# DOMAIN ADAPTATION USING RIEMANNIAN GEOMETRY OF SPD MATRICES

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Signal and Image Processing Lab

#### Goal

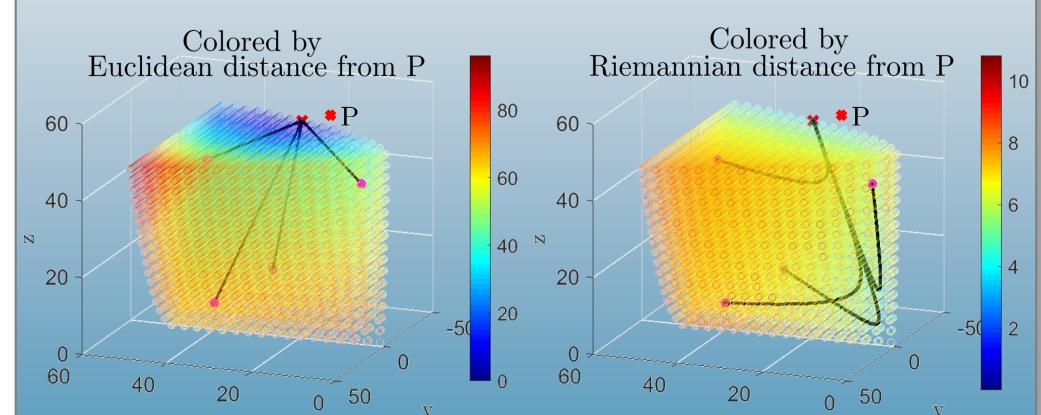
- Goal: Feature extraction and classification of a dataset with multiple domains.
- Objective: Obtain a new representation using an unsupervised domain adaptation method based on parallel transport (PT) and moments alignment.
- Applicability: Domain adaptation and classification of high-dimensional noisy electrophysiological (EEG) signals collected from different subjects, where each subject is considered as a different domain.

#### Problem Formulation

- Let  $\{X_i^{(1)}, y_i^{(1)}\}_{i=1}^{N_1}$  be the source set and let  $\{X_i^{(2)}, y_i^{(2)}\}_{i=1}^{N_2}$  be the target set.
- Each set k = 1, 2 contains  $N_k$  matrices of data observations  $\boldsymbol{X}_i^{(k)} \in \mathbb{R}^{d \times T_i^{(k)}}$ , such that d is the observation dimension,  $T_i^{(k)}$  is the observation length and  $y_i^{(k)}$  is the corresponding label.
- Let  $P_i^{(k)} \in \mathbb{R}^{d \times d}$  denote the sample covariance of the data matrix  $X_i^{(k)}$ , given by  $P_i^{(k)} \triangleq \frac{1}{T_i^{(k)}} X_i^{(k)} \left( X_i^{(k)} \right)^T$ , where for simplicity we assume zero mean.
- We aim to find a new representation for  $\{P_i^{(1)}\}$  and  $\{P_i^{(2)}\}$ , that will allow to train a classifier on  $\{P_i^{(1)}\}$  and to apply it to  $\{P_i^{(2)}\}$  (domain adaptation).

## SPD Matrices

- A symmetric matrix  $P \in \mathbb{R}^{d \times d}$  is positive-definite (SPD) if all its eigenvalues are strictly positive, or equivalently, if  $\mathbf{v}^T P \mathbf{v} > 0$  for every  $\mathbf{v} \neq 0$ .
- The set of all SPD matrices is an open convex cone, constituting a differential Riemannian manifold  $\mathcal{M}$ .
- Illustration: The manifold of  $2 \times 2$  SPD matrices



Each point (x, y, z) represents a matrix  $\mathbf{M} = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$  $\mathbf{M} > 0$  iff x > 0, z > 0 and  $y^2 < xz$ .

The 4 magenta points represent matrices with equal Riemannian distance from P. The curves are the Euclidean and Riemannian geodesic respectively.

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# • The Riemannian Cone Manifold of SPD Matrices

• Let  $\mathcal{T}_{\mathbf{P}}\mathcal{M}$  be the tangent space at the point  $\mathbf{P} \in \mathcal{M}$ , equipped with the following inner product:

$$\left\langle oldsymbol{S}_1, oldsymbol{S}_2 
ight
angle_{\mathcal{T}_{oldsymbol{P}}\mathcal{M}} = \left\langle oldsymbol{P}^{-rac{1}{2}} oldsymbol{S}_1 oldsymbol{P}^{-rac{1}{2}}, oldsymbol{P}^{-rac{1}{2}} oldsymbol{S}_2 oldsymbol{P}^{-rac{1}{2}} 
ight
angle$$

where  $S_1, S_2 \in \mathcal{T}_{P}\mathcal{M}$  are two symmetric matrices.

• Let  $P_1, P_2 \in \mathcal{M}$ ; the Riemannian geodesic distance is defined by:

$$\delta_R\left(oldsymbol{P}_1,oldsymbol{P}_2
ight) riangleq \left\|\log\left(oldsymbol{P}_1^{-rac{1}{2}}oldsymbol{P}_2oldsymbol{P}_1^{-rac{1}{2}}
ight)
ight\|_F$$

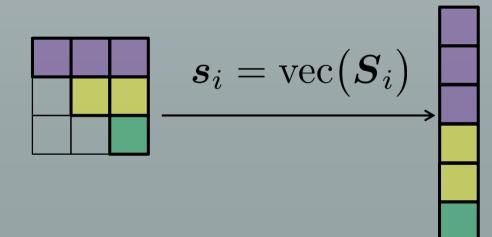
• The Riemannian mean of a set  $\{P_i \in \mathcal{M}\}_{i=1}^N$  is defined using the Fréchet mean:

$$\overline{P} \triangleq \operatorname*{arg\,min}_{P \in \mathcal{M}} \sum_{i=1}^{N} \delta_R^2 (P, P_i)$$

• The logarithmic mapping from  $P_i \in \mathcal{M}$  to  $S_i \in \mathcal{T}_P \mathcal{M}$  is defined by:

$$oldsymbol{S}_i = \mathrm{Log}_{oldsymbol{P}}ig(oldsymbol{P}_iig) riangleq oldsymbol{P}^{rac{1}{2}} \mathrm{log} ig(oldsymbol{P}^{-rac{1}{2}}oldsymbol{P}_ioldsymbol{P}^{-rac{1}{2}}ig)oldsymbol{P}^{rac{1}{2}}$$

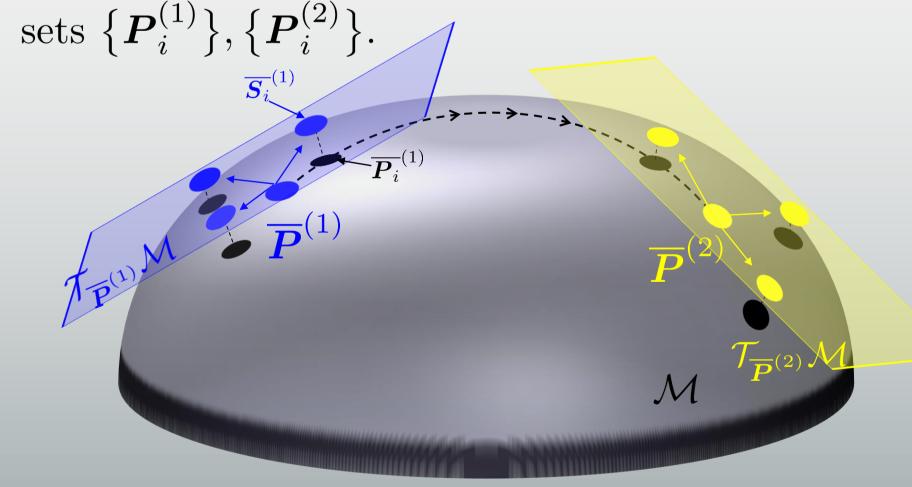
ullet We denote the vector representation  $oldsymbol{s}_i = ext{vec}(oldsymbol{S}_i)$ 



Where  $\text{vec}(\cdot)$  is the vectorized upper triangular of a symmetric matrix, with  $\sqrt{2}$  weights for its off-diagonal elements.

## Parallel Transport (PT)

• Let  $\overline{P}^{(1)}$ ,  $\overline{P}^{(2)}$  be the Riemannian means of the two



• The PT from  $\overline{P}^{(1)}$  to  $\overline{P}^{(2)}$  of any SPD matrix in  $\{P_i^{(1)}\}$  is given by:

$$oldsymbol{\Gamma}_i^{(1)} = \Gamma_{\overline{oldsymbol{P}}^{(1)} o \overline{oldsymbol{P}}^{(2)}} \left(oldsymbol{P}_i^{(1)}
ight) = oldsymbol{E} oldsymbol{P}_i^{(1)} oldsymbol{E}^T$$
 where  $oldsymbol{E} = \left(\overline{oldsymbol{P}}^{(2)} \left(\overline{oldsymbol{P}}^{(1)}
ight)^{-1}
ight)^{rac{1}{2}}$ .

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- X. Pennec, P. Fillard, and N. Ayache, A riemannian framework for tensor computing, International Journal of computer vision, 2006.
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## PT and Moments Alignment

## Algorithm 1

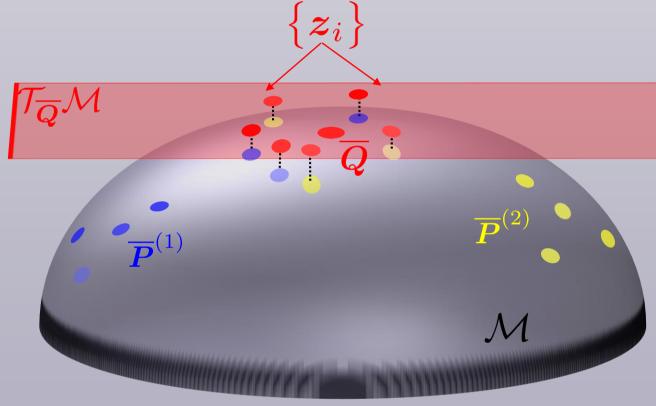
Input: K sets  $\left\{ \boldsymbol{P}_{i}^{(k)} \in \mathbb{R}^{d \times d} \right\}_{i=1}^{N_{k}}, k = 1, \dots, K$ .

Output: K matrices  $\left\{ \boldsymbol{Y}^{(k)} \in \mathbb{R}^{D \times N_{k}} \right\}_{k=1}^{K}, D = d\left(d+1\right)/2$ 

Where column  $y_i^{(k)}$  is the aligned vector representation of the matrix  $\boldsymbol{P}_i^{(k)}$ .

- 1. For each set  $\left\{\boldsymbol{P}_{i}^{(k)}\right\}_{i=1}^{N_{k}}$ , compute the Riemannian mean  $\overline{\boldsymbol{P}}^{(k)}$ .
- 2. Compute  $\overline{\boldsymbol{Q}}$ , the Riemannian mean of  $\left\{\overline{\boldsymbol{P}}^{(k)}\right\}_{k=1}^{K}$ .
- 3. For k = 1..., K:
  - (a) For  $i = 1, ..., N_k$ :
    - i. Apply PT:  $\Gamma_i^{(k)} = \Gamma_{\overline{P}^{(k)} \to \overline{Q}} (P_i^{(k)})$
    - ii. Project  $\Gamma_i^{(k)}$  to a Euclidean space:

$$oldsymbol{z}_i^{(k)} = ext{vec} \Big( \overline{oldsymbol{Q}}^{-rac{1}{2}} ext{Log}_{\overline{oldsymbol{Q}}} \Big( oldsymbol{\Gamma}_i^{(k)} \Big) \overline{oldsymbol{Q}}^{-rac{1}{2}} \Big)$$



- (b) Collect  $\mathbf{Z}^{(k)} = \left[ \mathbf{z}_1^{(k)}, \mathbf{z}_2^{(k)}, \dots, \mathbf{z}_{N_k}^{(k)} \right]$
- (c) Apply SVD  $\boldsymbol{Z}^{(k)} = \boldsymbol{U}^{(k)} \boldsymbol{\Lambda}^{(k)} \boldsymbol{V}^{(k)}$ .
- (d) If  $k \neq 1$ , for each  $j \in \{1, 2, ..., D\}$  update the columns of  $\boldsymbol{U}^{(k)} : \boldsymbol{u}_j^{(k)} \leftarrow \text{sign}\left(\left\langle \boldsymbol{u}_j^{(1)}, \boldsymbol{u}_j^{(k)} \right\rangle\right) \boldsymbol{u}_j^{(k)}$
- (e) Compute  $\boldsymbol{Y}^{(k)} = (\boldsymbol{U}^{(k)})^T \boldsymbol{Z}^{(k)}$ .

# Experimental Results

#### EEG Data

#### Raw data:

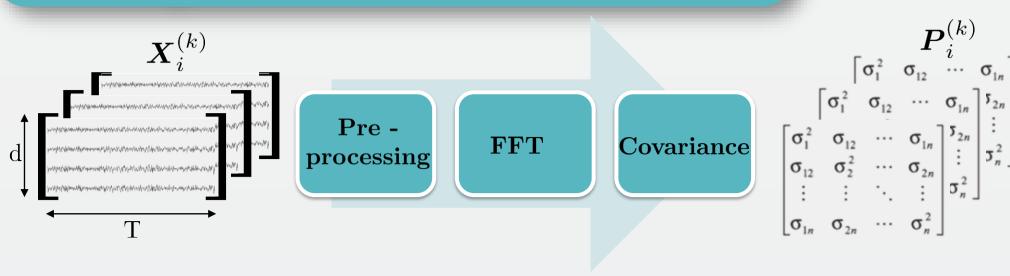
- EEG recordings from 11 subjects of ages ranging from 7 to 16 years.
- 64 EEG electrodes.
- 3 types of stimuli: visual, auditory and somatosensory.

#### Pre-processing:

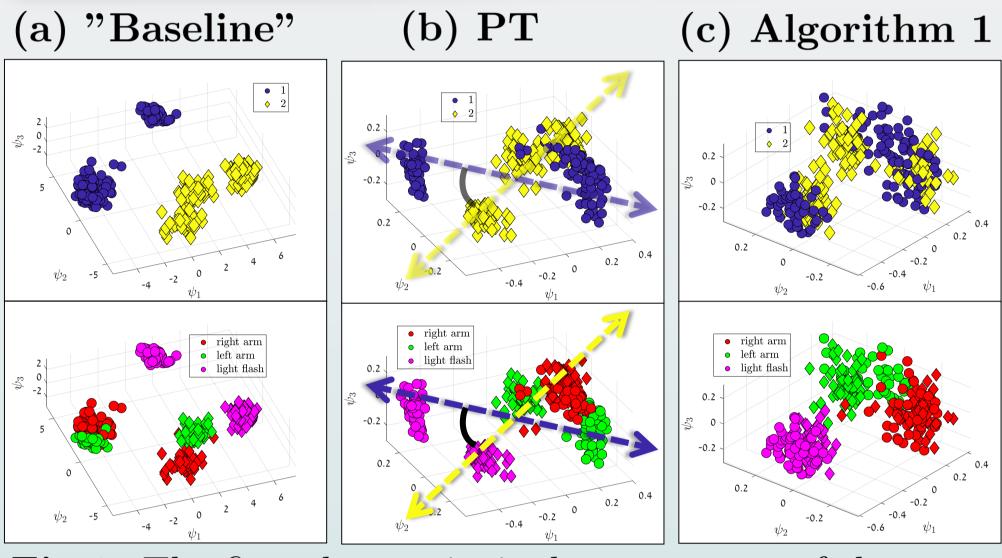
- Organizing the recordings into trials of 1 second, and downsampling to 1KHz.
- Excluding of malfunctioning electrodes and highly noisy trials.
- Applying FFT and taking the absolute value.

After pre-processing, the data contain recordings from 37 electrodes, and include 80-500 repeated trials per stimulus for each subject.

# Experimental Results

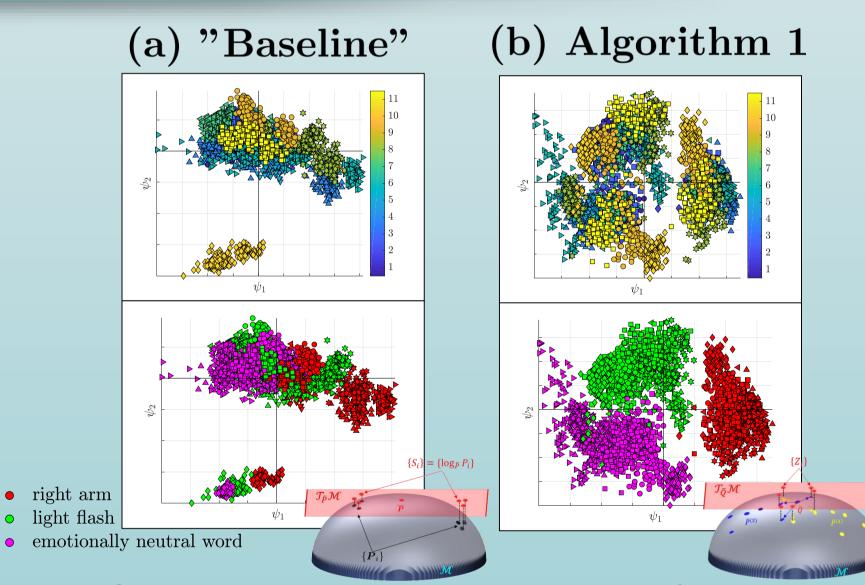


### 2 Subjects



**Fig.1.** The first three principal components of the representation of the trials obtain by the different algorithms: (a) "Baseline", (b) "PT" and (c) Algorithm 1.

## Multiple Subjects



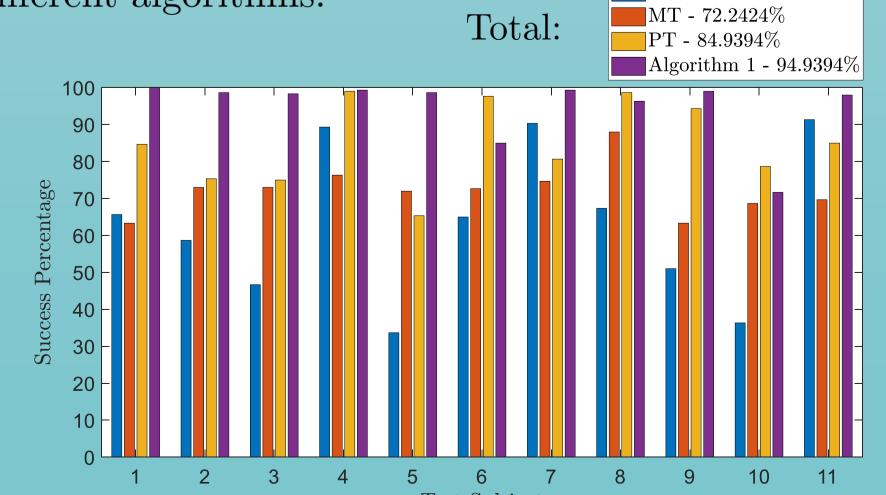
**Fig.2.** The first two principal components of the representation of the trials obtain by: (a) "Baseline" and (b) Algorithm 1.

## Classification Results

Fig.3. Classification results of the responses to three different stimuli from 11 subjects, using a cubic SVM classifier, based on the representation obtained by the different algorithms.

Baseline - 63.2121%

MT - 72.2424%



We remark that the sign of the second PC of subjects 5 and 6 was manually flipped (note that their respective angles were 89° and 95°).