

Statistical rank selection for incomplete low-rank matrices

Yao Xie

School of Industrial and Systems Engineering
Georgia Institute of Technology

May 15, 2019

Joint work with Alexander Shapiro and Rui Zhang

Present at ICASSP 2019

Low-rank matrix completion

- ▶ Incomplete and noisy observations

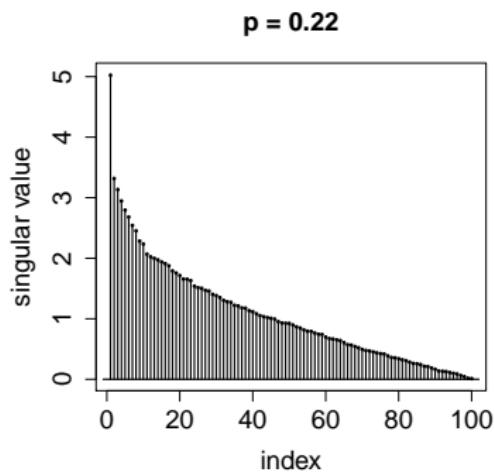
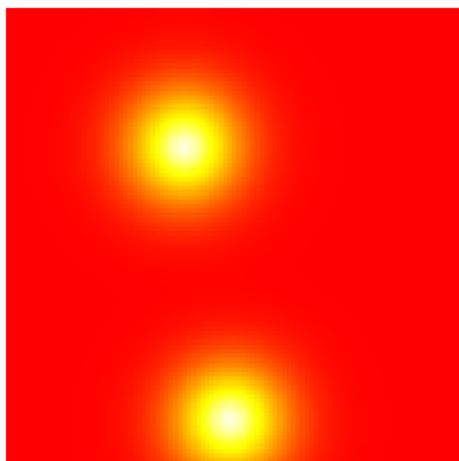
$$Y_{i,j} = X_{i,j} + \epsilon_{i,j}, \quad (i, j) \in \Omega \subset [m_1] \times [m_2]$$

- ▶ Recommender systems

| | | | | | | |
|---|---------|----------|----------------------|-------|---------------------|----------------------------|
| | TITANIC | AVENGERS | BEAUTY AND THE BEAST | BRAVE | MONSTERS UNIVERSITY | 10 THINGS I HATE ABOUT YOU |
| 1 | 5 | | | | 2 | |
| | | 3 | 2 | | | |
| | 5 | | | | 1 | |
| 3 | | 4 | | | | 3 |
| 5 | | | | 2 | | |
| | 3 | 2 | | | | 1 |

Example: Determine the number of sources from incomplete observations

$$Y_{i,j} = X_{i,j} + \epsilon_{i,j}, \quad (i, j) \in \Omega \subset [m_1] \times [m_2]$$



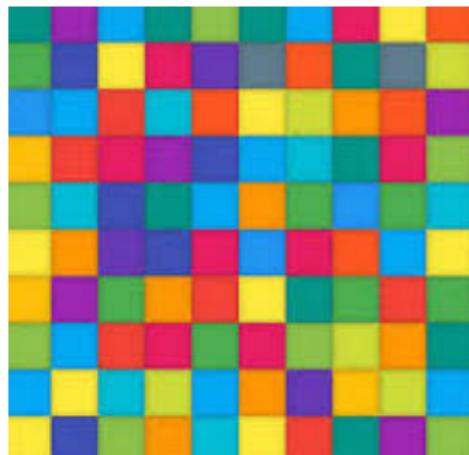
(Chen, Mitra '17)

Low-rank models

$$Y_{i,j} = \underbrace{X_{i,j}}_{\text{low-rank}} + \epsilon_{i,j}, \quad (i, j) \in \Omega \subset [m_1] \times [m_2]$$



low-rank



high-rank

Prior work

- ▶ **Convex relaxation:** **noiseless**

(Candes, Recht '08, Candes, Tao '08, Gross '09)

$$\min_Z \|Z\|_* \text{ subject to } Y_{ij} = Z_{ij}, (i, j) \in \Omega.$$

- ▶ **Convex relaxation robustness to noise**

(Candes, Plan '09, Negahban, Wainwright '10, Koltchinskii et al. '10)

$$\min_Z \underbrace{f(Z; Y)}_{\text{empirical loss}} + \lambda \|Z\|_*$$

- ▶ **Non-convex optimization**

Burer, Monteiro '03, Rennie Srebro '05, Jain, Netrapalli, Sanghavi '12, Ma, Wang, Chi, Chen '17 ...

$$\min_{U \in \mathbb{R}^{n_1 \times r}, V \in \mathbb{R}^{n_1 \times r}} \sum_{(i,j) \in \Omega} [(UV^T)_{ij} - Y_{ij}]^2 + \text{regularizer}$$

Motivation

- ▶ Select “rank” parameter in algorithm

$$\min_{U \in \mathbb{R}^{n_1 \times r}, V \in \mathbb{R}^{n_1 \times r}} \sum_{(i,j) \in \Omega} [\underbrace{(UV^T)_{ij}}_{\text{low-rank}} - Y_{ij}]^2 + \text{regularizer}_X$$

- ▶ Determine “true” rank when the underlying matrix is low-rank

$$Y_{i,j} = \underbrace{X_{i,j}}_{\text{low-rank}} + \epsilon_{i,j}, \quad (i, j) \in \Omega \subset [m_1] \times [m_2]$$

Problem formulation

Noisy and possibly biased observations of a subset of matrix entries

$$Y_{ij} = X_{ij}^* + N^{-1/2} \Delta_{ij} + \varepsilon_{ij}, \quad (i, j) \in \Omega,$$

- ▶ $X^* \in \mathcal{M}_{r^*}$ low-rank matrix
- ▶ N effective sample size
- ▶ Δ_{ij} deterministic bias term
- ▶ $N^{1/2} \varepsilon_{ij} \xrightarrow{\text{in dist}} \mathcal{N}(0, \sigma_{ij}^2)$ variance can be different

Goal: determine r^* using statistical test procedure

Assumptions

Typical assumptions

- ▶ Non-adaptive, random sampling: each $(i, j) \in \Omega$ independently with probability p
- ▶ Random noise: i.i.d. sub-Gaussian noise
- ▶ Ground truth: M^* is low-rank

Here

- ▶ Ω is deterministic



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Our contribution

- ▶ Develop a new statistical test procedure to determine the rank
- ▶ Solve a sequence of “fitting” problems with different r

$$\min_{U \in \mathbb{R}^{n_1 \times r}, V \in \mathbb{R}^{n_1 \times r}} \sum_{(i,j) \in \Omega} [(UV^T)_{ij} - Y_{ij}]^2$$

- ▶ Examine residuals to decide

Example: true rank is 6.

Table: *sequential rank test*

| rank | p-value | $\hat{\sigma}^2 (= Z)$ | rank | p-value | $\hat{\sigma}^2 (= Z)$ |
|------|---------|------------------------|----------|-------------|------------------------|
| 1 | 0.82 | 34995.5 | 5 | 0.84 | 5050.63 |
| 2 | 0.86 | 26751.3 | 6 | 0.43 | 97.7 |
| 3 | 0.92 | 18719.6 | 7 | 0.76 | 96.6 |
| 4 | 0.62 | 11231.8 | 8 | 0.96 | 96.7 |

Formal results: How to select r ?

- ▶ Solve a sequence of weighted least squares test statistic

$$T_N(r) := N \min_{Y \in \mathcal{M}_r} \sum_{(i,j) \in \Omega} w_{ij} (M_{ij} - Y_{ij})^2,$$

$w_{ij} := 1/\hat{\sigma}_{ij}^2$ with $\hat{\sigma}_{ij}^2$ being consistent estimates of σ_{ij}^2

\mathcal{M}_r : (manifold) of all rank- r matrices

- ▶ $m = |\Omega|$ number of measurements

Asymptotic properties of test statistic

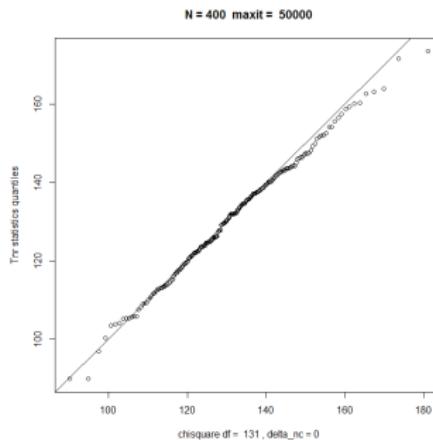
$$T_N(r) \Rightarrow \chi^2(df_r, \delta_r),$$

1. degrees of freedom

$$df_r = |\Omega| - \dim(\mathcal{M}_r) = m - r(n_1 + n_2 - r),$$

2. noncentrality parameter

$$\delta_r = \min_{H \in \mathcal{T}_{\mathcal{M}_r}(Y^*)} \sum_{(i,j) \in \Omega} \sigma_{ij}^{-2} (\Delta_{ij} - H_{ij})^2.$$



Sequential test procedures

- ▶ Sequentially test $r = 1, 2, 3, \dots$ using $T_N(r)$
- ▶ “null” hypothesis that the “true” rank is r^*
- ▶ null hypothesis is rejected if
 - $T_N(r)$ is **large** enough on the scale of the χ^2 distribution
- ▶ perform such tests sequentially for increasing values of r

Table: sequential rank test

| rank | p-value | $\hat{\sigma}^2 (= Z)$ | rank | p-value | $\hat{\sigma}^2 (= Z)$ |
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Additional comments

- ▶ Role of values Δ_{ij} : suggest that “true” model is true only approximately
- ▶ noncentrality parameter

$$\delta_r = \min_{H \in \mathcal{T}_{\mathcal{M}_r}(Y^*)} \sum_{(i,j) \in \Omega} \sigma_{ij}^{-2} (\Delta_{ij} - H_{ij})^2.$$

indicates the deviation from the exact rank r model.

“Single” matrix observation

- ▶ Suppose $N = 1$, $\Delta_{ij} = 0$ and $\varepsilon_{ij} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$.
- ▶ Consider a sequence of index set

$$\Omega_0 \supset \Omega_1 \supset \Omega_2 \supset \cdots \supset \Omega_K,$$

$$|\Omega_{k-1}| - |\Omega_k| = L, \forall k = 1 \cdots K.$$

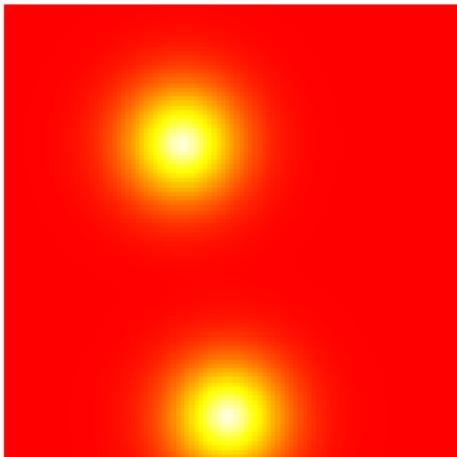
- ▶ Let

$$X_i = \min_{Y \in \mathcal{M}_r} \sum_{(i,j) \in \Omega_i} (M_{ij} - Y_{ij})^2,$$

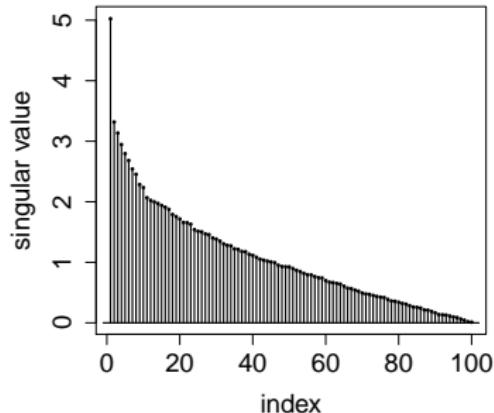
$$Z_i = (X_{i-1} - X_i)/L.$$

- ▶ $\sqrt{K}(\bar{Z} - \sigma^2)$ converge in distribution to $\mathcal{N}(0, 2\sigma^4/L)$

Example: Determine the number of sources



$p = 0.22$



| rank | p-value | rank | p-value |
|----------|-------------|------|---------|
| 1 | 0.00 | 4 | 1.00 |
| 2 | 0.15 | 5 | 1.00 |
| 3 | 0.98 | 6 | 1.00 |

Summary

$$Y_{ij} = X_{ij}^* + N^{-1/2} \Delta_{ij} + \varepsilon_{ij}, \quad (i, j) \in \Omega,$$

- ▶ How to select rank r ? **Sequential χ^2 test**
- ▶ Test statistic

$$T_N(r) := N \min_{Y \in \mathcal{M}_r} \sum_{(i,j) \in \Omega} w_{ij} (M_{ij} - Y_{ij})^2 \Rightarrow \chi^2(df_r, \delta_r),$$

| rank | p-value | rank | p-value |
|----------|-------------|------|---------|
| 1 | 0.00 | 4 | 1.00 |
| 2 | 0.15 | 5 | 1.00 |
| 3 | 0.98 | 6 | 1.00 |

- ▶ Role of values Δ_{ij} : suggest that “true” model is true only approximately; non-central parameter δ_r indicates so

Thank you!

References

1. Matrix completion with deterministic pattern - a geometric perspective. A. Shapiro, Y. Xie, and R. Zhang. IEEE Transactions on Signal Processing. Volume: 67 , Issue: 4 , Feb.15, 15 2019