

COUNTING DENSE OBJECTS IN REMOTE SENSING IMAGES

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Method

Main challenge

- Dataset scarcity;
- Scale variation;
- Complex cluttered background;
- Orientation arbitrariness

Contribution

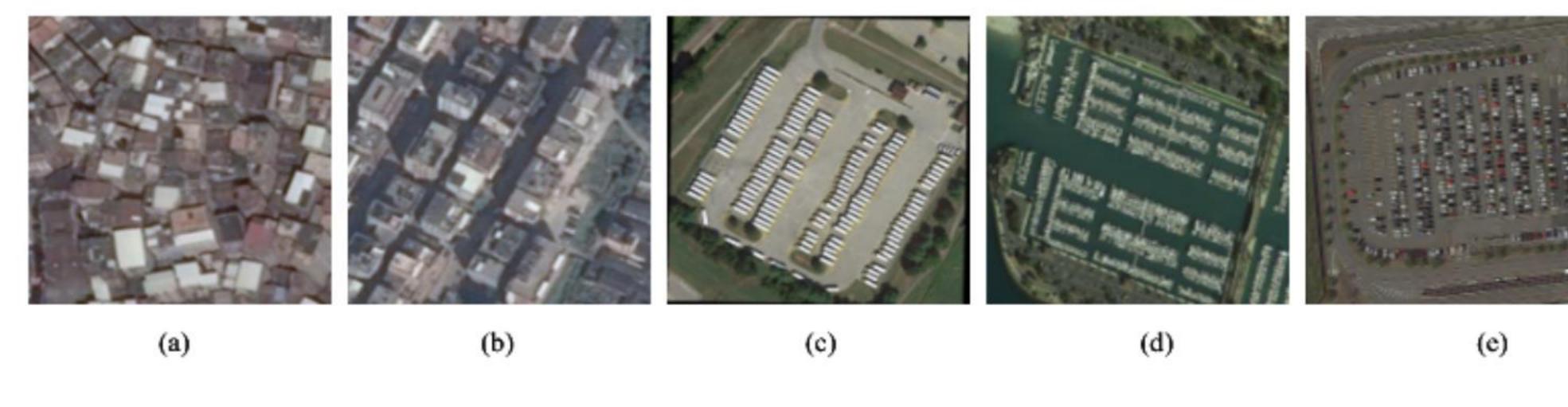


Fig. 1: Representative images of RSOC dataset. (a)-(e) represent the images of building_A, building_B, large-vehicle, ship and small-vehicle, respectively.

Table 1: There are four different kinds of objects in the dataset: building, ship, large vehicle and small vehicle. We split the dataset into five subsets according to the density levels of the objects. Building_A has larger density level than Building_B. It also worth noting that for data annotation, building subsets are labeled with center point, and other three ones adopt bounding box, preprocessing to compute their center points when generating their ground truth density maps.

| Dataset | Images | Training/Test | Average Resolution | Statistics | | | | |
|---------------|--------|---------------|--------------------|------------|-----|---------|------|--|
| | | | Average Resolution | Total | Min | Average | Max | |
| Building_A | 360 | 179/181 | 512×512 | 19,963 | 34 | 55.45 | 142 | |
| Building_B | 2108 | 1026/1082 | 512×512 | 56,252 | 15 | 26.69 | 76 | |
| Ship | 137 | 97/40 | 2558×2668 | 44,892 | 50 | 327.68 | 1661 | |
| Large-vehicle | 172 | 108/64 | 1552×1573 | 16,594 | 12 | 96.48 | 1336 | |
| Small-vehicle | 280 | 222/58 | 2473×2339 | 148,838 | 17 | 531.56 | 8531 | |

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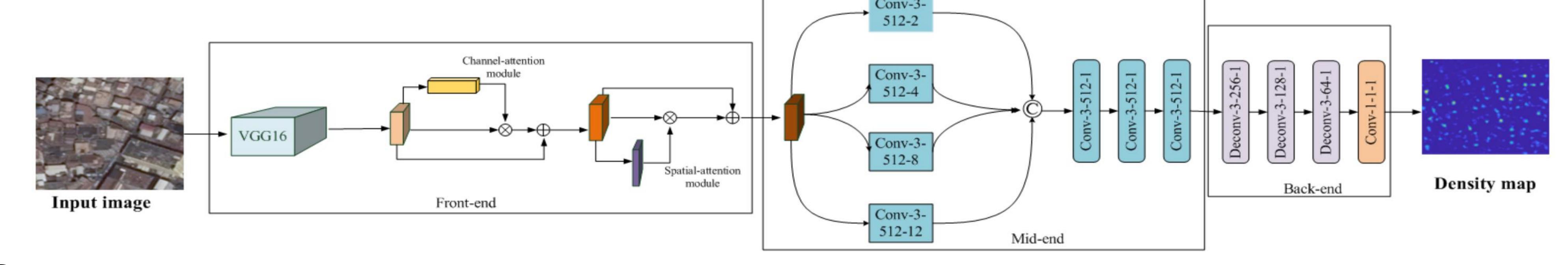


Fig. 2: Architecture of ASPDNet. The parameters of convolutional layers in the mid-end stage are denoted as "Conv-(kernel size)-(number of filters)-(dilation rate)", while the parameters in the back-end stage are represented as "Deconv-(kernel size)-(number of filters)-(stride)". The max-pooling layers are conducted over a 2×2 pixel window, with stride 2 (ignored in the figure). " \oplus ", " \otimes " and " \odot " represent matrix addition, matrix multiplication and matrix concatenation operation, respectively.

$L(\Theta) = \frac{1}{2N} \sum_{i=1}^{N} \|F(X_i; \Theta) - F_i^{GT}\|_2^2$

Results

Table 2: Performance comparison on Building_A and Building_B dataset.

| Method | Build | ling_A | Building_B | | |
|-----------------------|-------|--------|------------|-------|--|
| | MAE | RMSE | MAE | RMSE | |
| MCNN [1] | 14.33 | 19.47 | 13.11 | 16.60 | |
| CMTL [3] | 15.04 | 20.77 | 10.24 | 13.64 | |
| CSRNet [2] | 13.32 | 18.00 | 7.37 | 10.32 | |
| SFCN [4] | 13.14 | 17.56 | 6.31 | 8.33 | |
| ASPDNet(our proposed) | 10.21 | 14.27 | 5.31 | 7.02 | |

Table 4: Ablation studies on Building_A and Building_B dataset.

| Method | Build | ling_A | Building_B | | |
|-------------------|-------|--------|------------|-------|--|
| | MAE | RMSE | MAE | RMSE | |
| Baseline | 13.32 | 18.00 | 7.37 | 10.32 | |
| Baseline+CBAM | 12.95 | 17.51 | 7.71 | 9.90 | |
| Baseline+CBAM+SPM | 12.28 | 16.52 | 5.67 | 7.28 | |
| ASPDNet | 10.21 | 14.27 | 5.31 | 7.02 | |

Table 3: Performance comparison on Ship-, Large-vehicle and Small-vehicle sub datasets.

| Method | Ship | | Large-vehicle | | Small-vehicle | |
|-----------------------|--------|--------|---------------|-------|---------------|---------|
| | MAE | RMSE | MAE | RMSE | MAE | RMSE |
| MCNN [1] | 263.91 | 412.30 | 36.56 | 55.55 | 488.65 | 1317.44 |
| CMTL [3] | 251.17 | 403.07 | 61.02 | 78.25 | 490.53 | 1321.11 |
| CSRNet [2] | 240.01 | 394.16 | 34.10 | 46.42 | 443.72 | 1252.22 |
| SFCN [4] | 240.16 | 394.81 | 33.93 | 49.74 | 440.70 | 1248.27 |
| ASPDNet(our proposed) | 193.83 | 318.95 | 31.76 | 40.14 | 433.23 | 1238.61 |

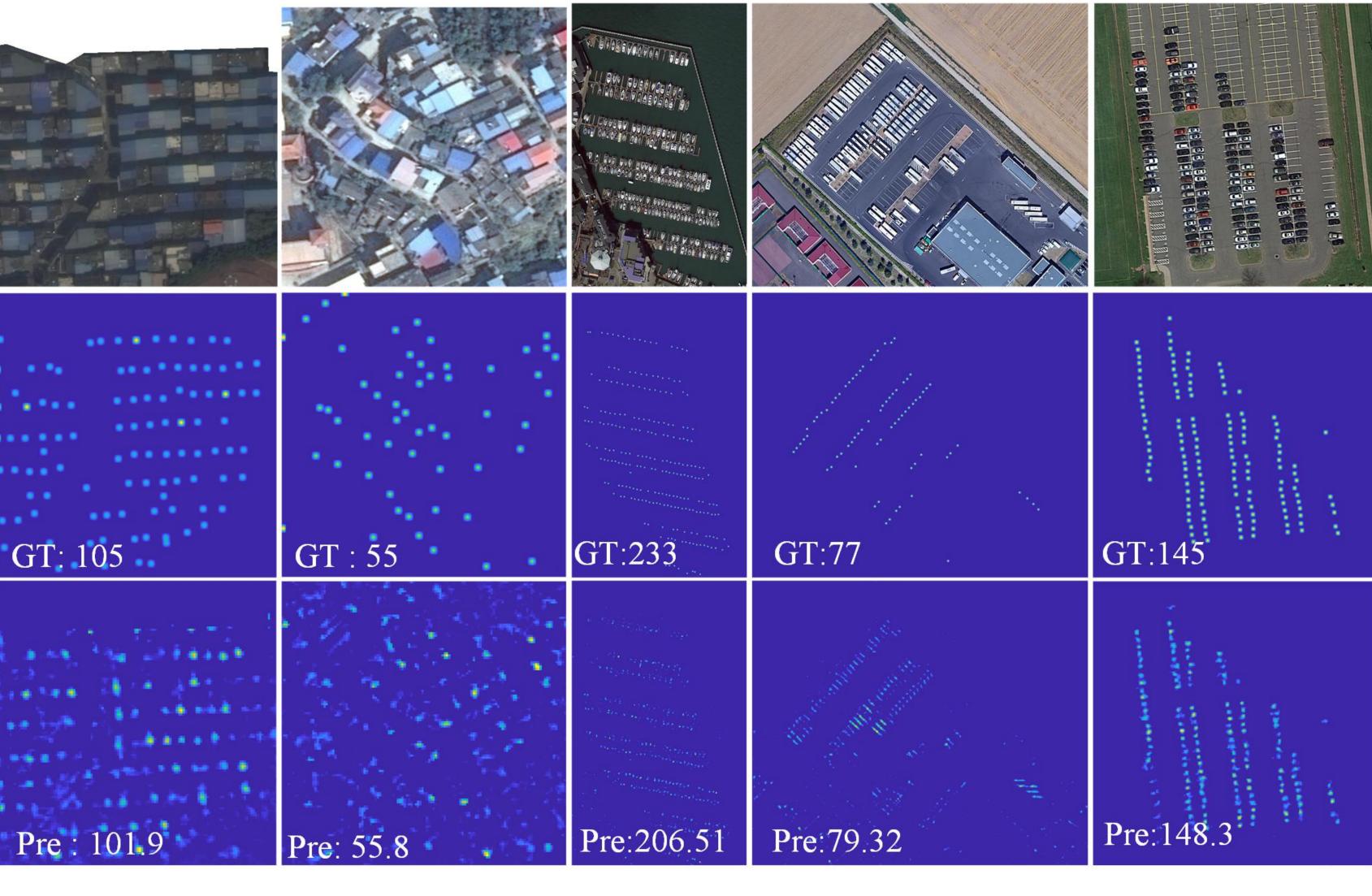


Fig. 3: Example Results on the RSOC dataset with the proposed method.