

END-TO-END FEEDBACK LOSS IN SPEECH CHAIN FRAMEWORK VIA STRAIGHT-THROUGH ESTIMATOR

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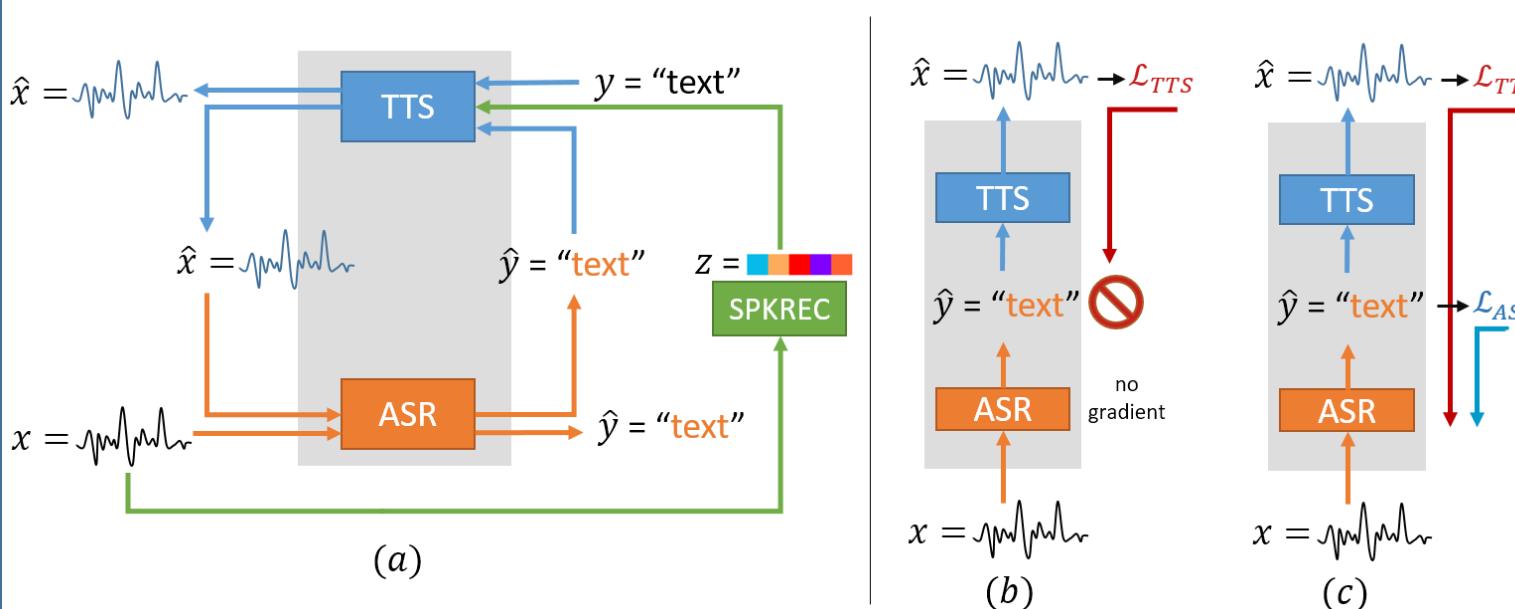
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1. Introduction

- Speech chain model integrates ASR and TTS into a single cycle during training.
- By combining both models, we could train with auxiliary feedback loss.
- **Problem:**
 - The output from ASR are discrete tokens
 - Non-differentiable (ASR → TTS)
- **Solution:**
 - Apply straight-through estimator on Gumbel-softmax or *argmax* sample

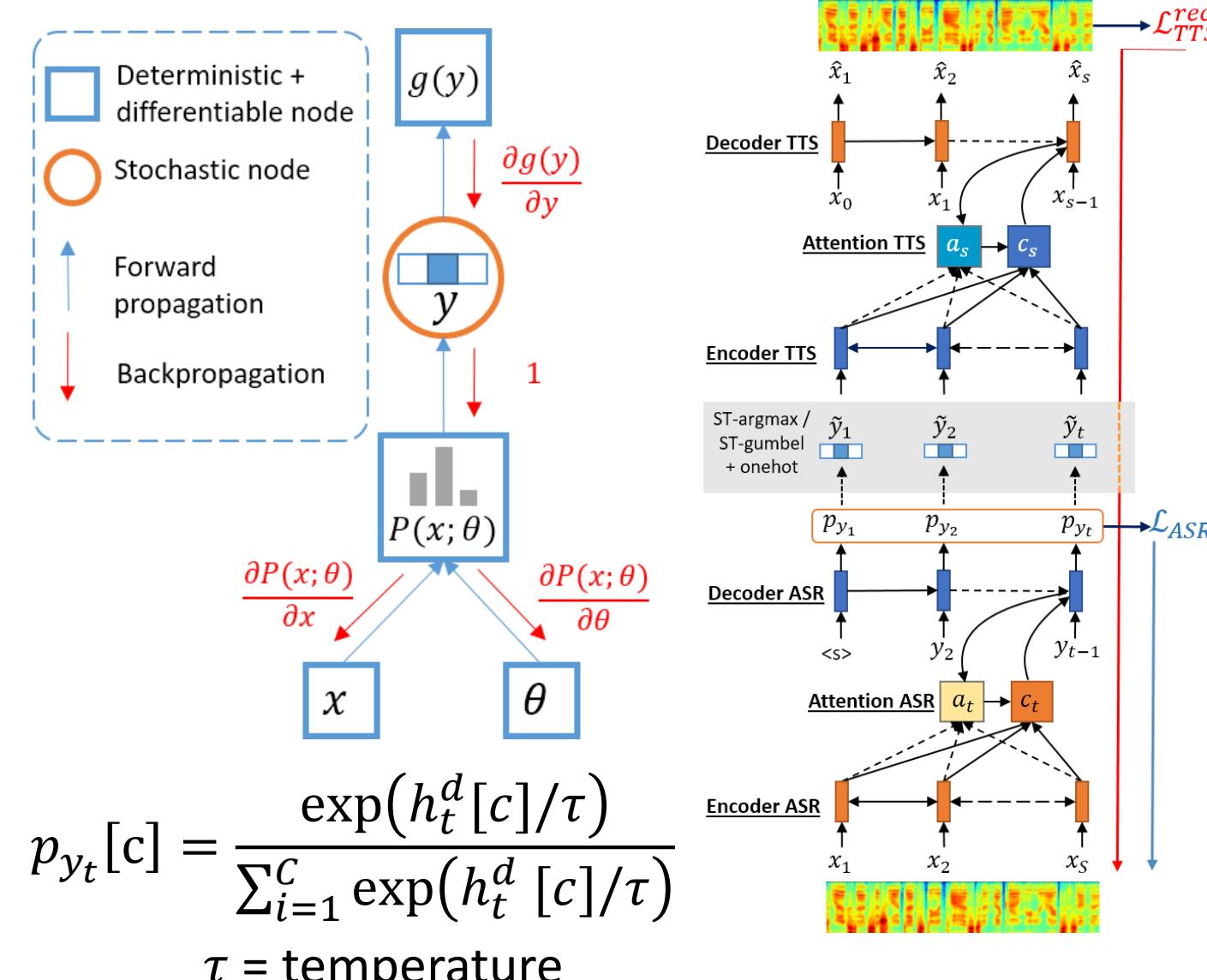
2. Speech Chain and Feedback loss



Feedback loss: $\mathcal{L}_{TTS} = \|x - \hat{x}\|_2^2$ where $x = TTS(\hat{y}, z)$

- Speech chain loop with speaker embedding module.
- Original: feedback \mathcal{L}_{TTS} can't be backpropagated through variable \hat{y} .
- Proposal:** Estimate gradient through variable \hat{y} with straight-through estimator.

3. Straight-through Estimator (ST)



New gradient \mathcal{L}_{TTS} w.r.t. θ_{ASR}

$$\begin{aligned} \frac{\partial \mathcal{L}_{TTS}^{rec}}{\partial \theta_{ASR}} &= \sum_{t=1}^T \frac{\partial \mathcal{L}_{TTS}^{rec}}{\partial \tilde{y}_t} \cdot \boxed{\frac{\partial \tilde{y}_t}{\partial p_{y_t}}} \cdot \frac{\partial p_{y_t}}{\partial \theta_{ASR}} \\ &\approx \sum_{t=1}^T \frac{\partial \mathcal{L}_{TTS}^{rec}}{\partial \tilde{y}_t} \cdot \boxed{1} \cdot \frac{\partial p_{y_t}}{\partial \theta_{ASR}}. \end{aligned}$$

4. Experiment

- Features: log Mel-spec (80-dim)
- Text: 26 letters (A-Z)+('-,) + <noise>
- Dataset: Wall Street Journal
 - Train: train_si284 (WSJ1)
 - Dev: dev93 & Test: eval92
- Hyperparams $\tau = [0.25, 0.5, 1, 2]$

Result on WSJ-1

Baseline		CER (%)	
Model	Generation	ST	CER (%)
Att MLP			7.12
Att MLP-MA			6.43
Proposed			
Model	Generation	ST	CER (%)
Att MLP-MA	Teacher-forcing	argmax	5.75
Att MLP-MA	Teacher-forcing	gumbel	5.7
Att MLP-MA	Greedy	argmax	5.84
Att MLP-MA	Greedy	gumbel	5.88

5. Discussion

- We introduced ST-estimator for training ASR module based on TTS feedback loss.
- The gradient in discretization problem can be replaced by identity Jacobian matrix.
- Our experiment shows that by adding auxiliary feedback loss, we improve the ASR performance further.