



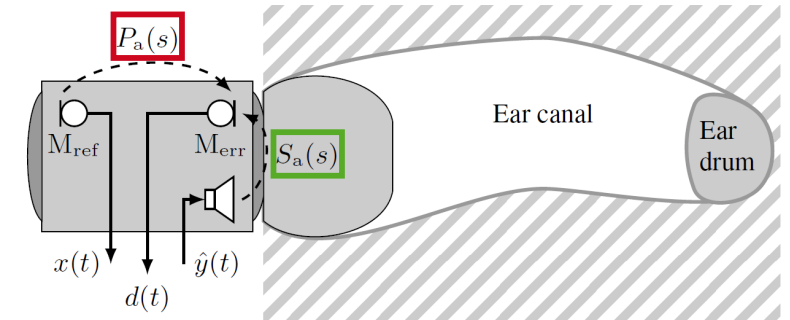
Primary Path Estimator based on Individual Secondary Path for ANC Headphones

Johannes Fabry, Peter Jax

ICASSP 2020

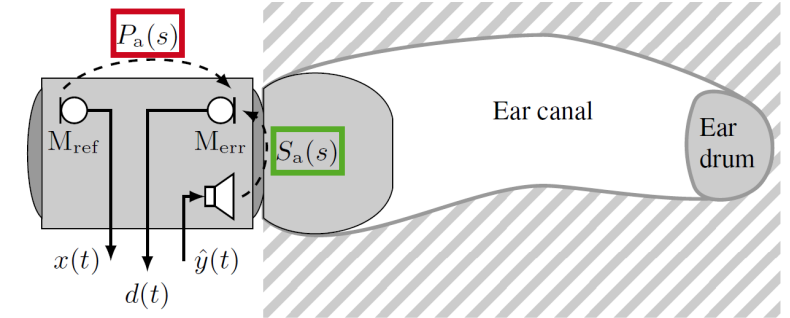
Use Case

- ANC headphones come with one-fits-all filter design
- ANC performance varies with individual ear physiology and fitting
- Add calibration step and individualize ANC filter
 - Measurement of secondary path $S_a(s)$ feasible by using inner loudspeaker
 - Measurement of primary path $P_a(s)$ not feasible and requires dedicated setup



Use Case

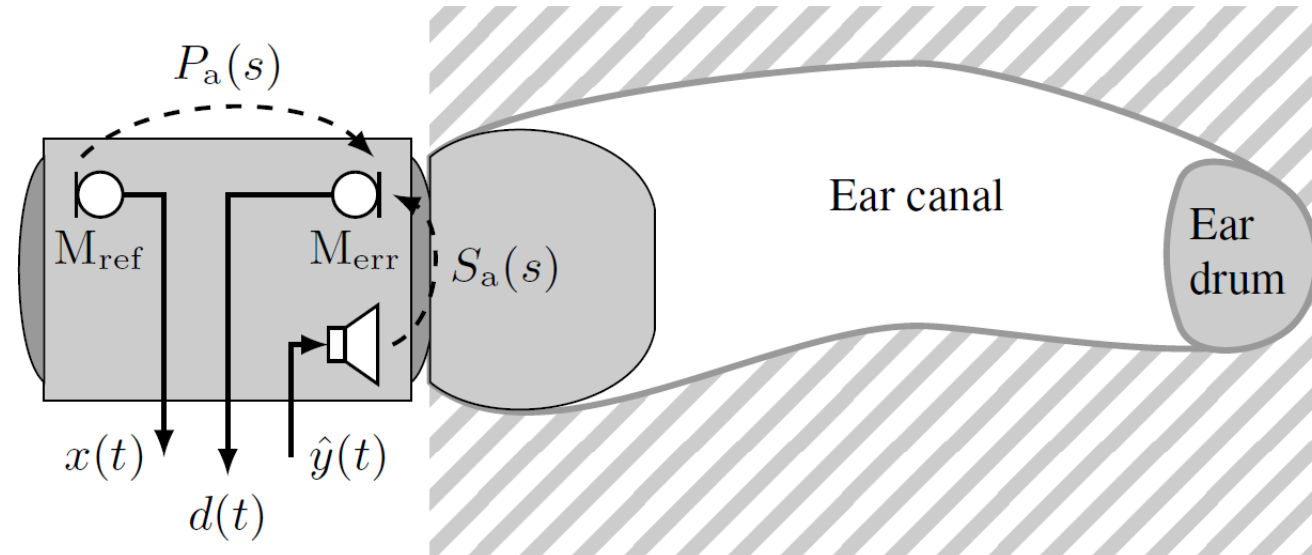
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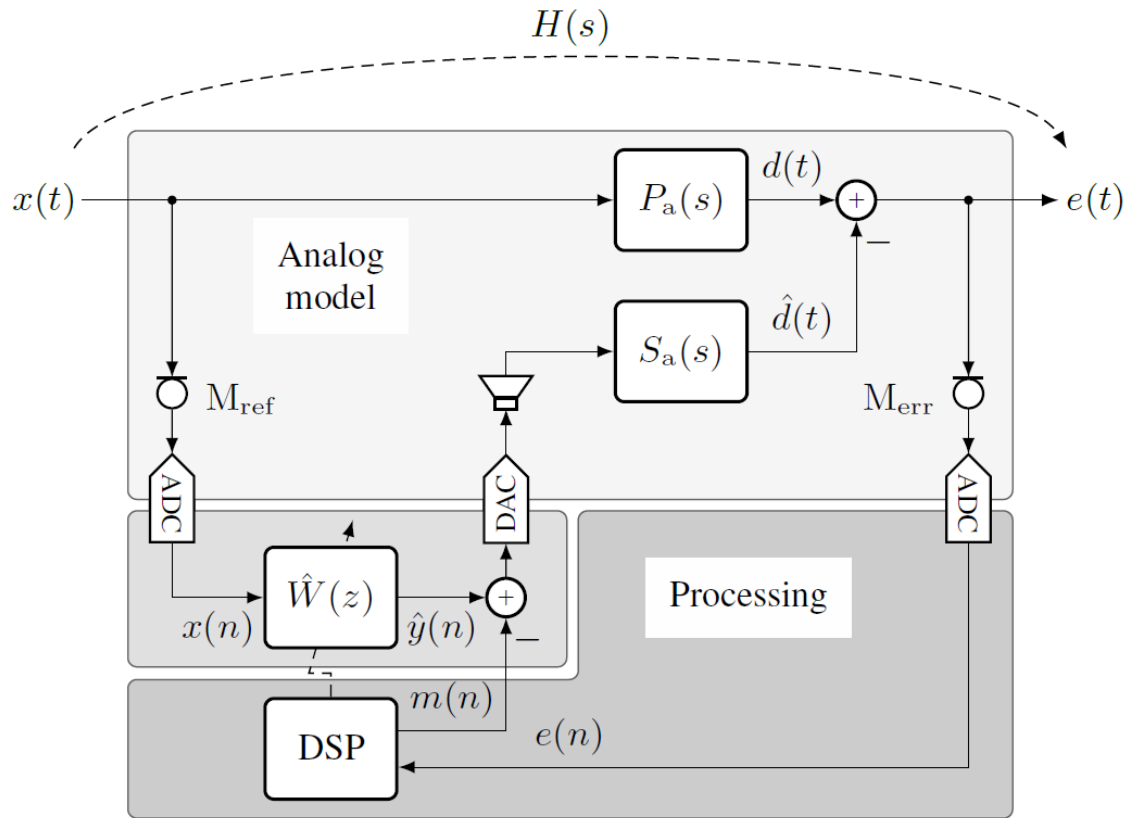
Use coherence of primary and secondary path to estimate primary path based on secondary path

→ Increase robustness of ANC with respect to individual fitting of headphone

Headphone Model



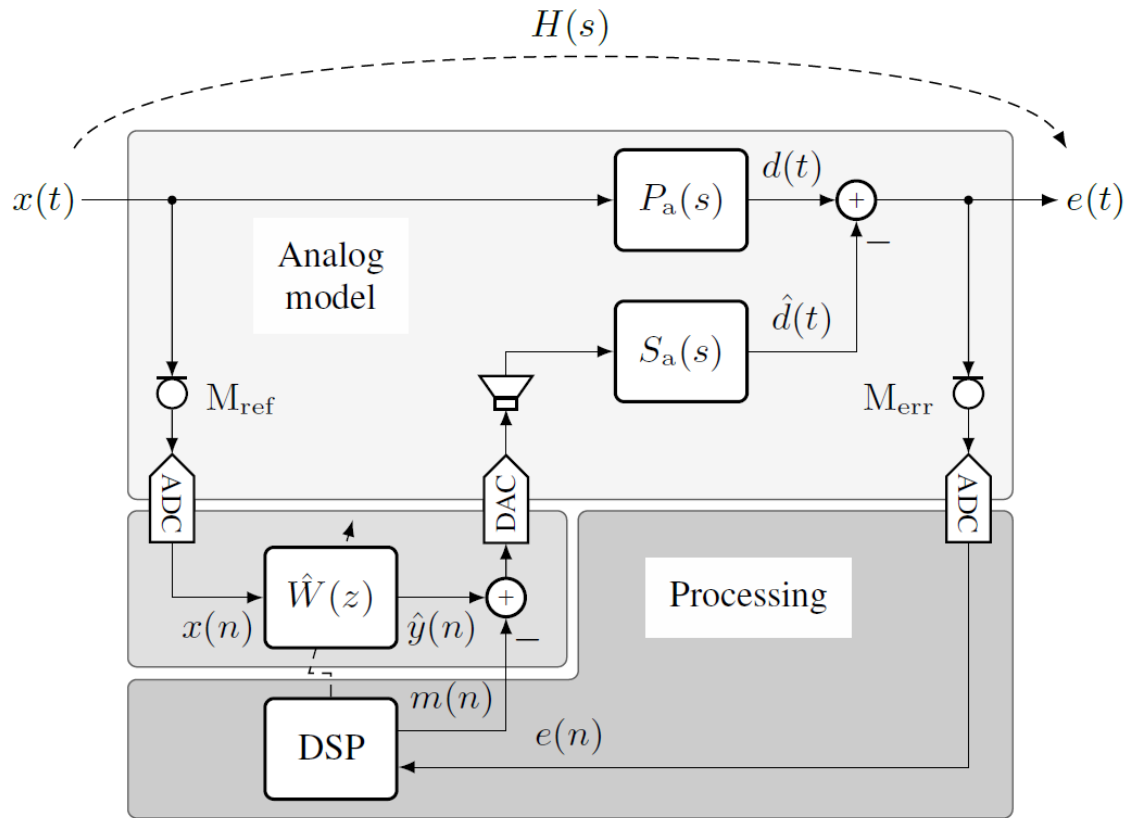
Feed-forward ANC Block Diagram



Introduction

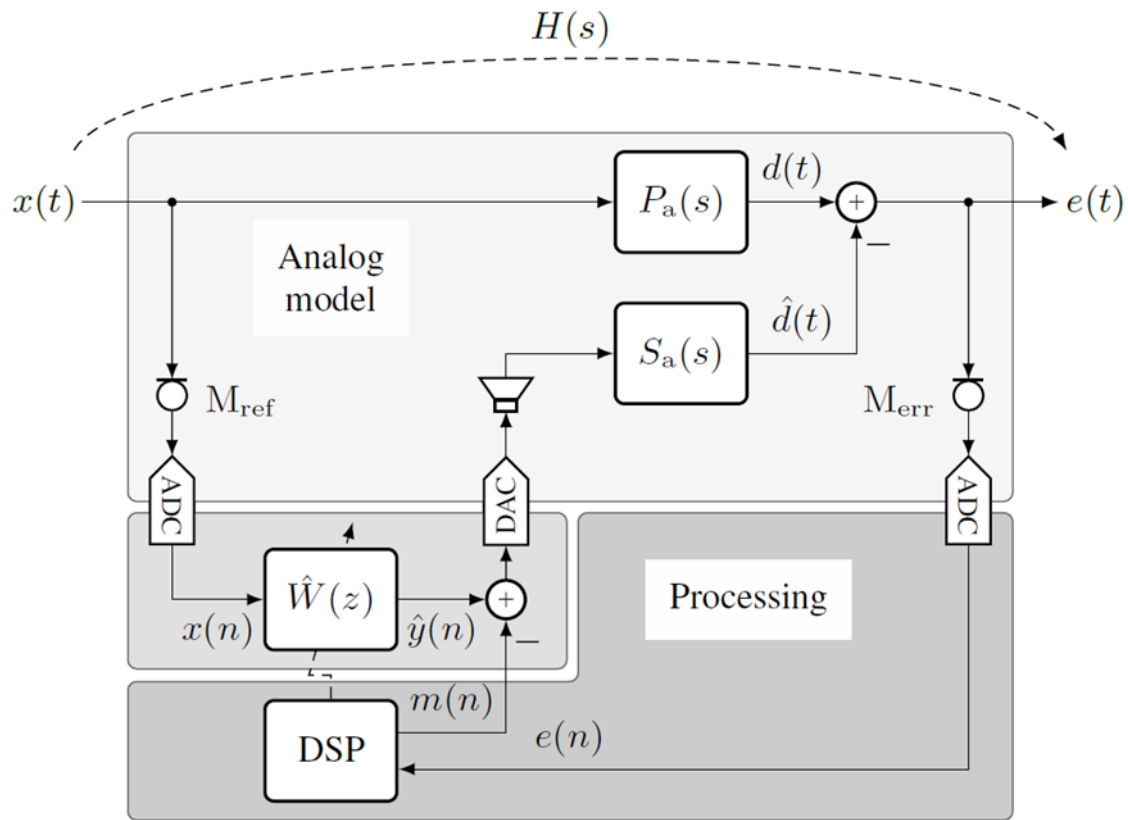
Feed-forward ANC Block Diagram

□ Analog model



Introduction

Feed-forward ANC Block Diagram

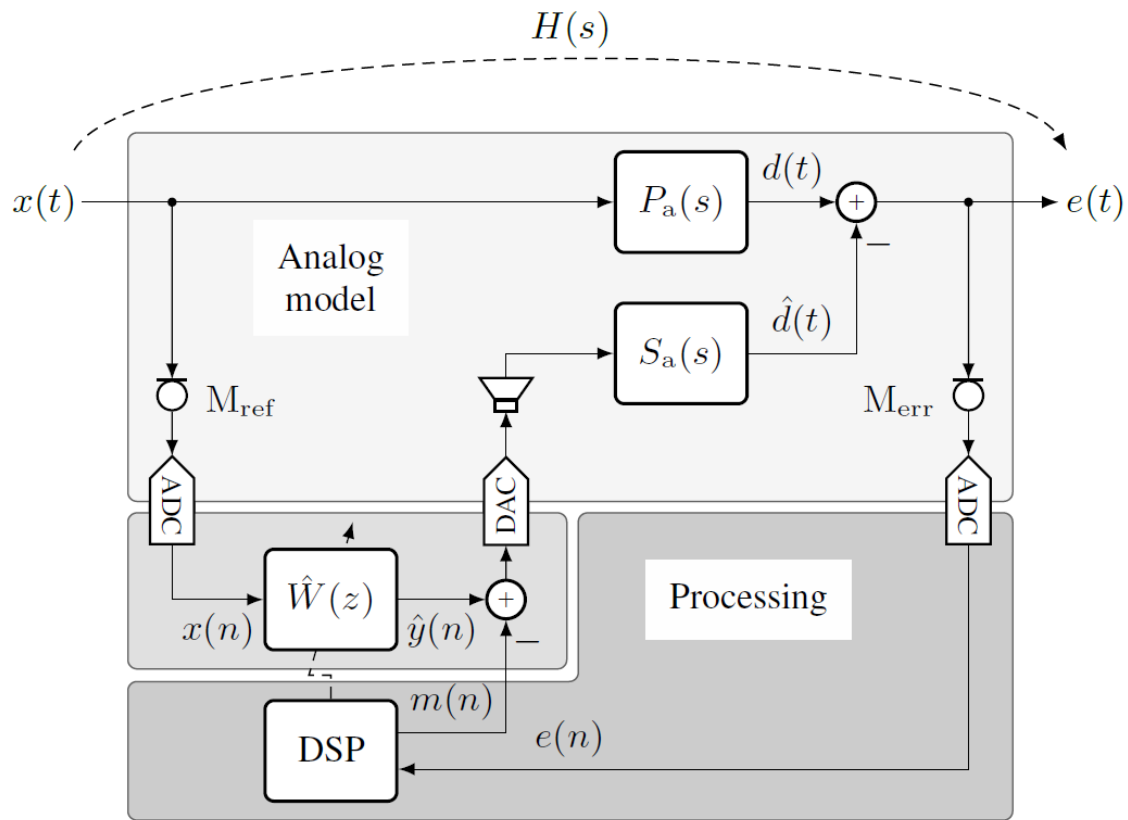





□ Analog model

■ Fast digital filter $\hat{W}(z)$

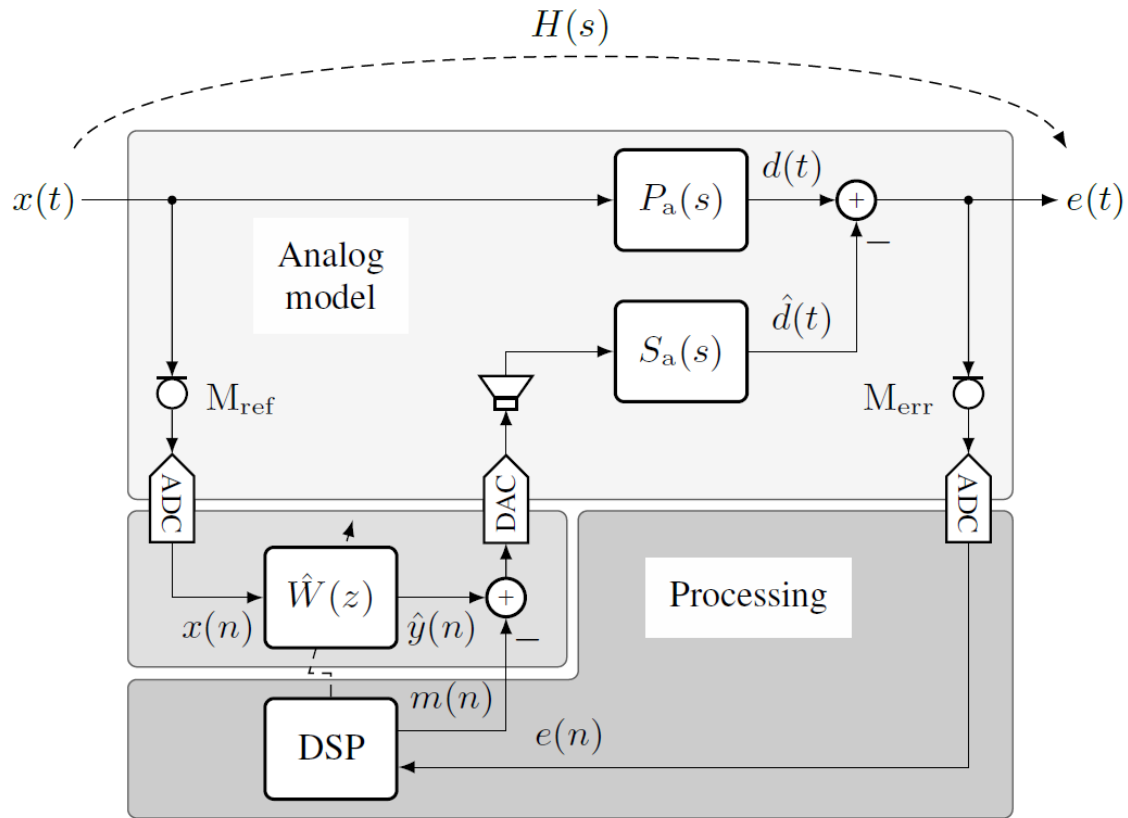
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Feed-forward ANC Block Diagram



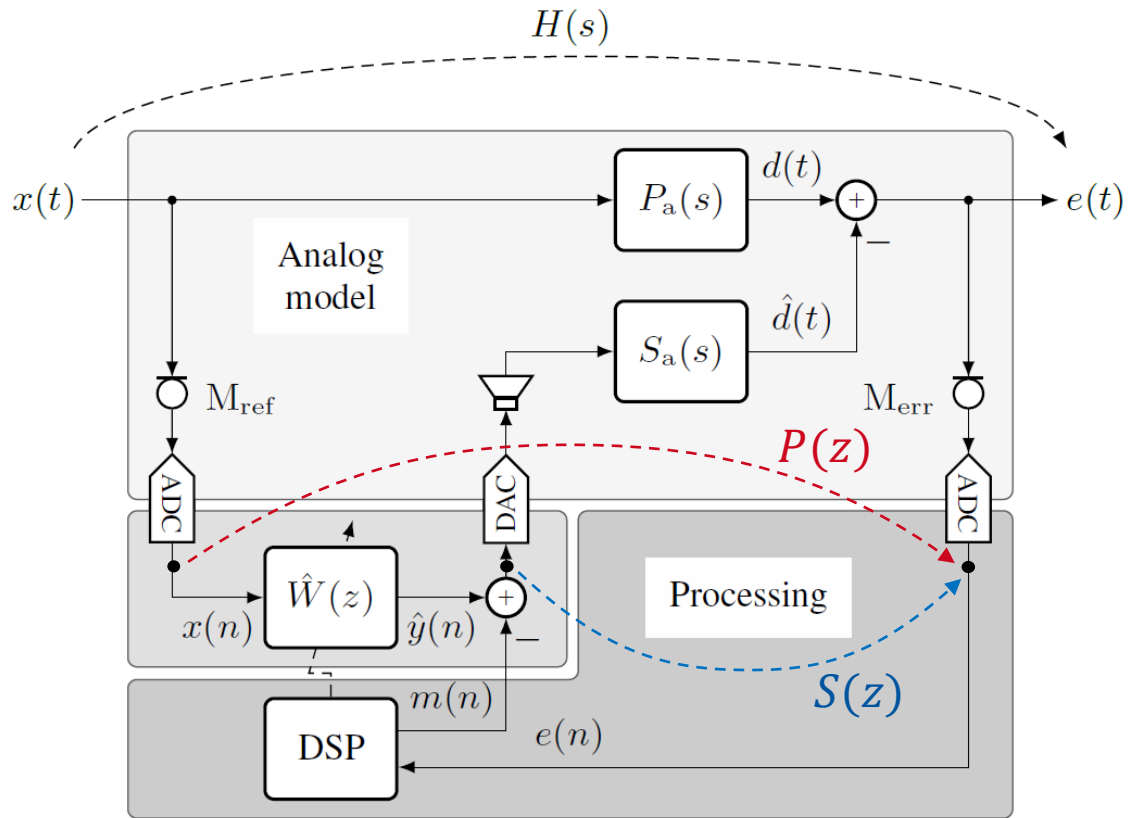
-  Analog model
-  Fast digital filter $\hat{W}(z)$
-  Processing unit

Feed-forward ANC Filter Design

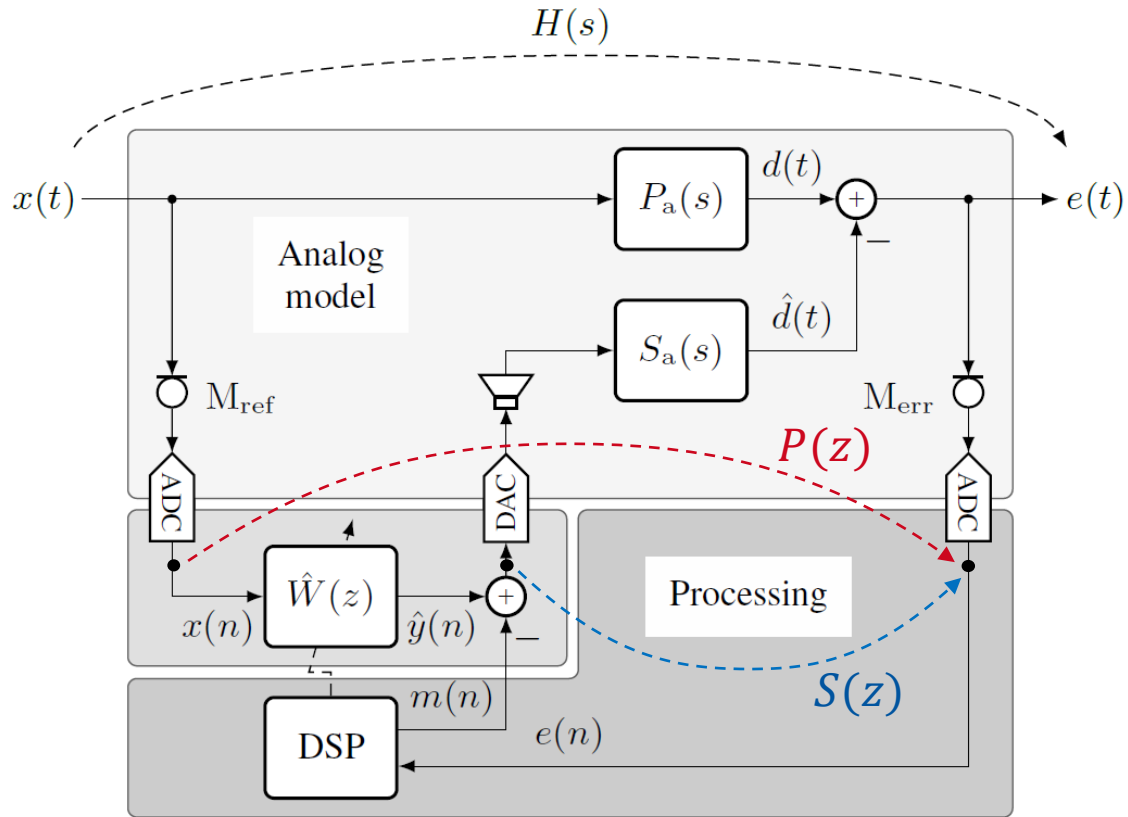


Introduction

Feed-forward ANC Filter Design



Feed-forward ANC Filter Design



■ Training set

$$\mathcal{T} = \{p_j, s_j \in \mathbb{R}^L \mid j = 1, \dots, J\}$$

of impulse responses

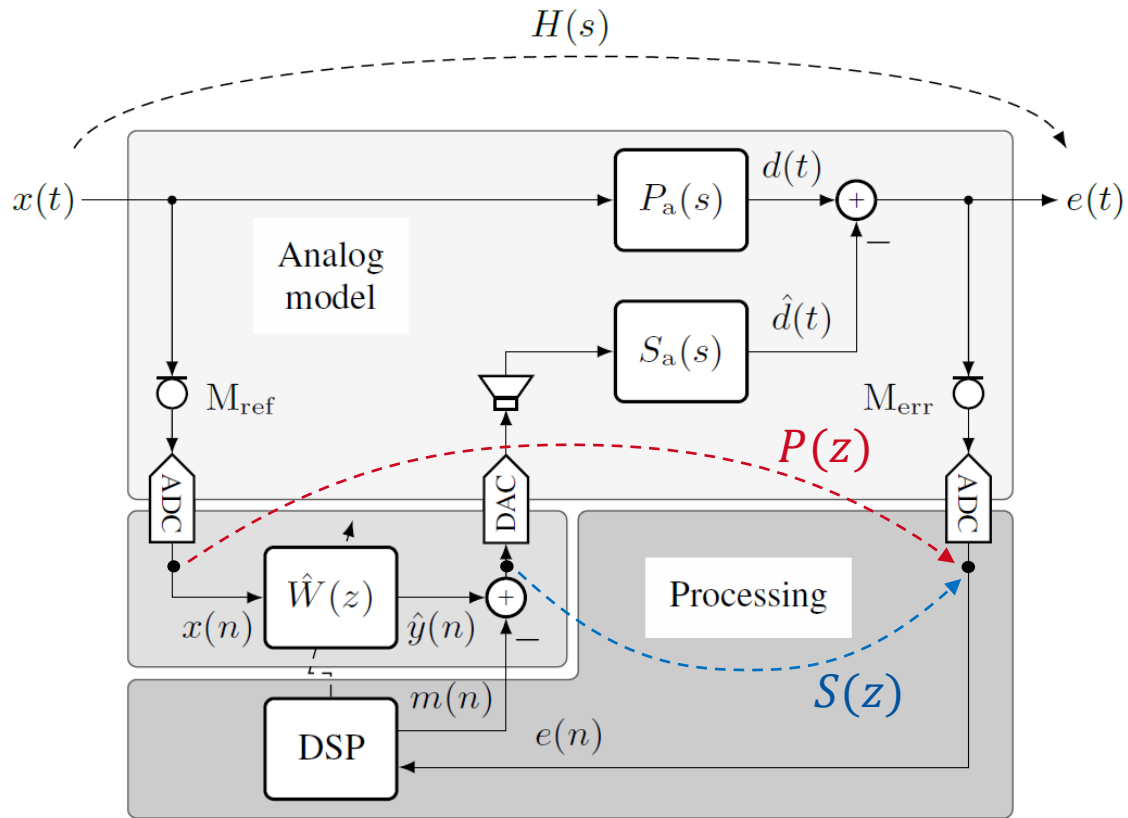
$$p = [p(0), p(1), \dots, p(L-1)]^T$$

$$s = [s(0), s(1), \dots, s(L-1)]^T$$

J Number of paths

L Filter length

Feed-forward ANC Filter Design



Training set

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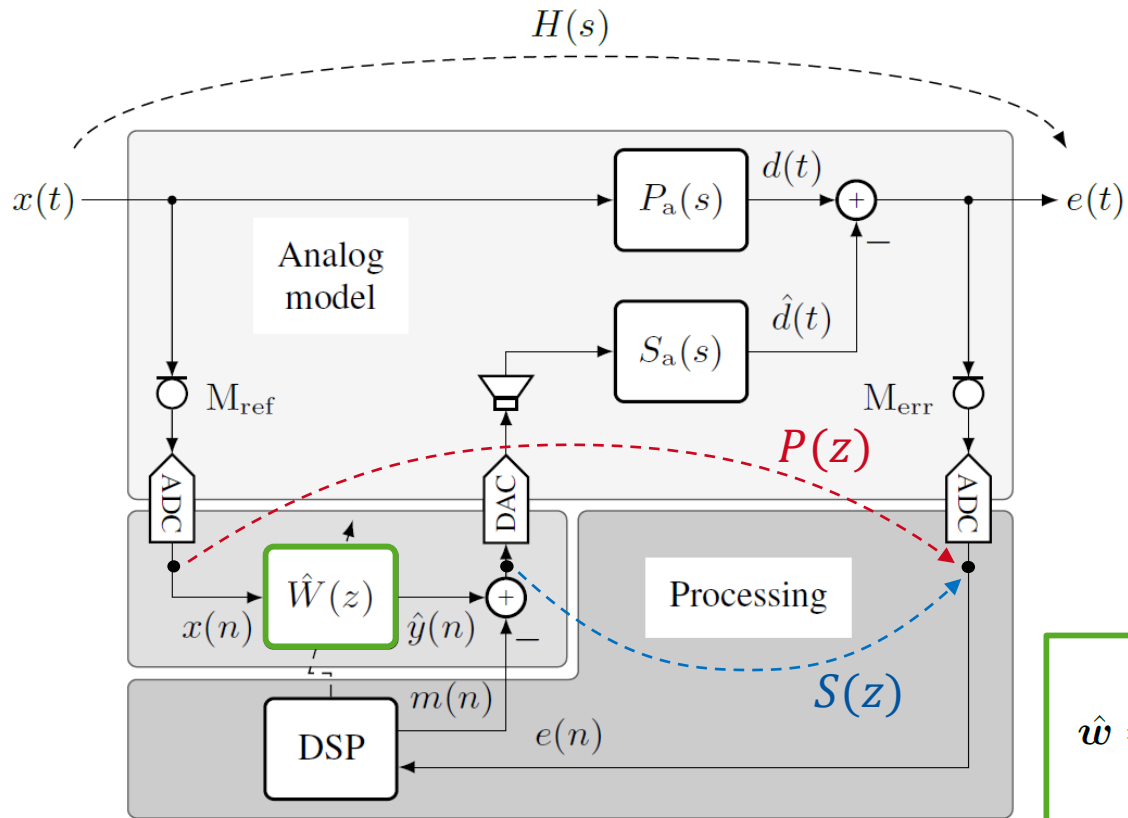
$$\mathbf{s} = [s(0), s(1), \dots, s(L-1)]^T$$

Cost function

$$C_{\mathbf{w}} = \sum_{j \in \mathcal{T}} \|\mathbf{p}_j^0 - \underline{\mathbf{s}}_j \mathbf{w}\|^2$$

- J Number of paths
- L Filter length
- \mathbf{p}^0 Zero-padded prim. Path
- $\underline{\mathbf{s}}$ Sec. path convolution matrix
- $\hat{\mathbf{w}}$ ANC FIR filter

Filter Design



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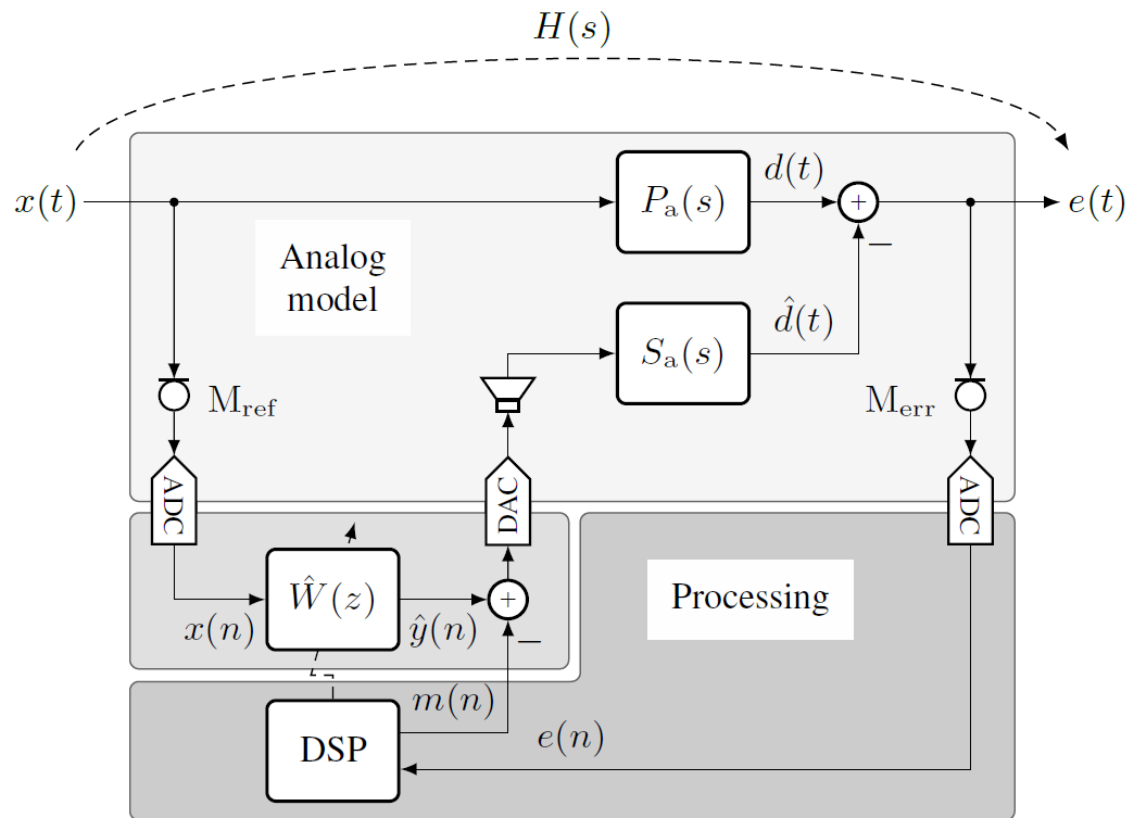
■ Cost function

$$\mathcal{C}_w = \sum_{j \in \mathcal{T}} \|\mathbf{p}_j^0 - \underline{\mathbf{s}}_j \mathbf{w}\|^2$$

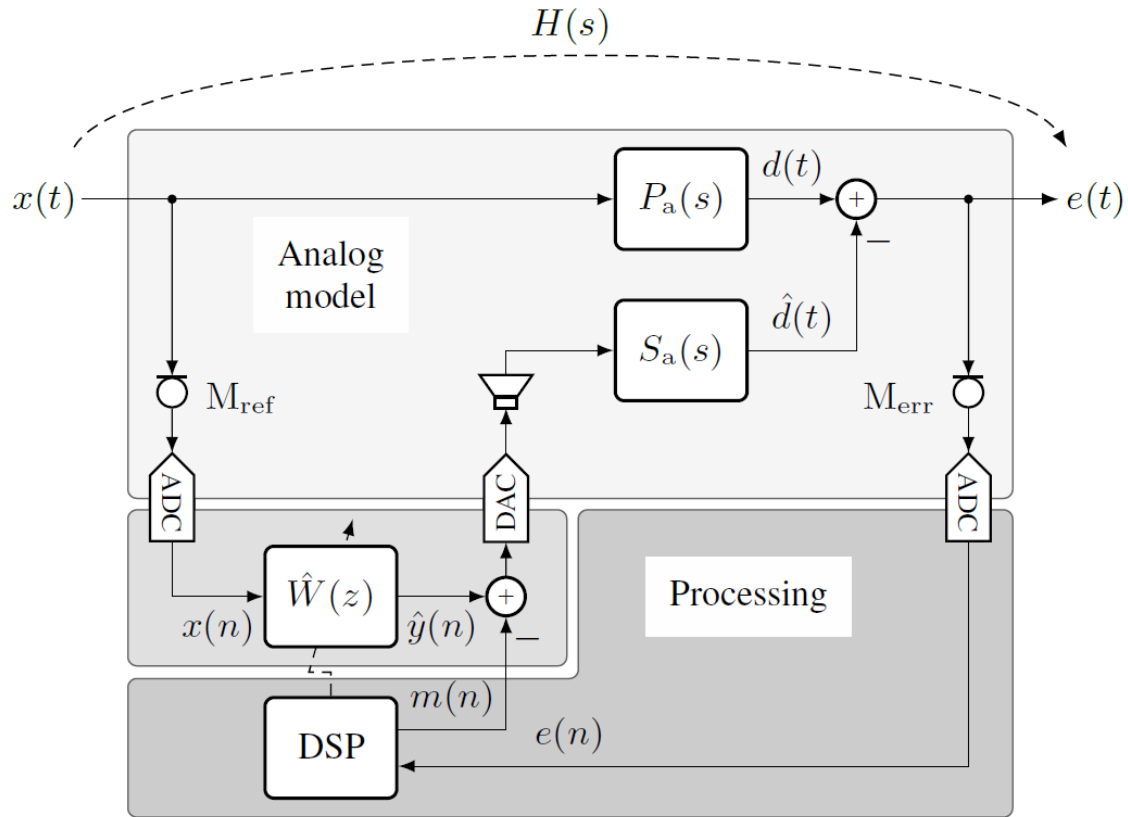
$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \mathcal{C}_w = \left(\sum_{j \in \mathcal{T}} \underline{\mathbf{s}}_j^T \underline{\mathbf{s}}_j \right)^{-1} \sum_{i \in \mathcal{T}} \underline{\mathbf{s}}_i^T \mathbf{p}_i^0$$

- J Number of paths
- L Filter length
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Secondary Path Measurement



Secondary Path Measurement



Filter design

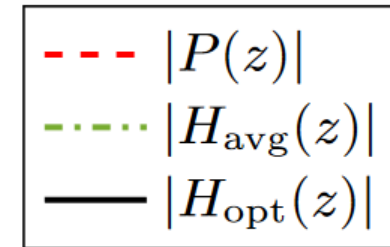
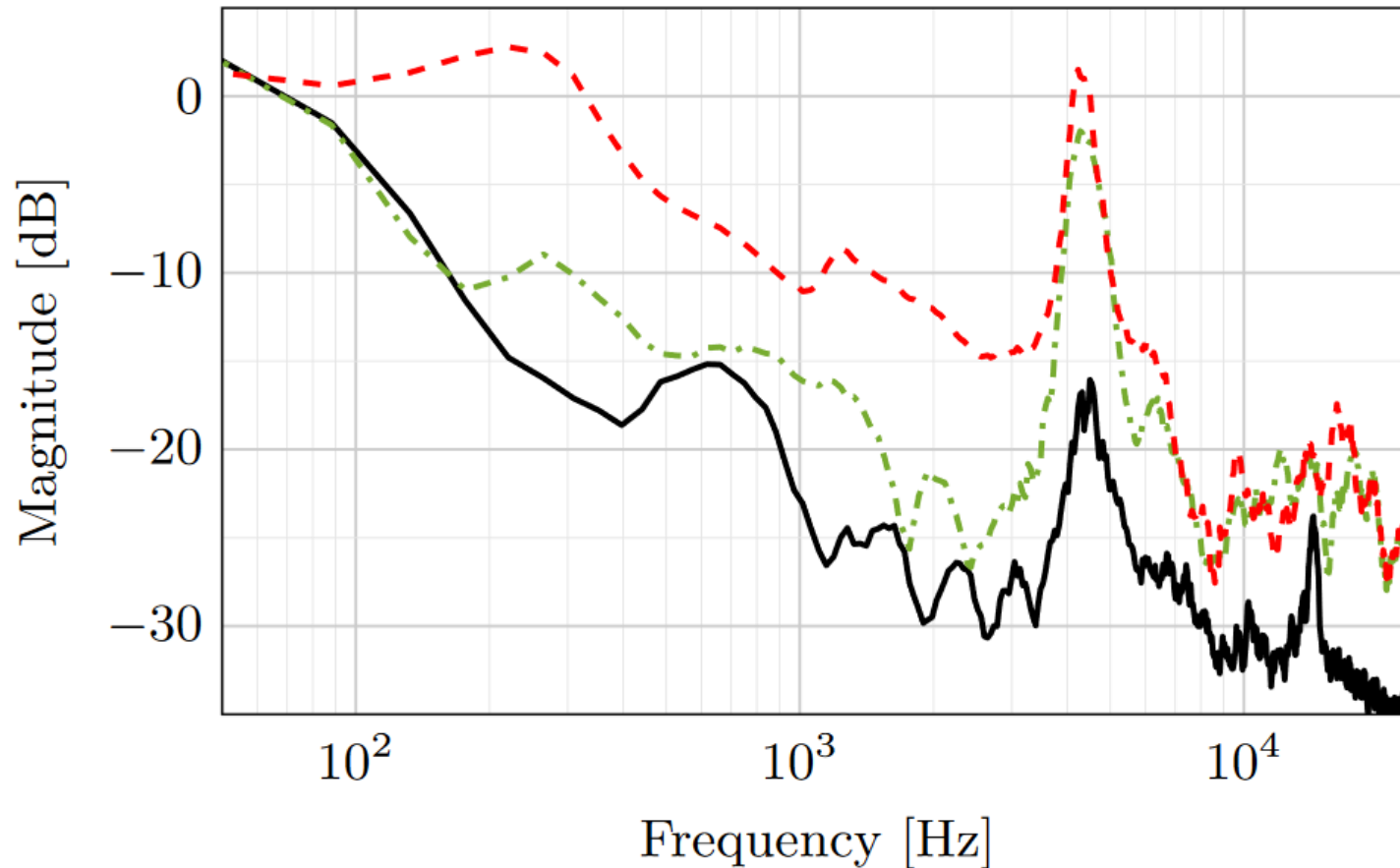
$$\hat{\mathbf{w}}_{\text{avg}} = \left(\underline{\mathbf{s}}^T \underline{\mathbf{s}} \right)^{-1} \underline{\mathbf{s}}^T \bar{\mathbf{p}}^0$$

based on individual secondary path
and averaged primary path

$$\bar{\mathbf{p}} = \frac{1}{J} \sum_{j \in \mathcal{J}} \mathbf{p}_j$$

Motivation

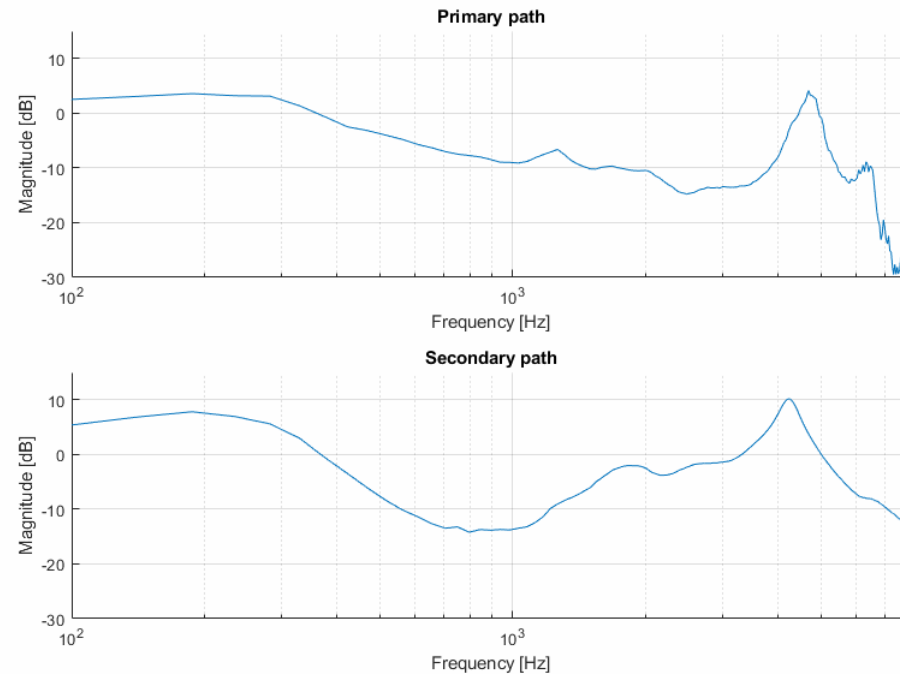
Median Individual Performance



- Better performance for perfect knowledge of primary path
- Can we reduce the gap?

Acoustic Paths

- Measurements of Bose QC20 for 25 subjects and different headphone fittings in anechoic chamber
- Strong coherence of primary and secondary paths in frequency domain





Primary Path Estimator

Goal

- Estimate primary path based on features from secondary path measurement



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Design Constrains

- Limited training data
 - Prevent overfitting
 - Ensure robustness
- Freq. regions of deterministic change

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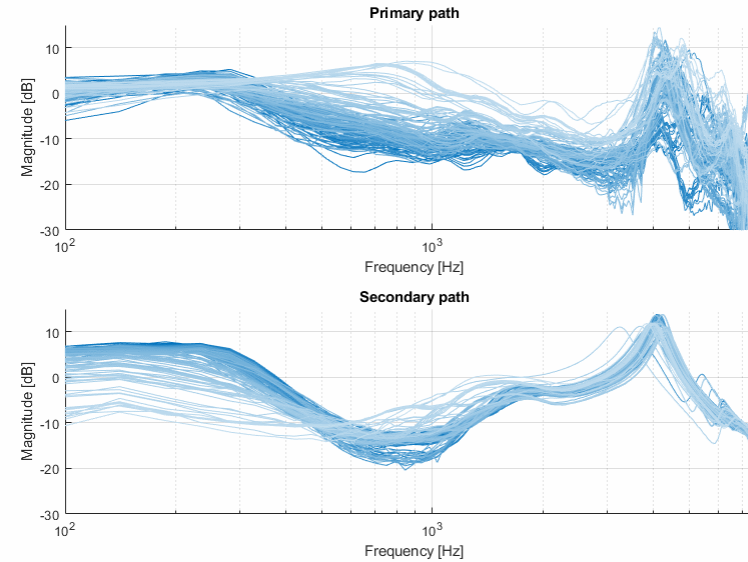
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- Perform dimensionality reduction
 - Principal component analysis
- Extract freq. regions

Primary Path Estimator

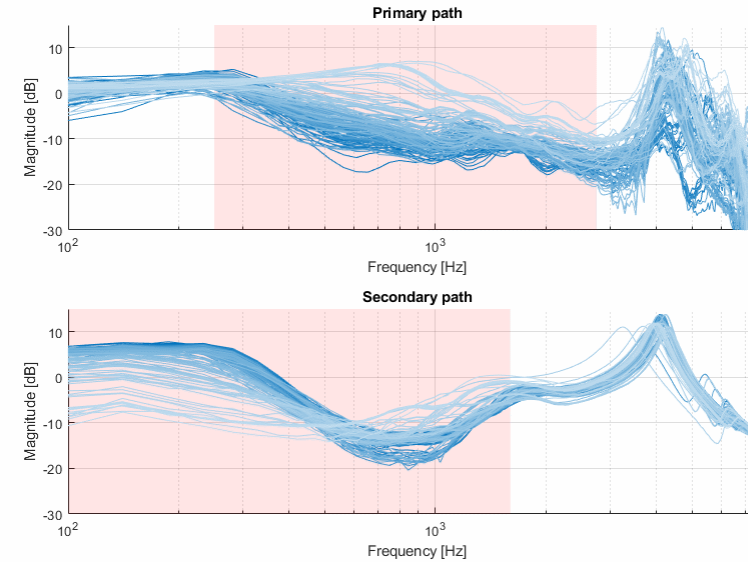
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Design Constrains

- Limited training data
 - Prevent overfitting
 - Ensure robustness

- Freq. regions of deterministic change



- Perform dimensionality reduction
 - Principal component analysis



- Extract freq. **regions**

Training: Principal Component Analysis (PCA)

- Extract regions by applying frequency domain window

$$P_q(z) = Q_p(z)P(z)$$

$$S_q(z) = Q_s(z)S(z)$$

- Perform PCA and dimensionality reduction on single-sided frequency domain vectors $\mathbf{P}_{q,j}, \mathbf{S}_{q,j} \in \mathcal{T}$.

- With $\hat{\mathbf{P}}_{q,j} = \bar{\mathbf{P}}_q + \underline{\mathbf{U}}_p \mathbf{g}_{p,j}$ obtain PCA gain vector by utilizing orthogonality of components

$$\mathbf{g}_{p,j} = \underline{\mathbf{U}}_p^H (\mathbf{P}_{q,j} - \bar{\mathbf{P}}_q)$$

and analogously for secondary path

Primary Path Estimator

Training: Linear Mapping

- Find matrix $\underline{\mathbf{a}} \in \mathbb{C}^{K_p \times K_s}$ that linearly maps secondary path PCA gains to primary path PCA gains
- Least squares cost function

$$\mathcal{C}_a = \sum_{j \in \mathcal{J}} \|\tilde{\mathbf{g}}_{p,j} - \underline{\mathbf{a}} \tilde{\mathbf{g}}_{s,j}\|^2 \quad \longrightarrow \quad \hat{\underline{\mathbf{a}}} = \arg \min_{\underline{\mathbf{a}}} \mathcal{C}_a = \sum_{j \in \mathcal{J}} \tilde{\mathbf{g}}_{p,j} \tilde{\mathbf{g}}_{s,j}^H \left(\sum_{i \in \mathcal{J}} \tilde{\mathbf{g}}_{s,i} \tilde{\mathbf{g}}_{s,i}^H \right)^{-1}$$

- Estimate primary path PCA gain

$$\hat{\mathbf{g}}_p = \bar{\mathbf{g}}_p + \hat{\underline{\mathbf{a}}} \mathbf{g}_s$$

Primary Path Estimator

Application summary

1. Measure individual secondary path
2. Calculate windowed single-sided frequency domain vector $S_q(z) = Q_s(z)S(z)$
3. Calculate secondary path PCA gain and estimate primary path PCA gain $\hat{\mathbf{g}}_p = \bar{\mathbf{g}}_p + \underline{\mathbf{a}}\mathbf{g}_s$
4. Calculate primary path estimate $\hat{\mathbf{P}} = \bar{\mathbf{P}} + \underline{\mathbf{U}}_p\hat{\mathbf{g}}_p$
5. Design feed-forward filter using individual primary and secondary path

Settings

- Set \mathcal{M} of $J = 173$ acoustic paths pairs for 25 subjects and different fittings
- Split \mathcal{M} randomly into training subset \mathcal{T} and validation subset \mathcal{V}
 - \mathcal{T} contains 80% of \mathcal{M}
 - \mathcal{V} contains remaining 20% of \mathcal{M}
- Train estimator based on \mathcal{T} and evaluate transfer function $H(z)$ for \mathcal{V}
- Repeat for 100 iterations

Length of acoustic paths: $L = 1024$

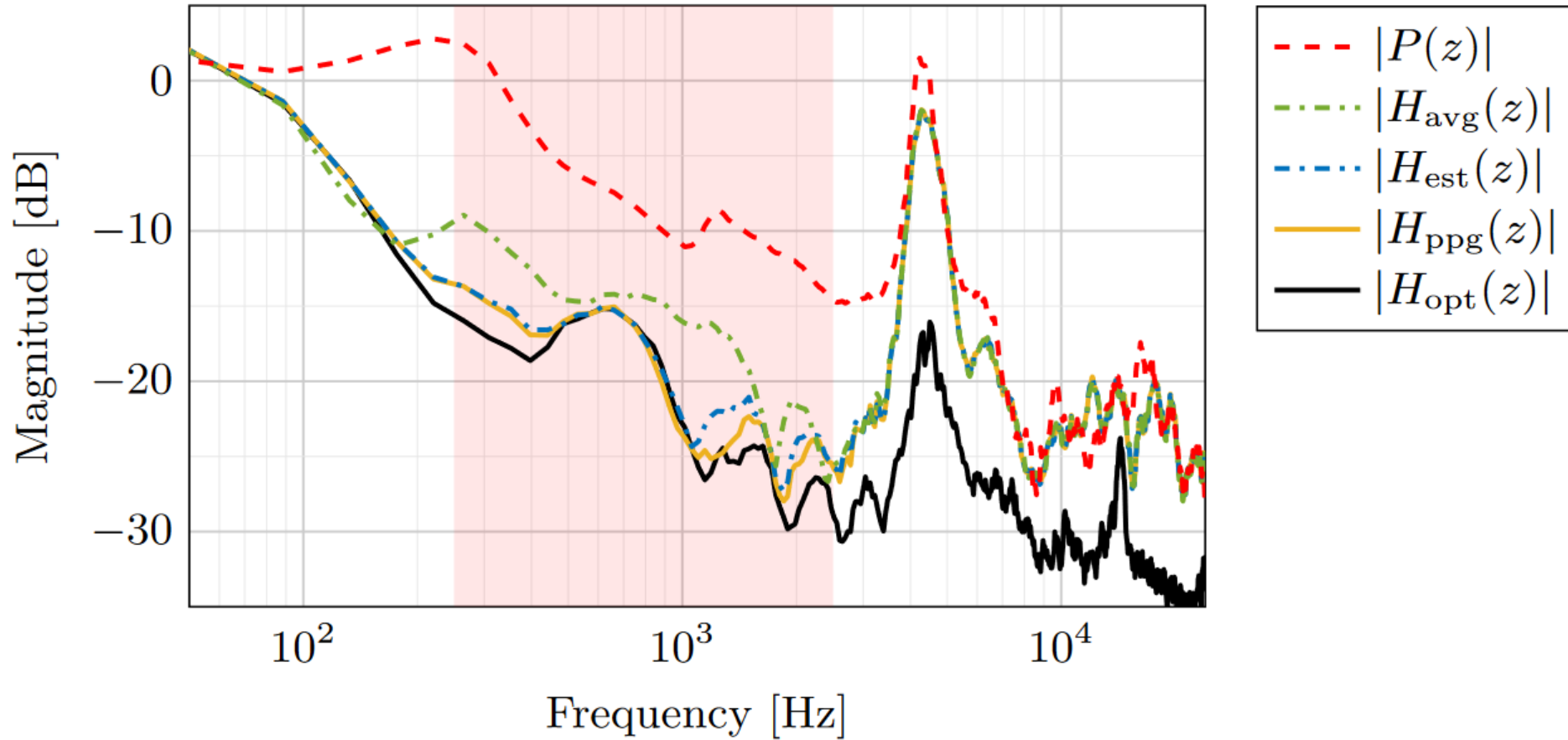
Length of feed-forward filter: $L_w = 64$

Sample rate: $f_s = 48$ kHz

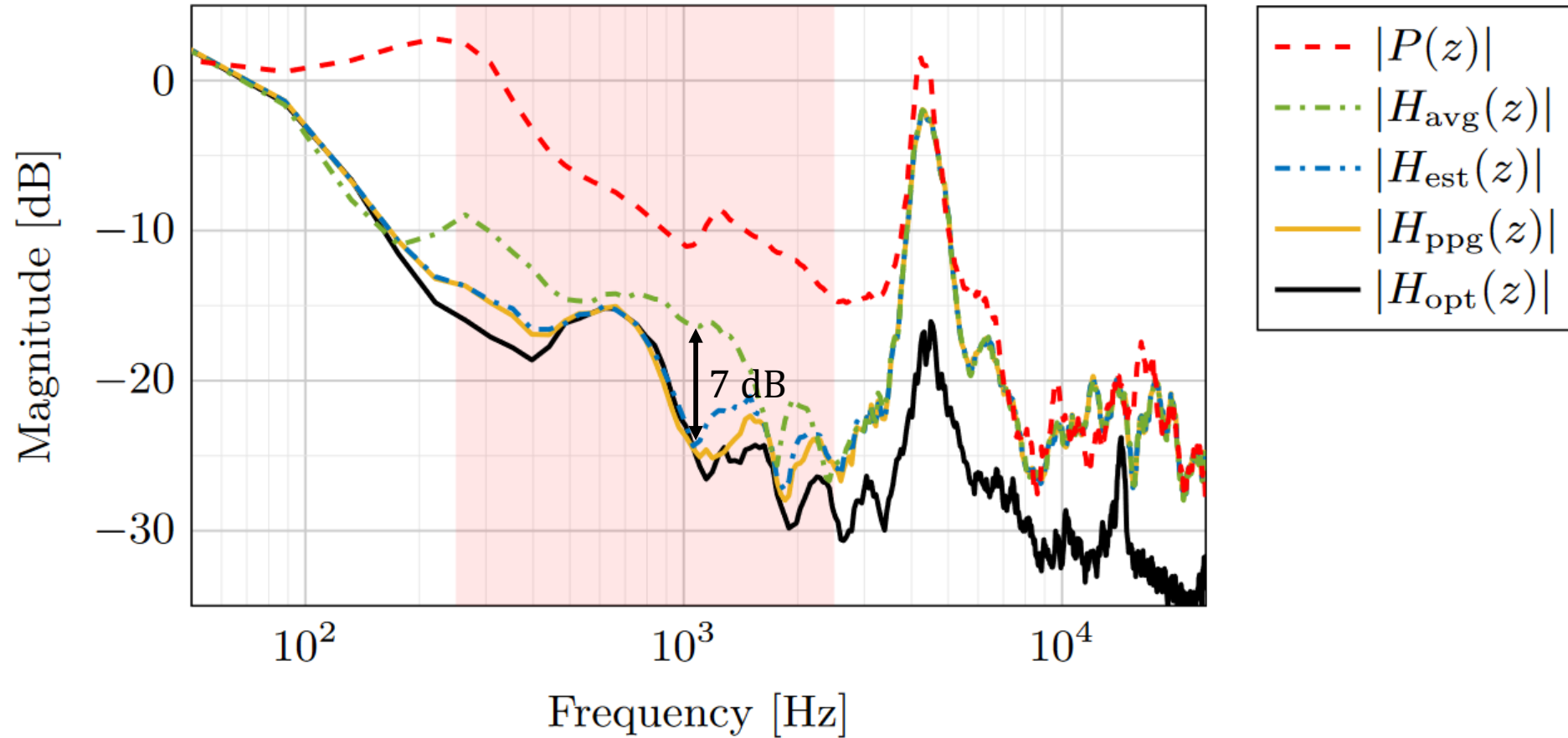
Number of prim. path comp.: $K_p = 1$

Number of sec. path comp.: $K_s = 3$

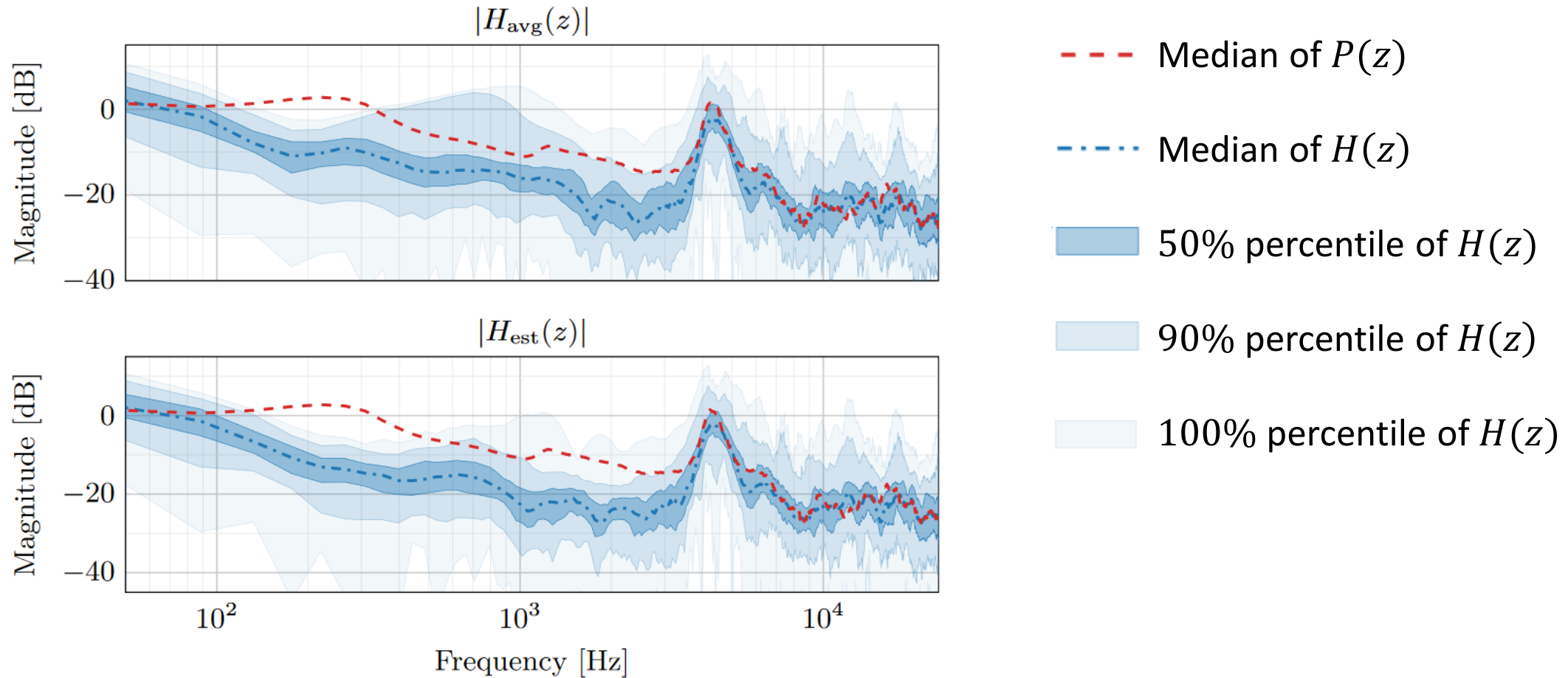
Median Individual Performance



Median Individual Performance



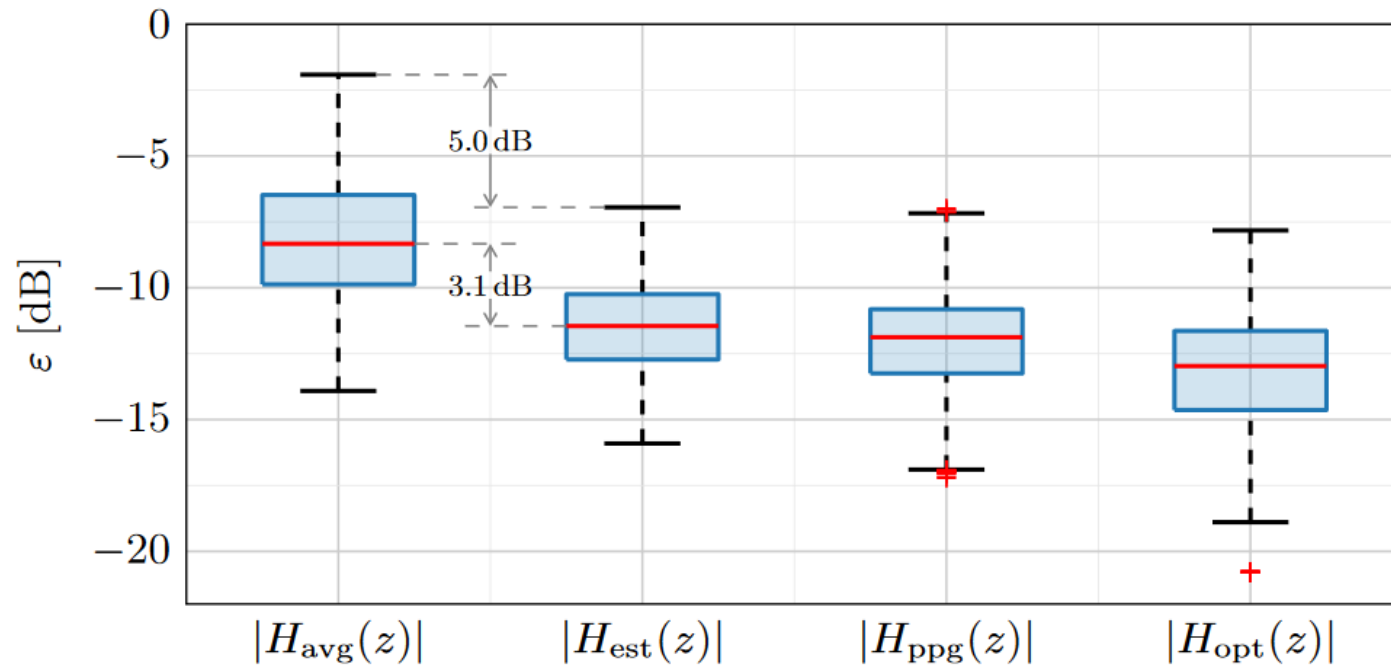
Uncertainty



Uncertainty

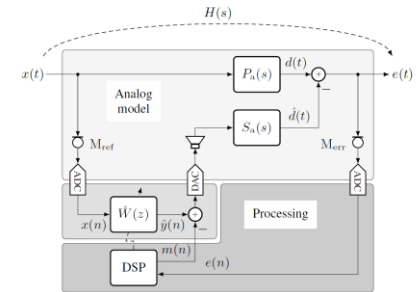
- Attenuation in deterministic region of primary path

- $$\varepsilon_j = \frac{\oint |H_{q,j}(z)|^2 dz}{\oint |P_{q,j}(z)|^2 dz}$$



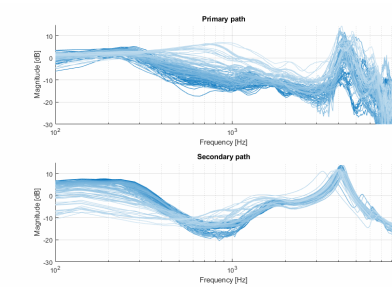
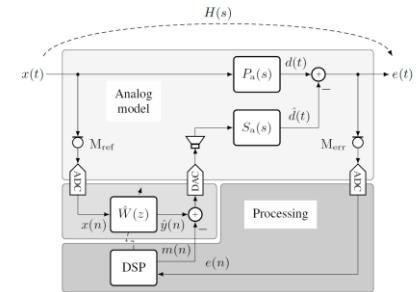
Conclusion

- Primary path estimator for individualization of ANC



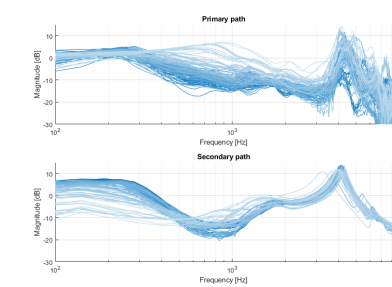
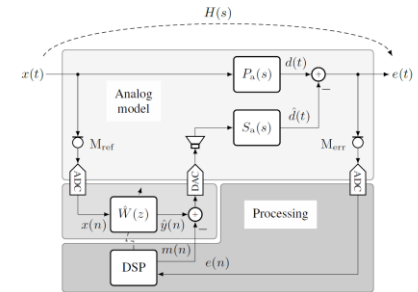
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Conclusion

- Primary path estimator for individualization of ANC
- Based on features from secondary path measurement
- Requires training stage
- Simulations show increased robustness of ANC

