

Pierre JACOB¹, David PICARD^{1,2}, Aymeric HISTACE¹, Edouard KLEIN³

1. ETIS, UMR 8051, Université Paris Seine, Université de Cergy-Pontoise, ENSEA, CNRS, F-95000, Cergy, France
 2. LIGM, UMR 8049, Ecole des Ponts, UPE, Champs-sur-Marne, France
 3. C3N, Pôle Judiciaire de la Gendarmerie Nationale, 5 Boulevard de l'Hautail, 95000 Cergy, France

Problems

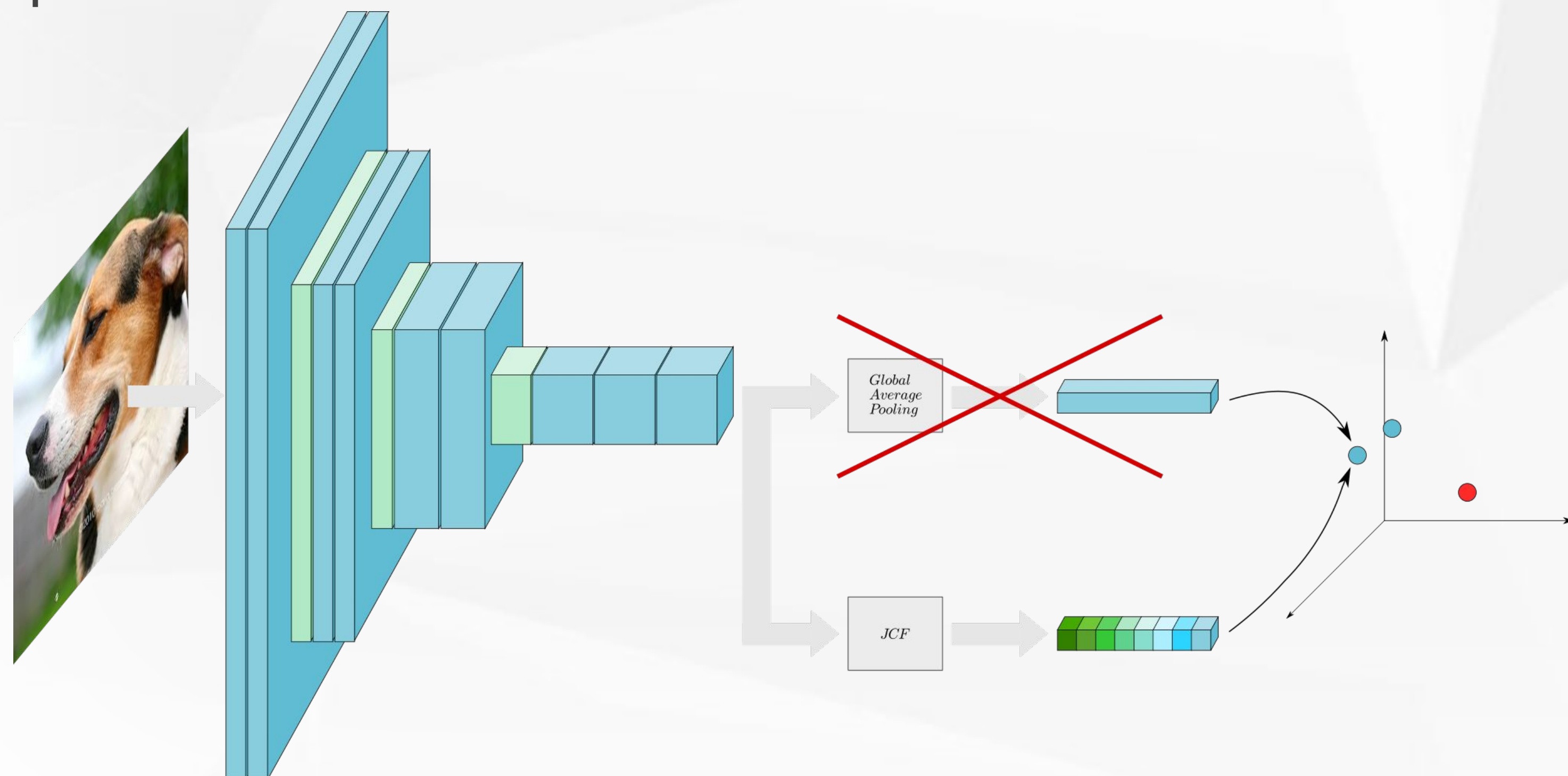
- How to build rich and compact representations ?
 - Fine-grained visual tasks => **Second-order pooling**
 - **Unrelated** feature aggregation => **Codebook strategies**
 - **Compactness** in representation learning => Deep metric learning (DML)
- What about the drawbacks ?
 - Second-order **dimensionality** is too large for DML
 - Codebook strategies further increase this **dimensionality**



Propositions

Joint Codebook-Factorization strategy

- Codebook + second-order pooling increases performances, albeit at a prohibitive cost
- Joint factorization and codebook strategy => rich and compact representations



Joint Codebook Factorization

Raw representation

- We duplicate the codebook assignment for symmetry purpose:

$$\mathbf{y} = \mathbf{h}(\mathbf{x}) \otimes \mathbf{x} \otimes \mathbf{h}(\mathbf{x}) \otimes \mathbf{x}$$

Raw projection

- The i-th dimension is computed as follows:

$$z_i = \langle \mathbf{w}_i ; \mathbf{h}(\mathbf{x}) \otimes \mathbf{x} \otimes \mathbf{h}(\mathbf{x}) \otimes \mathbf{x} \rangle$$

First factorization

- Rank-one factorization to split each pair of codebook assignment and feature:

$$z_i = \langle \mathbf{p}_i ; \mathbf{h}(\mathbf{x}) \otimes \mathbf{x} \rangle \langle \mathbf{q}_i ; \mathbf{h}(\mathbf{x}) \otimes \mathbf{x} \rangle$$

Second factorization

- Multi-rank factorization which generalize intra-projection in codebook strategies:

$$\mathbf{p}_i = \sum_j \mathbf{e}^{(j)} \otimes \mathbf{u}_{i,j}$$

$$\mathbf{q}_i = \sum_j \mathbf{e}^{(j)} \otimes \mathbf{v}_{i,j}$$

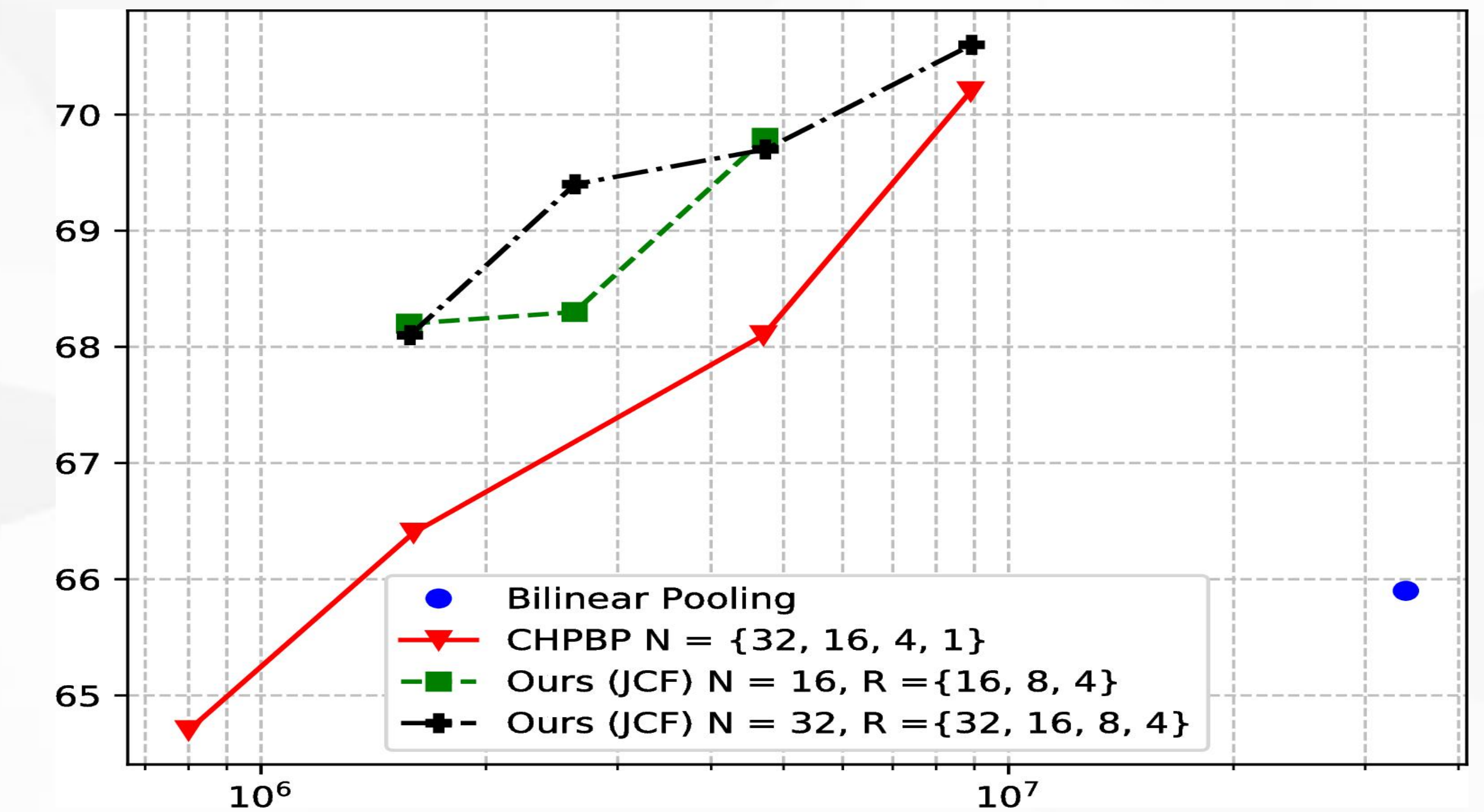
$$z_i = \left(\mathbf{h}(\mathbf{x})^\top \mathbf{U}_i^\top \mathbf{x} \right) \left(\mathbf{h}(\mathbf{x})^\top \mathbf{V}_i^\top \mathbf{x} \right)$$

Sharing projectors

- Entries in projection matrices can be shared between codebook entries:

$$z_i = \left(\mathbf{h}(\mathbf{x})^\top \mathbf{A} \tilde{\mathbf{U}}_i^\top \mathbf{x} \right) \left(\mathbf{h}(\mathbf{x})^\top \mathbf{B} \tilde{\mathbf{V}}_i^\top \mathbf{x} \right)$$

Results



Recall@1 against number of parameters

Method	CUB	CARS	SOP
HTL	57.1	<u>81.4</u>	74.8
JCF-32	60.1	82.6	77.4
JCF-32-8	<u>58.1</u>	74.2	<u>76.6</u>

Comparison to the state-of-the-art on three image retrieval datasets

Conclusion

- Codebook strategies further improve second-order pooling
- Joint codebook-factorization greatly reduces the representation size with fewer loss in performances
- Decrease in parameters can be handled by sharing projectors at the cost of a drop in performances

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