

WAVE PHYSICS INFORMED DICTIONARY LEARNING IN ONE DIMENSION



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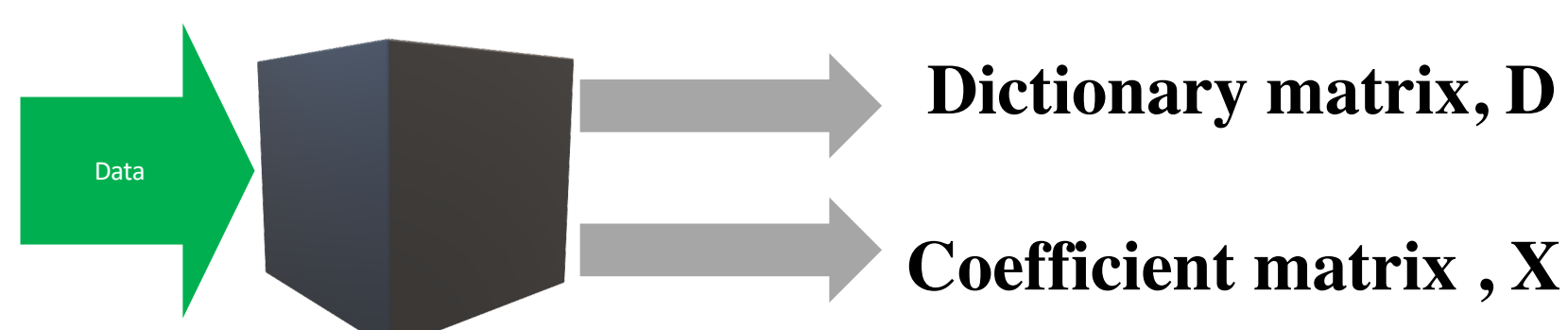
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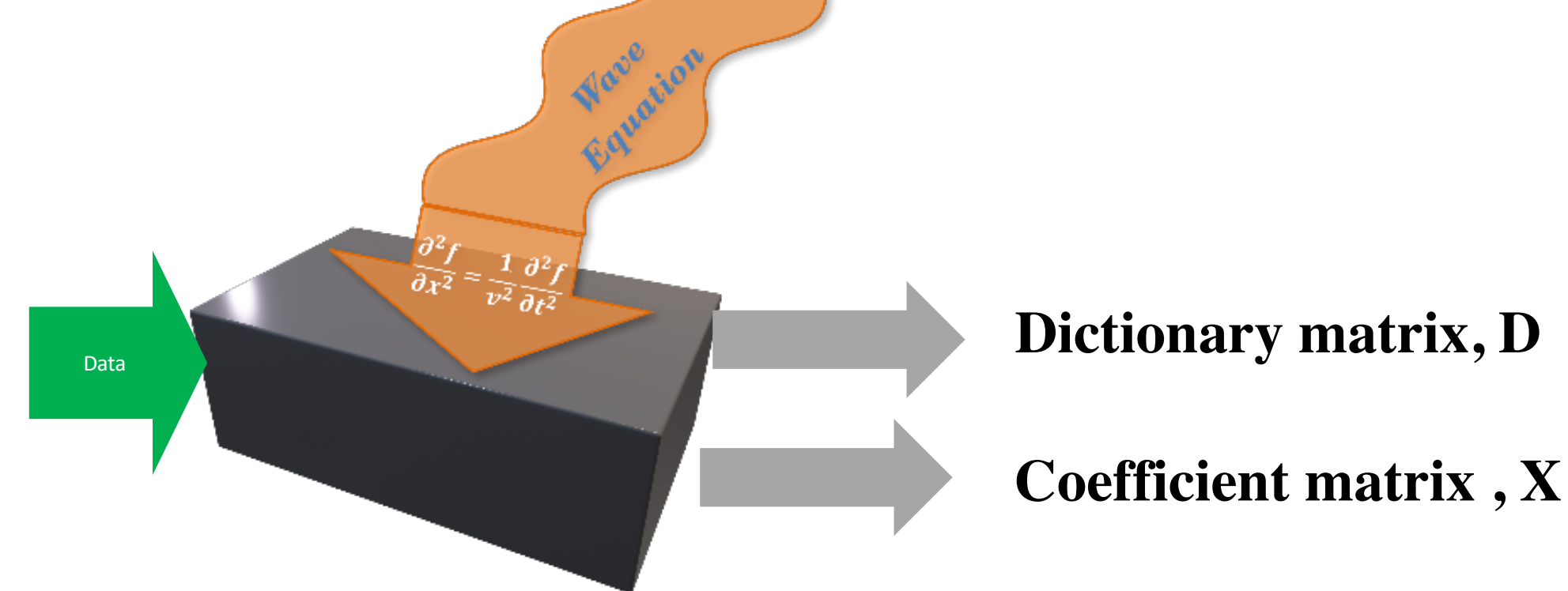
Introduction

- In Structural health monitoring, data-driven approaches to model behavior of waves to detect and locate damages has gained popularity.
- Recent works have used popular dictionary learning algorithm, K-SVD, to learn overcomplete dictionary for waves propagating in a metal plate.
- Instead of treating the K-SVD as a black box, we create a novel modification by enforcing domain knowledge.
- We look at how regularizing the K-SVD with one-dimensional wave equation affects the dictionary atoms

KSVD as a Black box



Wave-informed KSVD



Approach

The Physical Model: Domain Knowledge

- Wave Equation: $\frac{\partial^2 f}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$
- Space-time separability assumption:
 $f(x, t) = d(x)q(t)$
- Obtaining an eigenvalue problem by taking the Fourier transform (over time) of the wave equation with the space-time separability assumption:
 $\frac{\partial^2 d}{\partial x^2} F\{q\{t\}\} = \frac{1}{v^2} d(x) F\left\{\frac{\partial^2 q(t)}{\partial t^2}\right\} \Rightarrow \frac{\partial^2 d}{\partial x^2} = \frac{-\omega^2}{v^2} d$
- The discretized form of the Eigenvalue problem (to enforce physical consistence):

$$LD_i = g_k D_i \text{ where, } L_{3 \times 3} = \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix} \text{ (e.g.)}$$

Objective Function

$$\min_{D, X} \|Y - DX\|_F^2 + \sum_{j=1}^K \gamma_k \|LD_j - g_k D_j\|_2^2$$

Optimization Approach

- Alternatively update X and D as shown in the algorithm block.
- Additionally the parameter g_k is also updated in each step and set $\gamma_k \propto \frac{1}{g_k^2}$.

Algorithm: Wave Informed K-SVD

Algorithm 1 wave-informed K-SVD, **Input:** $Y \in R^{m \times n}$, $K \in N$

- 1: Initialize $D^{(0)}$, $g^{(0)} = (g_1^{(0)}, g_2^{(0)}, \dots, g_K^{(0)})$ and $iter$ (no. of iterations)
- 2: Set $t = 0$
- 3: **repeat**
- 4: *Sparse Code Stage:*
- 5: $i = 1, 2, \dots, N$; $\min_{X_i} \{\|Y_i - D^{(t)} X_i\|_F^2\}$ subject to $\|X_i\|_0 \leq s$
- 6: *Dictionary Update Stage:*
- 7: $g_k^{(t)} = D_k^{(t)T} L D_k^{(t)}$; $k = 1, 2, \dots, K$
- 8: $E_k^{(t)} = Y - \sum_{j \neq k} D_j^{(t)} \hat{X}_j^{(t)T}$; $k = 1, 2, \dots, K$
- 9: Let S contain indices of columns that are non-zero. Now $\tilde{E}_k^{(t)}$ is formed from $E_k^{(t)}$ by selecting columns indicated by S .
- 10: Eigen Value Decomposition of $\tilde{E}_k^{(t)} \tilde{E}_k^{(t)T} - \gamma_k (L - g_k I) (L - g_k I)^T = U \Delta U^{-1}$
- 11: Choose column $D_k^{(t)}$ to be first column of U
- 12: Update $\tilde{X}_k^{(t)} = \tilde{E}_k^{(t)T} D_k^{(t)}$
- 13: $\hat{X}_k^{(t)}$ is constructed from $\tilde{X}_k^{(t)}$ by placing the elements of the latter at the indices indicated by S , zeros otherwise.
- 14: $t \leftarrow t + 1$
- 15: **until** $t == iter$

Results

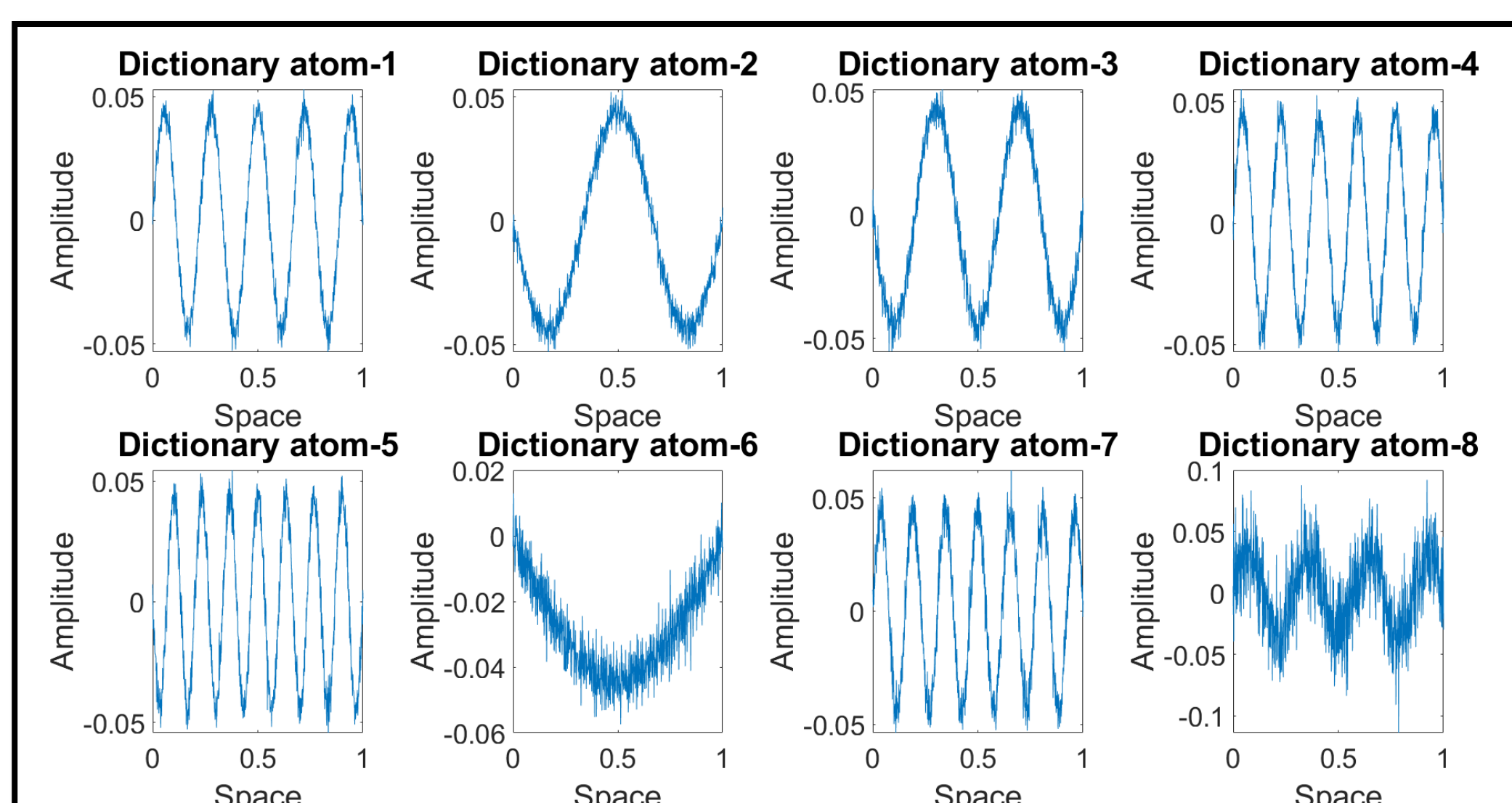
Data Model (fixed string):

$$y(x, t) = \sum_{k=1}^8 a_k \sin((2k-1)x) \sin(\omega_k t + \phi_k) e^{-4t} + n(x, t)$$

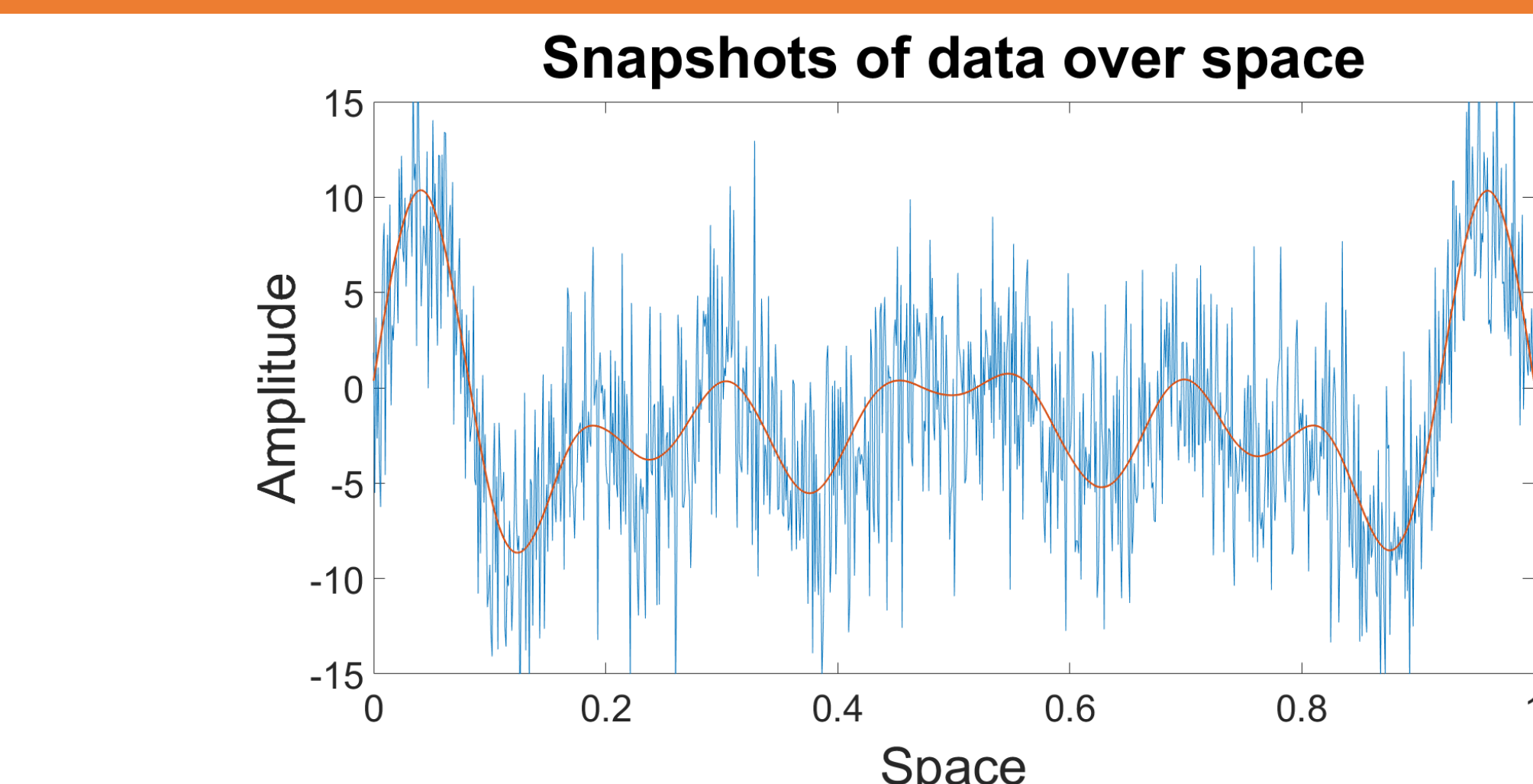
Where $\omega_k = vk$, where v is the velocity of the wave
And $n(x, t)$ is white Gaussian noise.

Algorithm Details:

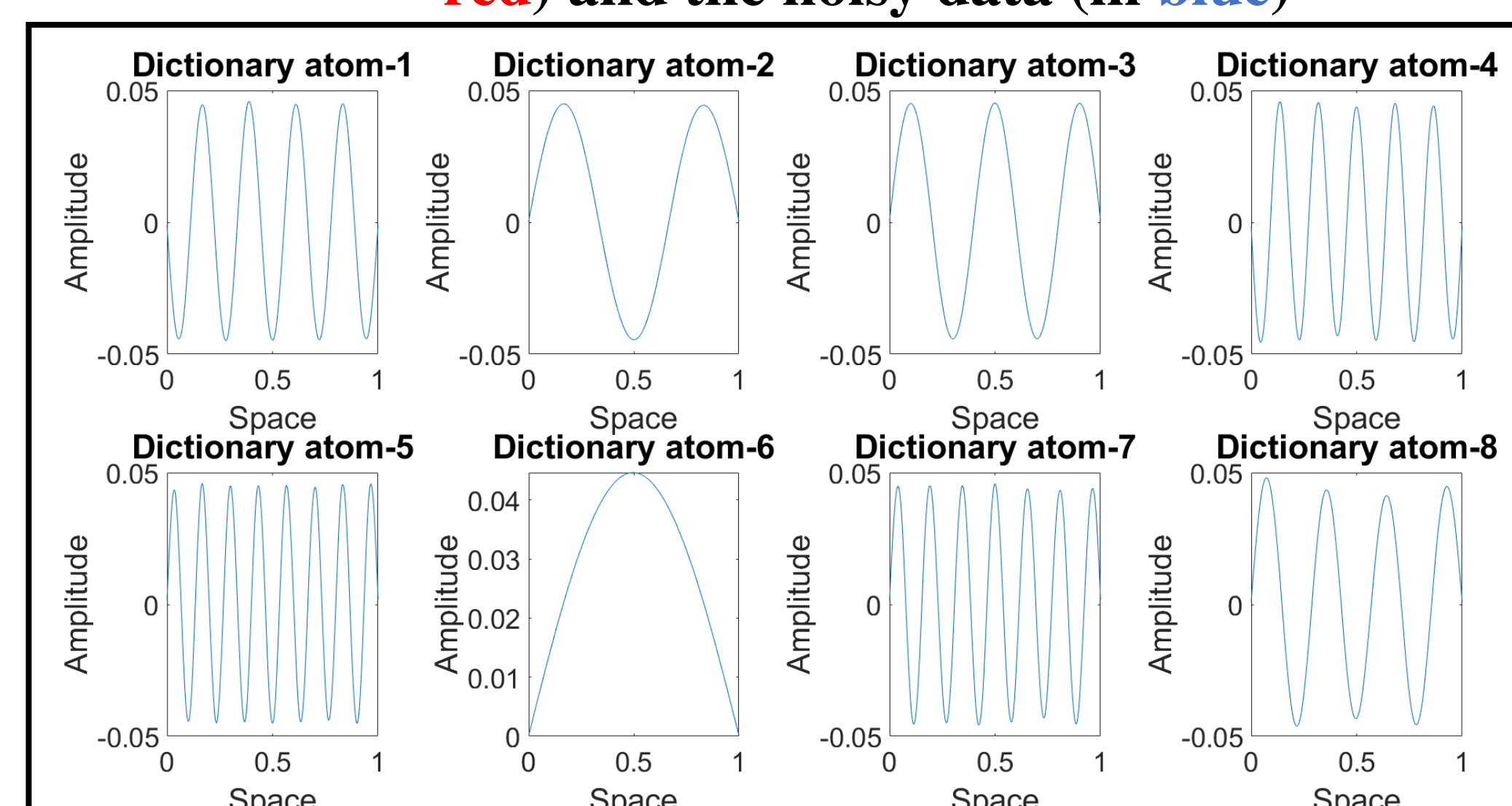
- $\gamma_0 \approx 10^7$, where $\gamma_k = \gamma_0 / g_k^2$.
- Sparsity $s = 1$ in Orthogonal matching pursuit part of the algorithm.



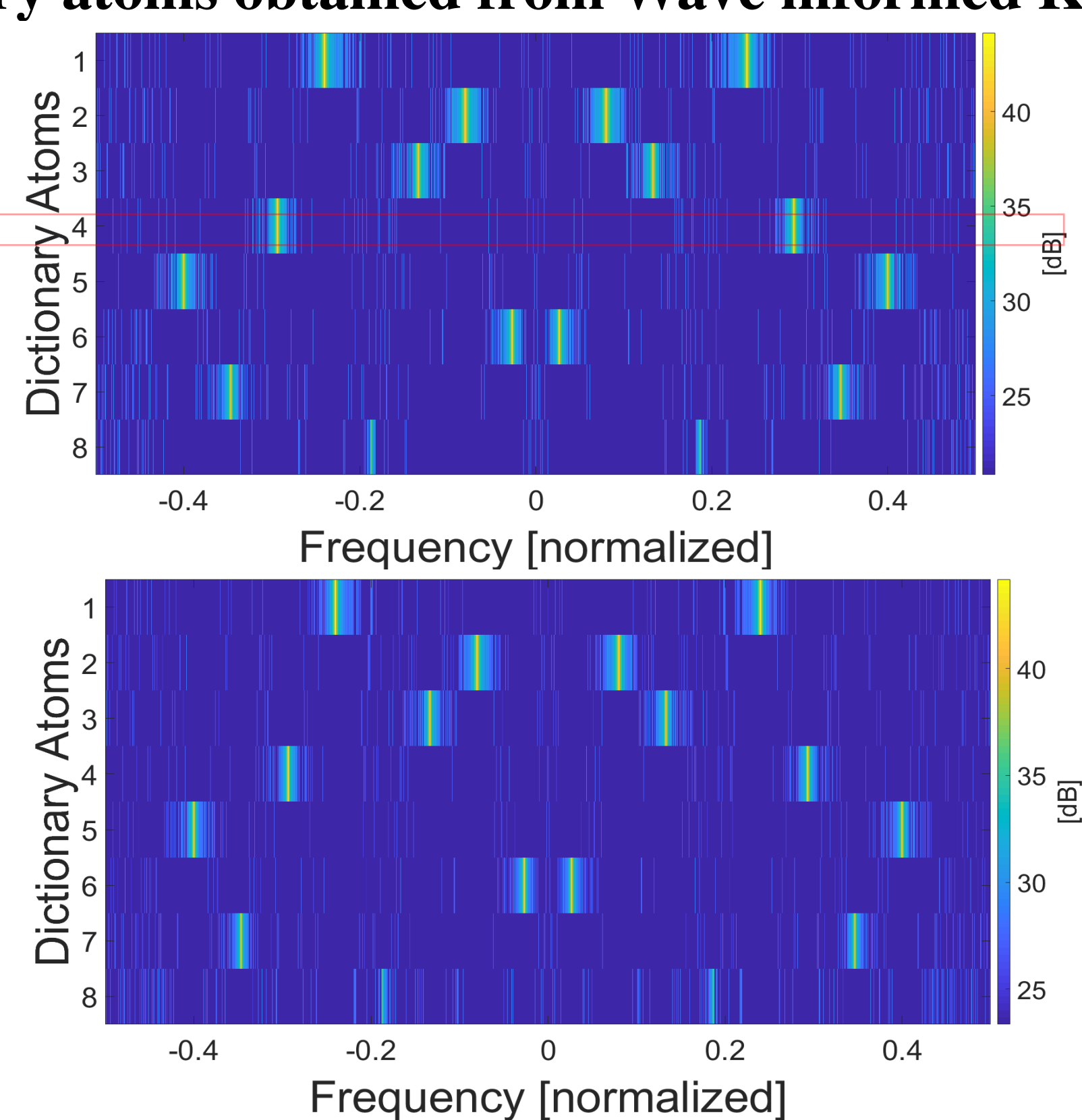
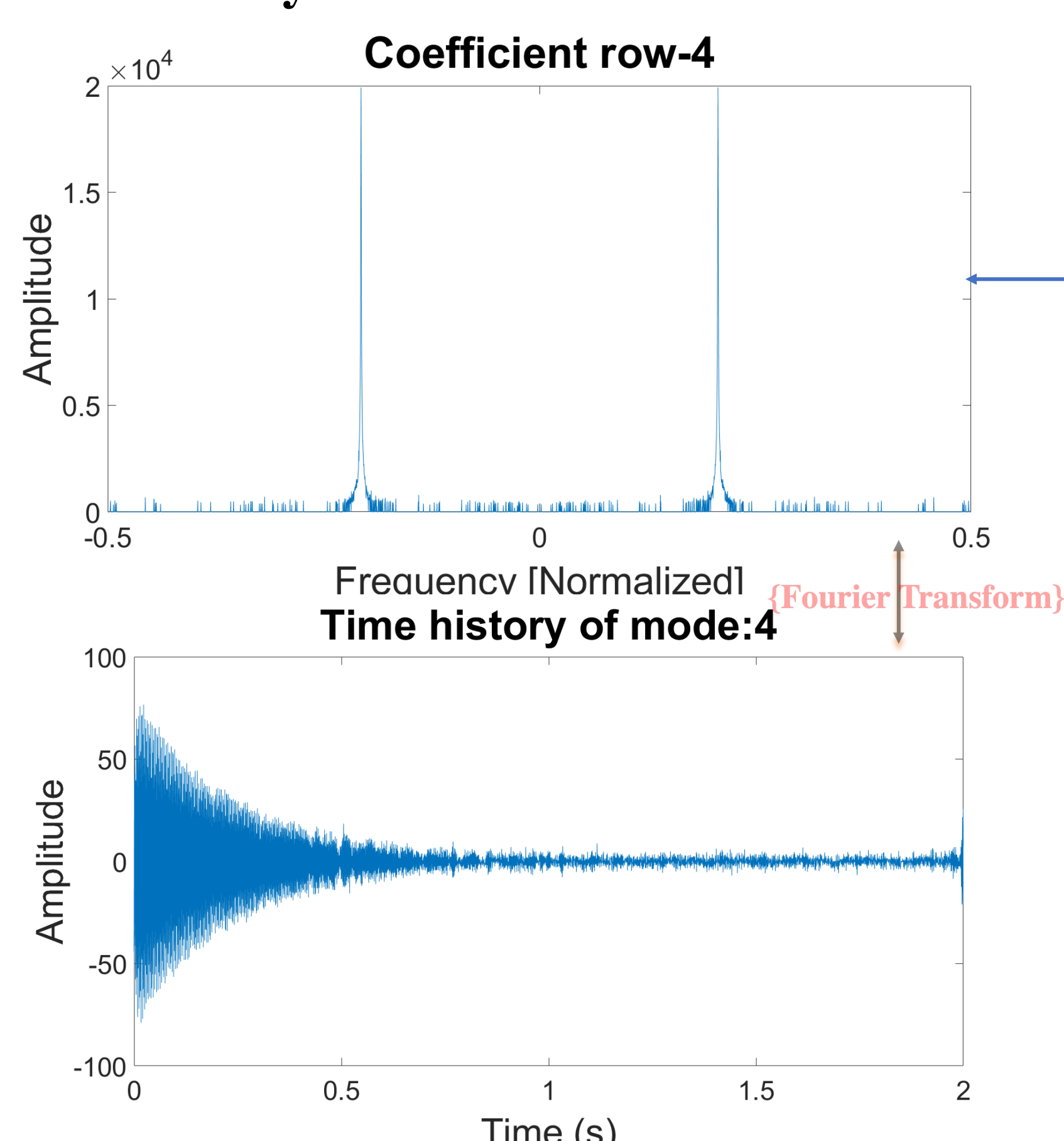
Dictionary atoms obtained from K-SVD



Data Reconstructed from Wave-Informed KSVD (in red) and the noisy data (in blue)



Dictionary atoms obtained from Wave informed K-SVD



The Coefficient Matrix from Wave-informed K-SVD (above) and K-SVD (below)

Conclusions

Observations and Future work

- Cleaner dictionary atoms from Wave-informed KSVD hints an enforcement of structure to the atoms.
- Future work will include modifying modern dictionary algorithms for wave data.
- Also, part of future work will include enforcing the wave constraint to sparse autoencoder

Acknowledgements

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