

Blind Denoising of Mixed Gaussian-Impulse Noise by Single CNN

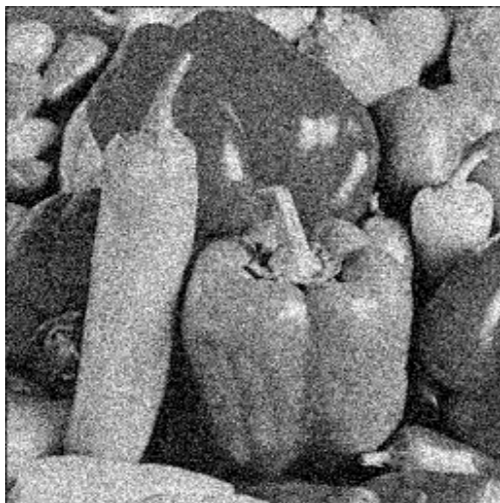
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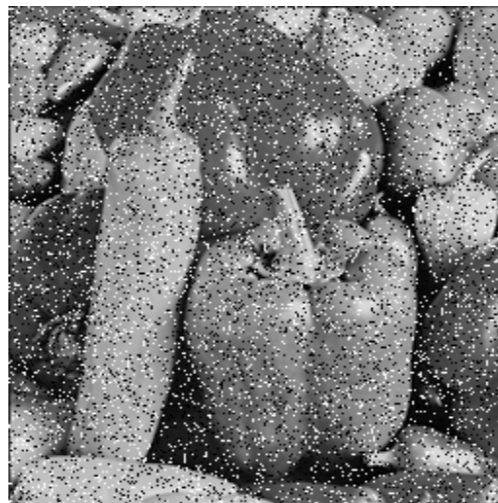
Introduction

- ▶ We propose a mixed noise removal method.

The mixture of Additive White Gaussian Noise (AWGN) and Impulse Noise (IN) is considered.



Additive White
Gaussian Noise



Random Value
Impulse Noise



AWGN-RVIN
mixed noise

- ▶ Our proposed method is based on CNN.

Type of noise

- Additive White Gaussian Noise (AWGN)

$$y_G(i, j) = x(i, j) + n_G(i, j)$$

 Caused by thermal motion in camera sensors

- Random Valued Impulse Noise (RVIN)
- Salt-and-Pepper Impulse Noise (SPIN)

$$y_I(i, j) = n_I(i, j) \quad \text{with probability } p \text{ (RVIN), } s \text{ (SPIN)}$$

 Caused by transmission error

Mixed noise

© Generally, it is rare that only one type of noise is added.



Mixed noise composed of AWGN and IN is considered.

$$y(i, j) = \begin{cases} n_{RVIN}(i, j) & \text{with probability } p \\ n_{SPIN}(i, j) & \text{with probability } s \\ x(i, j) + n_{AWGN}(i, j) & \text{with probability } 1 - p - s \end{cases}$$

$y(i, j)$: noisy pixel $x(i, j)$: noise-free pixel

$n_{RVIN}(i, j)$: Random Valued Impulse noise (RVIN)

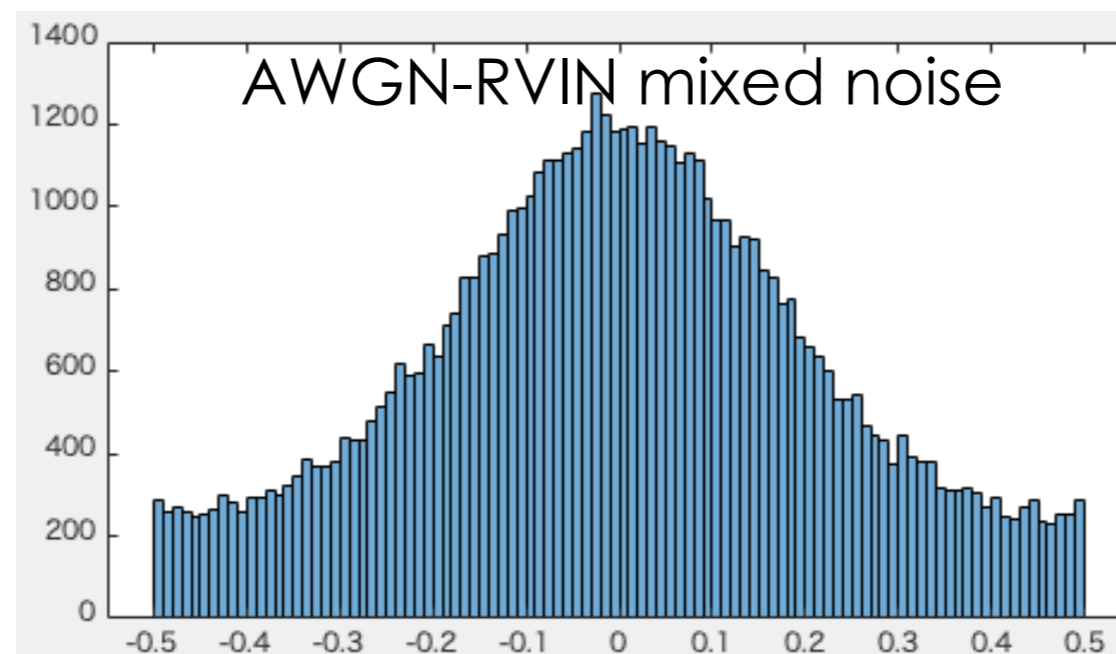
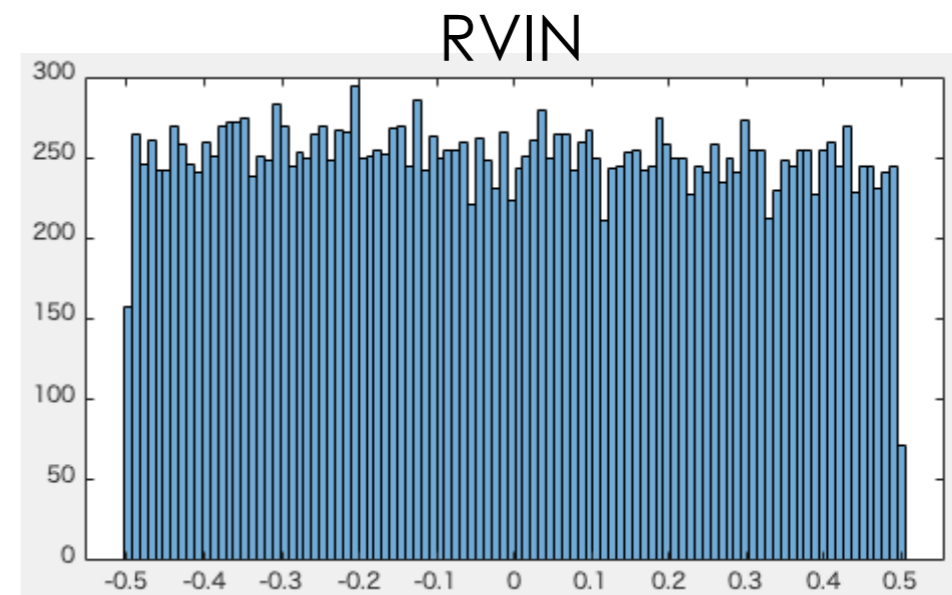
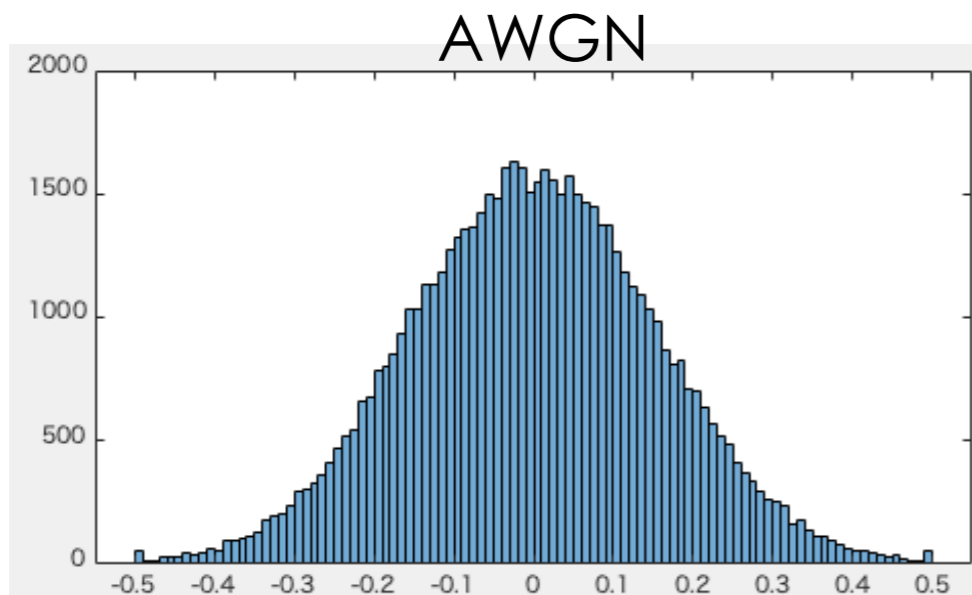
$n_{SPIN}(i, j)$: Salt and Pepper Impulse noise (SPIN)

$n_G(i, j)$: Additive White Gaussian noise (AWGN)

Mixed noise

© Mixed noise removal is more difficult than single noise removal.

→ Because the noise distribution model is complicated

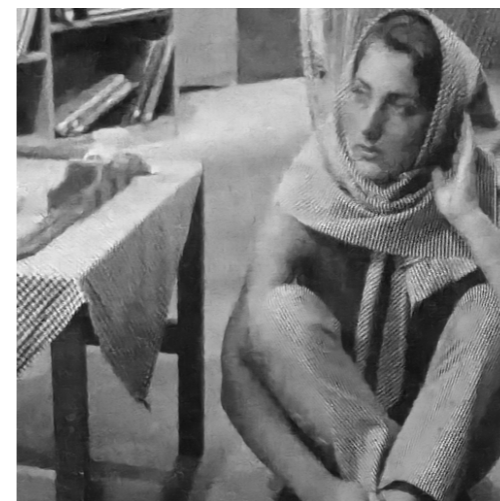
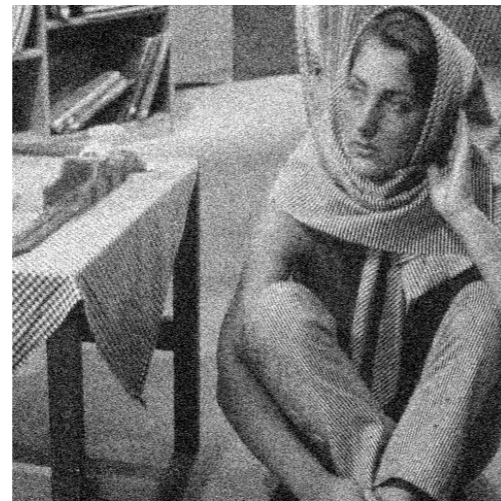


Mixed noise

- Denoising method for single noise removal cannot remove mixed noise effectively.

DnCNN

Single noise
 $\sigma = 30$ (AWGN)



26.05 dB

Mixed noise
 $\sigma = 30$ (AWGN)
 $p = 10$ (RVIN)



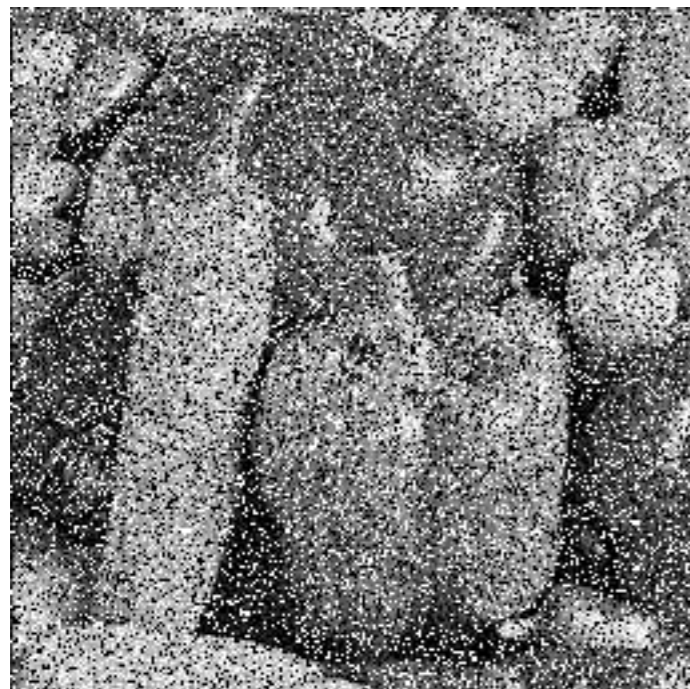
23.75 dB

Noisy
image

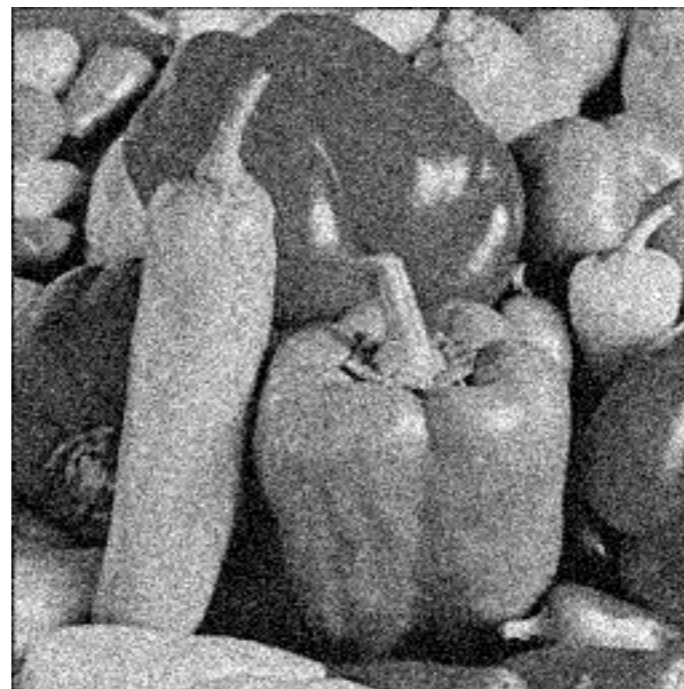
Denoised
image

Problem

- © In the conventional methods, noise removal is performed according to the distribution of noise.
→ Remove AWGN after removing RVIN & SPIN



AWGN + IN



AWGN



Denoised image

IN
removal

AWGN
removal

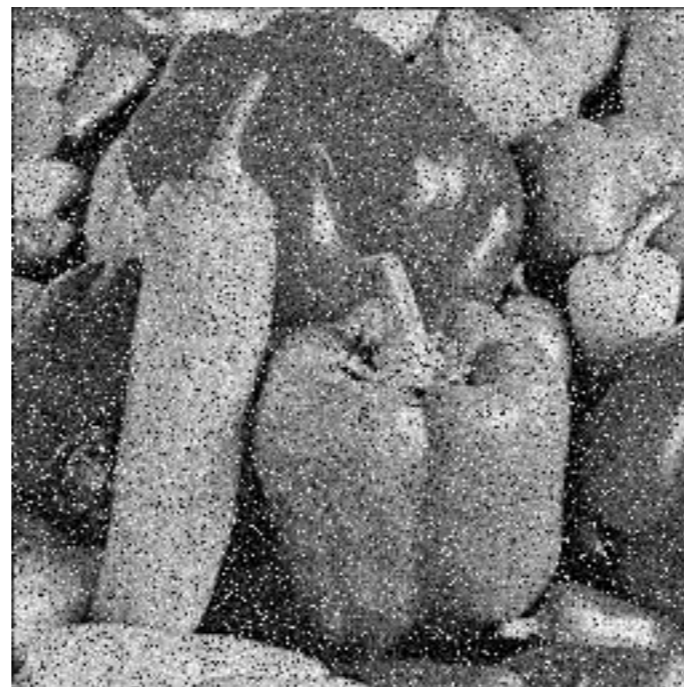
Problem

IN detection & removal becomes difficult when the noise level is high.

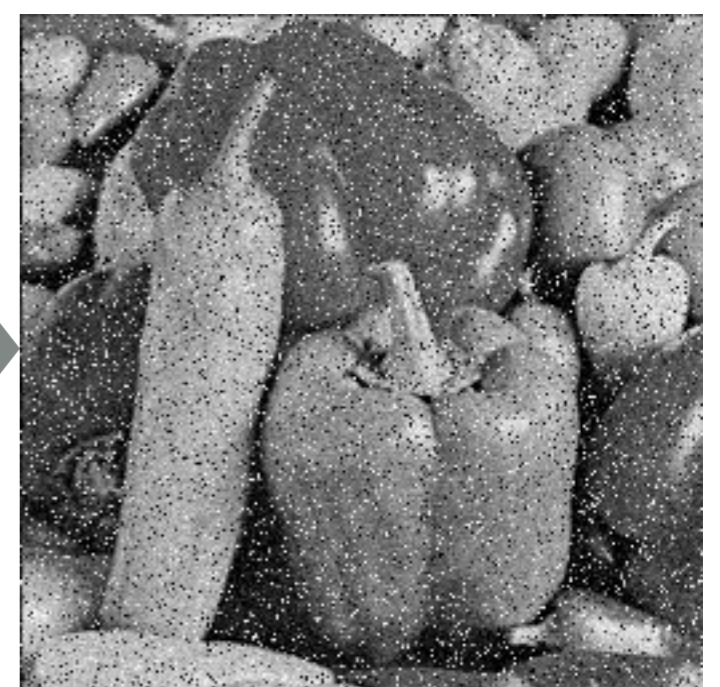
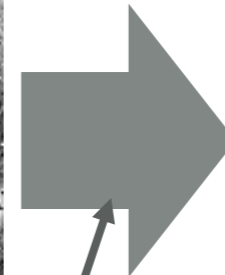
→ If the IN removal does not work well, subsequent AWGN removal will be adversely affected.



AWGN + IN



AWGN ?



Low-quality
Denoised image

IN
removal

AWGN
removal

Proposed method

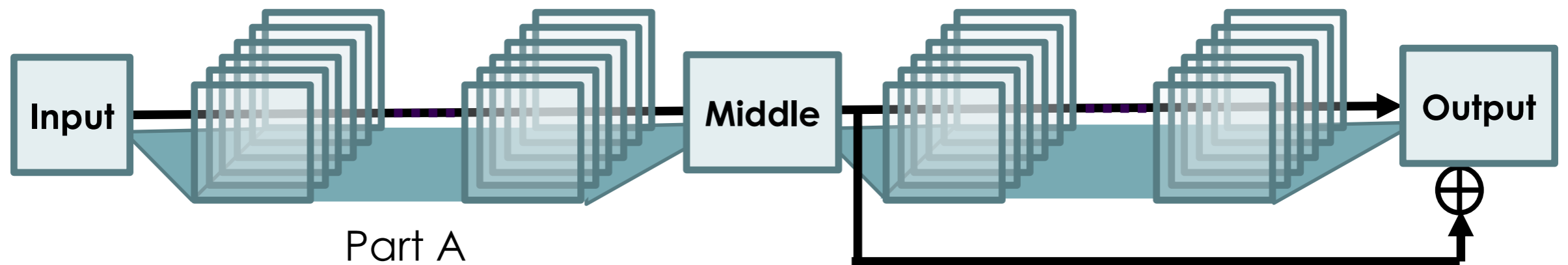
Our method

→ All denoise processing is performed in a single CNN.

Feature of our method

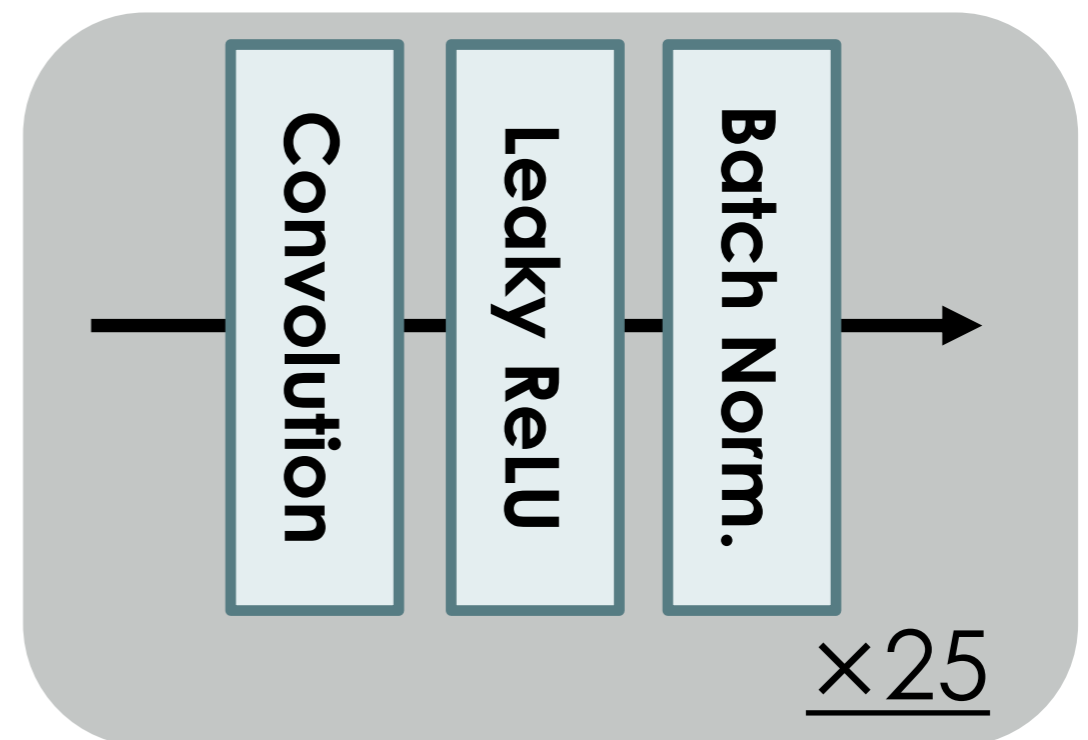
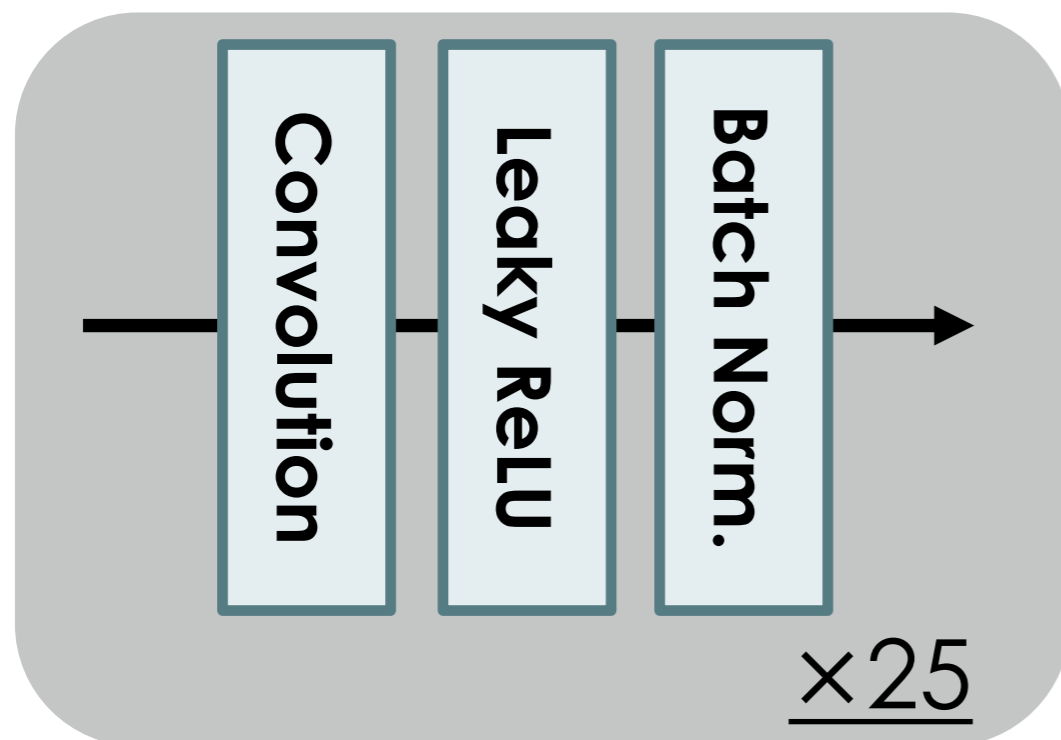
- Blind denoising
- Does not require pre-processing such as IN removal.
- Execution time is short compared to high-precision methods

CNN architecture



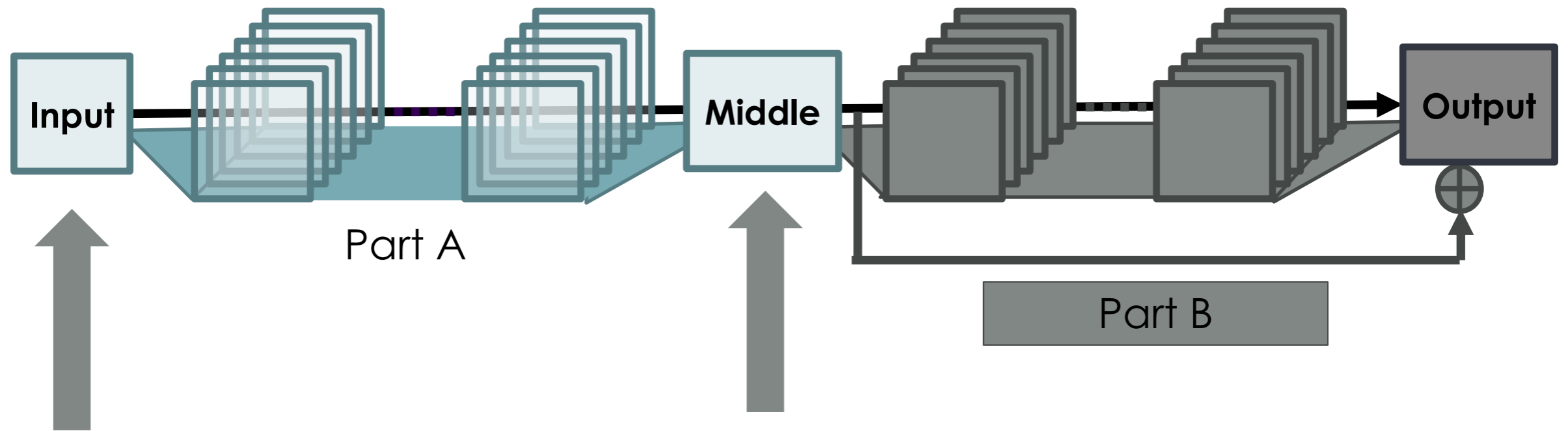
Part A

Part B



Training

① First step

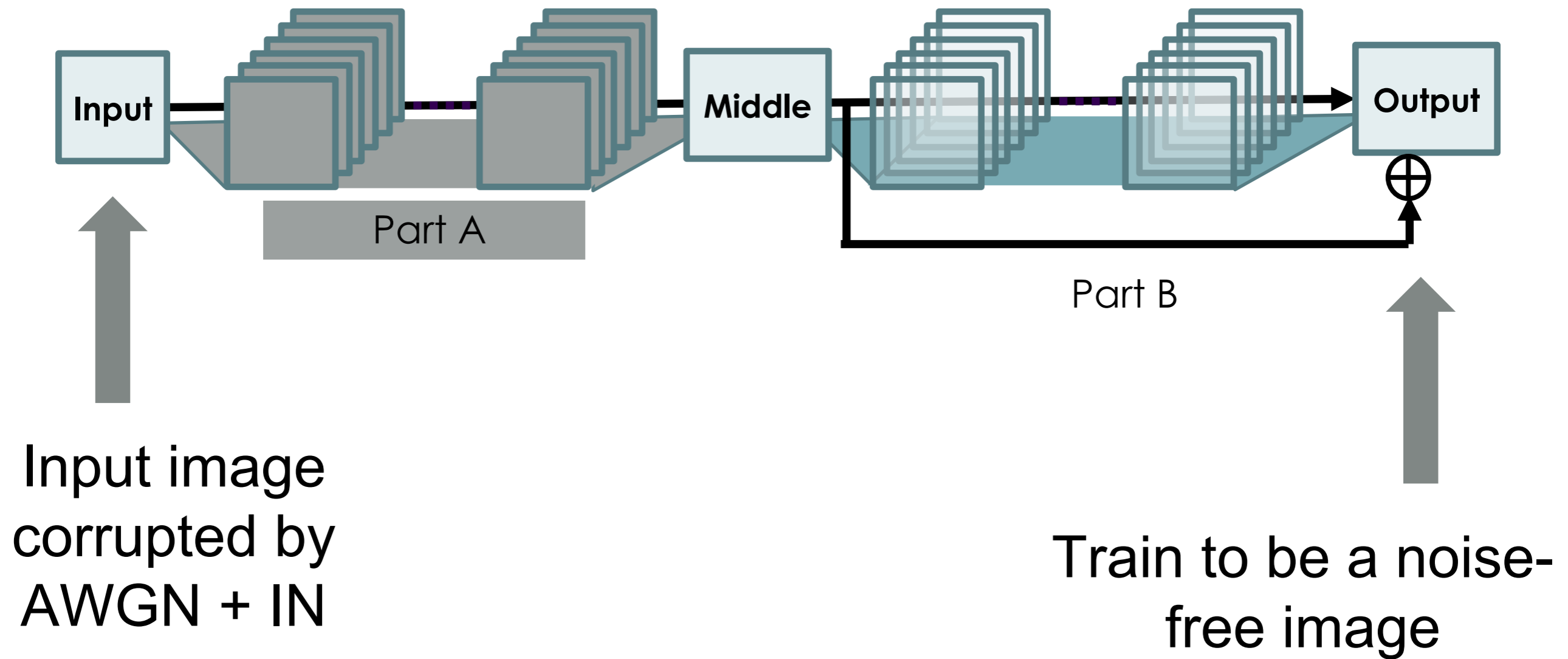


Input image
corrupted by
AWGN + IN

Train to be a
AWGN-only
image

Training

② Second step



Dataset

Microsoft COCO dataset is used for training.

The training image is corrupted by

$\sigma = [0, 10, 20, 30, 40, 50]$ ←AWGN

$p = [0, 5, 10, 15, 20, 25, 30, 35, 40, 45]$ ←RVIN

$s = [0 \sim 40]$ ←SPIN

→ By training with various noise levels, noise can be removed even if the noise level is not known
(Blind denoising)

Training parameters

- 6000 training images
 - Patch size: 33x33
 - Batch size: 256
 - Solver: Adam
 - Initial learning rate: 0.00001
 - Epoch: 10 (About 140000 iterations)
-
- About 30 hours to train with our MATLAB implementation on single GeForce GTX 1080Ti.

Conventional methods

- [1] Tao Chen and Hong Ren Wu, “Adaptive impulse detection using center-weighted median filters,” *IEEE Signal Processing Letters*, vol. 8, no. 1, pp. 1–3, 2001.
- [2] Kostadin Dabov, Alessandro Foi, Vladimir Katkovnik, and Karen Egiazarian, “Image denoising by sparse 3-d transform- domain collaborative filtering,” *IEEE Transactions on image processing*, vol. 16, no. 8, pp. 2080–2095, 2007.
- [3] L. Liu, L. Chen, C. P. Chen, Y. Y. Tang *et al.*, “Weighted joint sparse representation for removing mixed noise in image,” *IEEE transactions on cybernetics*, vol. 47, no. 3, pp. 600–611, 2017
- [4] M.T. Islam, S.M. Rahman, M.O. Ahmad, and M. Swamy, “Mixed gaussian-impulse noise reduction from images using convolutional neural network,” *Signal Processing: Image Communication*, vol.68, pp.26–41, 2018.

Comparison

Mixed noise
 $\sigma = 15$
 $p = 15, 30, 45$
 $s = 0$

Image	p	Method			
		AWCMF + BM3D	(ACWMF +) WSR	(ACWMF +) Islam's	Ours
Lena	15%	32.41	32.06	32.28	32.56
	30%	30.25	30.27	29.10	31.71
	45%	26.65	28.09	24.87	30.36
Barbara	15%	26.70	27.60	25.67	29.43
	30%	24.79	25.63	24.17	28.32
	45%	22.59	22.79	21.67	26.25
Bridge	15%	29.60	29.51	28.86	29.16
	30%	27.16	27.67	26.54	28.09
	45%	24.02	22.44	22.86	26.53
Boat	15%	29.65	29.16	29.12	30.30
	30%	27.55	27.72	27.02	29.19
	45%	24.78	25.17	23.62	27.60
Airplane	15%	33.42	33.66	32.52	32.87
	30%	30.36	31.79	28.81	31.88
	45%	25.51	26.73	23.32	30.44
Pepper	15%	34.94	35.02	34.07	33.49
	30%	31.60	32.26	29.90	33.36
	45%	26.71	28.73	24.54	32.09
Hill	15%	32.51	32.30	31.61	31.73
	30%	30.36	30.40	29.04	30.98
	45%	26.56	27.65	24.69	29.86
BSDS300	15%	27.64	27.03	27.70	28.51
	30%	25.76	25.78	25.29	27.30
	45%	22.88	23.59	22.13	25.87

Comparison

Mixed noise
 $\sigma = 25$
 $p = 15, 30, 45$
 $s = 0$

Image	p	Method			
		AWCMF + BM3D	(ACWMF +) WSR	(ACWMF +) Islam's	Ours
Lena	15%	29.87	29.81	29.87	30.46
	30%	28.10	28.41	27.93	29.79
	45%	25.53	26.32	24.88	28.54
Barbara	15%	24.91	24.87	24.52	27.28
	30%	23.57	23.58	23.36	26.35
	45%	21.91	22.04	21.65	24.75
Bridge	15%	26.76	26.37	26.61	26.72
	30%	25.32	25.31	25.10	25.97
	45%	22.98	21.40	22.62	24.81
Boat	15%	27.47	27.11	27.61	28.31
	30%	26.01	26.09	26.08	27.39
	45%	23.70	24.30	23.45	26.10
Airplane	15%	30.44	30.62	30.34	30.73
	30%	28.06	28.55	28.00	29.90
	45%	24.31	24.51	23.97	28.40
Pepper	15%	31.65	31.79	31.65	31.76
	30%	28.95	29.84	28.70	31.30
	45%	25.36	26.56	24.87	30.04
Hill	15%	29.70	29.30	29.48	29.55
	30%	28.09	28.41	27.80	28.99
	45%	25.16	26.10	24.59	28.01
BSDS300	15%	25.74	25.42	25.97	26.83
	30%	24.35	24.34	24.42	25.95
	45%	22.10	22.78	21.89	24.80

Comparison

Mixed noise

$\sigma = 20$

$p = 10$

$s = 15$

Image	Method			
	AMF + BM3D	(AMF +) WSR	(AMF +) Islam's	Ours
Lena	30.50	30.32	30.12	31.10
Barbara	25.10	25.81	24.68	28.11
Bridge	27.46	27.51	27.12	27.36
Boat	27.88	27.72	27.79	28.88
Airplane	30.85	30.98	30.17	31.22
Pepper	32.62	32.76	31.84	32.43
Hill	30.43	30.24	29.83	30.10
BSDS300	26.03	25.86	25.97	27.24

Comparison on running time

Mixed noise

$\sigma = 15$

$p = 15$

$s = 0$

Image	Device	Method			
		AWCMF + BM3D	(ACWMMF +) WSR	(ACWMMF +) Islam's	Ours
256x256	CPU	0.99 s	13.1 min.	2.07 s	6.48 s
	GPU	-	-	1.06 s	0.42 s
512x512	CPU	5.05 s	49.7 min.	7.22 s	30.39 s
	GPU	-	-	3.18 s	0.80 s

Comparison



Original



Noisy $\sigma=15, p=30$



ACWMMF + BM3D / 24.37dB



WSR / 25.60dB

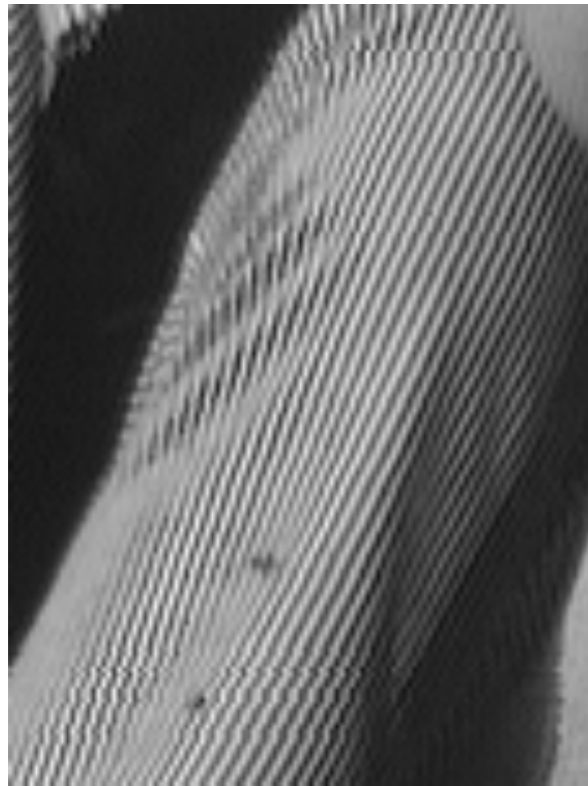


Islam's / 24.17dB

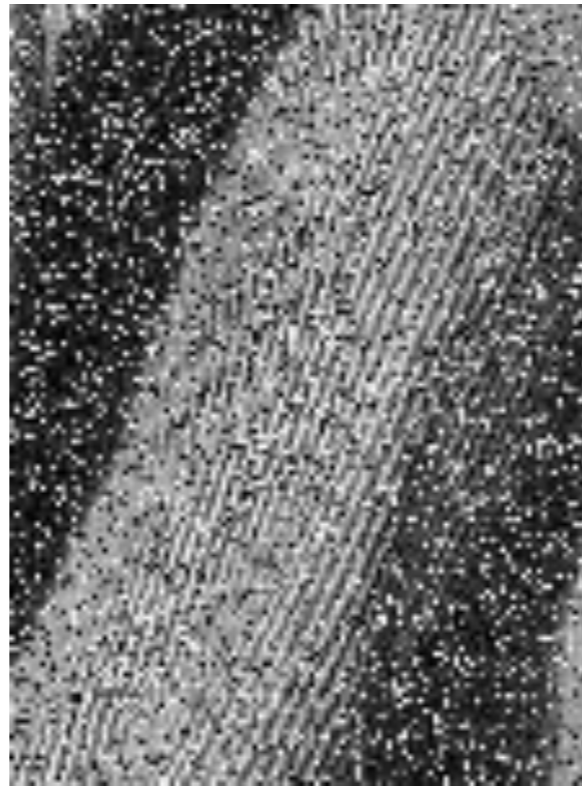


Proposed / 28.30dB

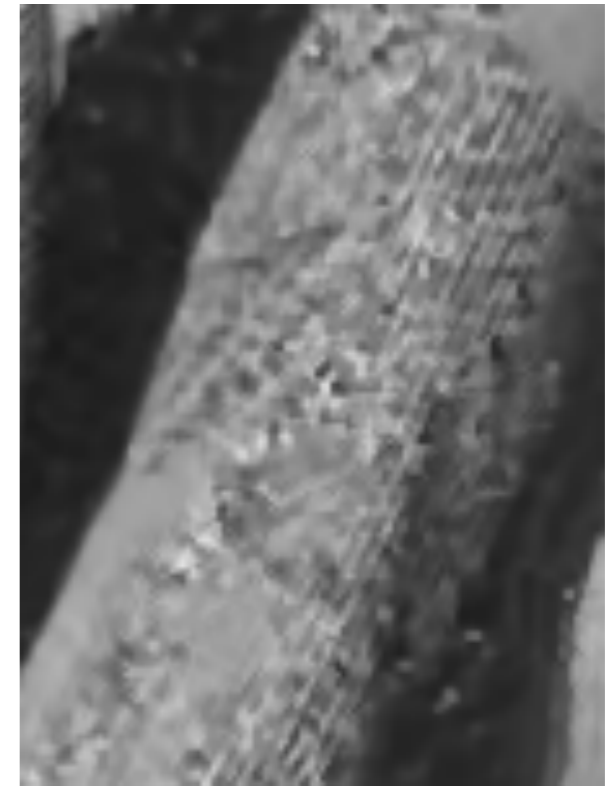
Comparison



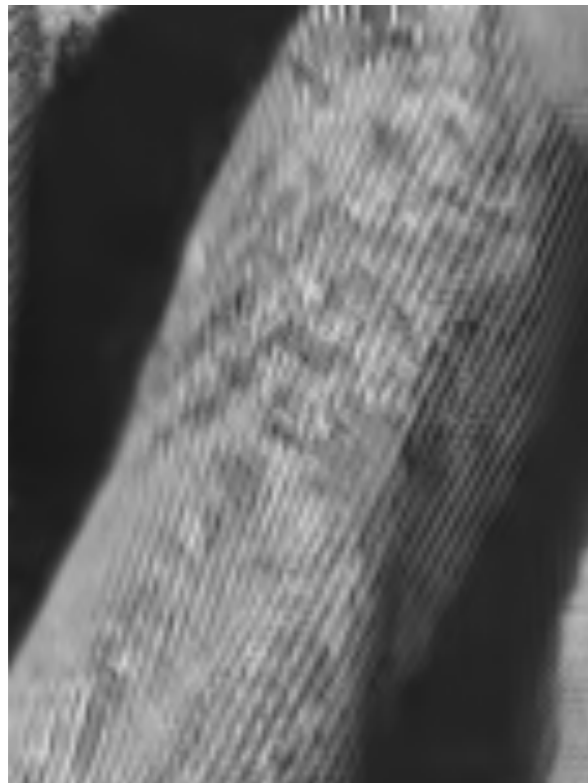
original



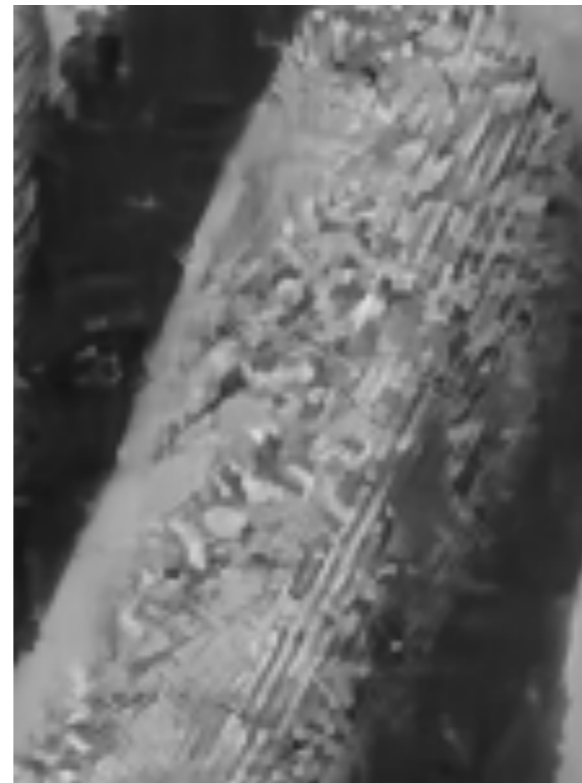
Noisy $\sigma=15, p=30$



ACWMMF + BM3D / 24.37dB



WSR / 25.60dB



Islam's / 24.17dB



Proposed / 28.30dB

Comparison



Original



Noisy $\sigma=20$, $p=10$, $s=15$



AMF + BM3D / 30.49dB



WSR / 30.31dB



Islam's / 30.12dB



Proposed / 31.09dB

Comparison



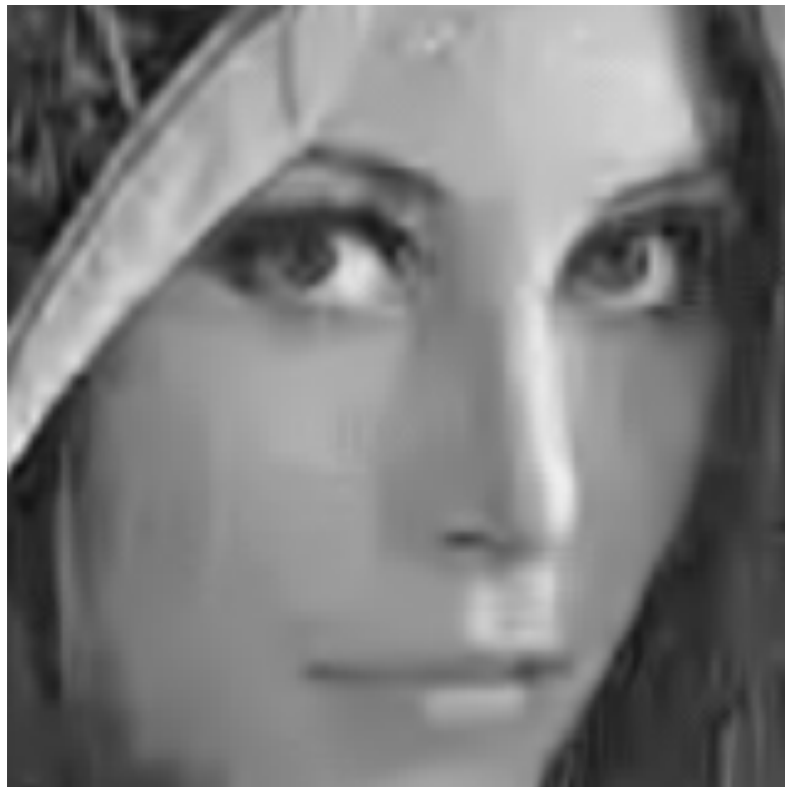
Original



Noisy $\sigma=20, p=10, s=15$



AMF + BM3D / 30.49dB



WSR / 30.31dB



Islam's / 30.12dB



Proposed / 31.09dB

Training method

Mixed noise

$\sigma = 25$

$p = 15,30,45$

Image	$(\sigma = 25)$ p	Training method		
		Proposed	Without division	Without skip connection
Test images	15%	29.24	27.72	28.07
	30%	28.54	26.82	27.65
	45%	27.22	25.46	26.53
BSDS300	15%	26.83	25.84	26.37
	30%	25.95	24.93	25.62
	45%	24.8	23.74	24.53

Conclusion

- We propose a new method for removing mixed noise based on CNN.
 - Blind denoising is achieved by training with various noise levels
 - Robustness against the noise is obtained by not using impulse noise removal method as preprocessing.

Thanks!

Source code is available at:
<http://tkhm.elec.keio.ac.jp/achievement>