







Tensor-based Blind fMRI Source Separation Without the Gaussian Noise Assumption – A  $\beta$ -Divergence Approach

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#### Magnetic Resonance Imaging

- Exploits magnetic properties of tissues.
- Anatomy of the body structural.



#### Figure: MRI scanner representation [1]

[1]'MRI a guided tour", Available online: https://nationalmaglab.org/education/magnet-academy

# Signal Acquisition (Single Coil)





#### Noise Characteristics (Single Coil)



With *p* being a random voxel location,  $A = \sqrt{A_r^2 + A_i^2}$  and the standard deviation of real and imaginary part being the same and equal to  $\sigma$ .

# Signal Acquisition (Multiple Coil)



- Used in parallel imaging to increase the acquisition rate.
- Reconstruction process is needed, for combining the signals from each individual coil.
- Reconstruction algorithms do not use linear mappings.
- The assumption of a single value of σ to characterize the whole data set is no longer valid.

#### Functional Magnetic Resonance Imaging

- Measures Blood Oxygen Level Dependent (BOLD) signal.
- Activation of the neurons functional.
- BOLD fluctuation is modelled by the haemodynamic response function (HRF).

-Determination of brain connectivity -Localization of activated sources



#### Blind Source Separation (BSS) for fMRI



## BSS for fMRI

#### Matrix-based approach



#### **Tensor-based approach**



[2]C. Chatzichristos et al, "Blind fMRI Source Unmixing via Higher-Order Tensor Decompositions", J. Neuroscience Methods, Vol. 315, pp 17-47, Mar. 2019

#### Tensor BSS for fMRI

The multi-way nature of the data is preserved in multi-linear (tensor) models, which, in general:

- Produce unique (modulo scaling and permutation ambiguities) representations under mild conditions.
- Can improve the ability of extracting spatiotemporal modes of interest.
- Facilitate neurophysiologically meaningful interpretations

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Least-squares (LS) optimization problem:

$$\min_{\mathbf{A},\mathbf{B},\mathbf{C}} \frac{1}{2} \| \mathscr{T} - [\![\mathbf{A},\mathbf{B},\mathbf{C}]\!] \|_{\mathsf{F}}^2$$

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- Poisson process: Kullback–Leibler (KL) divergence
- Multiplicative Gamma noise: Itakura–Saito (IS) divergence

## $\beta$ -divergences

 β-divergences interpolate between LS distance, KL divergence and IS divergence [3]

$$d_{\beta}(x,y) = \begin{cases} \frac{x^{\beta} + (\beta - 1)y^{\beta} - \beta x y^{\beta - 1}}{\beta(\beta - 1)} & \beta \in \mathbb{R} \setminus \{0, 1\} \\ x \log \frac{x}{y} - x + y & \beta = 1 \text{ (KL)} \\ \frac{x}{y} - \log \frac{x}{y} - 1 & \beta = 0 \text{ (IS)} \end{cases}$$

[3]M. Vandecapelle et al, "Rank-one Tensor Approximation with  $\beta$ -divergence Cost Functions", EUSIPCO 2019

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- β-divergences interpolate between LS distance, KL divergence and IS divergence [3]
- If  $\beta = 2$ , we obtain the Euclidean distance
- For  $\beta > 2$ , errors on larger values are penalized more heavily than for the LS criterion; for  $\beta < 2$ , the converse is true



[3]M. Vandecapelle et al, "Rank-one Tensor Approximation with  $\beta$ -divergence Cost Functions", El

#### Simulations



Figure: Sources used in the simulations [4]

[4] V. Calhoun et al, "Independent component analysis of fMRI data in the complex domain", Magn. Reson. Med, vol. 48, no. 1, pp. 180–192, Jul. 2002

#### First simulation with same noise variance



#### First simulation with same noise variance



Figure: Source 9 with high overlap is included in the initial sources

#### Second simulation with different noise variance



Figure: Histograms of the observed values at one spatial point. a) Real and imaginary noise variances are equal; b) the noise variance of the imaginary part is five times that of the real part.

#### Second simulation with different variance



Figure: Second simulation with the 8 sources [4] and different noise variance in the real and imaginary parts of the sources.

#### Conclusions

- First time that the Gaussian noise assumption and its influence on the fMRI BSS performance are tested in a tensorial framework.
- $\beta = 1$  (KL divergence) performs best in cases where different noise variances affect the real and imaginary data components.
- $\beta = 2.5$  gives the best separation results in all other cases.

#### Future work

- Application in real data
- Use of regularizers that force independence or sparsity in the spatial maps will be investigated



# Thank you Questions ??

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