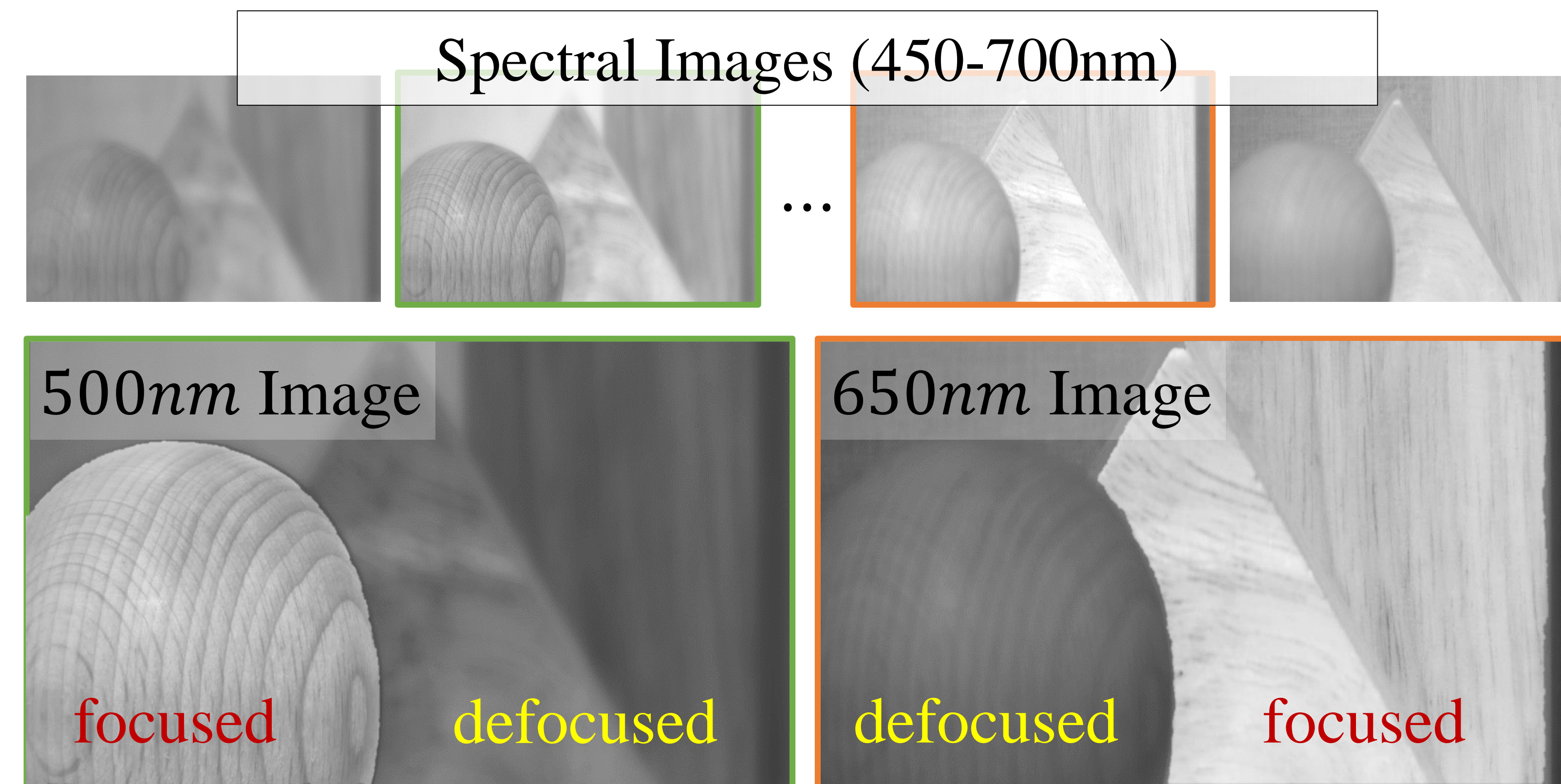


Goal

Our Goal: Simultaneous acquisition of clear multispectral image and scene depth from a blurred single multispectral image



- Different wavelength images have different focal positions

Depth Clues: Conventional depth-dependent blur and wavelength-dependent blur (known as chromatic aberration)

Imaging Model

Captured Image Gaussian Blur Texture (Pinhole)

$$I(x, y, \lambda) = k(x, y, \sigma(\lambda)) * P(x, y, \lambda)$$

- Both k and P are dependent on the wavelength λ

Depth

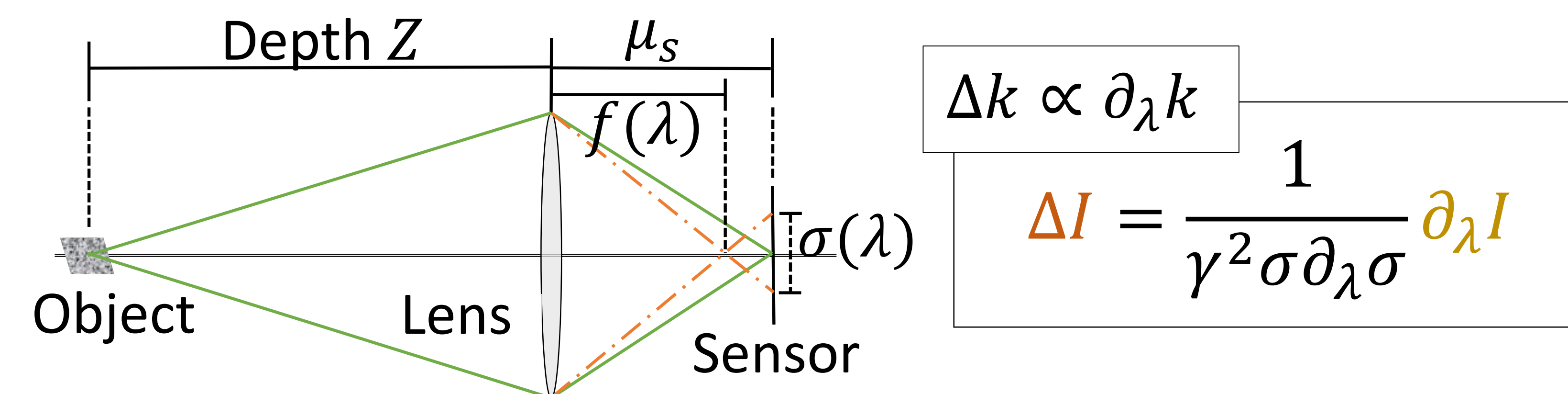
$$Z = \frac{\alpha(\lambda)\Delta I}{\beta(\lambda)\Delta I - \partial_{\lambda}I}$$

- x, y : spatial coordinates
- σ : variance of Gaussian
- α, β : lens parameters

- Depth Z can be derived by two types of derivative of captured image [1]; one is spatial (ΔI) and the other is spectral ($\partial_{\lambda}I$)

Method

Theory: Depth Z is actually derived as a closed form by the lens rule and the two types of derivatives of Gaussian blur



$$\Delta k \propto \partial_{\lambda}k$$

$$\Delta I = \frac{1}{\gamma^2 \sigma \partial_{\lambda} \sigma} \partial_{\lambda}I$$

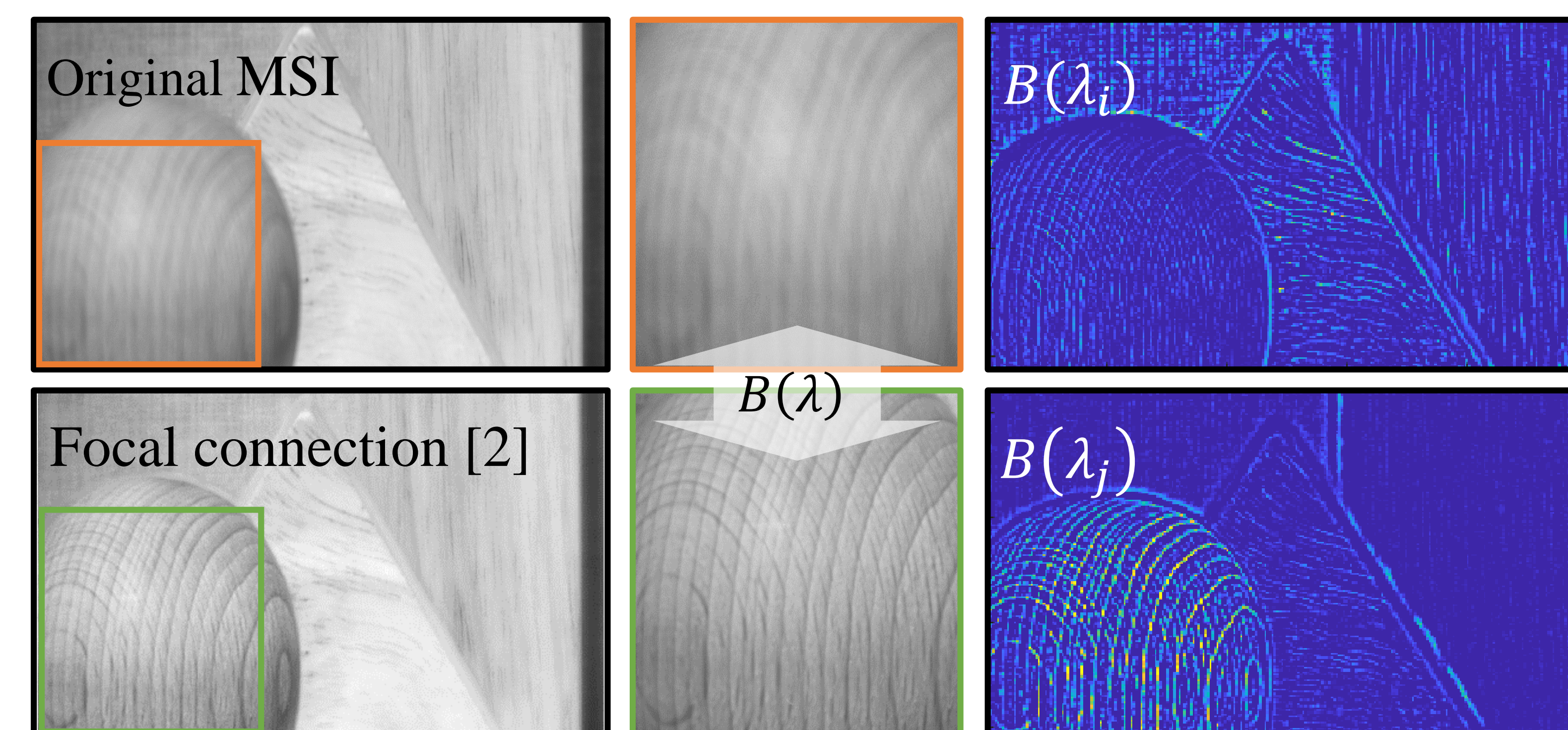
Lens rule

$$\sigma(\lambda) = \left(\frac{1}{Z} - \frac{1}{f(\lambda)} \right) \mu_s + 1$$

- γ : RMS width of Gaussian
- f : focal length of the lens
- μ_s : distance from the lens to the sensor

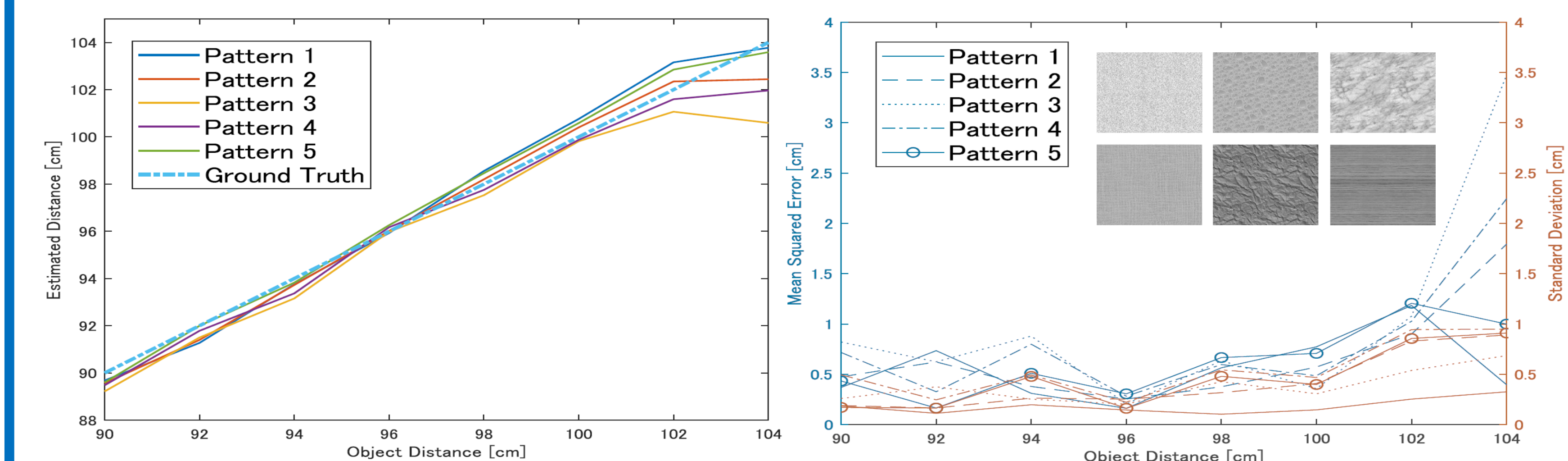
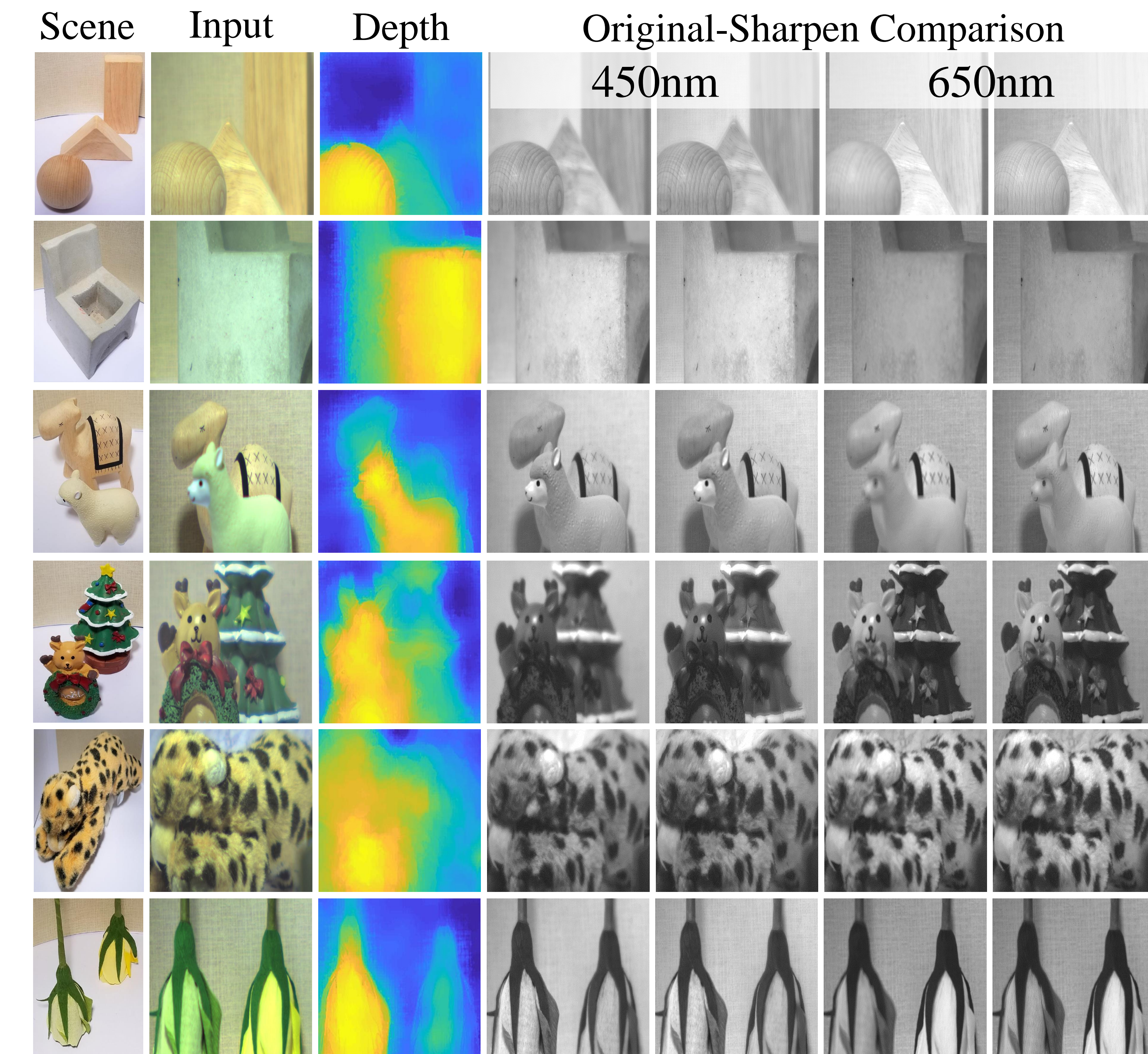
Computation: ΔI is obtained as laplacian filter. $\partial_{\lambda}I$ is approximated as the change of blurriness $B = I(\lambda) - I_{focused}(\lambda)$.

$$\partial_{\lambda}I = \partial_{\lambda}k * P = (k(\lambda_i) - k(\lambda_j)) * P \approx B(\lambda_i) - B(\lambda_j)$$



- Focal connected image are also utilized to generate clear multispectral image

Results



Website of our
laboratory



- [1]: Q.Guo, et al. ICCV'17, pp.966-974
[2]: H.Hariharan, et al. CVPR'07, pp.1-6