

Functional Epsilon Entropy

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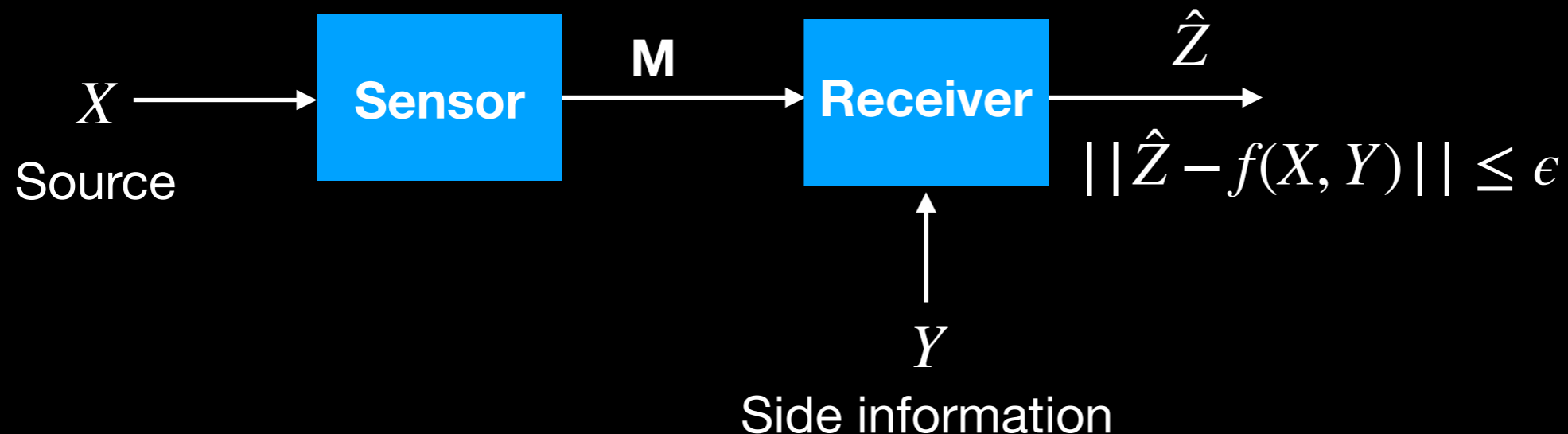
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Motivation

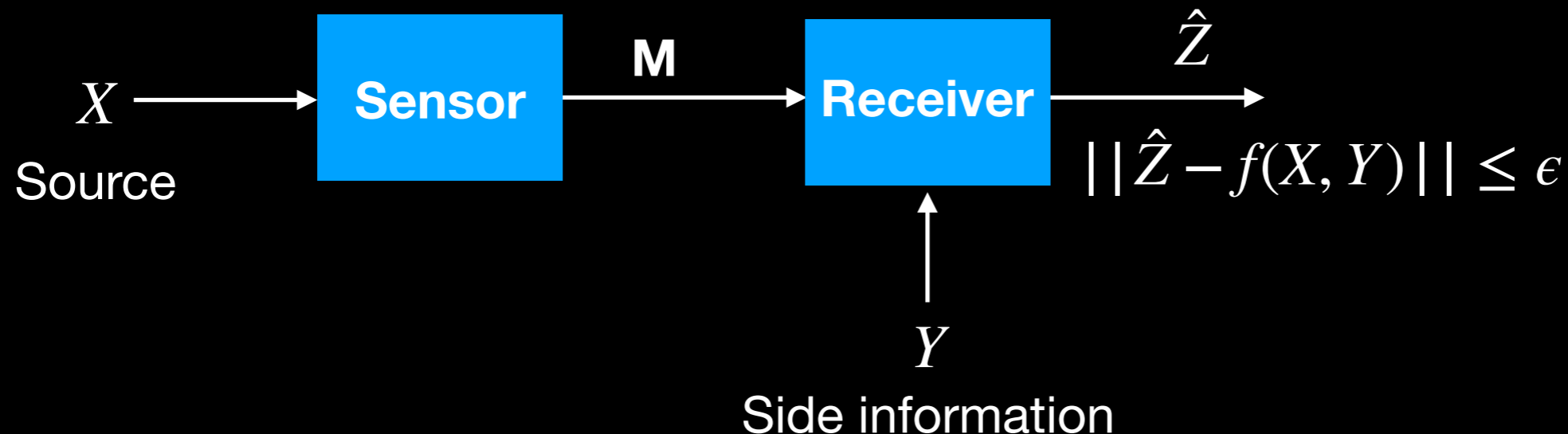
- Lossy functional source coding



- Sensor observes X
- Receiver observes Y
- Both agents want the receiver to compute $f(X, Y)$ as \hat{Z} such that $\|\hat{Z} - f(X, Y)\| \leq \epsilon$

Motivation

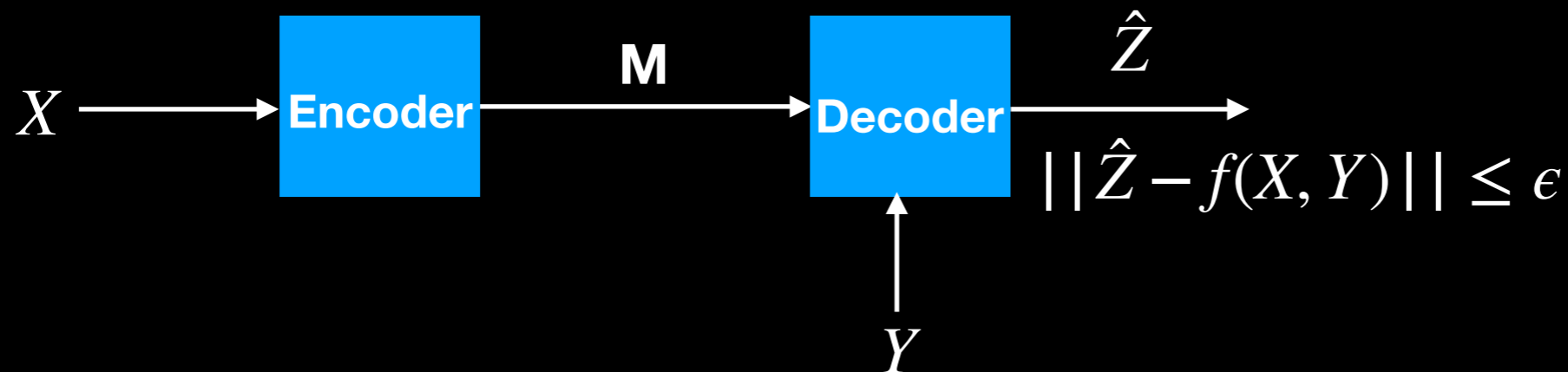
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Applications:

- Sensor networks: The receiver only needs to compute some function of the received data
- Big data and bioinformatics: Often only a known function of data is of interest and the observed data is not of primary importance. Observed data is often huge

Previous work: optimal codes



Yamamoto's solution [1]

$$R_{min} = \min_{\substack{U-X-Y \\ p \in \mathcal{P}(0)}} I(U; X | Y),$$

where $\mathcal{P}(0)$ is the set of all $p(u | x)$,

such that there exists a

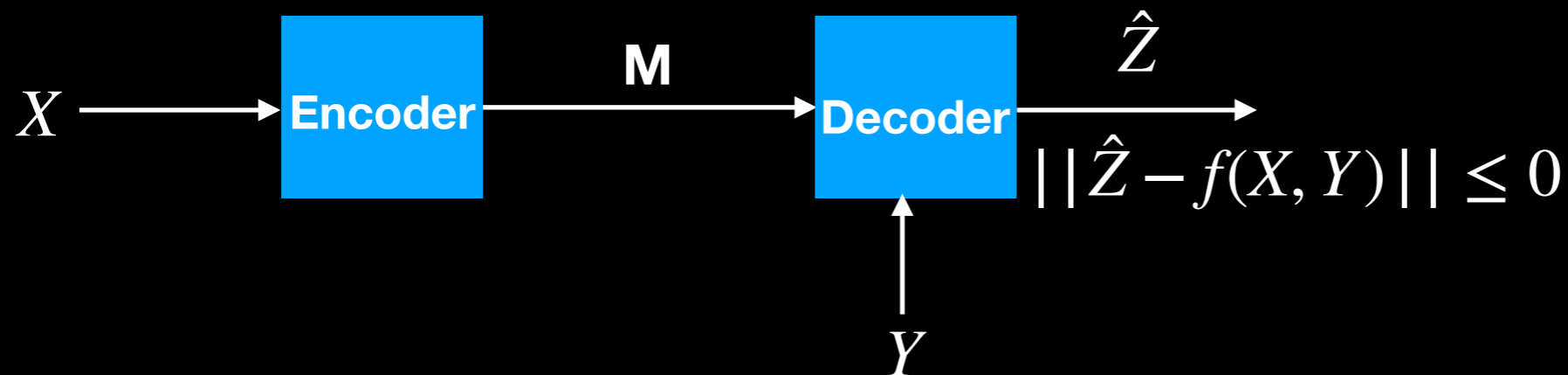
$g : \mathcal{U} \times \mathcal{Y} \mapsto \mathcal{Z}$ satisfying

$$E[1_{\|f(X,Y)-g(U,Y)\|>D}] \leq 0.$$

Salient features

- Optimal rates for *both lossless and lossy functional source coding*
- Depends on the existence of g and W which makes it *difficult to design practical codes* that achieve this rate

Previous work: lossless compression



Lossless case [2]

$$R_{min} = \min_{W-X-Y} I(W; X | Y)$$

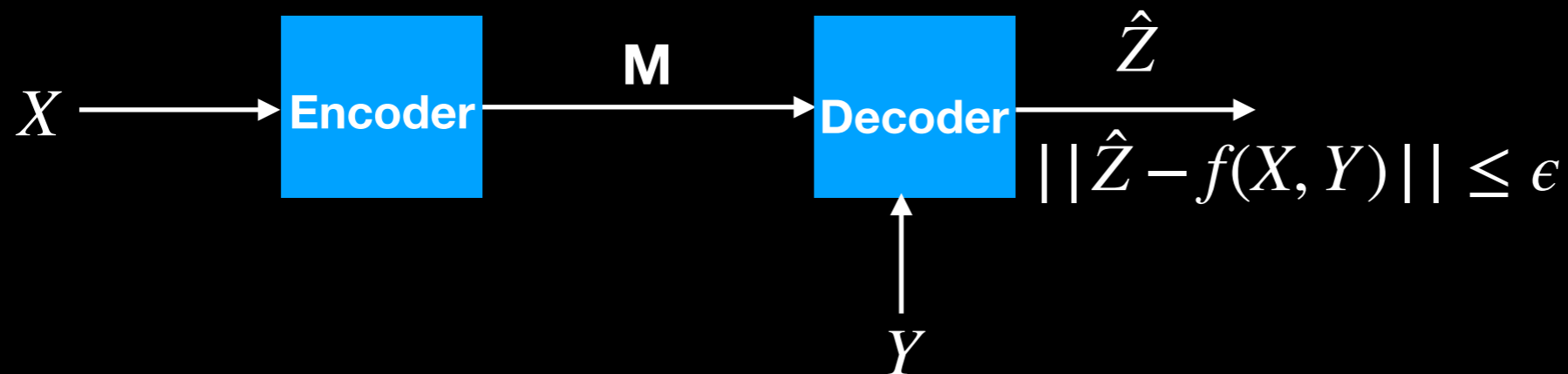
$X \in W \in \Gamma(G)$

where $\Gamma(G)$ is the set of all hyperedges of a **characteristic hypergraph** which can be constructed based on f , X , Y as a part of coding scheme [2].

Salient features

- Optimal codes
- Practical codes which can be implemented
- Works *only for lossless functional compression*

Previous work: maximal distortion



Efficient lossy codes [3]

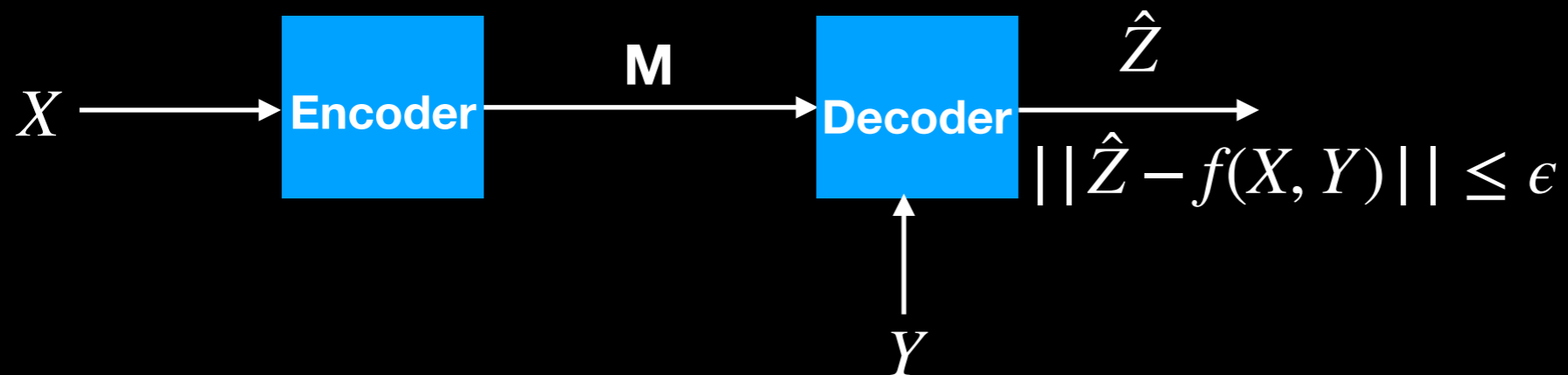
$$R_{min} \leq \min_{\substack{W - X - Y \\ X \in W \in \Gamma(G_D)}} I(W; X | Y)$$

where $\Gamma(G_D)$ is the set of all hyperedges of a ***D-characteristic hypergraph*** which can be constructed based on f , X , Y as a part of coding scheme [1].

Salient features

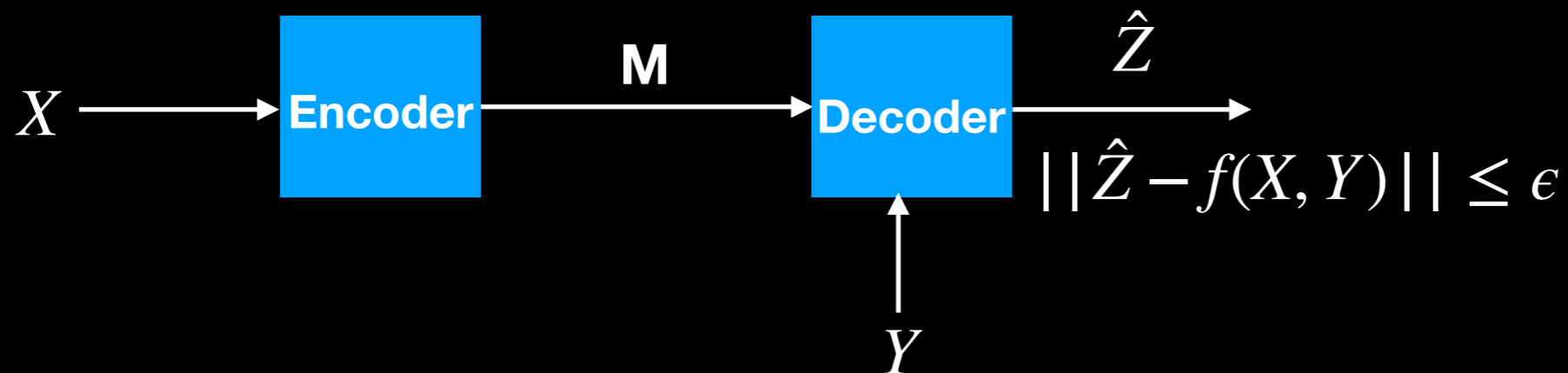
- Efficient *practical codes*
- Works for *lossy* functional compression under *maximal distortion*
- However, these codes are *suboptimal*

Unresolved/open problem



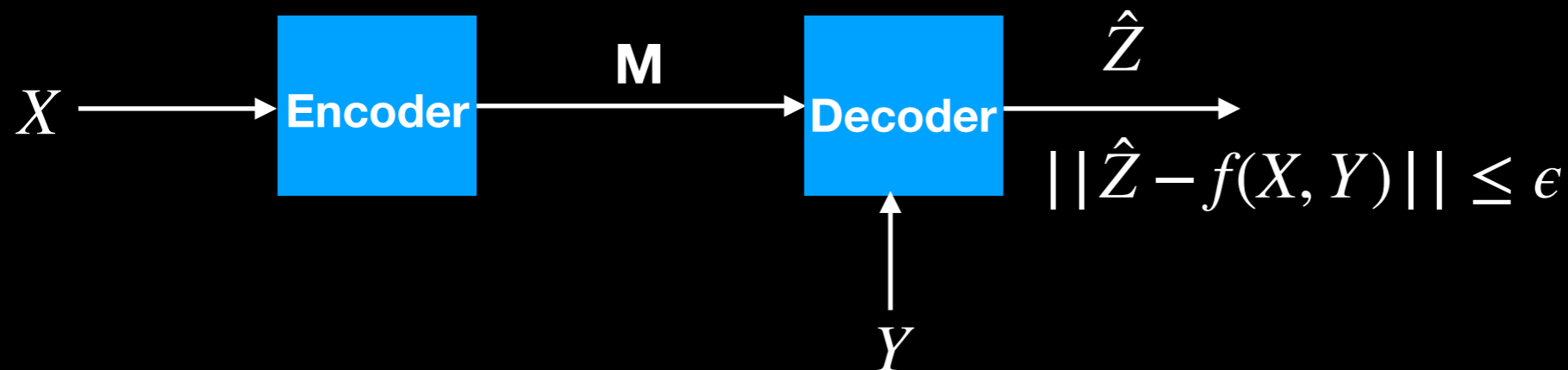
- **No optimal practical code known for lossy functional source coding**

Our contribution: optimal practical codes



- We close the gap between optimal codes and known practical codes for maximal distortion

Our contribution: optimal practical codes



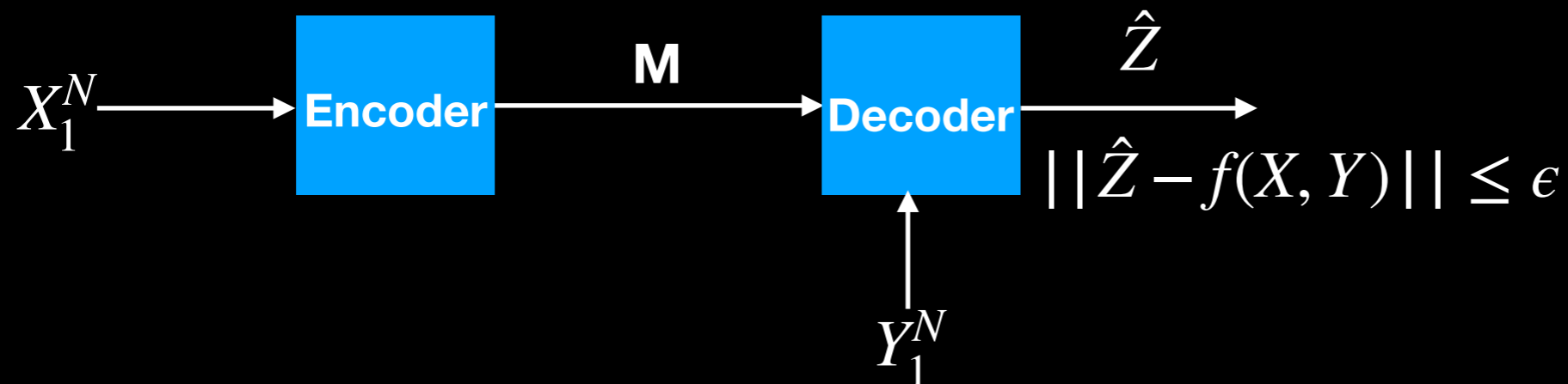
Optimal practical lossy codes

$R_{min} = H_{G_\epsilon}(X|Y),$
where $H_{G_\epsilon}(X|Y)$ is the **functional epsilon entropy**, defined later

Salient features

- **Practical** codes
- **Optimal** for **lossy** functional compression under **maximal distortion**
- Based on **better geometric construction** of hypergraphs compared to [3].

Problem setting



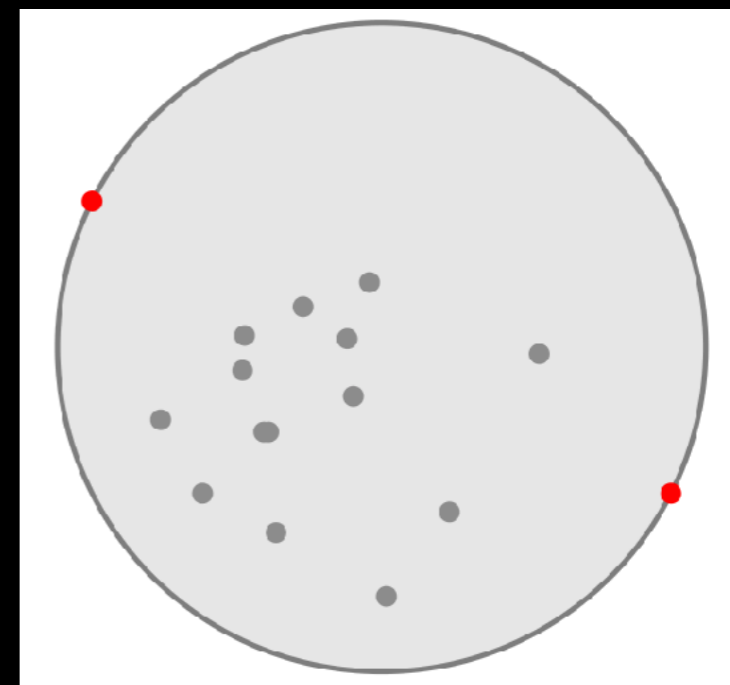
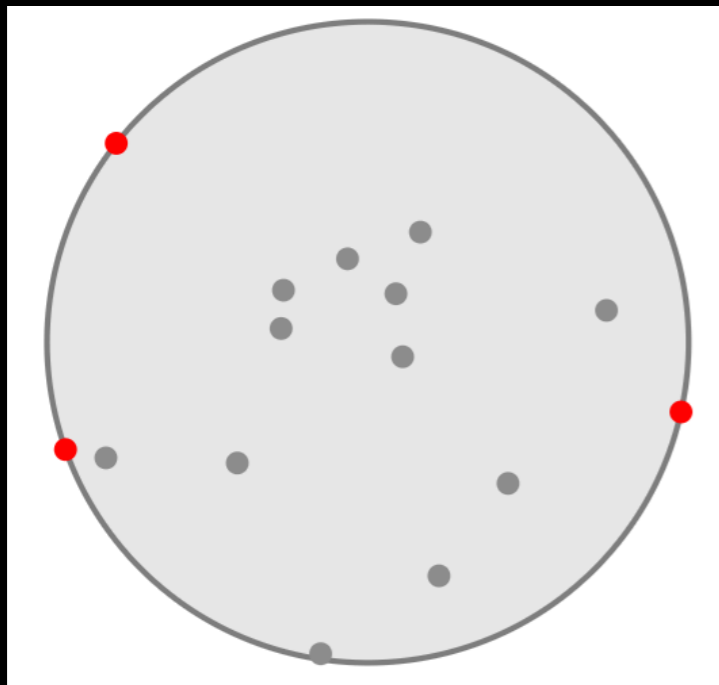
- (X, Y) are distributed as $P_{X,Y}$
- (X_1^N, Y_1^N) are N iid random variables, where $X_i \in \mathcal{X}, Y_i \in \mathcal{Y}$ for $i \in \{1, \dots, N\}$, and \mathcal{X}, \mathcal{Y} are finite sets.
- Reconstruct $f(X, Y)_1^N$ as \hat{Z}_1^N such that $P_{avg}(X, Y, \hat{Z}) \rightarrow 0$ as $N \rightarrow \infty$, where

$$P_{\epsilon}^{avg}(\hat{Z}^N, X^N, Y^N) = \frac{1}{N} \sum_{i=1}^N \Pr \left[||\hat{Z}_i - f(X_i, Y_i)|| > \epsilon \right]$$

Smallest enclosing circles

Smallest enclosing circles:

- For a set of point S , the circle with smallest radius covering all the points in S is called the smallest enclosing circle of S



Epsilon characteristic hypergraphs

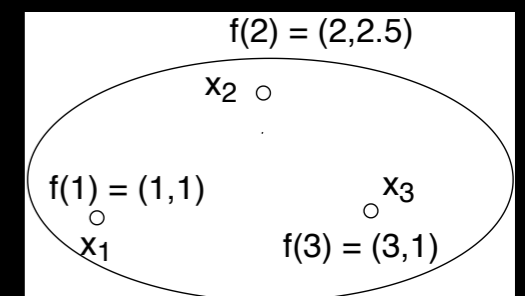
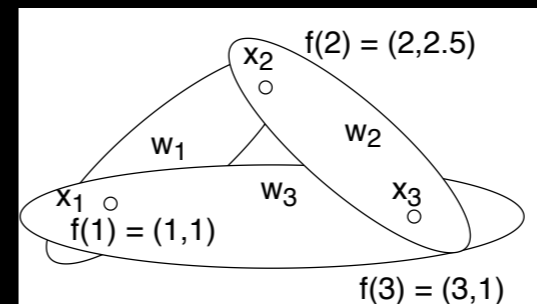
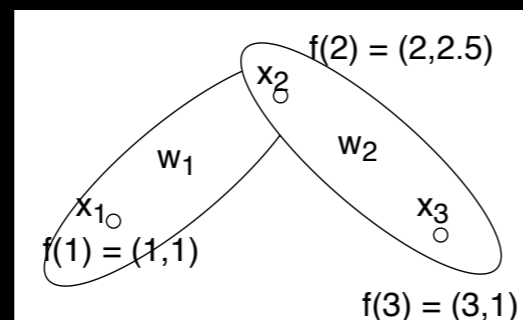
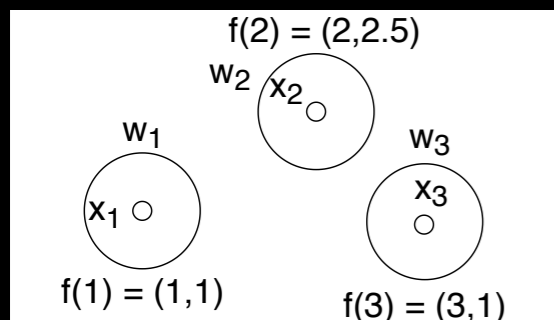
ϵ -characteristic hypergraph:

- Denoted by G_ϵ when the function f , and random variables X, Y are clear from context
- Vertex set of G_ϵ is \mathcal{X}
- Let $S \subseteq \mathcal{X}$ and $y \in \mathcal{Y}$, let $S_y = \{x : x \in S \text{ and } p(x, y) > 0\}$
- S is a hyperedge in G_ϵ if and only if the radius of the smallest enclosing circle containing the set of points $\{f(x, y) : x \in S_y\}$ is less than or equal to ϵ for all $y \in \mathcal{Y}$

Epsilon characteristic hypergraphs

Example:

- Let $f : \mathcal{X} \mapsto \mathcal{Z}$ be defined as $f(1) = (1,1)$, $f(2) = (2,2.5)$, $f(3) = (3,1)$, where $\mathcal{X} = \{1,2,3\}$ and X is uniformly distributed
- No side information Y in this example



$$0 \leq \epsilon < \frac{\sqrt{13}}{4}$$

$$\frac{\sqrt{13}}{4} \leq \epsilon < 1$$

$$1 \leq \epsilon < \frac{13}{12}$$

$$\frac{13}{12} \leq \epsilon$$

Functional epsilon entropy

Functional ϵ -entropy:

- Denoted by $H_{G_\epsilon}(X|Y)$

$$H_{G_\epsilon}(X|Y) = \min_{\substack{W-X-Y \\ X \in W \in \Gamma(G_\epsilon)}} I(W; X|Y),$$

where X induces a probability distribution over the vertices of the hypergraph G_ϵ . The random variable W is obtained by defining transition probabilities $p(w|x)$ over all hyperedges w that contain x , i.e. $p(w|x) \geq 0$ for all $x \in w \in \Gamma(G_\epsilon)$ and $\sum_{w \ni x} p(w|x) = 1$.

Main result: theorem

Theorem:

$$R_{min} = H_{G_\epsilon}(X|Y),$$

where R_{min} is obtained from Yamamoto's codes under maximal distortion

Yamamoto's solution [1]

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Main result: outline of the proof

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- **Proof:** $R_{min} \leq H_{G_\epsilon}(X|Y)$ is trivial since Yamamoto's codes are optimal. We need to show that $R_{min} \geq H_{G_\epsilon}(X|Y)$.
- Idea: For every U, g satisfying conditions in R_{min} , we need to find corresponding W that satisfy conditions in $H_{G_\epsilon}(X|Y)$.

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- Define $\hat{w}(u) = \{x : p(u, x) > 0\}$.

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- Rest of the proof is showing that the above definitions of W satisfy the required conditions.

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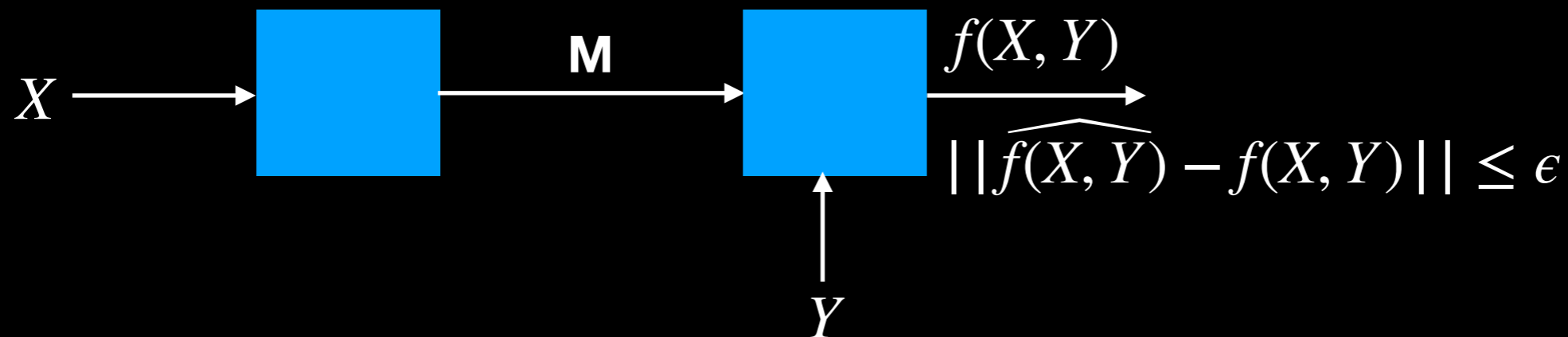
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- Rest of the proof is showing that the above definitions of W satisfy the required conditions.
- In particular, **smallest enclosing circles** play crucial role in the proof.

Main result: key insight



- Our coding scheme uses **better geometric methods** for constructing hypergraphs.
- In particular, [3] used **point-to-point comparison** for constructing hypergraphs.
- We use **smallest enclosing circles** to form hypergraphs, which we prove is **optimal**.

Consequences: constructing optimal practical codes in $O(N \log N)$ time

Optimal code construction:

$R_{min} = H_{G_\epsilon}(X|Y)$ implies optimal code construction reduces to:

- **Step 1:** Construct G_ϵ
- **Step 2:** Use polar coding technique

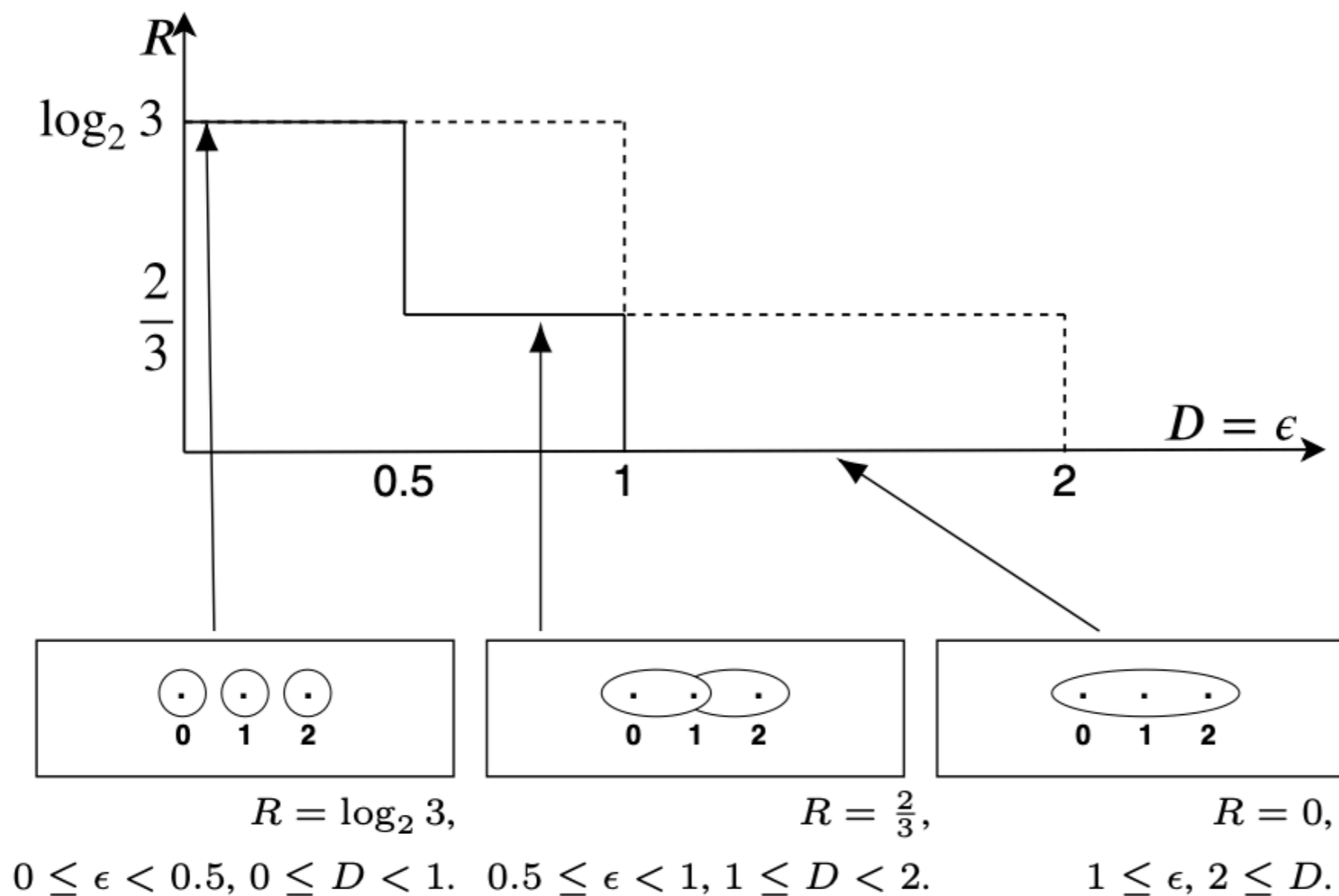
Time complexity:

Time complexity of the coding scheme = $O(N \log N)$ because:

- G_ϵ construction takes finite time
- Polar coding takes $O(N \log N)$ time

Consequences: Improvement in practical rate

Example: Consider the point to point source coding problem with no side information, X uniformly distributed over $\{0,1,2\}$ and take the function f as the identity function.

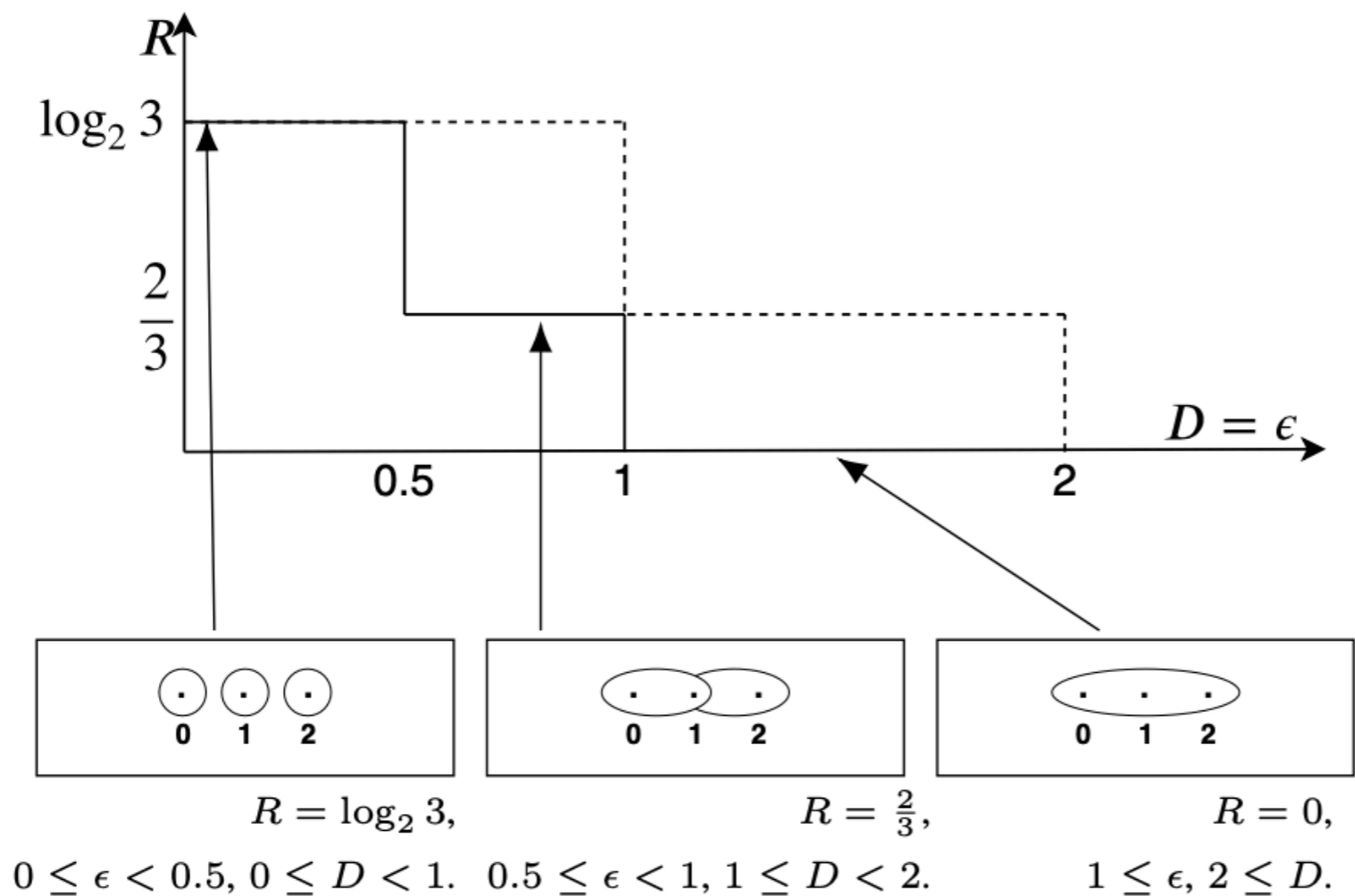


- **Solid line: our rate**
- **Dashed line: existing practical codes**

Other important findings

Discontinuity of functional ϵ -entropy

- Discontinuity of $H_{G_\epsilon}(X|Y)$ as a function of ϵ
- Fits our intuition of maximal distortion, but previously unknown

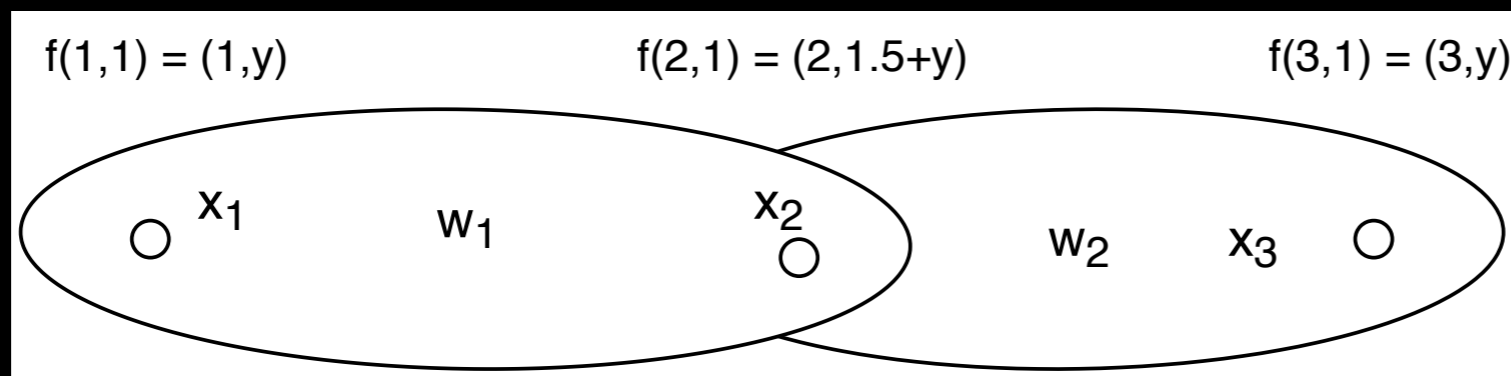


Other important findings

Overlapping hyperedges in G_ϵ

- In [2] where $\epsilon = 0$, $p(x, y) > 0$ implied non-overlapping hyperedges
- Using counterexample, we show that for $\epsilon > 0$, G_ϵ can have overlapping hyperedges

Example: Let X and Y be independent uniform random variables defined on the support set $\mathcal{X} = \{1, 2, 3\}$ and $\mathcal{Y} = \{1, 2\}$ respectively. Let $f : \mathcal{X} \times \mathcal{Y} \rightarrow \mathcal{Z}$, where $\mathcal{Z} \subset \mathbb{R}^2$, and f be defined as $f(1, y) = (1, y)$, $f(2, y) = (2, 1.5 + y)$, $f(3, y) = (3, y)$, and let $\epsilon = \frac{\sqrt{13}}{4}$. Then the characteristic hypergraph G_ϵ has overlapping hyperedges.



Other important findings

When f is unknown

- When f is a well-behaved function (e.g. L -Lipschitz continuous), we provide efficient coding schemes even when f is unknown

Corollary:

Let $f : \mathcal{X} \mapsto \mathcal{Z}$ be a L -Lipschitz continuous function. Then $R(\epsilon)$ can be upper-bounded as

$$R(\epsilon) \leq H_{G_{\epsilon/L}}(X),$$

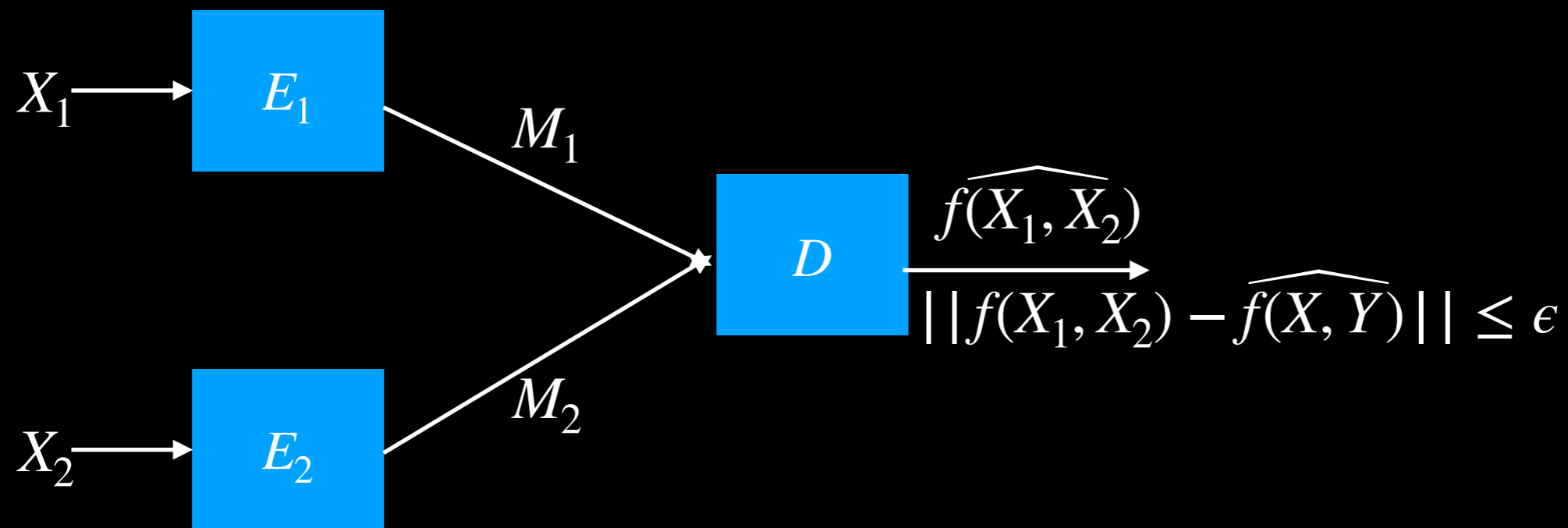
where $G_{\epsilon/L}$ is constructed with respect to the random variable X and the identity function and hence the upper-bound is achievable by the encoder even when f is unknown.

Summary

- **First optimal practical codes** for lossy functional source coding
- We **close the gap in rates** between practical and optimal codes under **maximal distortion**.
- We introduce **better geometrical methods** in our coding schemes improving on existing techniques
- **Rate region is discontinuous** as a function of fidelity parameter
- **Counterintuitive overlapping hyperedges** even for all positive probabilities
- Efficient coding schemes for **unknown but well-behaved functions**

Future work

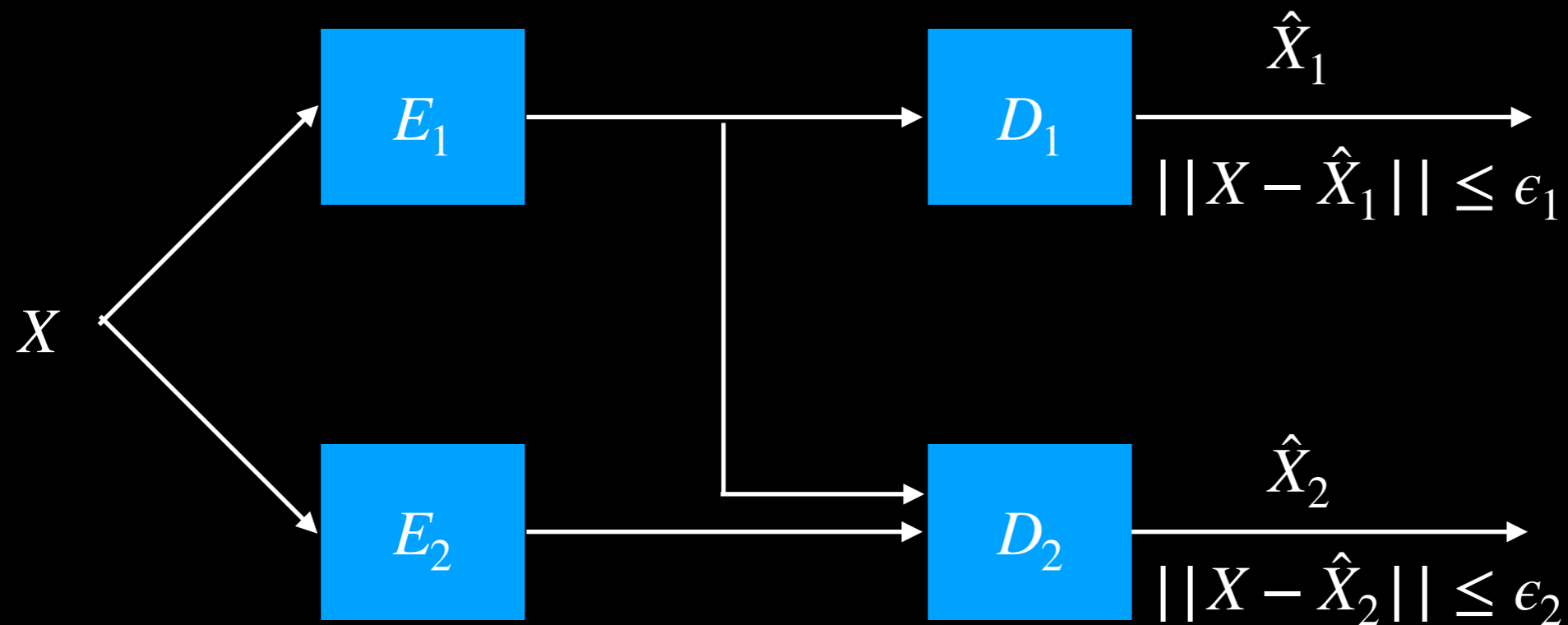
- Using similar geometric techniques progress are being made on **practical codes for distributed source coding** and **successive refinement problem**



Distributed source coding

Future work

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Successive refinement coding