}(\sigma_t) \boxplus \mathbf{A}^T \boxplus \mathbf{x}(t-1)$$

- variable vector \mathbf{z} :

$$\mathbf{z} \geq \mathbf{b}$$

$$\mathbf{z} \leq \boldsymbol{\eta}$$

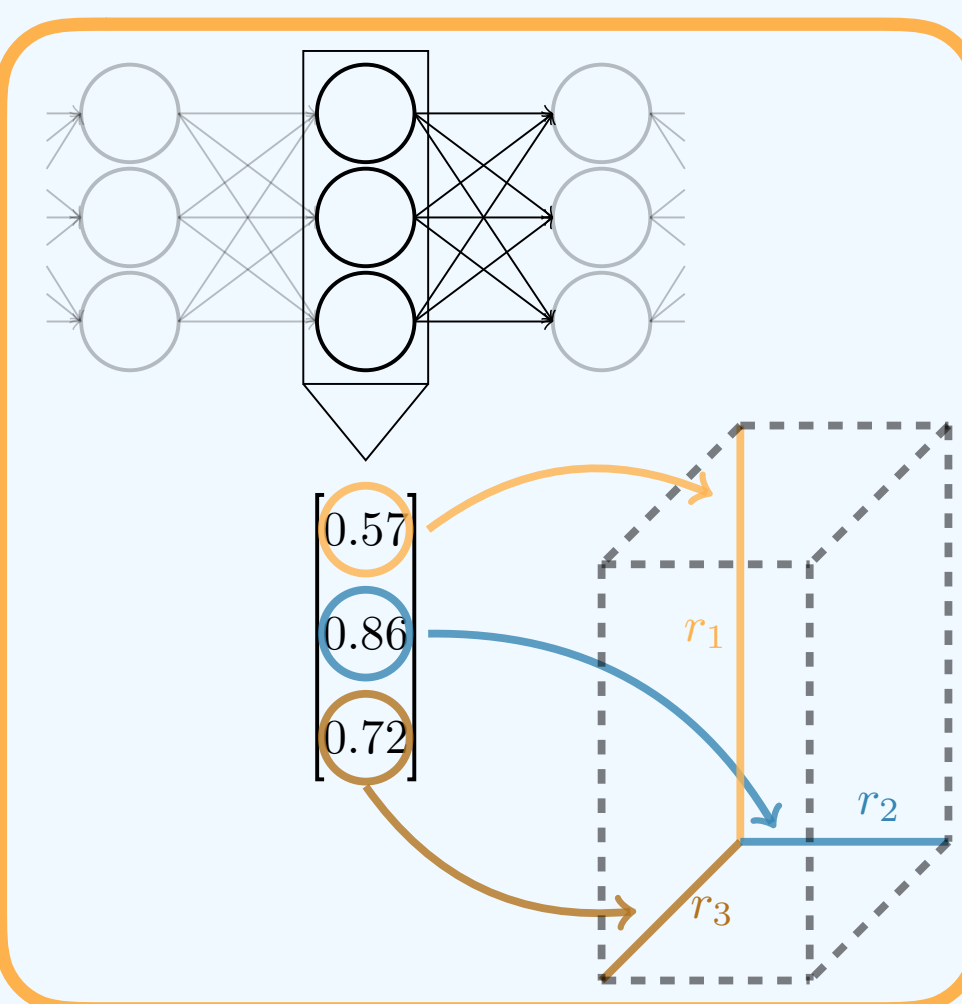
Viterbi update

Viterbi update + threshold

$$\mathbf{b} = \mathbf{P}(\sigma_t) \boxplus \mathbf{A}^T \boxplus \mathbf{x}(t-1)$$

$$\boldsymbol{\eta} = \theta + \frac{1}{2}(\mathbf{b}^T \boxplus \mathbf{b}) + 0$$

$$r_i = \boldsymbol{\eta} - z_i$$



- volume** metric:

$$\nu = -\frac{1}{|\text{supp}(\mathbf{z})|} \sum_{i \in \text{supp}(\mathbf{z})} \frac{\log r_i}{\log(\max \mathbf{r})}$$

- entropy** metric:

$$\varepsilon = -\frac{1}{|\text{supp}(\mathbf{z})|} \sum_{i \in \text{supp}(\mathbf{z})} -z_i(t) \cdot e^{-z_i(t)}$$

4. Examples

Weight pushing (2)

- original model:**

$$\mathbf{A} = \begin{bmatrix} \infty & 1 & 2 & \infty & \infty \\ \infty & \infty & \infty & 42 & \infty \\ \infty & \infty & \infty & \infty & 3 \\ \infty & \infty & \infty & \infty & \infty \\ \infty & \infty & \infty & \infty & \infty \end{bmatrix}, \quad \lambda = \begin{bmatrix} 0 \\ \infty \\ \infty \\ \infty \\ \infty \end{bmatrix}, \quad \rho = \begin{bmatrix} \infty \\ \infty \\ \infty \\ \infty \\ 2 \end{bmatrix}$$

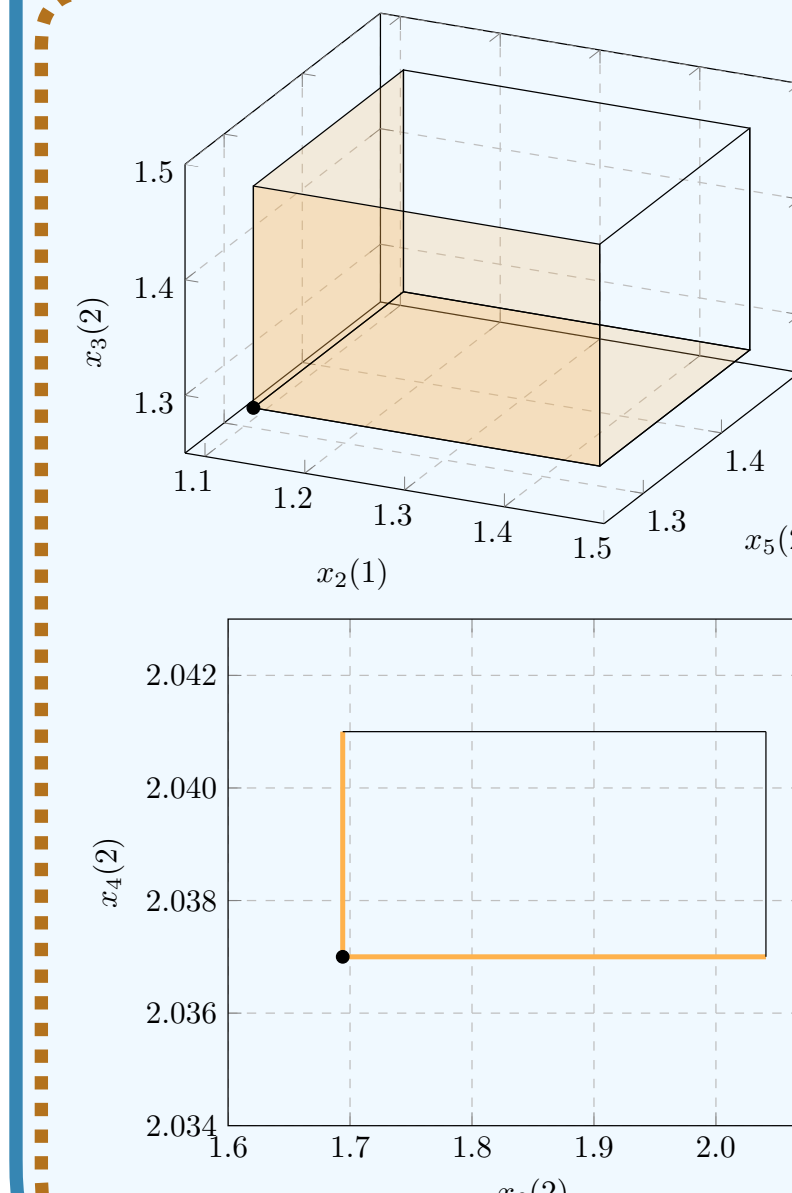
- final potential vector:**

$$\Delta(\mathbf{A}) = \begin{bmatrix} 0 & 1 & 2 & 43 & 5 \\ \infty & 0 & \infty & 42 & \infty \\ \infty & \infty & 0 & \infty & 3 \\ \infty & \infty & \infty & 0 & 0 \\ \infty & \infty & \infty & \infty & 0 \end{bmatrix}, \quad \mathbf{v}_\infty = \begin{bmatrix} 5 \\ 44 \\ 3 \\ 2 \\ 0 \end{bmatrix}$$

- new model:**

$$\mathbf{A} = \begin{bmatrix} \infty & 40 & 0 & \infty & \infty \\ \infty & \infty & \infty & 0 & \infty \\ \infty & \infty & \infty & \infty & 0 \\ \infty & \infty & \infty & \infty & \infty \\ \infty & \infty & \infty & \infty & \infty \end{bmatrix}, \quad \lambda = \begin{bmatrix} 5 \\ \infty \\ \infty \\ \infty \\ \infty \end{bmatrix}, \quad \rho = \begin{bmatrix} \infty \\ \infty \\ \infty \\ 0 \\ 0 \end{bmatrix}$$

Viterbi polytopes (1)



- system model:**

$$\mathbf{A} = \begin{bmatrix} \infty & 0.602 & 0.523 & 0.824 & 0.523 & \infty \\ \infty & \infty & \infty & 0.046 & 1 & \infty \\ \infty & \infty & \infty & \infty & 0.046 & \infty \\ \infty & \infty & \infty & \infty & \infty & 0 \\ \infty & \infty & \infty & \infty & \infty & \infty \end{bmatrix}$$

- Viterbi state vectors:**

$$\theta = 0.35$$

$$\mathbf{x}(1) = \begin{bmatrix} \infty \\ 1.125 \\ 1.28 \\ 1.581 \\ 1.28 \\ \infty \end{bmatrix}, \quad \mathbf{x}(2) = \begin{bmatrix} \infty \\ \infty \\ 1.694 \\ 2.083 \\ 2.037 \end{bmatrix}, \quad \mathbf{x}(3) = \begin{bmatrix} \infty \\ \infty \\ \infty \\ \infty \\ 2.217 \end{bmatrix}$$

5. Conclusion

Contributions

- modeling WFST algorithms in tropical algebra
- analyzing the geometry of Viterbi pruning
- unifying WFST algorithms under a common framework

Future work

- interpret the algorithms as **tropical eigenvalue** problems
- consider alternate bases
- model **intrusive** algorithms in tropical algebra

6. References

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